

Supplementary Material of MS2A: Memory Storage-to-Adaptation for Cross-domain Few-annotation Industrial Detection

Anonymous submission

1 More Comparisons to State-of-the-art Methods

We also compare the visual results between our method and state-of-the-art methods. Fig. 1 shows the comparisons on Indus-S \rightarrow Indus-T2. Our method can detect the same result as the ground truth though the object and environment change differently. Fig. 2 shows the comparisons on C \rightarrow F. In the foggy scene, we still detect some objects that even can no be found by human beings. In Fig. 3 and Fig. 4, we show the comparisons on K \rightarrow C and S \rightarrow C where S (SIM10K) is a simulated dataset. We can easily apply our method to synthetic-to-real task and achieve superior performance.

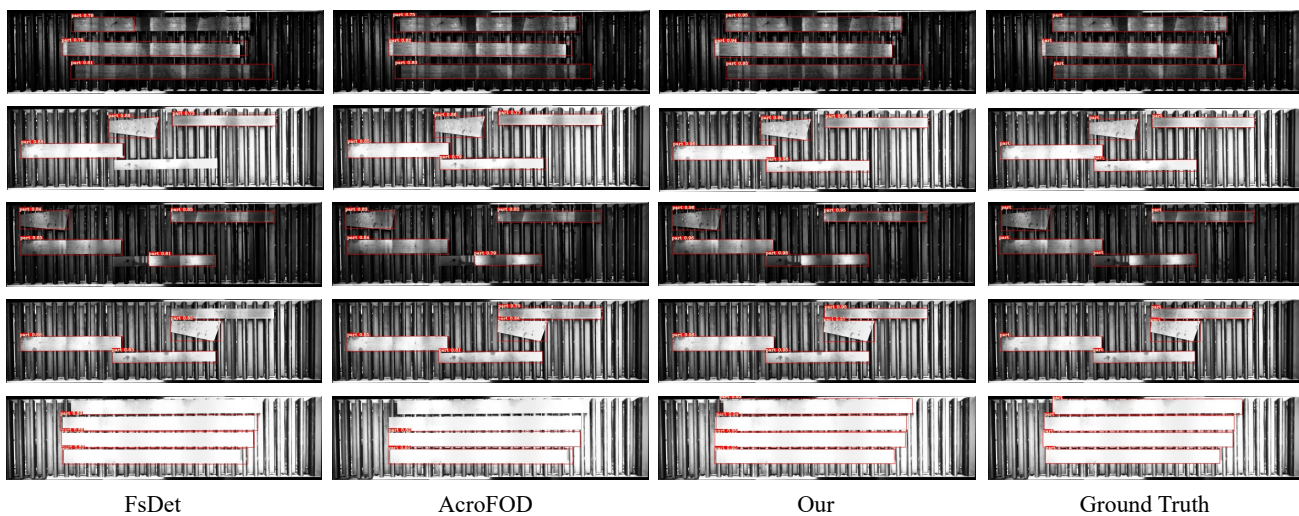


Figure 1: Comparisons on Indus-S→Indus-T2.

