

The Australian National University
2600 ACT | Canberra | Australia



Australian
National
University

School of Computing

College of Engineering, Computing
and Cybernetics (CECC)

Sprinkle Magic on the Dance: Enriching a Verified Choreographic Language with a Simply Typed Lambda Calculus

— Honours project (S1/S2 2024)

A thesis submitted for the degree
Bachelor of Advanced Computing (Research and Development)

By:
Xin Lu

Supervisor:
Dr. Michael Norrish

October 2024

Declaration:

I declare that this work:

- upholds the principles of academic integrity, as defined in the [University Academic Misconduct Rules](#);
- is original, except where collaboration (for example group work) has been authorised in writing by the course convener in the class summary and/or Wattle site;
- is produced for the purposes of this assessment task and has not been submitted for assessment in any other context, except where authorised in writing by the course convener;
- gives appropriate acknowledgement of the ideas, scholarship and intellectual property of others insofar as these have been used;
- in no part involves copying, cheating, collusion, fabrication, plagiarism or recycling.

October, Xin Lu

Acknowledgements

If you wish to do so, you can include some Acknowledgements here. If you don't want to, just comment out the line where this file is included.

There is absolutely no need to write an Acknowledgement section, so only do so when you *want* to – it's always important to stay sincere. One reason for including an acknowledgement could be to thank your supervisor for extraordinary supervision (or any other reason you deem noteworthy). Some supervisors sacrifice a lot, e.g., are always available, meet on weekends, provide multiple rounds of corrections for theses reports, or the like (keep in mind that writing a thesis is special for you, but not for them, so they do actually not have any reason to sacrifice their private time for this!). Seeing acknowledgements in this report can feel like a nice appreciation of this voluntary effort. For large works that form the end of some studies (like an Honours or Master thesis), it is also not uncommon to read acknowledgements to one's parents or partner. But again, completely optional!

Abstract

Distributed systems are ubiquitous but writing endpoint programs can be error-prone since mismatched message sending and receiving can lead to errors such as deadlock, where the system indefinitely awaits a message. Choreography offers a solution by providing a global description of how messages are exchanged among endpoints, where message mismatches are disallowed — a property called “deadlock-free by design.” The global choreography is then projected into process models for each endpoint via EndPoint Projection (EPP), preserving the deadlock-free property.

While many choreography languages focus on message exchange behaviors, few address the local computations occurring within endpoints. Most current languages assume local computation results or delegate them to external languages. While this offers a reasoning ground for studying message exchange behaviours of choreography, when it comes to writing a concrete choreography program, the former can only exchange literal values and the latter leads to cumbersome code due to the addition of an external computation program which typically involves conversions between choreography values and external data types.

Hence in this thesis, we extend Kalas, a state-of-art choreography language with verified end-to-end compilation, with a local language **Sprinkles**, such that local computations are handled gracefully within a few lines of codes. Moreover, it also allows us to formally analyse the message exchange behaviours of choreography when local computations are considered.

We design **Sprinkles** as a simply typed lambda calculus with function closure. We use a functional bis-step semantics with clocks to ensure the evaluation function for **Sprinkles** is total. We prove type soundness for the proposed semantics and typing rules. We also provide a strong normalisation proof for **Sprinkles**.

We extend the Kalas’ *let* transition with **Sprinkles** expressions. Besides common data types such as integer, string, and boolean, we also add function, pair, and sum types to the local computation in choreography. Common operators for our data types are included, such as addition, modulo, and negation. An integer-string converter is implemented as well to handle message strings in Kalas. Last but not least, we prove the enriched Kalas enjoys progress. We also show type preservation holds for non-recursive, synchronised transitions.

Table of Contents

1	Introduction	1
2	Background	5
2.1	Choreography as a Programming Diagram	5
2.2	Interactive Theorem Proving	6
2.3	Kalas	6
3	Related Work	7
3.1	Choreography Models	7
3.1.1	Typing System for Choreography	7
3.1.2	Handling Exceptions	8
3.2	Some Title	9
4	Sprinkles: A Simply Typed Lambda Calculus	11
4.1	Syntax	11
4.2	Semantics	12
4.2.1	Function Closure	13
4.3	Typing	14
4.3.1	Syntax	14
4.3.2	Typing Rules	14
4.3.3	Type Soundness	15
5	Strong Normalisation	17
6	The Enriched Choreography	19
6.1	Syntax	19
6.2	Semantics	19
6.3	Typing	19
6.3.1	Typing Rules	19
6.3.2	Main Properties	19
6.3.3	Type Soundness	19
7	Concluding Remarks	21
7.1	Conclusion	21
7.2	Future Work	21

8	Test	23
A	Appendix: Explanation on Appendices	27
B	Appendix: Explanation on Page Borders	29

Introduction

Distributed systems consist of multiple endpoints that communicate by exchanging messages, operating with asynchrony and parallelism as these messages are sent and received between the various endpoints. But programming distributed system is notoriously error-prone as programmer has to implement the communication protocol by developing individual endpoint programs. Mismatched message sending and receiving can lead to errors such as *deadlock*, where the system is waiting forever for a message.

Choreography arises as a programming diagram to address this issue by providing a concrete global description of how the messages are exchanged between endpoints in a distributed system. A choreography program is written in a similar style to the "Alice and Bob" notation by [Needham and Schroeder \(1978\)](#):

1. Alice \rightarrow Bob : *key*
2. Bob \rightarrow Alice : *message*

Thus message mismatches are disallowed from the choreographic perspective. A property we refer to as *deadlock free by design*. The global choreography is then projected into process models for each endpoint via EndPoint Projection (EPP), with properties such as deadlock free by design preserved ([Hallal et al., 2018](#)).

