## Image Filtering

Image filtering - changes the range (pixel values) of an image.

The goal of inge
filtering is modify or
enhance inge properties
and/or extract valuable
in form tion from a picture.

- · De nois ing
- · edge detection
- · Corner detection

		black							
Noise	example				Salt				
		70	9	98	91	Pepto (			
		92	90	93	12'	Noise			
		91	Ô	90	91				
		90	7/	193	255				
					77	1			

white

essimule ~ 41

How do we handle this?

thesh each pixel's

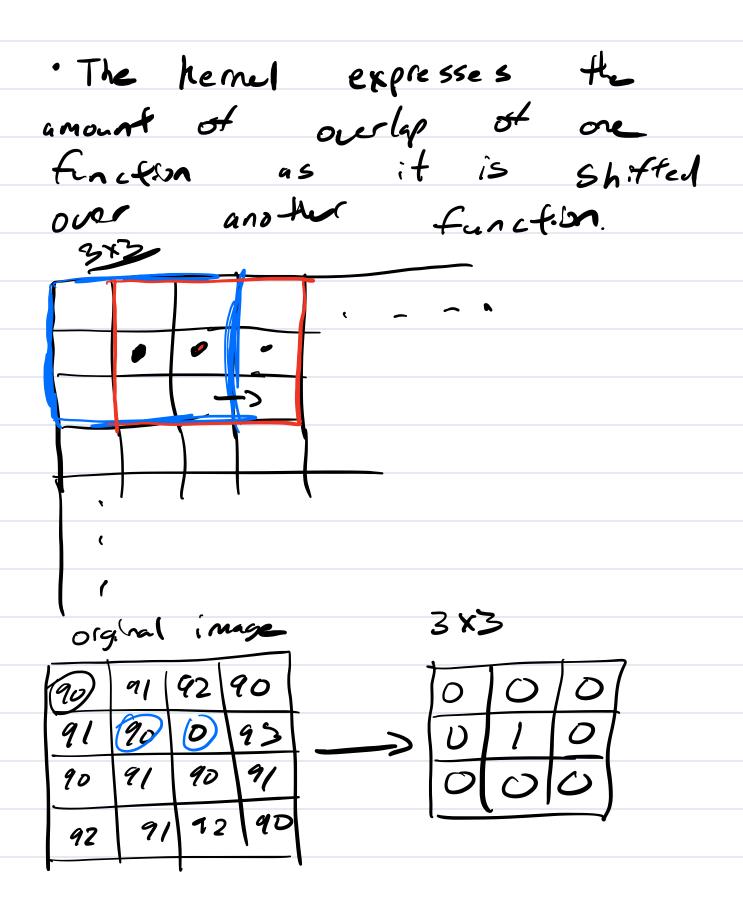
neighbors

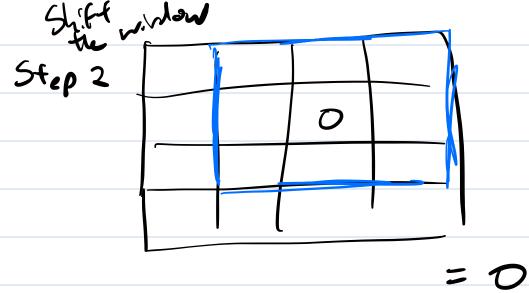
, 3 x 3 w.w.

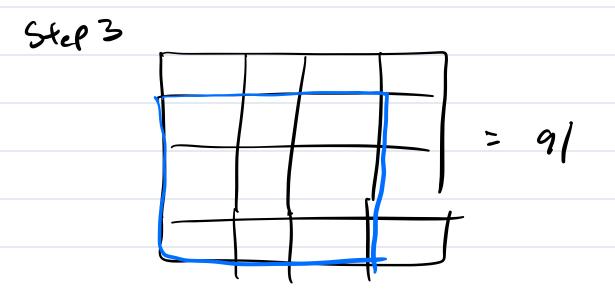
express this window as
a 20 convolution.