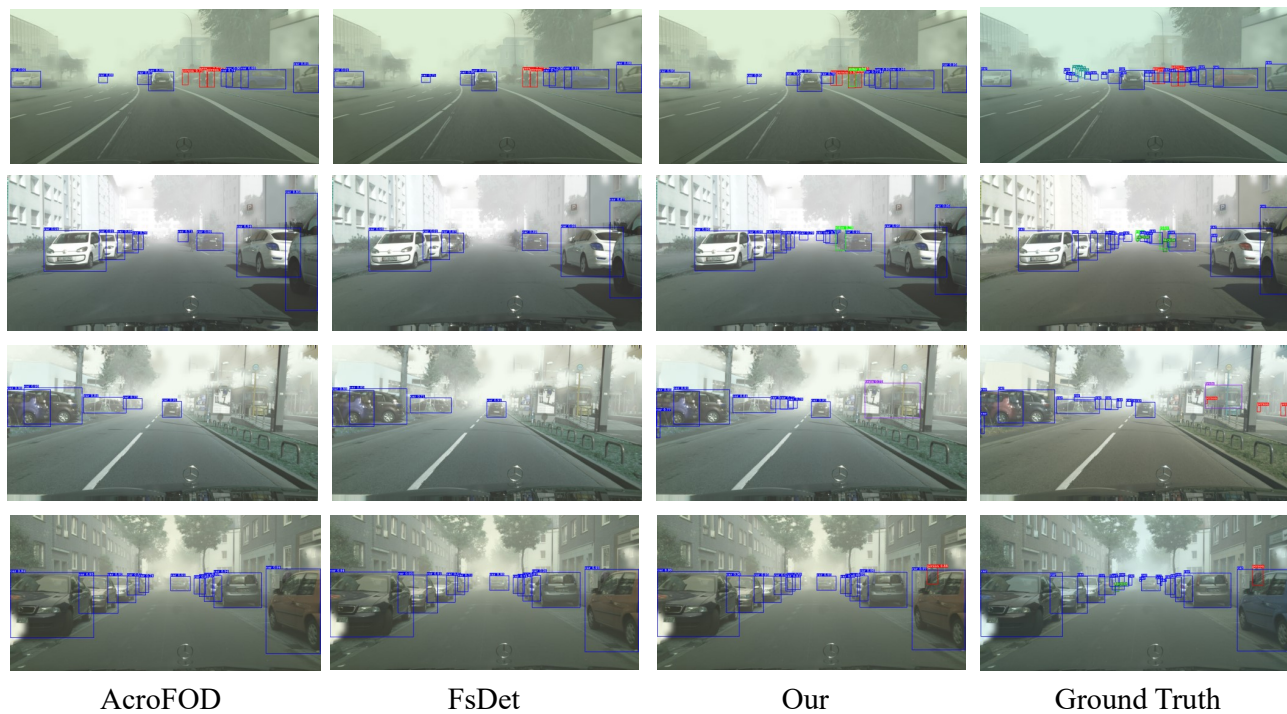


Figure 2: Comparisons on C→F.