While most choreography languages focus on the message exchange behaviours, few pay attention to the local computation happening in the individual endpoint. It is shown by [Hirsch and Garg \(2022\)](#) that as long as the local language exhibits type preservation and progress, the choreography inherits these properties as well. Thus, when analyzing message exchange behaviors in choreography—such as multiparty sessions, asynchrony, and parallelism—one can safely assume good behaviours of local computation ([Montesi and Yoshida, 2013](#); [Cruz-Filipe and Montesi, 2017](#); [Carbone and Montesi, 2013](#)).

But when it comes to writing the choreography program that implements concrete system behaviours, if local computation is ever required by the system, one must describe the inputs and outputs of local computations. Current work either delegate this part to an assumed well-behaved external implementation, for example, Kalas [Pohjola et al. \(2022\)](#) and Pirouette [Hirsch and Garg \(2022\)](#), or provide a basic framework where only Church numerals are considered,

as in Core Choreography (CC) [Cruz-Filipe and Montesi \(2017\)](#). This makes writing choreography program with local computation implementation an unpleasant experience. For instance, a choreography program in Kalas, where the client computes modulo locally using input from the server and then sends the result back, will look like:

Example 1.0.1 (Local computation — Modulo).

Kalas	External computation
<pre> 1. server.var → client.x; 2. let v@client = mod(x) in 3. client.v → server.result;</pre>	<pre> fun mod x = case Option.map (fn s ⇒ valOf (Int.fromString s)) (hd x) of None ⇒ None Some n ⇒ Some [Int.toString (n MOD y)]</pre>

In Kalas, processes communicate exclusively via strings. Therefore, in the external implementation of `mod(x)`, the string value of x must first be converted to a number. Then client computes the modulo on the converted input. Afterward, the result is converted back to a string before updating the client process variable v . We can easily see from this example that how data type conversions between choreography and external language lead to cumbersome code.

Thus this thesis extends Kalas, a verified choreography language with machine-checked end-to-end compilation, by introducing **Sprinkles**, a simple language of expressions over types such as integers, strings and booleans. Using the extended Kalas, local computations can be handled gracefully within a few lines of codes. The previous choreography where client computes the modulo of input integer can be written as in [Example 1.0.2](#).

By providing a concrete local language syntax and semantics, we are able to formally analyse the message exchange behaviours of choreography in terms of progress and type preservation when local computations are considered. We show that type soundness and strong normalisation properties of **Sprinkles** lead to progress for the enriched Kalas. Our semantics and typing system also allow us to show type preservation for non-recursive and synchronised transitions in the enriched Kalas.

Example 1.0.2 (Local computation with Sprinkles — Modulo).

```

1. server.var → client.x;
2. let v@client = StrOf ((NumOf (Var x)) Mod (Var y)) in
3. client.v → server.result;
```

To summarise, this thesis provides three main contributions.

- The first contribution is **Sprinkles**, a simply typed lambda calculus with function closure. According to the approach taken by [Owens et al. \(2016\)](#), we use a functional big-step semantics with clocks to ensure the evaluation function for **Sprinkles**' expressions is total. Our evaluation strategy is call-by-value. We also provide a typing system and give type soundness proof for the proposed semantics and typing rules. **Sprinkles** is implemented using the higher-order logic proof assistant HOL4 ([Slind and Norrish, 2008](#)) and all the proofs are conducted within HOL4.
- The second contribution is the strong normalization proof for **Sprinkles**. We follow the standard practice for proving strong normalization in simply typed lambda calculus, with a specific case for function closure in the definition of the strong normalization relation.

- The third contribution is Kalas enriched with **Sprinkles**. Besides common data types such as integer, string, and boolean, we also add function, pair, and sum types to the local computation in Kalas. Common operators for our data types are included, such as addition, modulo, and negation. Integer-string convertor is implemented as well for the integration with Kalas. Last but not least, we prove the enriched Kalas enjoys progress. We also show type preservation holds for non-recursive, synchronised transitions in the enriched Kalas.

Background

2.1 Choreography as a Programming Diagram

A distributed system can be defined as a collection of autonomous computing elements that behaves to its users' expectations ([Mullender, 1990](#)). Message exchanges are heart of the distributed system designs cause it allows nodes to collaborate and share resources with each other. Otherwise there is no need to put different nodes inside one connected network. Using a traditional way to describe a distributed system, one will have to give a detailed description of operations at each node in the system. For example, a communication between node A and node B is achieved by A sending the message and B receiving the message. But mismatched message sending and receiving can happen and these endpoint programs may fail to prevent the system from deadlocks or race among messages.

Choreography raises as an effort to eliminate incorrect system implementation by only providing a global description on how messages should be exchanged within the system. This approach is analogous to dance choreography, which outlines steps and movements for an entire performance without focusing on individual dancers' control points.

While it is fascinating to have no mismatched messages in choreography perspective, choreography cannot be run directly on individual nodes in a system and thus endpoint programs are still required by implementation. Thus the idea of EndPoint Projection (EPP) is proposed in which a choreography is projected into endpoint programs such that each endpoint correctly implements the behaviours described by its role in the choreography. This idea is first described by the design document of Web Services Choreography Description Language (WS-CDL) ([W3C WS-CDL Working Group, 2005](#)), and [Carbone et al. \(2007\)](#) further formalise it into the theory of EPP, namely the *soundness* and *completeness* properties for a given EPP. Soundness means that all projected endpoint communications adhere to the choreography description and completeness means that all communications described by the choreography are projected into endpoint codes.

