

3th exercise

9.

$$\begin{cases} x = r \sin \phi \sin \theta \\ y = r \cos \phi \sin \theta \\ z = r \cos \theta \end{cases}$$

$$\begin{aligned} \left| \frac{\partial(x, y)}{\partial(\theta, \phi)} \right| &= \begin{vmatrix} \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \end{vmatrix} = \begin{vmatrix} r \sin \phi \cos \theta & r \cos \phi \sin \theta \\ r \cos \phi \cos \theta & -r \sin \phi \sin \theta \end{vmatrix} \\ &= -r^2 \sin^2 \phi \cos \theta \sin \theta - r^2 \cos^2 \phi \sin \theta \cos \theta \\ &= -r^2 \cos \theta \sin \theta \end{aligned}$$

$$\begin{aligned} \left| \frac{\partial(z, x)}{\partial(\theta, \phi)} \right| &= \begin{vmatrix} \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \\ \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \end{vmatrix} = \begin{vmatrix} -r \sin \theta & 0 \\ r \sin \phi \cos \theta & r \cos \phi \sin \theta \end{vmatrix} \\ &= -r^2 \cos \phi \sin^2 \theta \end{aligned}$$

$$\begin{aligned} \left| \frac{\partial(y, z)}{\partial(\theta, \phi)} \right| &= \begin{vmatrix} \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \end{vmatrix} = \begin{vmatrix} r \cos \phi \cos \theta & -r \sin \phi \sin \theta \\ -r \sin \theta & 0 \end{vmatrix} \\ &= -r^2 \sin \phi \sin^2 \theta \end{aligned}$$

$$\begin{aligned} *F &= q \sin \theta d\theta \wedge d\phi \\ &= q \sin \theta \left| \frac{\partial(x^i, x^j)}{\partial(\theta, \phi)} \right| dx^i \wedge dx^j \\ &= q \sin \theta \left(\left| \frac{\partial(x, y)}{\partial(\theta, \phi)} \right| dx \wedge dy + \left| \frac{\partial(z, x)}{\partial(\theta, \phi)} \right| dz \wedge dx + \left| \frac{\partial(y, z)}{\partial(\theta, \phi)} \right| dy \wedge dz \right) \\ &= -q \sin \theta (r^2 \cos \theta \sin \theta dx \wedge dy + r^2 \cos \phi \sin^2 \theta dz \wedge dx + r^2 \sin \phi \sin^2 \theta dy \wedge dz) \\ &= -qr^2 \sin^2 \theta (\cos \theta dx \wedge dy + \cos \phi \sin \theta dz \wedge dx + \sin \phi \sin \theta dy \wedge dz) \\ &= *F_{12} dx \wedge dy + *F_{31} dz \wedge dx + *F_{23} dy \wedge dz \end{aligned}$$

$$\begin{cases} (*F)_{12} = -qr^2 \sin^2 \theta \cos \theta \\ (*F)_{23} = -qr^2 \sin^3 \theta \sin \phi \\ (*F)_{31} = -qr^2 \sin^3 \theta \cos \phi \\ \text{others} = 0 \end{cases}$$

a. failed Orz

b.

$$\begin{aligned} *(F dx^\mu \wedge dx^\nu) &= \frac{1}{2!} \varepsilon^{\mu\nu}{}_{\sigma\rho} (*F)_{\mu\nu} dx^\sigma \wedge dx^\rho \\ -F_{\sigma\rho} dx^\sigma \wedge dx^\rho &= \varepsilon^{\mu\nu}{}_{\sigma\rho} (*F)_{\mu\nu} dx^\sigma \wedge dx^\rho \quad (\mu < \nu) \\ &= (\varepsilon^{12}{}_{\sigma\rho} (*F)_{12} + \varepsilon^{23}{}_{\sigma\rho} (*F)_{23} + \varepsilon^{13}{}_{\sigma\rho} (*F)_{13}) dx^\sigma \wedge dx^\rho \\ F_{\sigma\rho} dx^\sigma \wedge dx^\rho &= -(\varepsilon^{12}{}_{\sigma\rho} (*F)_{12} + \varepsilon^{23}{}_{\sigma\rho} (*F)_{23} + \varepsilon^{13}{}_{\sigma\rho} (*F)_{13}) dx^\sigma \wedge dx^\rho \end{aligned}$$

$$\begin{aligned} F_{01} &= -(*F)_{23} = qr^2 \sin^3 \theta \sin \phi \\ F_{02} &= (*F)_{13} = qr^2 \sin^3 \theta \cos \phi \\ F_{03} &= -(*F)_{12} = qr^2 \sin^2 \theta \cos \theta \\ \text{others} &= 0 \end{aligned}$$

c. see above $c=1$

$$\begin{aligned}\vec{E} &= qr^2\sin^2\theta(\sin\theta\sin\phi dx + \sin\theta\cos\phi dy + \cos\theta dz) \\ &= qr^2\sin^2\theta dr\end{aligned}$$

$$\vec{B} = 0$$

d.

$$\begin{aligned}r\sin^2\theta &= r\left(1 - \left(\frac{z}{r}\right)^2\right) \\ &= r - \frac{z^2}{r} = \sqrt{x^2 + y^2 + z^2} - \frac{z^2}{\sqrt{x^2 + y^2 + z^2}}\end{aligned}$$

$$\begin{aligned}\frac{\partial *F_{23}}{\partial x} &= \frac{\partial(-qr^2\sin\phi\sin^3\theta)}{\partial x} \\ &= -q\frac{\partial(xr\sin^2\theta)}{\partial x} \\ &= -q - x\frac{\partial(r\sin^2\theta)}{\partial x} \\ &= -q - x \times \frac{x}{r} - x \times \frac{z^2}{r^2} \times \frac{x}{r} \\ &= -q - \frac{x^2}{r} - \frac{x^2z^2}{r^3}\end{aligned}$$

$$\begin{aligned}\frac{\partial *F_{31}}{\partial y} &= \frac{\partial(-qr^2\cos\phi\sin^3\theta)}{\partial y} \\ &= -q\frac{\partial(yr\sin^2\theta)}{\partial y} \\ &= -q - \frac{y^2}{r} - \frac{y^2z^2}{r^3}\end{aligned}$$

$$\begin{aligned}\frac{\partial *F_{12}}{\partial z} &= \frac{\partial(-qr^2\cos\theta\sin^2\theta)}{\partial z} \\ &= -q\frac{\partial(zr\sin^2\theta)}{\partial z} \\ &= -q - z\frac{\partial(r\sin^2\theta)}{\partial z} \\ &= -q - z\left(\frac{z}{r} + \frac{z^2}{r^2}\frac{z}{r} - \frac{2z}{r}\right) \\ &= -q + \frac{z^2}{r} - \frac{z^4}{r^3}\end{aligned}$$

$$\begin{aligned}d(*F) &= d(*F_{\mu\nu}dx^\mu \wedge dx^\nu) \\ &= d(*F)_{\mu\nu} \wedge dx^\mu \wedge dx^\nu \\ &= \partial_\sigma(*F)_{\mu\nu}dx^\sigma \wedge dx^\mu \wedge dx^\nu \\ &= \partial_\sigma(*F)_{\mu\nu}dx^{[\sigma} \wedge dx^\mu \wedge dx^{\nu]} \\ &= 4! \times \partial_{[\sigma}(*F)_{\mu\nu]}dx^\sigma \wedge dx^\mu \wedge dx^\nu \text{ and } \sigma < \mu < \nu \\ &= 4! \times \frac{1}{3}(\partial_\sigma(*F)_{\mu\nu} + \partial_\mu(*F)_{\nu\sigma} + \partial_\nu(*F)_{\sigma\mu})dx^\sigma \wedge dx^\mu \wedge dx^\nu \\ &= 8 \times (\partial_1(*F)_{23} + \partial_2(*F)_{31} + \partial_3(*F)_{12})dx \wedge dy \wedge dz \\ &= 8 \times \left(-q - \frac{x^2}{r} - \frac{x^2z^2}{r^3} + -q - \frac{y^2}{r} - \frac{y^2z^2}{r^3} - q + \frac{z^2}{r} - \frac{z^4}{r^3}\right)dx \wedge dy \wedge dz\end{aligned}$$

