Small signal versus Large signal

Linear systems:

$$F(ax) = aF(x)$$

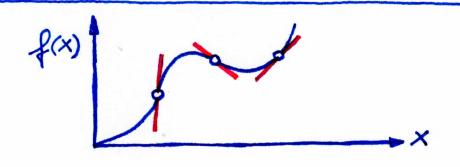
Non-linear systems

Linear circuit elements

$$\Rightarrow \qquad \Upsilon \propto V$$

Non-linear circuit elements

Mathematics: Any non-linear function fox can be linearized in the vicinity of a point x.



Electronics: Any non-linear circuit can be linearized in the vicinity of its operating point.

Example: Diode

$$T_D = \frac{dV}{dI} = \left(\frac{dI}{dV}\right)^{-1}$$

=> For small signals, mean a certain operating point, the diode has the differential resistance $T_D = \frac{dV}{dI} \Big|_{\text{operating point}} = \left(\frac{dI}{dV}\right)^{-1} \Big|_{\text{oper. point}}$

$$T_{E} = \frac{dV}{dI} = \left(\frac{dI}{dV}\right)^{-1} = \left(\frac{dI_{E}}{dV_{BE}}\right)^{-1} = \left(\frac{d}{dV_{BE}}I_{E}\right)^{-1}$$

$$= \left(I_o e^{V_{BE}/V_t} \frac{1}{V_t} \right)^{-1} = \left(\frac{I_E}{V_t} \right)^{-1} = \frac{V_t}{I_E}$$

$$\Rightarrow \qquad r_{\mathsf{E}} = \frac{V_{\mathsf{t}}}{T_{\mathsf{E}}}$$

Also
$$r_{\rm E} = \frac{V_{\rm t}}{I_{\rm E}} = \frac{V_{\rm t}}{I_{\rm B}(\beta+1)} \approx \frac{V_{\rm t}}{\beta I_{\rm B}}$$