- maybe two important results but not namely

- idea of CC

- common aspected in choreography: asynchrony ...

2.2 Interactive Theorem Proving

- what is higher-order logic - how proofs are done using HOL - recInduct in HOL - tactics - finite maps?

2.3 Kalas

- overview including intro to its compiler - semantics - implementation in HOL

Related Work

some intro ..

3.1 Choreography Models

some intro ..

3.1.1 Typing System for Choreography

Choreography language model can ensure deadlock freedom without using a typing system. The property is typically proven through structural induction on the choreography's semantics, where an applicable rule always enables reduction, or reduction follows by inductive hypothesis (Carbone and Montesi, 2013; Cruz-Filipe and Montesi, 2017; Pohjola et al., 2022). Typing system in this case might still be desired since it can discipline choreography in other ways such as correct protocol implementation.

Channel Choreography (ChC) by Carbone and Montesi (2013) is a rich choreography language where a choreography program consists of where a program consists of roles, threads, and sessions that implement communication protocols. Deadlock freedom is guaranteed by its semantics, while the typing system ensures correct protocol implementation by sessions. The typing context includes three components: a service environment Γ , which stores global types for public channels specifying session execution and local expressions (annotated with threads); a thread environment Θ , which tracks the roles of threads in each session; and a session environment Δ , which stores the types of active sessions.

It ensures that a well-typed choreography, with public channels specified by Γ and threads assuming roles in Θ , maintains disciplined sessions governed by Δ . Additionally, runtime typing introduces a delegation environment to handle changes in typing context due to asynchrony or parallelism, ensuring the program adheres to the protocol during execution.

When local computation is involved in the choreography, since we cannot solve the halting problem in semantics by deciding whether the local computation will terminate, a typing system is desired to reassert deadlock freedom. To the best of our knowledge, the closet work to this

discussion is Pirouette by [Hirsch and Garg \(2022\)](#). They assume a substitution model with small-step semantics for the local language. Based on a set of admissible typing rules for the sake of providing a reasoning ground, their results show that type preservation and progress in the local language ensure the same for the choreography language. Their progress result aligns with our results, but our local language adopts big-step semantics and thus preservation for choreography requires strong normalisation from local language rather than type preservation.

Pirouette is a higher-order functional choreography language with three value types: local values, local functions (mapping local values to choreographies), and global functions (mapping choreographies to choreographies). This structure enables choreographies to return values, forming the basis of its typing system. On the other hand, since neither Kalas or the enriched Kalas has return values, our typing system mainly checks for the well-formedness of a choreography within the typing environment and if any local computation is involved, we discipline it with its own typing system in a localised typing environment. Pirouette types its local values in a similar projected typing environment, binding variables to types at a specific location.

Another state-of-art functional choreography language Chor λ by [Cruz-Filipe et al. \(2022\)](#) uses a different approach than Pirouette, where choreographies are interpreted as terms in λ -calculus. Chor λ assumes local values for communications, without focusing on how they are computed. This results in a distinct typing system: local value types are annotated with roles and are part of the global types, rather than being projected from a global environment. Type preservation and progress follow from Chor λ 's typing and semantic rules.

3.1.2 Handling Exceptions

- Choral: an object-oriented choreography implemented as a java library ([Giallorenzo et al., 2024](#)). It treats choreography as class and EPP as generating role classes from the choreography implementation. It also offloads the local computation to Java. Higher-order functional choreography models such as Pirouette and Chor λ can be viewed as formal model candidates for it. Its type checker is similar to the typing system in ChC where it has types for public channels where roles for sender and receiver are specified as well as the type of messages being communicated and it also has local types annotated with roles.

In terms of communication failure which may raise an exception when a role is trying to perform operation based on reading from the place where a received message has not arrived yet, Choral implements the failure model in RC by [Montesi and Peressotti \(2017\)](#), using recover strategies such as capped attempts or timer within java try-catch block.

- RC, a model where communication failure is considered, recover strategy for senders and receivers, either while loop until received (exactly once delivery for setting 1), or with a timer or capped tries (best efforts); typing system to ensure almost once delivery (and exactly one delivery where message won't be lost); they use configuration where sender and receiver have stacks and it is initially false, with payload value, or ticked meaning no longer in the stack (sent/received) to implement send/received and the failure rules for semantics and typings; we do not consider message sending failure, but we do have exception caused by local computation failure (e.g. division by zero) or bad message value type (not a string), and we record the exception using transition labels. But we do not consider any recover strategy and always transits the choreography into a termination state (nil)

3.2 Some Title

- functional big-step semantics [Owens et al. \(2016\)](#)
- STLC; language with environment semantics - our typing is not unique
- SN for STLC; Weak and strong SN in terms of non-deterministic; my language is deterministic

Sprinkles: A Simply Typed Lambda Calculus

- we introduce **Sprinkles**, a language over expressions; Adopting a functional big-step semantics (owens), we define an interpreter that evaluate expressions to values; we evaluate expressions with clocks to ensure termination, thus our evaluation function is total. Expressions in **Sprinkles** can also be evaluated into exceptions. We include common arithmetic errors such as division by zero, and integer-string conversion errors such as bad formatted strings. The latter is included for the integration with Kalas, since a process may want to perform integer arithmetic based on the received string which does not encode a valid integer.

Sprinkles is deterministic in a sense that if we increase the clocks an expression will be evaluated to the same values or exceptions.

- **Sprinkles** closely resembles a STLC, but uses a dynamic environment to store values of free variables, so we always evaluate the given expression inside an environment E . This leads to typing expressions in a typing environment G that stores types for free variables. This setup, further requires the typed expression being evaluated in a *correct* environment E in the type soundness proof, given the typing environment G where the expression was typed.

