

SECOND ORDER:  $y'' + p(t)y' + q(t)y = g(t)$ ;  $y(t) = C_1y_1(t) + C_2y_2(t)$

wronskion:  $w(t) = \det[y_1, y_2, \dots, y_1', y_2'] = y_1y_2' - y_1'y_2 \neq 0$  (linearly independent, not multiples of each other)

$L[y_1] = y_1'' + p(t)y_1' + q(t)y_1 = g(t)$

CONSTANT COEFFICIENT:  $ay'' + by' + cy = 0$ ;  $y(t) = e^{rt}$ ;  $ar^2 + br + c = 0$

CASE 1  $r_1, r_2 \in R$ ,  $r_1 \neq r_2$ ;  $b^2 - 4ac > 0$ ;  $y(t) = C_1e^{r_1t} + C_2e^{r_2t}$

CASE 2  $r_1, r_2 \in R$ ,  $r_1 = r_2$ ;  $b^2 - 4ac = 0$ ;  $y(t) = C_1e^{rt} + C_2te^{rt}$

REDUCTION OF ORDER:

$y_2 = y_1h$ ,  $y_2' = y_1'h + y_1h'$ ,  $y_2'' = y_1''h + 2y_1'h' + y_1h''$

$y_1''h + 2y_1'h' + y_1h'' + p(t)(y_1'h + y_1h') + q(t)(y_1h) = (y'' + py' + qy)h + (2y' + py)h' + yh''$  (should)  $= (2y' + py)h' + yh''$ ,

$u = h'$ ;  $yu' + (2y' + py)u = 0$

get  $u$  to one side, integrate to find  $u$  (has C); integrate to get  $h$  (has D) and plug in to  $y_2 = y_1h$ ; choose  $C$  and  $D$  to be easy.

CASE 3  $r_1, r_2 \notin R$ ;  $b^2 - 4ac < 0$ ;  $\frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = r = \lambda \pm i\omega$ ;

$y_1^c = e^{\lambda + i\omega} = e^{\lambda t}(\cos(\omega t) + i \sin(\omega t))$

$y_2^c = e^{\lambda - i\omega} = e^{\lambda t}(\cos(\omega t) - i \sin(\omega t))$

$y_1(t) = e^{\lambda t} \cos(\omega t)$   $y_2(t) = e^{\lambda t} \sin(\omega t)$

CAUCHY-EULER

$ax^2y'' + bxy' + cy = 0$ ;  $y = x^r$ ;  $ar(r-1) + br + c = 0$  roots  $r_1, r_2$

CASE 1:  $y = C_1x^{r_1} + C_2x^{r_2}$

CASE 2:  $y = C_1x^r + C_2x^r \ln(x)$

CASE 3:  $y = C_1x^\lambda \cos(\omega \ln(x)) + C_2x^\lambda \sin(\omega \ln(x))$

polar:  $y = Re^{\lambda t} \cos(\omega t - \phi)$ ;  $y(t) = (R \cos(\phi))e^{\lambda t} \cos(\omega t) + (\sin(\phi))e^{\lambda t} \sin(\omega t)$

$R \cos \phi = C_1$ ,  $R \sin \phi = C_2$

METHOD OF UNDETERMINED COEFFICIENTS (must be constant coefficient)

$ae^{bt} \rightarrow Ae^{bt}$

$a \cos(ct) + b \sin(ct) \rightarrow A \cos(ct) + B \sin(ct)$

$at^n \rightarrow A_{n+1}t^{n+1} + \dots + A_1$

$g(t) = P_n(t)e^{at}(\alpha \cos(bt) + \beta \sin(bt))$ ;  $y_p(t) = Q_n(t)e^{at} \cos(bt) + R_n(t)e^{at} \sin(bt)$

addition of  $g_1, g_2 \dots$  results in addition of solutions

you just guessed  $y_p$ , derive  $y_p'$  and  $yh_p''$ , multiply t if resonance

plug those in to  $L[y_p] = g$  and solve for A's and B's; sets of (A's and B's) for each term

plug those into guess for  $y_p$  and  $y(t) = y_h + y_p$ , plug in ICs to solve for  $C_1, C_2$

VARIATION OF PARAMETERS (must be in standard form)

must know homo  $y_1, y_2$ ;  $y_p(t) = u_1y_1 + u_2y_2$ ;  $u_1' = \frac{-y_2g}{W}$ ;  $u_2' = \frac{y_1g}{W}$

$u = \int u'dt + A_n$ , plug in to get  $y_p$ , choose  $A_1, A_2$  to make it easy.

LINEAR OSCILATOR

$mu'' + cu' + ku = F_0 \cos(\omega t)$

$\omega_0 = \sqrt{\frac{k}{m}}$ ;  $kx = mg$ ;  $c = \frac{F}{v}$ ;  $r = \pm \sqrt{\frac{-k}{m}}$

$u(t) = e^{\lambda t}(C_1 \cos(\omega t) + \sin(\omega t))$

undetermined coefficients oscilator:  $D = c^2\omega^2 + (k - m\omega^2)^2$

$u_p(t) = A \cos(\omega t) + B \sin(\omega t)$ ;  $u_p' = -A\omega \sin(\omega t) + B\omega \cos(\omega t)$ ;  $u_p'' = -\omega^2 A \cos(\omega t) - \omega^2 B \sin(\omega t)$

max amplitude?  $R' = 0$ ,  $D = 0$ ,  $R = \sqrt{A^2 + B^2}$ ,  $\omega$  sorta close to  $\omega_0$

FREE UNDAMPED

$u(t) = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t) = R \cos(\omega_0 t - \phi)$

$C_1 = u(0) = R \cos(\phi)$ ;  $C_2 = \frac{u'(0)}{\omega_0} = R \sin(\phi)$

$= \frac{2\pi}{\omega_0}$ ; frequency  $= \frac{\omega_0}{2\pi} = \frac{1}{period}$ ; amplitude  $= R = \sqrt{C_1^2 + C_2^2}$ ;  $\phi = \arctan(\frac{C_2}{C_1})$

FREE DAMPED

$u = e^{rt}$ ;  $r = \frac{-c \pm \sqrt{c^2 - 4mk}}{2m}$ ; sqrt: ( $< 0$  under, not strong, overshoots, disipating wave) ( $= 0$  cryticially, perfect, decays as fast as possible without overshooting) ( $> 0$  over, too strong, slower, slow decay)

FORCED UNDAMPED

$\omega_0 \neq \omega$  small wave.  $\omega_0 \approx \omega$  bigger wave.  $\omega_0 = \omega$  resonance, grows linearly

FORCED DAMPED

$u_p(t) = A \cos(\omega t) + B \sin(\omega t)$

LAPLACE TRANSFORM

$$F(s) = \int_0^\infty f(t)e^{-st}dt$$

$$\text{linear, } L(af(t) + bg(t)) = aL(f(t)) + bL(g(t))$$

$$ay'' + by' + cy = f(t); \ a(s^2Y - sy_0 - y'_0) + b(sY - y_0) + c(Y) = F; \ Y = \frac{F + asy_0 + ay'_0 + by_0}{as^2 + bs + c}$$