$$\begin{aligned}
&= 8 \times \left(-3q - \frac{r^2}{r} + \frac{2z^2}{r} - \frac{z^2 r^2}{r^3} \right) dx \wedge dy \wedge dz \\
&= 8 \times \left(-3q - r + \frac{z^2}{r} \right) dx \wedge dy \wedge dz
\end{aligned}$$

$$\begin{aligned}
\int d(*F) &= \int 8 \times \left(-3q - r + \frac{z^2}{r} \right) dx \wedge dy \wedge dz \\
&= 8 \times \int \left(-3q - r + \frac{z^2}{r} \right) d\tau \\
&= 8 \times \int (-3q - r + r \cos^2 \theta) r^2 \sin \theta dr d\theta d\phi \\
&= -24 \times q \times \frac{4}{3} \pi R^3 - 8 \times 4\pi \int_0^R r^3 dr + 8 \times 2\pi \int_0^R r^3 dr \int_0^\pi \cos^2 \theta \sin \theta d\theta \\
&= -32q\pi R^3 - 32\pi \times \frac{R^4}{4} + 16\pi \times \frac{R^4}{4} \left(-\int_0^\pi \cos^2 \theta d\cos \theta \right) \\
&= -32q\pi R^3 - 32\pi \times \frac{R^4}{4} + 16\pi \times \frac{R^4}{4} \left(\int_{-1}^1 t^2 dt \right) \\
&= 32\pi \left(\frac{1}{2} \times \frac{R^4}{4} \times \frac{2}{3} - qR^3 - \frac{R^4}{4} \right) \\
&= -32\pi R^3 \left(q + \frac{R}{6} \right)
\end{aligned}$$

11.

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$$\begin{aligned}
S &= \int_\gamma A^{(3)} \\
F^{(4)} &= dA^{(3)}
\end{aligned}$$

$$F_{[\mu\nu\sigma\rho]} = F_{\mu\nu\sigma\rho}; F_{(\mu\nu\sigma\rho)} = 0 \Rightarrow \mu < \nu < \sigma < \rho \text{ and } \mu, \nu, \sigma, \rho = 0, 1, \dots, 10$$

a. $A^{(1)} \rightarrow 0$ -from particle $\Rightarrow A^{(3)} \rightarrow 2$ -from particle ?

b. $E_{\mu\nu\sigma} = F_{0\mu\nu\sigma} \Rightarrow \#E_{\mu\nu\sigma} = 3 \times C_{10}^3 = 360$

according to $\nabla_\mu E_\mu = q$ definite charge $q = \nabla_\mu E_{\mu\nu\sigma}$ and is have 36 componets

c. $(*F^{(4)})$ is 7-form the $\tilde{A}^{(6)}$ 6-form \rightarrow 3-form particle

d. no idea ,but guess $A^{(3)}$

1.

a. $\nabla_\lambda \varepsilon_{\mu\nu\rho\sigma} = 0$

$$\begin{aligned}
\varepsilon^{\mu\nu\rho\sigma} \nabla_\lambda \varepsilon_{\mu\nu\rho\sigma} &= \nabla_\lambda \varepsilon^{\mu\nu\rho\sigma} \varepsilon_{\mu\nu\rho\sigma} - \varepsilon_{\mu\nu\rho\sigma} \nabla_\lambda \varepsilon^{\mu\nu\rho\sigma} \\
&= \nabla_\lambda 4! - \varepsilon^{\alpha\beta\gamma\eta} g_{\mu\alpha} g_{\nu\beta} g_{\rho\gamma} g_{\sigma\eta} \nabla_\lambda \varepsilon^{\mu\nu\rho\sigma} \\
&= -\varepsilon^{\alpha\beta\gamma\eta} \nabla_\lambda g_{\mu\alpha} g_{\nu\beta} g_{\rho\gamma} g_{\sigma\eta} \varepsilon^{\mu\nu\rho\sigma} \\
&= -\varepsilon^{\alpha\beta\gamma\eta} \nabla_\lambda \varepsilon_{\alpha\beta\gamma\eta} \\
2 \times \varepsilon^{\mu\nu\rho\sigma} \nabla_\lambda \varepsilon_{\mu\nu\rho\sigma} &= 0
\end{aligned}$$

b. $\nabla_\rho g^{\mu\nu} = 0$

$$\begin{aligned}\nabla_\rho \delta_\mu^\nu &= \partial_\rho \delta_\mu^\nu + \Gamma_{\rho\lambda}^\nu \delta_\mu^\lambda - \Gamma_{\rho\mu}^\lambda \delta_\lambda^\nu \\ &= \Gamma_{\rho\mu}^\nu - \Gamma_{\rho\mu}^\nu \\ &= 0\end{aligned}$$

$$\begin{aligned}\nabla_\rho \delta_\mu^\nu &= \nabla_\rho (g^{\nu\sigma} g_{\sigma\mu}) \\ 0 &= g^{\nu\sigma} \nabla_\rho g_{\sigma\mu} + g_{\sigma\mu} \nabla_\rho g^{\nu\sigma} \\ 0 &= g_{\sigma\mu} \nabla_\rho g^{\nu\sigma}\end{aligned}$$

therefore $\nabla_\rho g^{\nu\sigma} = 0$

2. $\mu, \nu, \sigma, \rho \dots \in \{x, y, z\}$ $\mu', \nu', \sigma', \rho' \dots \in \{r, \theta, \phi\}$

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases}$$

gradient.

$$\begin{aligned}\nabla_\mu \phi \hat{e}^\nu_\nu \delta_\nu^\mu &= \frac{\partial x^{\mu'}}{\partial x^\mu} \nabla_{\mu'} \phi \delta_\nu^\mu \frac{\partial x^\nu}{\partial x^{\nu'}} \hat{e}^{\nu'}_{\nu'} \\ &= \frac{\partial x^{\mu'}}{\partial x^\mu} \frac{\partial x^\nu}{\partial x^{\nu'}} \partial_{\mu'} \phi \delta_\nu^\mu \hat{e}^{\nu'}_{\nu'} \\ &= \partial_{\mu'} \phi \hat{e}^{\mu'}_{\mu'} \\ &= \partial_r \phi dr + \partial_\theta \phi d\theta + \partial_\phi \phi d\phi\end{aligned}$$

div.