4.1 Syntax

- syntax definition (+ exceptions) with brief explanation

Definition 1 (Sprinkles syntax). Values *and* expressions *in Sprinkles*, ranged over by v, e , are inductively defined by the grammar

$$\begin{aligned}
v &::= \text{IntV } n \mid \text{StrV } s \mid \text{BoolV } b \mid \text{Clos } s \ e \ E \mid \text{PairV } v_1 \ v_2 \mid \text{SumLV } v \mid \text{SumRV } v \\
bop &::= \text{Add} \mid \text{Concat} \mid \text{Mult} \mid \text{Div} \mid \text{Mod} \mid \text{Less} \mid \text{And} \mid \text{Or} \mid \text{Eq} \mid \text{Sub} \mid \text{Pair} \\
uop &::= \text{Not} \mid \text{NumOf} \mid \text{StrOf} \mid \text{Fst} \mid \text{Snd} \mid \text{SumL} \mid \text{SumR} \\
e &::= \begin{array}{lll} \text{Var } x & (var) & \text{StrLit } s \quad (str) \\ \text{IntLit } n & (int) & \text{BoolLit } b \quad (bool) \\ \text{BinOp } bop \ e_1 \ e_2 & (bop) & \text{Uop } uop \ e \quad (uop) \\ \text{If } bg \ e_1 \ e_2 & (if) & \text{Let } x \ e_1 \ e_2 \quad (let) \\ \text{Fn } x \ e & (fn) & \text{App } e_1 \ e_2 \quad (app) \\ \text{Case } e \ x \ e_1 \ y \ e_2 & (case) & \end{array}
\end{aligned}$$

Function and application syntax are standard. Same as if and let. Case here is for sum types. $\text{Var } x$ represents variable where x is a string that represents variable's name. We include literals for string, integer and boolean in our syntax to allow expressions such as $\text{BinOp Add (Var } x) (\text{IntLit } 1)$. For the sake of readability, we will write the addition example as $\text{Add (Var } x) (\text{IntLit } 1)$, and same for any binary or unary operators examples.

We abstract binary and unary operators to allow shorter syntax definitions. This makes extending binary and unary operators easy since we only need to register the new operator in bop or uop definition and provide the corresponding evaluation rule. It also greatly reduces the number of cases generated in proofs that rely on syntax forms of an expression since we only have one case for all binary operators and one case for all unary operators. Though those two cases typically rely on lemmas that establish the desired properties for all operators, as discussed in Section ?, most operators cases can be proven using the same tactics and where some operator case in the lemma proof differs from the others is usually the essential subproof that is required to re-establish the desired property after introducing this operator to our language. Thus separating concrete operator syntax definitions from language syntax definitions also enabling a neat proof maintenance process when new operators are introduced.

We include exceptions to handle division by zero and bad formatted integer strings. They are thrown by the corresponding operators. We define evaluation results as either values, or we encounter a type error (for example, $\text{Add (IntLit } 1) (\text{BoolLit } T)$), or we reach an exception, or the evaluation times out for the given clock.

4.2 Semantics

As discussed above, we defined our semantics using evaluation function rather than relation. The size of expressions are decreasing except for the application case, so we decrease the clock to ensure termination. Semantics for if, let, case are standard. When evaluating a variable, we try to look up for the value corresponds to the variable name in the given environment. If we try to look up an unknown variable name, the evaluation function will return with type error. Environments are implemented as finite maps in HOL4, as discussed in Section ?.

- semantics rules

Our evaluation strategy is call-by-value. For evaluating binary or unary operations, we first evaluate the argument expressions into values, and then use another function eval_bop or eval_uop to apply the operators by the specified rules on the evaluated values and return the result. eval_bop and eval_uop are where concrete evaluation rules for each operator is defined.

For example, $\text{eval_exp } c \ E \ (\text{NumOf } (\text{Var } x))$ will first compute $\text{eval_exp } c \ E \ (\text{Var } x)$ by looking up name x in E . If x is unknown to E , the function will return TypeError and propagate it to

the top. Otherwise it will return the value v stored under the name x in E and we move to compute `eval_uop NumOf v` . If v is not a correctly formatted integer string (for example, if it contains a non-numeric character), `eval_uop NumOf v` will return *ExnBadStr*. Otherwise, it will return the converted integer value `IntV n` . Again, the format checking and conversion algorithm are implemented in `eval_uop`'s definition. The same applies to evaluating any binary operations. Definitions of `eval_uop` and `eval_bop` are included in Appendix ?.

- typed example: `eval_exp c \emptyset`

4.2.1 Function Closure

- function semantics rule

We store the bindings of free variables (i.e. the environment) into the closure value when evaluating a function definition. So we never lose track of values for bound variables when evaluating a function definition that appears nested in another function definition. If we don't keep track of values for bound variables, when we finish evaluating a function definition that contains nested function definitions, only the inner most bound variable will appear bound and the inner most function body will be the expression to be evaluated when we apply this nested function definition to a value. Since we now lose bindings for all the other bound variables from outer scopes, we are unable to finish the evaluation of application.

- example

This is illustrated by Example ?. When we are evaluating `Fn y (Add (Var x) (Var y 1))` in line 5 we know x is bound to 1. But we lose this information when we choose `(y , Add (Var x) (Var y))` to be the evaluation result. So we only know y is bound to `IntLit 2` when we try to evaluate `Add (Var x) (Var y 1)` in line 7.

