

# **Sprint 1**

**Package Delivery Robot  
in Apartment**

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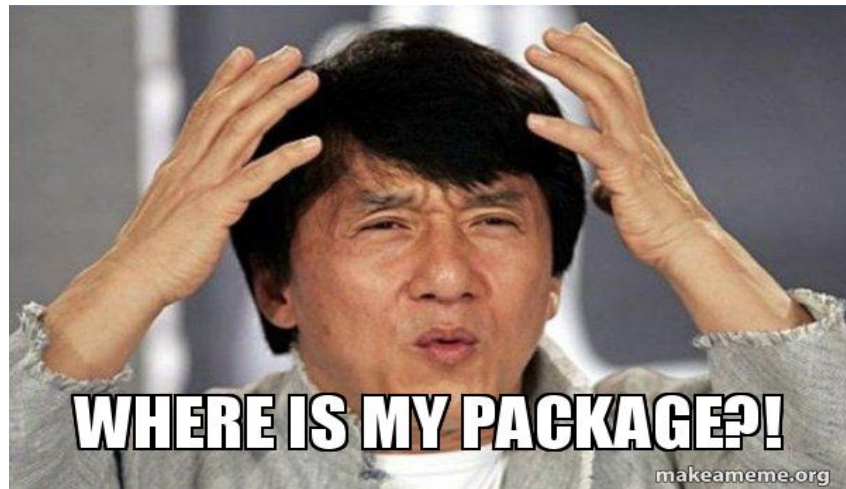
# Outline

- Product Mission
- Potential Users
- Literature Review
- User Strory
- Minimum Valuable Product (MVP)
- Techonology & Development Environment



- What to solve —→ Package Receiving Problem
- Why solve it —→ Packages in the mail room mistaken by others

**210 million packages were stolen from Americans in 2021: report**





- Everyone who has the demand for receiving packages.
  - Focus on apartments → Normally have a mail room.

Product  
Mission

Potential  
Users

Literature  
review

User Story

MVP

Technology &  
Development



Actual Robot used in a hotel in Singapore

Product  
Mission

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Technology &  
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- **As an apartment resident**, I want to have an app that can deliver my packages to my door by just tapping the user interface and schedule when the packages will be sent at my door
- Because the packages sometimes mistaken by others, we may need a delivery robot that can read the personal information of the packages and classify them correctly.



Image Credits: Fedex



- **As developer**, collecting the data of the working environments as much as possible is required.
- Maintain the robot is an issue, so avoid the robot to bump into obstacles to cause damaged plays an important role.

Product  
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Users

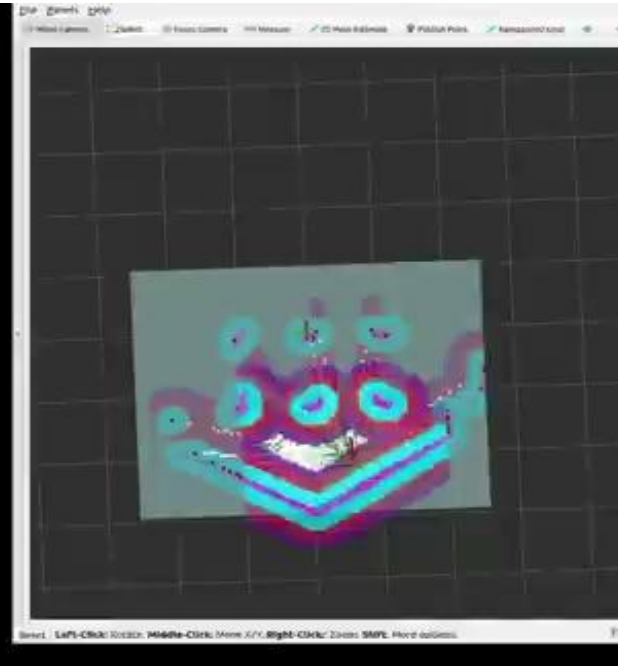
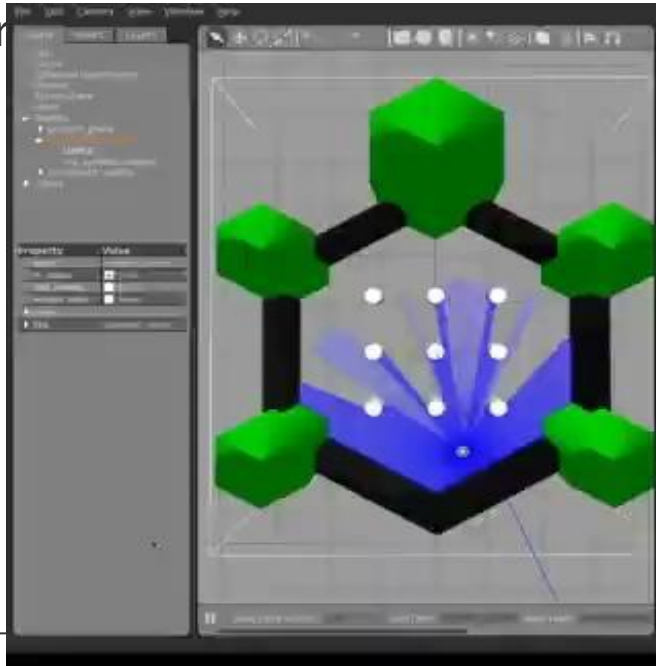
Literature  
review

