## Vector Manifold

$$X = u\cos(v)e_x + u\sin(v)e_y + (u\cos(v) + w)e_z$$

Basis Vectors

$$e_u = \cos(v)e_x + \sin(v)e_y + \cos(v)e_z$$

$$e_v = -u\sin(v)e_x + u\cos(v)e_y - u\sin(v)e_z$$

$$\boldsymbol{e}_w = \boldsymbol{e_z}$$

Reciprocal Basis Vectors

$$e^{u} = \cos(v)e_{x} + \sin(v)e_{y}$$

$$\boldsymbol{e}^{v} = -\frac{\sin(v)}{u}\boldsymbol{e}_{\boldsymbol{x}} + \frac{\cos(v)}{u}\boldsymbol{e}_{\boldsymbol{y}}$$

$$oldsymbol{e}^w = -oldsymbol{e_x} + oldsymbol{e_z}$$

Dot Products

$$e_u \cdot e^u = 1$$

$$\mathbf{e}_u \cdot \mathbf{e}^v = 0$$

$$\mathbf{e}_u \cdot \mathbf{e}^w = 0$$

$$\boldsymbol{e}_v \cdot \boldsymbol{e}^u = 0$$

$$\mathbf{e}_v \cdot \mathbf{e}^v = 1$$

$$\boldsymbol{e}_v \cdot \boldsymbol{e}^w = 0$$

$$\boldsymbol{e}_w \cdot \boldsymbol{e}^u = 0$$

$$\boldsymbol{e}_w \cdot \boldsymbol{e}^v = 0$$

$$e_w \cdot e^w = 1$$