By using function closure to record values of all bound variables when a function definition is being evaluated, we are able to evaluate `Add (Var x) (Var y 1)`, as illustrated in line 7 of Example ?. It is possible that a function body contains unbound free variables, but such expression cannot be typed in an empty environment and it is reasonable to make its evaluation fail. Discussions on typing for function closure are in Section ?.

- another example

Detour on Restricted Function Closure

The Kalas repository states an interesting property: Given a bigger state Γ_1 that contains Γ , the choreography c still transits into c' and Γ'_1 contains Γ' .

- Property theorem.

However, our S-FN invalidates this property since a bigger state may result in a closure value that contains a bigger environment, so we will not be able to transit into the same c' . In order to re-establish this property, we modify S-FN to store a restricted environment instead: `(DRESTRICT E (freevars e) $\setminus s$)`, where DRESTRICT is defined as:

- definition of DRESTRICT

The restricted closure should at least contain bindings of variables that appear free from the perspective of the current function definition scope, as much as provided by the environment in which the current function definition is evaluated. Such that if we apply the evaluated restricted

function closure to a value, if we were able to evaluate the application without restriction, we will be able to evaluate to the same result with restriction.

But we further require the restricted environment to exclude storing the value of the variable bound by current function definition in the current environment if any. This still allows us to evaluate an application to the same result because if we ever apply this function to a value we will always bind s with the provided value, leaving the previous value of s stored in the environment irrelevant.

Excluding storing s is also necessary. If we only restrict E with $\text{free_vars } e$, since e can have s as free variables and Γ does not need to contain binding for s for evaluating $\text{Fn } s \ e$, $(\text{DRESTRICT } (\text{localise } \Gamma \ p) (\text{free_vars } e))$ may not contain binding for s . But since Γ' contains Γ , Γ' may contain binding for s and thus $(\text{DRESTRICT } (\text{localise } \Gamma' \ p) (\text{free_vars } e))$ contains binding for s , making the closure evaluated in a bigger state larger than the closure evaluated in the smaller state.

But this restriction is too strict that it makes evaluation for currying function in Example ? fails, illustrated in Example ?. Because we exclude storing the variable bound by current function definition into the closure for all such variables in a function definition that has nested function definition, we encounter the same issue as in Example ? where no function closure is used: we lose bindings for all the previously bound variables and the evaluation fails.

- currying failure example.

We argue that this issue can be mitigated by only further excluding the bound variable in the inner most function definition since bindings for all previously bound variables are necessary for evaluation of application of nested functions to values. And by excluding the truly and only unnecessary binding of the inner most function definition bound variable s , the above argument still applies and we are able to achieve the same closure when evaluating in a bigger state. However, this interesting property lives on its own in Kalas repository and no other theorems are dependant on it. Given the time constrain for this project, we delegate the fixing to future work. If not specified, we always refer to the unrestricted S-FN.

Recursion

- how the recursion is not supported in our semantics; we don't support fixed point (as in the abstraction book which can't be cited); letrec

- properties: clock increment (cases on result) (and clock decrement) - closure: issues with dynamic environment, so we use lexical environment; do we explain restricting to $\text{fv}(e)$ and how? - exceptions

4.3 Typing

4.3.1 Syntax

- rich data types: int, string, boolean, sum type, pair type, closure, ... - typecheck - uoptype, boptype - valuetype - envtype

4.3.2 Typing Rules

- typecheck - uoptype, boptype - valuetype: closure - no type uniqueness

- maybe an example of what program typing rules allow and which disallow and it is actually meaningful
- `typecheck_*_thm`: the inversion (generation) lemma, (Pierce, 2002); we can calculate the types of subterm of a well-typed term; all automatically handled by HOL4, for matching the subgoals (when no IH), OR for using the IH
- `valuetype_EQ_*` lemma: canonical forms of types (Pierce, 2002), used for type soundness proof, where we only have `v` and we don't have the form of `v`; only needed for boolean value, function value and sum value, where those are intermediate evaluated values in semantics and after the IH has been applied and we want to have a canonical form of `v` rather than merely the name `v` itself, because we want the results from IH to match the evaluation semantics in goal, which operates on concrete value forms rather than a name of the value; it's for using the IH results (to match the evaluation process in goal)
- If no intermediate evaluated values are involved in the semantics, we don't have to use IH since no recursive calls to evaluation thus no IH to use; in this case '`irule value_type_*`' moves one step higher in the proof tree to the previous sub-proof tree, transforming the goal; we will have the concrete form of values in goal since we rewrite the evaluation definition in our goal
- `envtype`: analogous to the "Preservation of types under substitution" lemma in a substitution semantics type soundness proof (Pierce, 2002); our equivalent version is by `envtype`; so substitution gives free variables meaning, we do this by `FLOOKUP` (var case using `envtype_def`; other that contains intermediate value evaluation using `envtype update lemma`)
- bop type soundness and uop type soundness is just the same as operator case in the type soundness proof for a simply typed lambda calculus
- operators: `uoptype` soundness and `boptype` soundness (use the invertability) - `typecheck`: reducing typing environment (for soundness fn case)

4.3.3 Type Soundness

- fn case: - `envtype_DRESTRICT` - `typecheck_update_sub_fv`: which needs `typecheck_drestrict` (which needs `typecheck_env_fv`), a strengthening on the typing context
- other cases: mostly need `envtype_lemma` to ensure the updated environments still has `envtype`

