First we define known quantities

$$In[\theta] := \Delta := r^2 - 2 \operatorname{M} r + a^2$$

$$\Sigma := r^2 + a^2 \operatorname{Cos}[\theta]^2$$

$$J := \operatorname{CDiracDelta}[r - r\theta] \operatorname{DiracDelta}[\theta - \frac{\pi}{2}]$$

$$Jm \dagger := \left(\sqrt{2} \left(r - \overline{\theta} \operatorname{a} \operatorname{Cos}[\theta]\right)\right)^{-1} + \overline{\theta} \left(r^2 + a^2\right) \operatorname{Sin}[\theta] \operatorname{J}$$

$$Jn := -\frac{a \Delta}{5} \operatorname{Sin}[\theta]^2 \operatorname{J}$$

Now for J2, we can ignore  $\partial_{\varphi}$  since Jm and Jn are independent of it

$$J_{2} = \frac{-\Delta}{2\sqrt{2} \sum (r - ia \cos \theta)^{2}} \left[ \sqrt{2} \left( \frac{\partial}{\partial r} - \frac{a}{\Delta} \frac{\partial}{\partial \varphi} + \frac{1}{r - ia \cos \theta} \right) (r - ia \cos \theta)^{2} J_{\overline{m}} \right]$$

$$+ 2 \left( \frac{\partial}{\partial \theta} - \frac{i}{\sin \theta} \frac{\partial}{\partial \varphi} + \frac{ia \sin \theta}{r - ia \cos \theta} \right) \frac{\sum (r - ia \cos \theta)}{\Delta} J_{n}$$

$$(2.12)$$

$$In[\bullet]:= J2 := \frac{-\Delta}{2 \sqrt{2} \Sigma \left(r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]\right)^{2}}$$

$$\left(\sqrt{2} \left(\partial_{r} # + \frac{1}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} #\right) \&@\left(\left(r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]\right)^{2} \operatorname{Jmt}\right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} #\right) \&@\left(\left(r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]\right)^{2} \operatorname{Jmt}\right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} #\right) \&@\left(\left(r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]\right)^{2} \operatorname{Jmt}\right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Sin}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]} \right) + 2 \left(\partial_{\theta} # + \frac{\overline{\imath} \operatorname{a} \operatorname{Cos}[\theta]}{r - \overline{\imath}$$

Finally for the integration we need to first look at the definition of the SpinWeighted spherical harmonics

Since all SpinWeighted spherical harmonics, here denoted  $_s Y_{lm}(\theta, \phi) = Y[s, l, \theta, \phi]$  behave in the  $\phi$  argument as  $Exp[i m \phi]$  and since all other variables are independent of  $\phi$  in the equation above We have

 $\int Y[s,l,m,\theta,\phi] = 2 \pi \text{ DiracDelta}[m,0] Y[s,l,m,\theta,0].$  Then we can integrate over  $\theta$ .

$${}^{2}J_{lm}(r) = \int_{0}^{2\pi} \int_{0}^{\pi} \frac{(r - ia \cos \theta)^{2}}{(r_{+} - r_{-})^{2}} \sum_{j=1}^{2} J_{2} \int_{-1}^{2\pi} \overline{Y}_{lm} \sin \theta \, d\theta \, d\varphi$$

In[o]:=

We can split the integrand into two parts depending if we have DiracDelta $\left[\theta - \frac{\pi}{2}\right]$  or the derivative DiracDelta' $\left[\theta - \frac{\pi}{2}\right]$ .

and we will use the standard properties

$$\int_{-\infty}^{\infty} f(x) \, \delta(x - a) \, dx = f(a)$$

$$\int f(x) \, \delta^{(n)}(x) \, dx = -\int \frac{\partial f}{\partial x} \, \delta^{(n-1)}(x) \, dx.$$

First part

$$In[a]:= \frac{\left(\mathbf{r} - \mathbf{i} \text{ a } \mathsf{Cos}[\boldsymbol{\theta}]\right)^2}{\left(\mathsf{rp} - \mathsf{rm}\right)^2} \; \boldsymbol{\Sigma} \; \boldsymbol{\mathsf{J2}} \; \mathsf{Conjugate}[\mathsf{Y}[-1, \, \mathsf{l}, \, \mathsf{0}, \, \boldsymbol{\theta}, \, \mathsf{0}]];$$

$$\% \; /. \; \mathsf{DiracDelta}[-\pi + 2 \; \boldsymbol{\theta}] \to 1 \; /. \; \mathsf{DiracDelta}[-\pi + 2 \; \boldsymbol{\theta}] \to 0;$$

$$\mathsf{FirstPart} \; = \; \% \; /. \; \boldsymbol{\theta} \to \frac{\pi}{2}$$

$$Out[a]:= -\frac{1}{2 \sqrt{2} \; (-\mathsf{rm} + \mathsf{rp})^2} \left(\mathbf{a}^2 - 2 \; \mathsf{M} \; \mathsf{r} + \mathsf{r}^2\right) \mathsf{Conjugate}[\mathsf{Y}[-1, \, \mathsf{l}, \, \mathsf{0}, \, \frac{\pi}{2}, \, \mathsf{0}]]$$