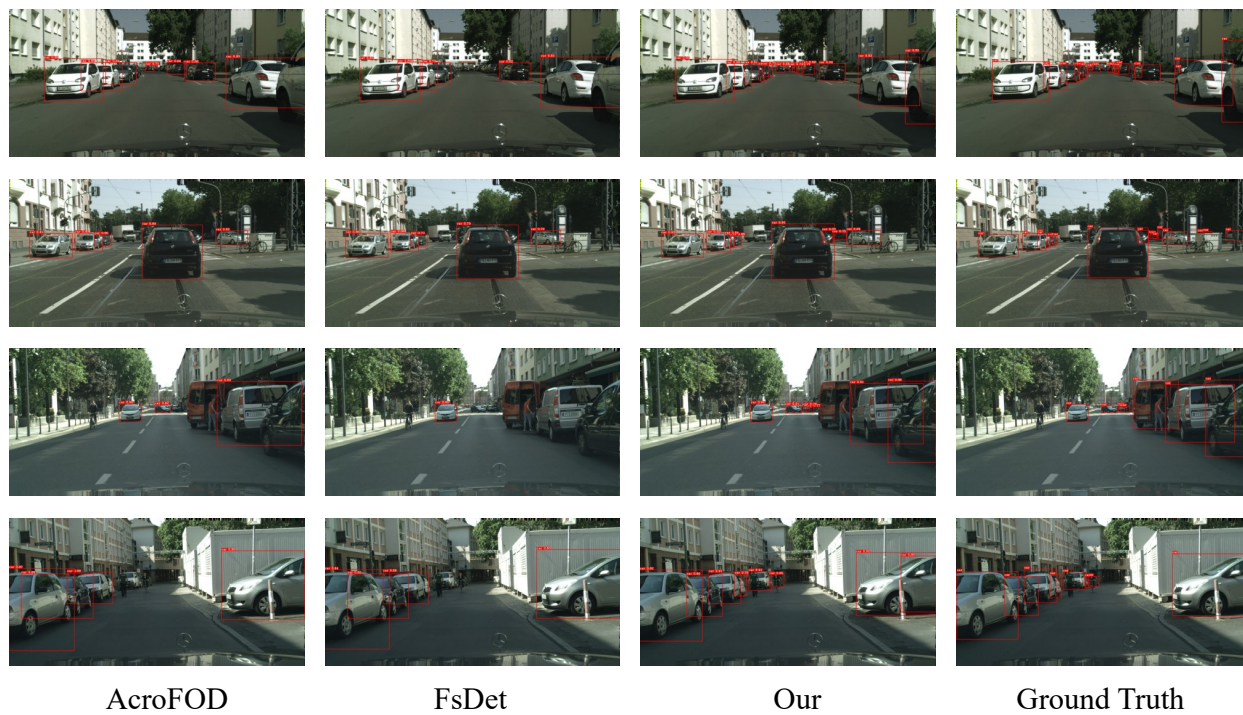


Figure 3: Comparisons on $K \rightarrow C$.

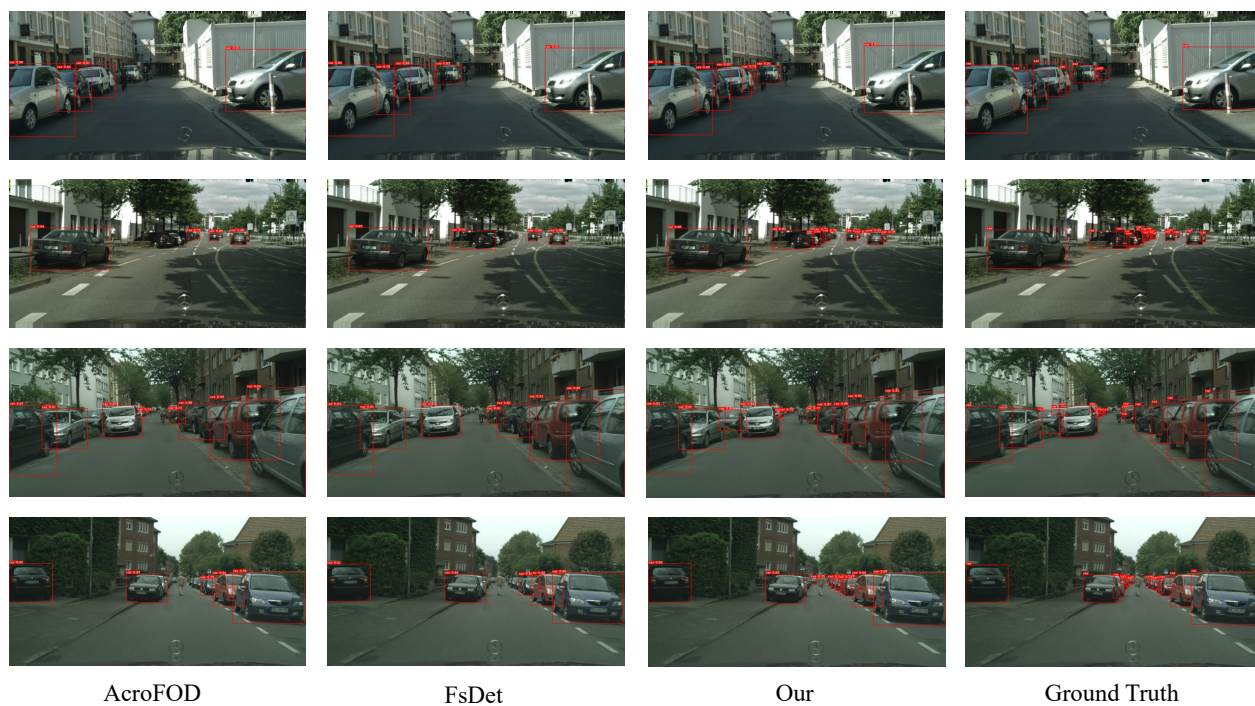


Figure 4: Comparisons on $S \rightarrow C$.