Strong Normalisation

- why it is necessary - the halting problem discussion.
- our language is deterministic with the clock lemma, so strong normalisation is the same as weak normalisation
- issue with directly proving: not strong enough IH for the applied term for app case, the applied term may get bigger, cause the e from closure value may be bigger; same issue for a substitution model in (Pierce, 2002) - so sn_v says for a closure to be in sn_v , for any v (argument to function) that in sn_v ("halts"), the evaluation of function body applying v halts
- induction on typing rules/types (e.g. from t', t to $t; t'$)
- fn case: sn_e for a function expression of function types, transforms into sn_v function types function value (closure) by rewriting the evaluation; which is satisfied by IH — 1. IH says for every dynamic environment that nicely matches the updated typing environment, $sn_e t' e$

The Enriched Choreography

6.1 Syntax

6.2 Semantics

- exceptions

6.3 Typing

6.3.1 Typing Rules

6.3.2 Main Properties

6.3.3 Type Soundness

Concluding Remarks

If you wish, you may also name that section “*Conclusion and Future Work*”, though it might not be a perfect choice to have a section named “A & B” if it has subsections “A” and “B”. Also note that you don’t necessarily have to use these subsections; that also depends on how much content you have in each. (E.g., having a section header might be odd if it contains just three lines.)

7.1 Conclusion

This section usually summarizes the entire paper including the conclusions drawn, e.g., did the developed techniques work? Maybe add why or why not. Also don’t hold back on limitations of your work; it shows that you understood what you have done. And science isn’t about claiming how great something is, but about objectively testing hypotheses. Also note that every single scientific paper has such a section, so you can check out many examples, preferably at top-tier venues, e.g., by your supervisor(s).

7.2 Future Work

- asynchronus messages; confluence property - Progress for EPP

Test

We define what it is for a choreograph to be well-formed with the $G, Th \vdash c \checkmark$ relation.

This is a theorem:

$$\vdash \Gamma, \Theta \vdash c \checkmark \wedge \text{chorEnvtype } \Gamma \ s \wedge \text{chorEnvsn } \Gamma \ s \Rightarrow \\ \exists \tau \ l \ s' \ c'. s \triangleright c \xrightarrow[l]{\tau} s' \triangleright c' \vee \neg \text{not_finish } c$$

$$\vdash \text{not_finish } c \wedge \text{chorEnvsn } \Gamma \ s \wedge \text{chorEnvtype } \Gamma \ s \wedge \\ \Gamma, \Theta \vdash c \checkmark \wedge s \triangleright c \xrightarrow[l]{\tau} s' \triangleright c' \Rightarrow \\ \exists \Gamma'. \\ \text{chorEnvsn } \Gamma' \ s' \wedge \text{chorEnvtype } \Gamma' \ s' \wedge \\ \Gamma', \Theta \vdash c' \checkmark$$

$$\vdash \text{envtype } G \ E \wedge G \vdash_s e : ty \Rightarrow \\ (\exists v. \text{eval_exp } c \ E \ e = \text{Value } v \wedge \text{value_type } v \ ty) \vee \\ (\exists \text{exn}. \text{eval_exp } c \ E \ e = \text{Exn } \text{exn}) \vee \\ \text{eval_exp } c \ E \ e = \text{Timeout}$$

$$\vdash \emptyset \vdash_s e : t \Rightarrow \\ (\exists cl \ v \ E. \text{eval_exp } cl \ E \ e = \text{Value } v \wedge \text{sn}_v \ t \ v) \vee \\ \exists cl \ \text{exn} \ E. \text{eval_exp } cl \ E \ e = \text{Exn } \text{exn}$$

The transition relation looks like $\text{eval_exp } clk \ E \ exp$

Theorem 1. *some text here*

1. (Operational completeness) *If $G, Th \vdash c \checkmark$ then there exist ...*

2. (Operational soundness) *If $\text{eval_exp } clk \ E \ exp$ then there exist ...*

Definition 2 (Kalas syntax). *Choreographies in Kalas, ranged over by C , are inductively defined by the grammar*

$$\begin{array}{llll}
C ::= & p_1.v_1 \rightarrow p_2.v_2; C & (com) & p_1 \rightarrow p_2[b]; C & (sel) \\
& \text{if } v@p \text{ then } C_1 \text{ else } C_2 & (if) & \text{Let } v \text{ p } e \ C & (let) \\
& \mu X. C & (fix) & X & (var) \\
& 0 & (nil) & &
\end{array}$$

Definition 3 (Sprinkles syntax). Values and expressions in *Sprinkles*, ranged over by v, e , are inductively defined by the grammar

$$\begin{array}{ll}
v ::= & \text{IntV } n \mid \text{StrV } s \mid \text{BoolV } b \mid \text{Clos } s \ e \ E \mid \text{PairV } v_1 \ v_2 \mid \text{SumLV } v \mid \text{SumRV } v \\
bop ::= & \text{Add} \mid \text{Concat} \mid \text{Mult} \mid \text{Div} \mid \text{Mod} \mid \text{Less} \mid \text{And} \mid \text{Or} \mid \text{Eq} \mid \text{Sub} \mid \text{Pair} \\
uop ::= & \text{Not} \mid \text{NumOf} \mid \text{StrOf} \mid \text{Fst} \mid \text{Snd} \mid \text{SumL} \mid \text{SumR} \\
e ::= & \begin{array}{ll} \text{Var } x & (var) \quad \text{StrLit } s \quad (str) \\ \text{IntLit } n & (int) \quad \text{BoolLit } b \quad (bool) \\ \text{BinOp } bop \ e_1 \ e_2 & (bop) \quad \text{Uop } uop \ e \quad (uop) \\ \text{If } bg \ e_1 \ e_2 & (if) \quad \text{Let } x \ e_1 \ e_2 \quad (let) \\ \text{Fn } x \ e & (fn) \quad \text{App } e_1 \ e_2 \quad (app) \\ \text{Case } e \ x \ e_1 \ y \ e_2 & (case) \end{array}
\end{array}$$