$$\begin{aligned}\nabla_\mu V^\mu &= \nabla_\mu \delta_\nu^\mu V^\nu \\ &= \frac{\partial x^{\mu'}}{\partial x^\mu} \frac{\partial x^\nu}{\partial x^{\nu'}} \nabla_{\mu'} \delta_\nu^\mu V^{\nu'} \\ &= \frac{\partial x^{\mu'}}{\partial x^\mu} \frac{\partial x^\mu}{\partial x^{\nu'}} \nabla_{\mu'} V^{\nu'} \\ &= \delta_{\nu'}^{\mu'} \nabla_{\mu'} V^{\nu'} \\ &= \nabla_{\mu'} V^{\mu'} \\ &= \partial_r V^r + \Gamma_{r\mu}^r V^{\mu'} + \partial_\theta V^\theta + \Gamma_{\theta\mu}^\theta V^{\mu'} + \partial_\phi V^\phi + \Gamma_{\phi\mu}^\phi V^{\mu'}\end{aligned}$$

reference: pro_3 $\Gamma_{\lambda\mu}^\lambda = \partial_\mu \ln |\sqrt{g_{\lambda\lambda}}|$ and $g_{rr} = 1$; $g_{\theta\theta} = r^2$; $g_{\phi\phi} = r^2 \sin^2 \theta$

$$\begin{aligned}\Gamma_{rr}^r &= 0 & \Gamma_{\theta r}^\theta &= \frac{1}{r} & \Gamma_{\phi r}^\phi &= \frac{1}{r} \\ \Gamma_{r\theta}^r &= 0 & \Gamma_{\theta\theta}^\theta &= 0 & \Gamma_{\phi\theta}^\phi &= \frac{1}{\tan \theta} \\ \Gamma_{r\phi}^r &= 0 & \Gamma_{\theta\phi}^\theta &= 0 & \Gamma_{\phi\phi}^\phi &= 0\end{aligned}$$

$$\nabla_{\mu'} V^{\mu'} = \partial_r V^r + \partial_\theta V^\theta + \partial_\phi V^\phi + \frac{2V^r}{r} + \frac{V^\theta}{\tan \theta}$$

curl. reference: $\Gamma_{\mu\mu}^\lambda = -\frac{1}{2}(g_{\lambda\lambda})^{-1}\partial_\lambda g_{\mu\mu}$

$$\begin{aligned}\Gamma_{\phi\phi}^r &= -\frac{1}{2}\partial_r r^2 \sin^2\theta & \Gamma_{\phi\phi}^\theta &= -\frac{1}{2r}\partial_\theta r^2 \sin^2\theta & \Gamma_{\mu\mu}^\phi &= 0 \\ &= -r \sin^2\theta & &= -r \sin\theta \cos\theta \\ \Gamma_{\theta\theta}^r &= -\frac{1}{2}\partial_r r^2 = -r & \Gamma_{rr}^\theta &= 0\end{aligned}$$

$$\begin{aligned}\varepsilon^{\mu\nu}{}_\rho \nabla_\mu w_\nu dx^\sigma &= g_{\sigma\rho} \varepsilon^{\mu\nu\rho} \nabla_\mu w_\nu dx^\sigma \\ &= \frac{g_{\sigma\rho}}{\sqrt{|g|}} \tilde{\varepsilon}^{\mu\nu\rho} \nabla_\mu w_\nu dx^\sigma \\ &= \frac{g_{rr} dr}{r^2 \sin\theta} (\nabla_\theta w_\phi - \nabla_\phi w_\theta) + \frac{g_{\theta\theta} d\theta}{r^2 \sin\theta} (\nabla_\phi w_r - \nabla_r w_\phi) \\ &\quad + \frac{g_{\phi\phi} d\phi}{r^2 \sin\theta} (\nabla_\theta w_\phi - \nabla_\phi w_\theta) \\ &= \frac{dr}{r^2 \sin\theta} (\partial_\theta w_\phi - \partial_\phi w_\theta - \Gamma_{\theta\phi}^\lambda w_\lambda + \Gamma_{\phi\theta}^\lambda w_\lambda) \\ &\quad + \frac{r^2 d\theta}{r^2 \sin\theta} (\partial_\phi w_r - \partial_r w_\phi - \Gamma_{\phi r}^\lambda w_\lambda + \Gamma_{r\phi}^\lambda w_\lambda) \\ &\quad + \frac{r^2 \sin^2\theta d\phi}{r^2 \sin\theta} (\partial_\theta w_\phi - \partial_\phi w_\theta - \Gamma_{\theta\phi}^\lambda w_\lambda + \Gamma_{\phi\theta}^\lambda w_\lambda) \\ &= \frac{dr}{r^2 \sin\theta} (\partial_\theta w_\phi - \partial_\phi w_\theta) \\ &\quad + \frac{r d\theta}{r \sin\theta} (\partial_\phi w_r - \partial_r w_\phi) \\ &\quad + \frac{r \sin\theta d\phi}{r} (\partial_\theta w_\phi - \partial_\phi w_\theta)\end{aligned}$$

another version from wiki

$$\begin{aligned}\text{grad}\phi &= \partial_r \phi + \frac{1}{r} \partial_\theta \phi + \frac{1}{r \sin\theta} \partial_\phi \phi \\ \text{div } \vec{V} &= \frac{1}{r^2 \sin\theta} \left(\frac{\partial(V_1 r^2 \sin\theta)}{\partial r} + \frac{\partial(V_2 r \sin\theta)}{\partial \theta} + \frac{\partial(V_3 r)}{\partial \phi} \right) \\ &= \frac{1}{r^2 \sin\theta} (r^2 \sin\theta \partial_r V_1 + V_1 \times 2r \sin\theta + r \sin\theta \partial_\theta V_2 + V_2 \times r \cos\theta + r \partial_\phi V_3) \\ &= \partial_r V_1 + \frac{2V_1}{r} + \frac{1}{r} \partial_\theta V_2 + \frac{V_2}{r \tan\theta} + \frac{1}{r \sin\theta} \partial_\phi V_3 \\ &= \partial_r V_1 + \frac{1}{r} \partial_\theta V_2 + \frac{1}{r \sin\theta} \partial_\phi V_3 + \frac{2V_1}{r} + \frac{V_2}{r \tan\theta} \\ \text{curl } \vec{V} &= \frac{1}{r^2 \sin\theta} (\partial_\theta (V_3 r \sin\theta) - \partial_\phi (V_2 r)) \vec{e}_r \\ &\quad + \frac{1}{r^2 \sin\theta} (\partial_\phi V_1 - \partial_r (V_3 r \sin\theta)) \vec{e}_\theta \\ &\quad + \frac{r \sin\theta}{r^2 \sin\theta} (\partial_r (V_2 r) - \partial_\theta V_1) \vec{e}_\phi \\ &= \frac{1}{r^2 \sin\theta} (r \sin\theta \partial_\theta V_3 + V_3 r \cos\theta - r \partial_\phi V_2) \vec{e}_r \\ &\quad + \frac{1}{r \sin\theta} (\partial_\phi V_1 - r \sin\theta \partial_r V_3 - V_3 \sin\theta) \vec{e}_\theta \\ &\quad + \frac{1}{r} (r \partial_r V_2 + V_2 - \partial_\theta V_1) \vec{e}_\phi\end{aligned}$$

then if transform below : $\nabla_\mu \phi$, $\nabla_\mu V^\mu$ and $\varepsilon^{\mu\nu}{}_\rho \nabla_\mu w_\nu dx^\sigma$ are consistent with what in the wiki obviously!

$$\begin{aligned}w_r &= V_1 = V^r & dr &= \vec{e}_r = (\partial_r) \\ \frac{w_r}{r} &= V_2 = r V^\theta & r d\theta &= \vec{e}_\theta = \frac{(\partial_\theta)}{r} \\ \frac{w_r}{r \sin\theta} &= V_3 = r \sin\theta V^\phi & r \sin\theta d\phi &= \vec{e}_\phi = \frac{(\partial_\phi)}{r \sin\theta}\end{aligned}$$

therefore they are should not be the same,becuse they are one certain quality acting on different kinds of vectors.

ps: I just take a easy case of curl, for the curl of V^μ I haven't made it to transform.

