

# Lec6\_Image\_Classification

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**Classification:** class label, predict label of unseen sample based on learned from training sample

**Supervised learning:** training set + validation set → model → testing set + label

K nearest neighbors (kNN Classifier)

- $k=1$ : assign the unseen with the label of its nearest neighbor
- $k>1$ : assign the dominating label among these of the  $k$  nearest neighbors

Bayesian classifiers

$P(A|x)$ : prob of A is observed when seeing an  $x$  - The Conditional Probability (Likelihood)

$P(B|x)$ : prob of B is observed when seeing an  $x$

$$P(A|x) = P(x|A)P(A)/P(x) \quad P(A) = P(A)/P(A+B) \quad P(x|A) = P(x)/P(A)$$

$$P(B|x) = P(x|B)P(B)/P(x) \quad P(B) = P(B)/P(A+B) \quad P(x|B) = P(x)/P(B)$$

Decision function:  $x$  is A if  $P(A|x) > P(B|x)$ , B otherwise

Advantages: • Fast, Extendable to multi class problems • Requires less training examples, Works well for categorical data

Disadvantages: • Features are assumed to be independent to each other (not true in real world applications) • Zero frequency problem

Support vector machines (SVM)

**Linear Separators**

$$[W \ -1]^T [xy] + b = -y + wx = 0$$

$$w^T x + b = 0 \quad f(x) = \text{sign}(w^T x) + b$$

**Margin** separator:

$$r = \frac{\mathbf{w}^T \mathbf{x}_i + b}{\|\mathbf{w}\|}$$

support vector: Examples closest to hyperplane 超平面 margin  $\rho$  of the separator: distance b/t support vectors

**Maximum Margin Classification:** Probably Approximately Correct(PAC theory), Implies that only SV matter; other training examples are ignorable.

**Soft Margin Classification:** not linearly separable

Slack variables  $\xi_i$  can be added to allow misclassification of difficult or noisy examples, resulting margin called soft

**Non-linear SVMs:**  $\Phi: x \rightarrow \varphi(x)$

### Kernel Functions

Linear:  $K(x_i, x_j) = x_i^T x_j$  - Mapping  $\Phi: x \rightarrow \varphi(x)$ , where  $\varphi(x)$  is  $x$  itself

Polynomial of power  $p$ :  $K(x_i, x_j) = (1 + x_i^T x_j)^p$  - where  $\varphi(x)$  has  $(d+p, p)$  dimension

Gaussian (radial-basis function):  $K(x_i, x_j) = \exp(-\frac{\|x_i - x_j\|^2}{2\sigma^2})$  - where  $\varphi(x)$  is infinite-dim: every point mapped

$$\exp\left(-\frac{\|x_i - x_j\|^2}{2\sigma^2}\right)$$

**Higher-dimensional space** still has intrinsic dimensionality (mapping is not onto, but linear separators in it correspond to non-linear separator in original space)

Rock Paper Scissors

Tutorial

```
## extract features
sift = cv2.SIFT_create()
def get_feat(img):
    # return hog(img)
    # return sift_feat(img)
    return gray_histogram(img)

def calc_distance(x, y):
    return L2_distance(x, y)
# return L2_distance_sift(x, y)

def sift_feat(img):
    kps, des = sift.detectAndCompute(img, None)
    responses = [kp.response for kp in kps]
    order = np.argsort(responses)[::-1]
    return np.array(des[order[:30]])

def gray_histogram(img: np.array, norm: bool = True) -> np.array:
    if img.shape[-1] == 3:
        img = cv2.cvtColor(img, cv2.COLOR_RGB2GRAY)
    hist = np.array([len(img[img == i]) for i in range(256)])
    if norm:
        return hist / np.size(img)

    return hist

def L2_distance(x, y):
    return ((x - y) ** 2).sum() ** 0.5

def L2_distance_sift(x, y):
    dist = ((x[:, None] - y[None, :])**2).sum(axis=-1).min(axis=-1)
    dist.sort()
    return dist[:15].mean()
```

```

for sample in samples['train']:
    sample.feats = get_feats(sample.img)
for sample in samples['val']:
    sample.feats = get_feats(sample.img)

# **kNN #works only for few imgs, don't have model for classification(2/4)**
def kNN(test_sample, train_samples, k=3):
    distances = []
    for sample in train_samples:
        distance = calc_distance(test_sample.feats, sample.feats)
        distances.append((distance, sample))

    distances = sorted(distances, key=lambda x: x[0])[:k]

    label_count = {}
    plt.figure(figsize=((k+1)*4, 4))
    plt.subplot(1, k+1, 1)
    plt.title(f'{test_sample.fname} in G{test_sample.label}(val)')
    plt.imshow(test_sample.img)

    for i, (distance, sample) in enumerate(distances):
        plt.subplot(1, k+1, i+2)
        plt.title(f'{sample.fname} in G{sample.label}(train)')
        plt.imshow(sample.img)
        label_count[sample.label] = label_count.get(sample.label, 0) + 1
    max_label, max_count = -1, 0

    for label, count in label_count.items():
        if count > max_count:
            max_label, max_count = label, count
    test_sample.pred = max_label

**# train with SVM**
model = SVC(kernel='rbf')

train_samples = [sample.feats for sample in samples['train']]
train_labels = [sample.label for sample in samples['train']]
model.fit(train_samples, train_labels)

# test with SVM
test_samples = [sample.feats for sample in samples['val']]
results = model.predict(test_samples)
for sample, result in zip(samples['val'], results):
    sample.pred = result
    print(sample.fname, 'with label', sample.label, 'is predicted as',
          sample.pred)
# display the results (target images with the predicted labels and ground truth
label)

```