User Story

MVP

Technology &  
Development

- Short demo in ROS 2. Control the turtlebot to navigate in a simple environment







- Robot Operation System (ROS )
- There are ROS1 & ROS 2. Why ROS 2 ?

|       | Numbers of robots | Platform           | Real-time performance | Stability |
|-------|-------------------|--------------------|-----------------------|-----------|
| ROS 1 | Single            | Linux              | Lack of support       | Not good  |
| ROS 2 | Multiple          | OS, Windows, Linux | Support               | better    |

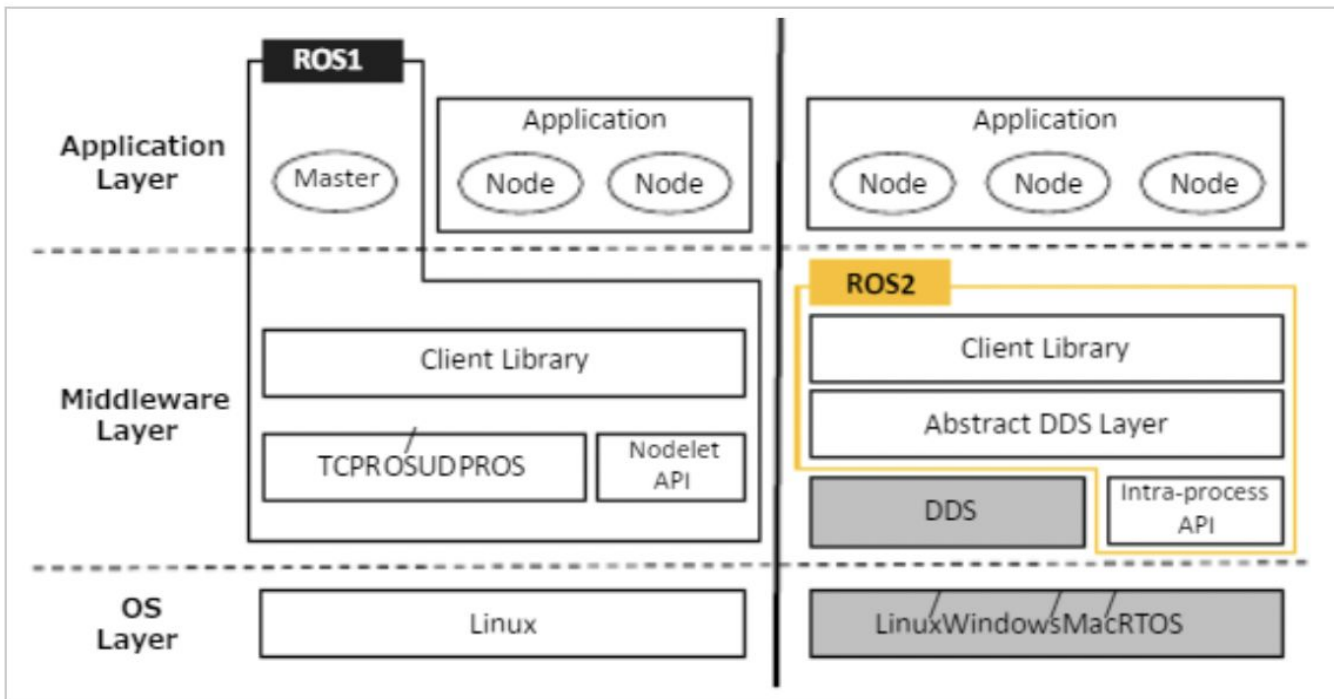


Figure credit to Y. Maruyama, S. Kato, and T. Azumi. Exploring the Performance of ROS2. In Proc. of ACM EMSOFT, pages 5:1–5:10, 2016.

## Next Sprint

1. Simulate the robot in complex environment to examine the navigation packages and other functions.
2. Come up with an idea to make the robot upload and download the packages.
3. Any possible errors need to be modified during the process.

Question ?