3.

$$\Gamma_{\mu\nu}^\lambda = \frac{1}{2}g^{\lambda\sigma}(\partial_\mu g_{\nu\sigma} + \partial_\nu g_{\sigma\mu} - \partial_\sigma g_{\mu\nu})$$

$$g_{\mu\nu} = g_{\mu\nu}\delta_\mu^\nu$$

therefore

$$\begin{aligned} g^{ii}g_{ii} &= 1 \\ \Rightarrow g^{ii} &= (g_{ii})^{-1} \end{aligned}$$

.

$$\begin{aligned} \Gamma_{\mu\nu}^\lambda &= \frac{1}{2}g^{\lambda\sigma}(\partial_\mu g_{\nu\sigma} + \partial_\nu g_{\sigma\mu}) \\ &= \frac{1}{2}g^{\lambda\sigma}\partial_\mu g_{\nu\sigma} + \frac{1}{2}g^{\lambda\sigma}\partial_\nu g_{\sigma\mu} \\ &= 0 \end{aligned}$$

.

$$\begin{aligned} \Gamma_{\mu\mu}^\lambda &= \frac{1}{2}g^{\lambda\sigma}(\partial_\mu g_{\mu\sigma} + \partial_\mu g_{\sigma\mu} - \partial_\sigma g_{\mu\mu}) \\ &= \frac{1}{2}g^{\lambda\lambda}(-\partial_\sigma g_{\mu\mu}) \\ &= -\frac{1}{2}g^{\lambda\lambda}\partial_\lambda g_{\mu\mu} \\ &= -\frac{1}{2}(g_{\lambda\lambda})^{-1}\partial_\lambda g_{\mu\mu} \end{aligned}$$

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$$\begin{aligned} \Gamma_{\mu\lambda}^\lambda &= \frac{1}{2}g^{\lambda\sigma}(\partial_\mu g_{\nu\sigma} + \partial_\nu g_{\sigma\mu} - \partial_\sigma g_{\mu\nu}) \\ &= \frac{1}{2}g^{\lambda\lambda}(\partial_\mu g_{\lambda\lambda} + 0 - 0) \\ &= \frac{1}{2}(g_{\lambda\lambda})^{-1}\partial_\mu g_{\lambda\lambda} \\ &= \frac{1}{2}\partial_\mu \ln|g_{\lambda\lambda}| \\ &= \partial_\mu \ln|\sqrt{g_{\lambda\lambda}}| \end{aligned}$$

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$$\begin{aligned} \Gamma_{\lambda\lambda}^\lambda &= \frac{1}{2}(g_{\lambda\lambda})^{-1}\partial_\lambda g_{\lambda\lambda} \\ &= \partial_\lambda \ln|\sqrt{g_{\lambda\lambda}}| \end{aligned}$$

4.

a.

$$\begin{cases} x = uv\cos\phi \\ y = uv\sin\phi \\ z = \frac{1}{2}(u^2 - v^2) \end{cases}$$

$$\begin{aligned}\frac{\partial x}{\partial u} &= v \cos \phi & \frac{\partial y}{\partial u} &= v \sin \phi & \frac{\partial z}{\partial u} &= u \\ \frac{\partial x}{\partial v} &= u \cos \phi & \frac{\partial y}{\partial v} &= u \sin \phi & \frac{\partial z}{\partial v} &= -v \\ \frac{\partial x}{\partial \phi} &= -uv \sin \phi & \frac{\partial y}{\partial \phi} &= uv \cos \phi & \frac{\partial z}{\partial \phi} &= 0\end{aligned}$$

$$\begin{aligned}\begin{cases} dx = v \cos \phi du + u \cos \phi dv - uv \sin \phi d\phi \\ dy = v \sin \phi du + u \sin \phi dv + uv \cos \phi d\phi \\ dz = 2u du - 2v dv \end{cases} \\ \cos \phi dx + \sin \phi dy &= v(\cos^2 \phi + \sin^2 \phi) du + u(\cos^2 \phi + \sin^2 \phi) dv \\ &= v du + u dv\end{aligned}$$

$$\begin{aligned}\begin{cases} v du + u dv &= \cos \phi dx + \sin \phi dy \\ u du - v dv &= \frac{1}{2} dz \end{cases} \\ \Rightarrow \begin{cases} (v^2 + u^2) du &= v(\cos \phi dx + \sin \phi dy) + \frac{1}{2} u dz \\ (u^2 + v^2) dv &= u(\cos \phi dx + \sin \phi dy) - \frac{1}{2} v dz \end{cases} \\ \Rightarrow \begin{cases} du &= \frac{v \cos \phi}{u^2 + v^2} dx + \frac{v \sin \phi}{u^2 + v^2} dy + \frac{u}{2(u^2 + v^2)} dz \\ dv &= \frac{u \cos \phi}{u^2 + v^2} dx + \frac{u \sin \phi}{u^2 + v^2} dy - \frac{v}{2(u^2 + v^2)} dz \end{cases}\end{aligned}$$

$$\begin{aligned}dx &= v \cos \phi \left(\frac{v \cos \phi}{u^2 + v^2} dx + \frac{v \sin \phi}{u^2 + v^2} dy + \frac{u}{2(u^2 + v^2)} dz \right) \\ &\quad + u \cos \phi \left(\frac{u \cos \phi}{u^2 + v^2} dx + \frac{u \sin \phi}{u^2 + v^2} dy - \frac{v}{2(u^2 + v^2)} dz \right) \\ &\quad - uv \sin \phi d\phi \\ &= \cos^2 \phi dx + \cos \phi \sin \phi dy - uv \sin \phi d\phi \\ uv \sin \phi d\phi d\phi &= -\sin^2 \phi dx + \cos \phi \sin \phi dy \\ d\phi &= -\frac{\sin \phi}{uv} dx + \frac{\cos \phi}{uv} dy\end{aligned}$$

then

$$\begin{aligned}\frac{\partial u}{\partial x} &= \frac{v \cos \phi}{u^2 + v^2} & \frac{\partial v}{\partial x} &= \frac{u \cos \phi}{u^2 + v^2} & \frac{\partial \phi}{\partial x} &= -\frac{\sin \phi}{uv} \\ \frac{\partial u}{\partial y} &= \frac{v \sin \phi}{u^2 + v^2} & \frac{\partial v}{\partial y} &= \frac{u \sin \phi}{u^2 + v^2} & \frac{\partial \phi}{\partial y} &= \frac{\sin \phi}{uv} \\ \frac{\partial u}{\partial z} &= \frac{u}{2(u^2 + v^2)} & \frac{\partial v}{\partial z} &= -\frac{v}{2(u^2 + v^2)} & \frac{\partial \phi}{\partial z} &= 0\end{aligned}$$

b.

$$\begin{aligned}\partial_u &= \frac{\partial x}{\partial u} \partial_x + \frac{\partial y}{\partial u} \partial_y + \frac{\partial z}{\partial u} \partial_z \\ &= v \cos \phi \partial_x + v \sin \phi \partial_y + u \partial_z\end{aligned}$$

$$\begin{aligned}\partial_v &= \frac{\partial x}{\partial v} \partial_x + \frac{\partial y}{\partial v} \partial_y + \frac{\partial z}{\partial v} \partial_z \\ &= u \cos \phi \partial_x + u \sin \phi \partial_y - v \partial_z\end{aligned}$$

$$\begin{aligned}\partial_\phi &= \frac{\partial x}{\partial \phi} \partial_x + \frac{\partial y}{\partial \phi} \partial_y + \frac{\partial z}{\partial \phi} \partial_z \\ &= -uv \sin \phi \partial_x + uv \cos \phi \partial_y\end{aligned}$$

c.