$$T ::= \text{intT} \mid \text{strT} \mid \text{boolT} \mid \text{fnT } t_1 \ t_2 \mid \text{pairT } t_1 \ t_2 \mid \text{sumT } t_1 \ t_2$$

$$\begin{array}{l}
\text{sn}_v \text{ intT } (\text{IntV } n) \stackrel{\text{def}}{=} T \\
\text{sn}_v \text{ strT } (\text{StrV } s) \stackrel{\text{def}}{=} T
\end{array}$$

$$\begin{array}{l}
\text{eval_exp } c \ E \ (\text{Var } str) \stackrel{\text{def}}{=} \\
\quad \text{case } E \ str \text{ of None} \Rightarrow \text{TypeError} \mid \text{Some } v \Rightarrow \text{Value } v \\
\text{eval_exp } c \ E \ (\text{Fn } s \ e) \stackrel{\text{def}}{=} \\
\quad \text{Value } (\text{Clos } s \ e \ (\text{DRESTRICT } E \ (\text{free}_v \text{ars } e) \setminus \setminus s)) \\
\text{eval_exp } c \ E \ (\text{App } e_1 \ e_2) \stackrel{\text{def}}{=} \\
\quad \text{if } c > 0 \text{ then} \\
\quad \text{do} \\
\quad \quad v_1 \leftarrow \text{eval_exp } c \ E \ e_1; \\
\quad \quad v_2 \leftarrow \text{eval_exp } c \ E \ e_2; \\
\quad \quad \text{case } v_1 \text{ of} \\
\quad \quad \quad \text{IntV } v_{11} \Rightarrow \text{TypeError} \\
\quad \quad \quad \mid \text{StrV } v_{12} \Rightarrow \text{TypeError} \\
\quad \quad \quad \mid \text{BoolV } v_{13} \Rightarrow \text{TypeError} \\
\quad \quad \quad \mid \text{PairV } v_{14} \ v_{15} \Rightarrow \text{TypeError} \\
\quad \quad \quad \mid \text{SumLV } v_{16} \Rightarrow \text{TypeError} \\
\quad \quad \quad \mid \text{SumRV } v_{17} \Rightarrow \text{TypeError} \\
\quad \quad \quad \mid \text{Clos } s \ e \ E_1 \Rightarrow \text{eval_exp } (c - 1) \ E_1[s := v_2] \ e \\
\quad \quad \text{od} \\
\quad \text{else Timeout}
\end{array}$$

Choreography	External Computation
1. server .var \rightarrow client .x;	fun mod x =
2. let v@ client = mod(x) in	case Option.map (fn s \Rightarrow valOf (Int.fromString s)) (hd x) of
3. client .v \rightarrow server .result;	None \Rightarrow None
	Some n \Rightarrow Some [Int.toString (n MOD y)]

Table 8.1: semantics: communication rules. The function $wv(\alpha)$ returns the variable (if any) that is modified by α .

$$\begin{array}{c}
\text{COM} \frac{s(v_1, p_1) = \text{StrV } d \quad p_1 \neq p_2}{s \triangleright p_1.v_1 \rightarrow p_2.v_2; C \xrightarrow[\epsilon]{p_1.v_1 \triangleright p_2.v_2} s[(v_2, p_2) := \text{StrV } d] \triangleright C} \\
\\
\text{T-VAR} \frac{G \ x = ty}{G \vdash_s \text{Var } x : ty} \\
\\
\text{T-FN} \frac{G[s := t] \vdash_s e : ty}{G \vdash_s \text{Fn } s \ e : (\text{fnT } t \ ty)} \\
\\
\text{T-APP} \frac{G \vdash_s e_1 : (\text{fnT } t \ ty) \quad G \vdash_s e_2 : t}{G \vdash_s \text{App } e_1 \ e_2 : ty} \\
\\
\text{CT-COM} \frac{\Gamma(v_1, p_1) = \text{strT} \quad \{p_1; p_2\} \subseteq \Theta \quad p_1 \neq p_2 \quad \Gamma[(v_2, p_2) := \text{strT}], \Theta \vdash c \checkmark}{\Gamma, \Theta \vdash p_1.v_1 \rightarrow p_2.v_2; c \checkmark} \\
\\
\text{CT-LET} \frac{\text{localise } \Gamma \ p \vdash_s e : ety \quad \Gamma[(v, p) := ety], \Theta \vdash c \checkmark}{\Gamma, \Theta \vdash \text{Let } v \ p \ e \ c \checkmark}
\end{array}$$

1. `server.var` \rightarrow `client.x`;
2. `let` $v@client = \text{StrOf } ((\text{NumOf } (\text{Var } x)) \text{ Mod } (\text{Var } y))$ `in`
3. `client.v` \rightarrow `server.result`;

Appendix: Explanation on Appendices

Appendix: Explanation on Page Borders

What you find here is an explanation of why the border width keeps flipping from left to right – which you might have spotted and wondered why that’s the case.

Firstly, that is *intended* and thus correct, so there is no reason to worry about this. The reason is that this document is configured as a two-sided book, which means:

- We assume the document will be printed out,
- that this will be done in a two-sided mode (i.e., the document will be printed on both sides of each page), and
- that the bookbinding will be in the middle, just like in every book.

When you open the book, there are three borders of equal size n . This however requires that even pages have a border of n on their left and $\frac{n}{2}$ on their right, and odd pages have a border of $\frac{n}{2}$ on their left and n on their right. This is illustrated in Figure B.1.