' (on volution in 20 uses two images (matrix)

1) the orginal image
(2) and a kernel, serving
as a filter







Step U = 90 UxY 3x3 2x2  $90 \ 91 \ 92 \ 91$   $11 \ 90 \ 0 \ 93$   $10 \ 91 \ 90 \ 91$   $10 \ 91 \ 90 \ 91$   $10 \ 91 \ 90 \ 91$  $10 \ 91 \ 90 \ 91$ 

Issue - The impe is not the orginal size.

Solution - add a Padding/mask/
buffer to the orginal

.5 Different Padding nethods.

'Zero > add n11 Ø's

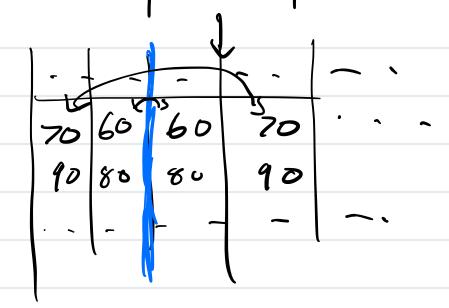
around the image

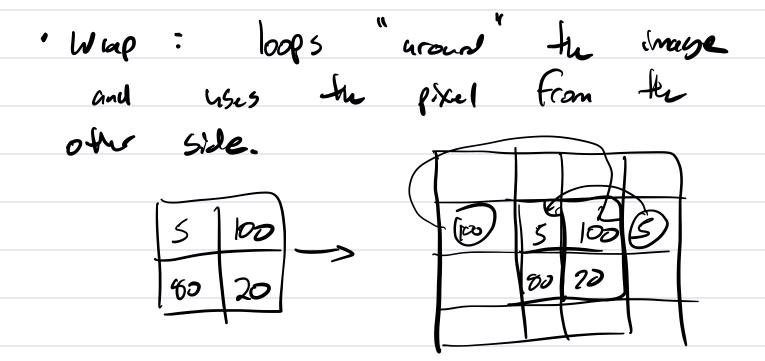
· Constant -> add a

· Clump -> extend the outside pixels st the orginal image

3X3	5	×5				_
	5	15	20	lag !	100	
5 20 100	5	45	20	105	Plaw	
10 40 110	10	10	40	110	110	1
20 50 129	20	20	50	(20	120	
'	20	20	50	120	120	

· minor > (eflect the pixels
i.e. sxs filer
60 70 all 2 pixels
60 90 around the edge





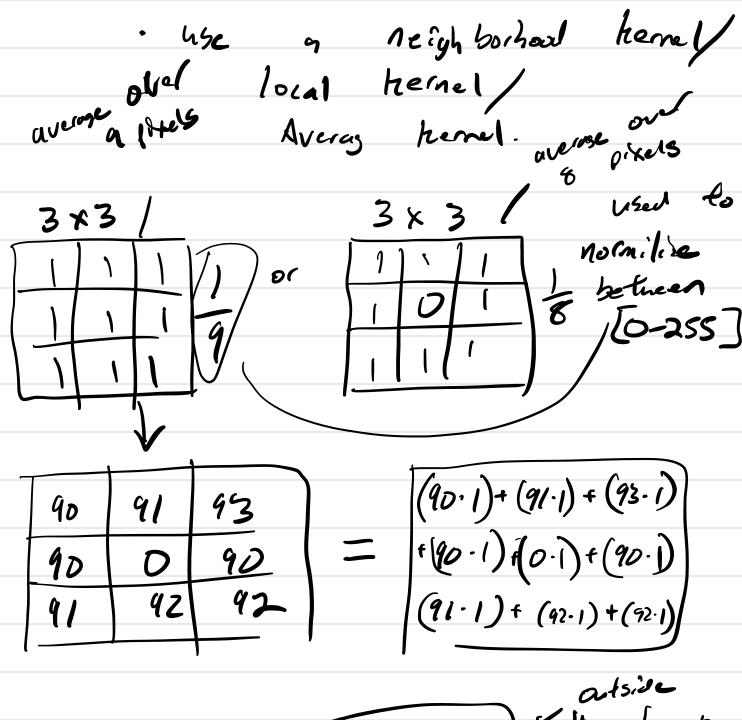
There one no real benifits
between the last 3 methods

· Zero/ constent - adds a

mre noticalk a ctifact around

the edge.

## · De-noish / blumbs



20 90 3+3 Files ural 3 + 3

6 + 4