$$\begin{aligned}g_{\mu'\nu'} &= \frac{\partial \xi^\mu}{\partial \xi^{\mu'}} \frac{\partial \xi^\nu}{\partial \xi^{\nu'}} g_{\mu\nu} \\ &= \frac{\partial \xi^\mu}{\partial \xi^{\mu'}} \frac{\partial \xi^\nu}{\partial \xi^{\nu'}} \delta_{\mu\nu}\end{aligned}$$

$$\text{set: } \vec{e}_\mu = \left(\frac{\partial x}{\partial \xi^{\mu'}}, \frac{\partial y}{\partial \xi^{\mu'}}, \frac{\partial z}{\partial \xi^{\mu'}} \right)$$

$$g_{\mu'\nu'} = \vec{e}_\mu \cdot \vec{e}_\nu$$

$$\begin{aligned} g_{11} &= \frac{\partial x}{\partial u} \frac{\partial x}{\partial u} + \frac{\partial y}{\partial u} \frac{\partial y}{\partial u} + \frac{\partial z}{\partial u} \frac{\partial z}{\partial u} \dots \\ &= v^2 \cos^2 \phi + v^2 \sin^2 \phi + u^2 \\ &= v^2 + u^2 \end{aligned}$$

$$\begin{aligned} g_{22} &= \frac{\partial x}{\partial v} \frac{\partial x}{\partial v} + \frac{\partial y}{\partial v} \frac{\partial y}{\partial v} + \frac{\partial z}{\partial v} \frac{\partial z}{\partial v} \\ &= u^2 \cos^2 \phi + u^2 \sin^2 \phi + v^2 \\ &= u^2 + v^2 \end{aligned}$$

$$\begin{aligned} g_{33} &= \frac{\partial x}{\partial \phi} \frac{\partial x}{\partial \phi} + \frac{\partial y}{\partial \phi} \frac{\partial y}{\partial \phi} + \frac{\partial z}{\partial \phi} \frac{\partial z}{\partial \phi} \\ &= (-uv \sin \phi)^2 + (uv \cos \phi)^2 \\ &= u^2 v^2 \end{aligned}$$

$$\begin{aligned} g_{12} = g_{21} &= \vec{e}_1 \cdot \vec{e}_2 \\ &= v u \cos^2 \phi + u v \sin^2 \phi - uv \\ &= 0 \end{aligned}$$

$$\begin{aligned} g_{13} = g_{31} &= \vec{e}_1 \cdot \vec{e}_3 \\ &= -u v^2 \cos \phi \sin \phi + u v^2 \sin \phi \cos \phi \\ &= 0 \end{aligned}$$

$$\begin{aligned} g_{23} = g_{32} &= \vec{e}_2 \cdot \vec{e}_3 \\ &= -u^2 v \cos \phi \sin \phi + u^2 v \sin \phi \cos \phi \\ &= 0 \end{aligned}$$

$$g = \begin{pmatrix} u^2 + v^2 & & \\ & u^2 + v^2 & \\ & & u^2 v^2 \end{pmatrix}$$

$$g^{-1} = \begin{pmatrix} \frac{1}{u^2 + v^2} & & \\ & \frac{1}{u^2 + v^2} & \\ & & \frac{1}{u^2 v^2} \end{pmatrix}$$

d.

$$\Gamma_{\mu\nu}^\sigma = \frac{1}{2} g^{\sigma\rho} (\partial_\mu g_{\nu\rho} + \partial_\nu g_{\mu\rho} - \partial_\rho g_{\mu\nu})$$

$$\begin{aligned} \Gamma_{\mu\nu}^u &= \frac{1}{2} g^{uu} (\partial_\mu g_{\nu u} + \partial_\nu g_{\mu u} - \partial_u g_{\mu\nu}) \\ \Gamma_{u\nu}^u &= \frac{1}{2} g^{uu} (\partial_u g_{\nu u} + \partial_\nu g_{u u} - \partial_u g_{u\nu}) \\ &= \frac{1}{2} g^{uu} \partial_\nu g_{u u} \\ &= \begin{cases} \frac{1}{2} g^{uu} \partial_u g_{u u} & \nu = u \\ \frac{1}{2} g^{uu} \partial_v g_{u u} & \nu = v \\ 0 & \nu = \phi \end{cases} = \begin{cases} \frac{u}{u^2 + v^2} & \nu = u \\ \frac{v}{u^2 + v^2} & \nu = v \\ 0 & \nu = \phi \end{cases} \\ \Gamma_{v\nu}^u &= \frac{1}{2} g^{uu} (\partial_v g_{\nu u} + \partial_\nu g_{v u} - \partial_u g_{v\nu}) \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2}g^{uu}(\partial_v g_{vu} - \partial_u g_{vv}) \\
&= \begin{cases} \frac{1}{2}g^{uu}(\partial_v g_{vu} - \partial_u g_{vv}) & \nu = v \\ 0 & \nu = \phi \end{cases} = \begin{cases} \frac{-\partial_u g_{vv}}{2(u^2+v^2)} & \nu = v \\ 0 & \nu = \phi \end{cases} \\
&= \begin{cases} -\frac{u}{u^2+v^2} & \nu = v \\ 0 & \nu = \phi \end{cases} \\
\Gamma_{\phi\phi}^u &= \frac{1}{2}g^{uu}(2\partial_\phi g_{\phi u} - \partial_u g_{\phi\phi}) \\
&= \frac{-uv^2}{u^2+v^2} \\
\Gamma_{\mu\nu}^v &= \frac{1}{2}g^{vv}(\partial_\mu g_{\nu v} + \partial_\nu g_{\mu v} - \partial_v g_{\mu\nu}) \\
\Gamma_{uv}^v &= \frac{1}{2}g^{vv}(\partial_u g_{\nu v} + \partial_\nu g_{uv} - \partial_v g_{uv}) \\
&= \frac{1}{2}g^{vv}(\partial_u g_{\nu v} - \partial_v g_{uv}) \\
&= \begin{cases} \frac{1}{2}g^{vv}(\partial_u g_{uv} - \partial_v g_{uu}) & \nu = u \\ \frac{1}{2}g^{vv}(\partial_u g_{vv} - \partial_v g_{uv}) & \nu = v \\ 0 & \nu = \phi \end{cases} = \begin{cases} -\frac{1}{2}g^{vv}\partial_v g_{uu} & \nu = u \\ \frac{1}{2}g^{vv}\partial_u g_{vv} & \nu = v \\ 0 & \nu = \phi \end{cases} \\
&= \begin{cases} -\frac{v}{u^2+v^2} & \nu = u \\ \frac{u}{u^2+v^2} & \nu = v \\ 0 & \nu = \phi \end{cases} \\
\Gamma_{v\nu}^v &= \frac{1}{2}g^{vv}(\partial_v g_{\nu v} + \partial_\nu g_{vv} - \partial_v g_{v\nu}) \\
&= \frac{1}{2}g^{vv}\partial_v g_{vv} \\
&= \begin{cases} \frac{1}{2}g^{vv}\partial_v g_{vv} & \nu = v \\ 0 & \nu = \phi \end{cases} = \begin{cases} \frac{2v}{2(u^2+v^2)} & \nu = v \\ 0 & \nu = \phi \end{cases} \\
&= \begin{cases} \frac{v}{u^2+v^2} & \nu = v \\ 0 & \nu = \phi \end{cases} \\
\Gamma_{\phi\phi}^v &= \frac{1}{2}g^{vv}(2\partial_\phi g_{\phi v} - \partial_v g_{\phi\phi}) \\
&= -\frac{2vu^2}{2(u^2+v^2)} \\
&= -\frac{vu^2}{u^2+v^2} \\
\Gamma_{\mu\nu}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_\mu g_{\nu\phi} + \partial_\nu g_{\mu\phi} - \partial_\phi g_{\mu\nu}) \\
&= \frac{1}{2}g^{\phi\phi}(\partial_\mu g_{\nu\phi} + \partial_\nu g_{\mu\phi}) \\
\Gamma_{uv}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_u g_{\nu\phi} + \partial_\nu g_{u\phi}) \\
&= \frac{1}{2}g^{\phi\phi}\partial_u g_{\nu\phi} \\
&= \begin{cases} \frac{1}{2}g^{\phi\phi}\partial_u g_{\phi\phi} & \nu = \phi \\ 0 & \text{others} \end{cases} = \begin{cases} \frac{2uv^2}{2u^2v^2} & \nu = \phi \\ 0 & \text{others} \end{cases} \\
&= \begin{cases} \frac{1}{u} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} \\
\Gamma_{v\nu}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_v g_{\nu\phi} + \partial_\nu g_{v\phi}) \\
&= \frac{1}{2}g^{\phi\phi}\partial_v g_{\nu\phi}
\end{aligned}$$

$$\begin{aligned}
&= \begin{cases} \frac{1}{2}g^{\phi\phi}\partial_\nu g_{\phi\phi} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} \\
&= \begin{cases} \frac{1}{v} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} \\
\Gamma_{\phi\phi}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_\phi g_{\phi\phi} + \partial_\phi g_{\phi\phi}) = 0
\end{aligned}$$

e.