$$\left(-8 \; \mathbf{i} \; \mathbf{a}^2 \; \mathsf{C} \; \mathsf{DiracDelta}[\mathsf{r} - \mathsf{r0}] + \sqrt{2} \left(3 \; \mathsf{r} \left(\frac{1}{\sqrt{2} \; \mathsf{r}} + 2 \; \mathbf{i} \; \mathsf{C} \; (\mathbf{a}^2 + \mathsf{r}^2) \; \mathsf{DiracDelta}[\mathsf{r} - \mathsf{r0}]\right) + \right) \right)$$

$$\mathsf{r}^2 \left(-\frac{1}{\sqrt{2} \; \mathsf{r}^2} + 4 \; \mathbf{i} \; \mathsf{C} \; \mathsf{r} \; \mathsf{DiracDelta}[\mathsf{r} - \mathsf{r0}] + 2 \; \mathbf{i} \; \mathsf{C} \; (\mathbf{a}^2 + \mathsf{r}^2) \; \mathsf{DiracDelta}[\mathsf{r} - \mathsf{r0}]\right)\right)$$

Second part

$$\frac{\left(r - \bar{\imath} \text{ a Cos}[\theta]\right)^{2}}{(rp - rm)^{2}} \text{ $\Sigma$ J2 Conjugate}[Y[-1, 1, 0, \theta, 0]];$$

$$\% \text{ $/$. DiracDelta}[-\pi + 2\theta] \rightarrow 0 \text{ $/$. DiracDelta}[-\pi + 2\theta] \rightarrow 1;$$

$$\text{SecondPart} = -D[\%, \theta] \text{ $/$. } \theta \rightarrow \frac{\pi}{2} \text{ $/$. Conjugate}[Y[-1, 1, 0, \frac{\pi}{2}, 0]] \rightarrow 1$$

$$\text{Out}[*] = -\frac{2 \, \bar{\imath} \, \sqrt{2} \, a^{2} \, C\left(a^{2} - 2 \, M \, r + r^{2}\right) \text{Conjugate}[Y[-1, 1, 0, \frac{\pi}{2}, 0]] \, \text{DiracDelta}[r - r0]}{(-rm + rp)^{2}} + \frac{\left(a^{2} - 2 \, M \, r + r^{2}\right)\left(2 - 8 \, a \, C \, r \, \text{DiracDelta}[r - r0]\right) \, Y^{(0,0,0,1,0)}[-1, 1, 0, \frac{\pi}{2}, 0]}{2 \, \sqrt{2} \, (-rm + rp)^{2}}$$

We get the solution

$$Out[*]* = -\frac{2i\sqrt{2} \text{ a}^2 \text{ C} \left(\text{a}^2 - 2 \text{ M r} + \text{r}^2\right) \text{Conjugate}[Y[-1, 1, 0, \frac{\pi}{2}, 0]] \text{ DiracDelta}[r - r0]}{(-rm + rp)^2} - \frac{1}{2\sqrt{2} (-rm + rp)^2} \left(\text{a}^2 - 2 \text{ M r} + \text{r}^2\right) \text{Conjugate}[Y[-1, 1, 0, \frac{\pi}{2}, 0]]}{\left(-8i \text{ a}^2 \text{ C DiracDelta}[r - r0] + \sqrt{2} \left(3 \text{ r} \left(\frac{1}{\sqrt{2} \text{ r}} + 2i \text{ C} \left(\text{a}^2 + \text{r}^2\right) \text{DiracDelta}[r - r0]\right) + r^2 \left(-\frac{1}{\sqrt{2} \text{ r}^2} + 4i \text{ C r DiracDelta}[r - r0] + 2i \text{ C} \left(\text{a}^2 + \text{r}^2\right) \text{DiracDelta}[r - r0]\right)\right)\right) + \frac{\left(\text{a}^2 - 2 \text{ M r} + \text{r}^2\right)\left(2 - 8 \text{ a C r DiracDelta}[r - r0]\right) \text{ Y}^{(0,0,0,1,0)}[-1, 1, 0, \frac{\pi}{2}, 0]}{2\sqrt{2} \left(-rm + rp\right)^2}$$

We should further utilize identities for the Y function but we can already see that we must have made a mistake

Since the solution given in the article (C = I  $\left(\frac{\Delta 0}{P0}\right)$ ) and (e = 0)

$${}^{2}J_{lm} = -\frac{\Delta\delta_{m0}}{\sqrt{2} (r_{+} - r_{-})^{2}} \left[ (Mae/\mathfrak{A}_{0}) + \pi \mathfrak{J}(\Delta_{0}/\mathfrak{A}_{0})^{1/2} \right]$$

$$\cdot \left[ i(r_{0}^{2} + a^{2})_{-1} \overline{Y}_{l0} \left( \frac{\pi}{2}, 0 \right) \delta'(r - r_{0}) \right]$$

$$+ \left\{ ir_{0}_{-1} \overline{Y}_{l0} \left( \frac{\pi}{2}, 0 \right) - a \left[ l(l+1) \right]^{1/2} {}_{0} \overline{Y}_{l0} \left( \frac{\pi}{2}, 0 \right) \right\} \delta(r - r_{0}) \right]$$

Is only quadratic in r, but our solution is at least quartic in r.