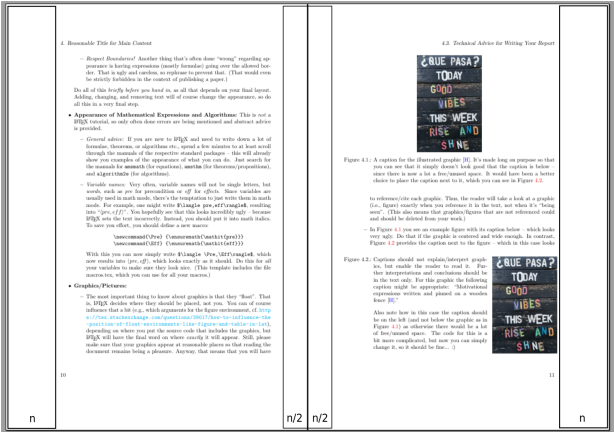


Figure B.1: Illustration showing why page borders flip.

Bibliography

- CARBONE, M.; HONDA, K.; AND YOSHIDA, N., 2007. Structured communication-centred programming for web services. In *Programming Languages and Systems: 16th European Symposium on Programming, ESOP 2007, Held as Part of the Joint European Conferences on Theory and Practice of Software, ETAPS 2007, Braga, Portugal, March 24-April 1, 2007. Proceedings 16*, 2–17. Springer. [Cited on page 5.]
- CARBONE, M. AND MONTESI, F., 2013. Deadlock-freedom-by-design: multiparty asynchronous global programming. 48, 1 (2013), 263–274. doi:10.1145/2480359.2429101. <https://dl.acm.org/doi/10.1145/2480359.2429101>. [Cited on pages 1 and 7.]
- CRUZ-FILIPPE, L.; GRAVERSEN, E.; LUGOVIĆ, L.; MONTESI, F.; AND PERESSOTTI, M., 2022. Functional choreographic programming. In *International Colloquium on Theoretical Aspects of Computing*, 212–237. Springer. [Cited on page 8.]
- CRUZ-FILIPPE, L. AND MONTESI, F., 2017. A core model for choreographic programming. In *Formal Aspects of Component Software: 13th International Conference, FACS 2016, Besançon, France, October 19-21, 2016, Revised Selected Papers 13*, 17–35. Springer. [Cited on pages 1, 2, and 7.]
- GIALLORENZO, S.; MONTESI, F.; AND PERESSOTTI, M., 2024. Choral: Object-oriented choreographic programming. *ACM Transactions on Programming Languages and Systems*, 46, 1 (2024), 1–59. [Cited on page 8.]
- HALLAL, R.; JABER, M.; AND ABDALLAH, R., 2018. From global choreography to efficient distributed implementation. In *2018 International Conference on High Performance Computing & Simulation (HPCS)*, 756–763. doi:10.1109/HPCS.2018.00122. https://ieeexplore.ieee.org/abstract/document/8514427?casa_token=B9uMnW0mxFEAAAAA:DMmhgwQZJnHAX6o6p-EHBs4K9rct4pEKen9fdt2CXHC6NOWZxpHT5FSZZFAchGBDjiqmPeviH1U. [Cited on page 1.]
- HIRSCH, A. K. AND GARG, D., 2022. Pirouette: higher-order typed functional choreographies. 6 (2022), 23:1–23:27. doi:10.1145/3498684. <https://dl.acm.org/doi/10.1145/3498684>. [Cited on pages 1 and 8.]
- MONTESI, F. AND PERESSOTTI, M., 2017. Choreographies meet communication failures. *arXiv preprint arXiv:1712.05465*, (2017). [Cited on page 8.]
- MONTESI, F. AND YOSHIDA, N., 2013. Compositional choreographies. In *CONCUR 2013 – Concurrency Theory* (Berlin, Heidelberg, 2013), 425–439. Springer. doi:10.1007/978-3-642-40184-8_30. [Cited on page 1.]

- MULLENDER, S., 1990. *Distributed systems*. ACM. [Cited on page 5.]
- NEEDHAM, R. M. AND SCHROEDER, M. D., 1978. Using encryption for authentication in large networks of computers. 21, 12 (1978), 993–999. doi:10.1145/359657.359659. <https://dl.acm.org/doi/10.1145/359657.359659>. [Cited on page 1.]
- OWENS, S.; MYREEN, M. O.; KUMAR, R.; AND TAN, Y. K., 2016. Functional big-step semantics. In *Programming Languages and Systems: 25th European Symposium on Programming, ESOP 2016, Held as Part of the European Joint Conferences on Theory and Practice of Software, ETAPS 2016, Eindhoven, The Netherlands, April 2–8, 2016, Proceedings 25*, 589–615. Springer. [Cited on pages 2 and 9.]
- PIERCE, B. C., 2002. *Types and programming languages*. MIT press. [Cited on pages 15 and 17.]
- POHJOLA, J. Å.; GÓMEZ-LONDOÑO, A.; SHAKER, J.; AND NORRISH, M., 2022. Kalas: A verified, end-to-end compiler for a choreographic language. In *13th International Conference on Interactive Theorem Proving (ITP 2022)*. Schloss-Dagstuhl-Leibniz Zentrum für Informatik. [Cited on pages 1 and 7.]
- SLIND, K. AND NORRISH, M., 2008. A brief overview of hol4. In *International Conference on Theorem Proving in Higher Order Logics*, 28–32. Springer. [Cited on page 2.]
- W3C WS-CDL WORKING GROUP, 2005. Web Services Choreography Description Language Version 1.0. Technical report, World Wide Web Consortium (W3C). <http://www.w3.org/TR/2004/WD-ws-cdl-10-20040427/>. Accessed: October 14, 2024. [Cited on page 5.]