$$\begin{aligned}
\nabla_\mu V^\mu &= \partial_\mu V^\mu + \Gamma_{\mu\lambda}^\mu V^\lambda \\
&= \partial_u V^u + \partial_v V^v + \partial_\phi V^\phi + \Gamma_{u\lambda}^u V^\lambda + \Gamma_{v\lambda}^v V^\lambda + \Gamma_{\phi\lambda}^\phi V^\lambda \\
&= \partial_u V^u + \partial_v V^v + \partial_\phi V^\phi \\
&\quad + \frac{u}{u^2+v^2}V^u + \frac{v}{u^2+v^2}V^v + \frac{u}{u^2+v^2}V^u + \frac{v}{u^2+v^2}V^v \\
&\quad + \frac{1}{u}V^u + \frac{1}{v}V^v \\
&= \partial_u V^u + \partial_v V^v + \partial_\phi V^\phi + \frac{2}{u^2+v^2}(V^u + V^v) + \frac{1}{u}V^u + \frac{1}{v}V^v \\
\nabla_\mu \nabla^\mu f &= \partial_u \nabla^u f + \partial_v \nabla^v f + \partial_\phi \nabla^\phi f + \frac{2}{u^2+v^2}(\nabla^u f + \nabla^v f) + \frac{1}{u}\nabla^u f + \frac{1}{v}\nabla^v f \\
&\quad + \partial_\mu \partial^\mu f + \partial_v \partial^v f + \partial_\phi \partial^\phi f + \frac{2}{u^2+v^2}(\partial^u f + \partial^v f) + \frac{1}{u}\partial^u f + \frac{1}{v}\partial^v f
\end{aligned}$$

5. $g = \begin{pmatrix} 1 & \\ & \sin^2\theta \end{pmatrix}; \quad g^{-1} = \begin{pmatrix} 1 & \\ & \frac{1}{\sin^2\theta} \end{pmatrix}$

$$\begin{aligned}
\Gamma_{\theta\phi}^\theta &= \frac{1}{2}g^{\theta\nu}(\partial_\theta g_{\phi\nu} + \partial_\phi g_{\theta\nu} - \partial_\nu g_{\theta\phi}) \\
&= \frac{1}{2}g^{\theta\theta}\partial_\phi g_{\theta\theta} = 0
\end{aligned}$$

$$\begin{aligned}
\Gamma_{\phi\phi}^\theta &= \frac{1}{2}g^{\theta\nu}(2 \times \partial_\phi g_{\phi\nu} - \partial_\nu g_{\phi\phi}) \\
&= \frac{1}{2}g^{\theta\theta}(-\partial_\theta g_{\phi\phi}) \\
&= -\sin\theta\cos\theta
\end{aligned}$$

$$\begin{aligned}
\Gamma_{\theta\theta}^\phi &= \frac{1}{2}g^{\phi\nu}(2 \times \partial_\theta g_{\theta\nu} - \partial_\nu g_{\theta\theta}) \\
&= 0
\end{aligned}$$

$$\begin{aligned}
\Gamma_{\theta\phi}^\phi &= \frac{1}{2}g^{\phi\nu}(\partial_\theta g_{\phi\nu} + \partial_\phi g_{\theta\nu} - \partial_\nu g_{\theta\phi}) \\
&= \frac{1}{2}g^{\phi\phi}\partial_\theta g_{\phi\phi} = \frac{1}{2\sin\theta}\cos\theta \\
&= \frac{1}{\tan\theta}
\end{aligned}$$

$$\begin{aligned}
\Gamma_{\phi\phi}^\phi &= \frac{1}{2}g^{\phi\nu}(2 \times \partial_\phi g_{\phi\nu} - \partial_\nu g_{\phi\phi}) \\
&= \frac{1}{2}g^{\phi\phi}(2 \times \partial_\phi g_{\phi\phi} - \partial_\phi g_{\phi\phi}) \\
&= 0
\end{aligned}$$

a. $\begin{cases} \phi = \phi_0 \\ \theta = \lambda \end{cases}$

$$\begin{aligned}
\frac{D}{d\lambda} \frac{d\theta}{d\lambda} &= \frac{d^2\theta}{d\lambda^2} + \Gamma_{\mu\nu}^\theta \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \\
&= \frac{d^2\theta}{d\lambda^2} - 2 \times \sin\theta\cos\theta \frac{d\phi_0}{d\lambda} \frac{d\phi_0}{d\lambda}
\end{aligned}$$

$$= \frac{d^2\theta}{d\lambda^2} = 0$$

$$\begin{aligned} \frac{D}{d\lambda} \frac{d\phi_0}{d\lambda} &= \frac{d^2\phi_0}{d\lambda^2} + \Gamma_{\mu\nu}^\phi \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \\ &= 0 - 2 \times \sin\theta \cos\theta \frac{d\theta}{d\lambda} \frac{d\phi_0}{d\lambda} \\ &= 0 \end{aligned}$$

$$\begin{cases} \phi = \lambda \\ \theta = \theta_0 \end{cases}$$

$$\begin{aligned} \frac{D}{d\lambda} \frac{d\theta_0}{d\lambda} &= \frac{d^2\theta_0}{d\lambda^2} + \Gamma_{\mu\nu}^\theta \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \\ &= 0 + \frac{1}{\tan\theta} \left(\frac{d\phi}{d\lambda} \right)^2 \\ &= \frac{1}{\tan\theta} \\ \frac{D}{d\lambda} \frac{d\phi}{d\lambda} &= \frac{d^2\phi}{d\lambda^2} + \Gamma_{\mu\nu}^\phi \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \\ &= \frac{d^2\phi}{d\lambda^2} + \frac{1}{\tan\theta} \frac{d\theta_0}{d\lambda} \frac{d\phi}{d\lambda} = 0 \end{aligned}$$

therefore when $\frac{1}{\tan\theta} = 0 \Rightarrow \theta = \frac{\pi}{2}$ the curve is geodesic.

b.

$$\frac{d}{d\lambda} V^\mu + \Gamma_{\nu\sigma}^\mu \frac{dx^\nu}{d\lambda} V^\sigma = 0$$

then set when $\lambda = 0$ $V^\mu = (1, 0)$

$$\begin{aligned} &\begin{cases} \frac{d}{d\lambda} V^\theta + \Gamma_{\phi\phi}^\theta \frac{d\phi}{d\lambda} V^\phi = 0 \\ \frac{d}{d\lambda} V^\phi + \Gamma_{\theta\phi}^\phi \left(\frac{d\phi}{d\lambda} V^\theta + \frac{d\theta}{d\lambda} V^\phi \right) = 0 \end{cases} \\ \Rightarrow &\begin{cases} \frac{d}{d\lambda} V^\theta - \sin\theta \cos\theta V^\phi = 0 \\ \frac{d}{d\lambda} V^\phi + \frac{1}{\tan\theta} V^\theta = 0 \end{cases} \\ \Rightarrow &\begin{cases} \frac{d}{d\lambda} V^\theta = 0 \\ \frac{d}{d\lambda} V^\phi = 0 \end{cases} \end{aligned}$$

$$\begin{aligned} \frac{d^2}{d\lambda^2} V^\theta - \sin\theta \sin\theta \frac{d}{d\lambda} V^\phi &= \frac{d^2}{d\lambda^2} V^\theta - \sin\theta \cos\theta \left(-\frac{1}{\tan\theta} V^\theta \right) \\ &= V^{\theta''} + \cos^2\theta V^\theta = 0 \end{aligned}$$

then

$$\begin{aligned} V^\theta &= A \cos(\cos\theta\lambda) + B \sin(\cos\theta\lambda) \\ V_0^\theta &= A = 1 \\ V^\phi &= \frac{1}{\sin\theta \cos\theta} \frac{d}{d\lambda} V^\theta \\ &= -\frac{\cos\theta}{\sin\theta \cos\theta} \times \cos\theta \sin(\cos\theta\lambda) + \frac{B \cos\theta}{\sin\theta \cos\theta} \times \cos(\cos\theta\lambda) \\ &= -\frac{1}{\sin\theta} \sin(\cos\theta\lambda) + \frac{B}{\sin\theta} \cos(\cos\theta\lambda) \\ V_0^\phi &= \frac{B}{\sin\theta} = 0 \\ \Rightarrow B &= 0 \end{aligned}$$

$$\vec{V} = \left(\cos(\cos\theta\lambda), \cdot \right)$$

the curve remain unchange

6.

$$\begin{aligned} ds^2 &= -(1+2\Phi)dt^2 + (1-2\Phi)dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2) \\ &= -dt^2 + dr^2 + r^2d\theta^2 + r^2\sin^2\theta d\phi^2 - 2\Phi(dt^2 + dr^2) \end{aligned}$$

$$\begin{aligned} g &= \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & r^2 & \\ & & & r^2\sin^2\theta \end{pmatrix} - 2\Phi \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 0 & \\ & & & 0 \end{pmatrix} \\ &= \begin{pmatrix} -1-2\Phi & & & \\ & 1-2\Phi & & \\ & & r^2 & \\ & & & r^2\sin^2\theta \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \Gamma_{\mu\nu}^t &= \frac{1}{2}g^{tt}(\partial_\mu g_{\nu t} + \partial_\nu g_{\mu t} - \partial_t g_{\mu\nu}) \\ &= \frac{1}{2}g^{tt}(\partial_\mu g_{\nu t} + \partial_\nu g_{\mu t}) \\ \Gamma_{t\nu}^t &= \frac{1}{2}g^{tt}\partial_\nu g_{tt} \\ &= \begin{cases} -\frac{1}{2} \times \frac{2}{-1-2\Phi} \frac{\partial\Phi}{\partial r} & \nu = r \\ 0 & \nu \neq r \end{cases} = \begin{cases} \frac{1}{2(1+2\Phi)} \frac{\partial(1+2\Phi)}{\partial r} & \nu = r \\ 0 & \nu \neq r \end{cases} \\ &= \begin{cases} \frac{1}{2} \frac{\partial \ln(1+2\Phi)}{\partial r} & \nu = r \\ 0 & \nu \neq r \end{cases} = \begin{cases} \frac{\partial_r \Phi}{1+2\Phi} & \nu = r \\ 0 & \nu \neq r \end{cases} \\ \Gamma_{r\nu}^t &= \frac{1}{2}g^{tt}(\partial_r g_{\nu t} + \partial_\nu g_{rt}) \\ &= \frac{1}{2}g^{tt}\partial_r g_{\nu t} \\ &= 0(\nu \neq t) \\ \Gamma_{\theta\nu}^t &= \frac{1}{2}g^{tt}(\partial_\theta g_{\nu t} + \partial_\nu g_{\theta t}) = 0 \\ \Gamma_{\phi\nu}^t &= \frac{1}{2}g^{tt}(\partial_\phi g_{\nu t} + \partial_\nu g_{\phi t}) = 0 \end{aligned}$$

$$\begin{aligned} \Gamma_{\mu\nu}^r &= \frac{1}{2}g^{rr}(\partial_\mu g_{\nu r} + \partial_\nu g_{\mu r} - \partial_r g_{\mu\nu}) \\ \Gamma_{t\nu}^r &= \frac{1}{2}g^{rr}(\partial_t g_{\nu r} + \partial_\nu g_{tr} - \partial_r g_{t\nu}) \\ &= -\frac{1}{2}g^{rr}\partial_r g_{t\nu} \\ &= \begin{cases} -\frac{1}{2}g^{rr}\partial_r g_{tt} & \nu = t \\ 0 & \nu \neq t \end{cases} \Rightarrow \begin{cases} -\frac{1}{2} \frac{-2}{1-2\Phi} \partial_r \Phi & \nu = t \\ 0 & \nu \neq t \end{cases} \\ &= \begin{cases} \frac{\partial_r \Phi}{1-2\Phi} & \nu = t \\ 0 & \nu \neq t \end{cases} = \begin{cases} -\frac{1}{2} \partial_r \ln(1-2\Phi) & \nu = t \\ 0 & \nu \neq t \end{cases} \\ \Gamma_{r\nu}^r &= \frac{1}{2}g^{rr}(\partial_r g_{\nu r} + \partial_\nu g_{rr} - \partial_r g_{r\nu}) \\ &= \frac{1}{2}g^{rr}\partial_\nu g_{rr} \\ &= \begin{cases} \frac{1}{2}g^{rr}\partial_r g_{rr} & \nu = r \\ 0 & \nu \neq t, r \end{cases} = \begin{cases} \frac{1}{2} \frac{-2}{1-2\Phi} \partial_r \Phi & \nu = r \\ 0 & \nu \neq t, r \end{cases} \\ &= \begin{cases} \frac{1}{2} \partial_r \ln(1-2\Phi) & \nu = r \\ 0 & \nu \neq t, r \end{cases} \end{aligned}$$

$$\begin{aligned}
\Gamma_{\theta\nu}^r &= \frac{1}{2}g^{rr}(\partial_\theta g_{\nu r} + \partial_\nu g_{\theta r} - \partial_r g_{\theta\nu}) \\
&= -\frac{1}{2}g^{rr}\partial_r g_{\theta\nu} \\
&= \begin{cases} -\frac{1}{2}g^{rr}\partial_r g_{\theta\theta} & \nu = \theta \\ 0 & \nu = \phi \end{cases} = \begin{cases} -\frac{r}{1-2\Phi} & \nu = \theta \\ 0 & \nu = \phi \end{cases} \\
\Gamma_{\phi\phi}^r &= \frac{1}{2}g^{rr}(2\partial_\phi g_{\phi r} - \partial_r g_{\phi\phi}) = -\frac{1}{2}g^{rr}\partial_r g_{\phi\phi} \\
&= -\frac{2r\sin^2\theta}{2(1-2\Phi)} = -\frac{r\sin^2\theta}{1-2\Phi} \\
\Gamma_{\mu\nu}^\theta &= \frac{1}{2}g^{\theta\theta}(\partial_\mu g_{\nu\theta} + \partial_\nu g_{\mu\theta} - \partial_\theta g_{\mu\nu}) \\
\Gamma_{t\nu}^\theta &= \frac{1}{2}g^{\theta\theta}(\partial_t g_{\nu\theta} + \partial_\nu g_{t\theta} - \partial_\theta g_{t\nu}) = 0 \\
\Gamma_{r\nu}^\theta &= \frac{1}{2}g^{\theta\theta}(\partial_r g_{\nu\theta} + \partial_\nu g_{r\theta} - \partial_\theta g_{r\nu}) \\
&= \frac{1}{2}g^{\theta\theta}\partial_r g_{\nu\theta} \\
&= \begin{cases} \frac{1}{2}g^{\theta\theta}\partial_r g_{\theta\theta} & \nu = \theta \\ 0 & \nu \neq \theta \end{cases} = \begin{cases} \frac{2r}{2r^2} & \nu = \theta \\ 0 & \nu \neq \theta \end{cases} \\
&= \begin{cases} \frac{1}{r} & \nu = \theta \\ 0 & \nu \neq \theta \end{cases} \\
\Gamma_{\theta\nu}^\theta &= \frac{1}{2}g^{\theta\theta}(\partial_\theta g_{\nu\theta} + \partial_\nu g_{\theta\theta} - \partial_\theta g_{\theta\nu}) \\
&= \frac{1}{2}g^{\theta\theta}\partial_\nu g_{\theta\theta} \\
&= 0 (\nu \neq t, r) \\
\Gamma_{\phi\phi}^\theta &= \frac{1}{2}g^{\theta\theta}(2\partial_\phi g_{\phi\theta} - \partial_\theta g_{\phi\phi}) \\
&= -\frac{2r^2\sin\theta\cos\theta}{2r^2} = -\sin\theta\cos\theta \\
\Gamma_{\mu\nu}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_\mu g_{\nu\phi} + \partial_\nu g_{\mu\phi} - \partial_\phi g_{\mu\nu}) \\
\Gamma_{t\nu}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_t g_{\nu\phi} + \partial_\nu g_{t\phi} - \partial_\phi g_{\mu\nu}) = 0 \\
\Gamma_{r\nu}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_r g_{\nu\phi} + \partial_\nu g_{r\phi} - \partial_\phi g_{r\nu}) \\
&= \frac{1}{2}g^{\phi\phi}\partial_r g_{\nu\phi} \\
&= \begin{cases} \frac{1}{2}g^{\phi\phi}\partial_r g_{\phi\phi} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} = \begin{cases} \frac{2r\sin^2\theta}{2r^2\sin^2\theta} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} \\
&= \begin{cases} \frac{1}{r} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} \\
\Gamma_{\theta\nu}^\phi &= \frac{1}{2}g^{\phi\phi}(\partial_\theta g_{\nu\phi} + \partial_\nu g_{\theta\phi} - \partial_\phi g_{\theta\nu}) \\
&= \frac{1}{2}g^{\phi\phi}\partial_\theta g_{\nu\phi} \\
&= \begin{cases} \frac{1}{2}g^{\phi\phi}\partial_\theta g_{\phi\phi} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} = \begin{cases} \frac{2r^2\sin\theta\cos\theta}{2r^2\sin^2\theta} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} \\
&= \begin{cases} \frac{1}{\tan\theta} & \nu = \phi \\ 0 & \nu \neq \phi \end{cases} \\
\Gamma_{\phi\phi}^\phi &= \frac{1}{2}g^{\phi\phi}(2\partial_\phi g_{\phi\phi} - \partial_\phi g_{\phi\phi}) = 0
\end{aligned}$$

a. at first assume that $R, \theta, \phi = \text{constant}$

$$x^\mu = (t, R, \theta, \phi)$$

$$\begin{aligned} \frac{d^2 x^\mu}{d\lambda^2} + \Gamma_{\sigma\rho}^\mu \frac{dx^\sigma}{d\lambda} \frac{dx^\rho}{d\lambda} - (-\nabla\Phi) &= 0 \\ \left\{ \begin{array}{l} \frac{d^2 t}{d\tau^2} + \Gamma_{\sigma\rho}^t \frac{dx^\sigma}{d\tau^2} \frac{dx^\rho}{d\tau^2} = 0 \\ \Gamma_{\sigma\rho}^r \frac{dx^\sigma}{d\tau^2} \frac{dx^\rho}{d\tau^2} = \partial_r \Phi \\ \Gamma_{\sigma\rho}^\theta \frac{dx^\sigma}{d\tau^2} \frac{dx^\rho}{d\tau^2} = 0 \\ \Gamma_{\sigma\rho}^\phi \frac{dx^\sigma}{d\tau^2} \frac{dx^\rho}{d\tau^2} = 0 \end{array} \right\} &\Rightarrow \left\{ \begin{array}{l} \frac{d^2 t}{d\tau^2} = 0 \\ \Gamma_{tt}^r \left(\frac{dt}{d\tau} \right)^2 = \partial_r \Phi \\ 0 = 0 \\ 0 = 0 \end{array} \right. \\ &\Rightarrow \left\{ \begin{array}{l} \frac{d^2 t}{d\tau^2} = 0 \\ \frac{\partial_r \Phi}{1-2\Phi} \left(\frac{dt}{d\tau} \right)^2 = \partial_r \Phi \end{array} \right. \\ &\Rightarrow \frac{dt}{d\tau} = \sqrt{1-2\Phi} \end{aligned}$$

$$\text{therefore : } t = \tau \sqrt{1-2\Phi} + t_0 = \tau \sqrt{1 + \frac{2GM}{R_i}} + t_0$$

since $R_2 > R_1$, the t_1 on the tall building, move faster.

b. geodesic

There are $r = R(\text{constant})$ and $\theta = \frac{\pi}{2}$

$$\begin{aligned} \frac{d^2 x^\mu}{d\lambda^2} + \Gamma_{\sigma\rho}^\mu \frac{dx^\sigma}{d\lambda} \frac{dx^\rho}{d\lambda} &= 0 \\ \left\{ \begin{array}{l} \frac{d^2 t}{d\lambda^2} + \Gamma_{\sigma\rho}^t \frac{dx^\sigma}{d\lambda} \frac{dx^\rho}{d\lambda} = 0 \\ \Gamma_{\sigma\rho}^r \frac{dx^\sigma}{d\lambda} \frac{dx^\rho}{d\lambda} = 0 \\ \Gamma_{\sigma\rho}^\theta \frac{dx^\sigma}{d\lambda} \frac{dx^\rho}{d\lambda} = 0 \\ \frac{d^2 \phi}{d\lambda^2} + \Gamma_{\sigma\rho}^\phi \frac{dx^\sigma}{d\lambda} \frac{dx^\rho}{d\lambda} = 0 \end{array} \right\} &\Rightarrow \left\{ \begin{array}{l} \frac{d^2 t}{d\lambda^2} = 0 \\ \Gamma_{tt}^r \left(\frac{dt}{d\lambda} \right)^2 + \Gamma_{\phi\phi}^r \left(\frac{d\phi}{d\lambda} \right)^2 = 0 \\ \Gamma_{\phi\phi}^\theta \left(\frac{d\phi}{d\lambda} \right)^2 = 0 \\ \frac{d^2 \phi}{d\lambda^2} = 0 \end{array} \right. \\ &\Rightarrow \left\{ \begin{array}{l} \frac{d^2 t}{d\lambda^2} = 0 \\ \frac{\partial_r \Phi}{1-2\Phi} \left(\frac{dt}{d\lambda} \right)^2 - \frac{R \sin^2 \frac{\pi}{2}}{1-2\Phi} \left(\frac{d\phi}{d\lambda} \right)^2 = 0 \\ -\sin \frac{\pi}{2} \cos \frac{\pi}{2} \left(\frac{d\phi}{d\lambda} \right)^2 = 0 \\ \frac{d^2 \phi}{d\lambda^2} = 0 \end{array} \right. \\ &\Rightarrow \left\{ \begin{array}{l} \frac{d^2 t}{d\lambda^2} = 0 \\ \frac{d^2 \phi}{d\lambda^2} = 0 \\ \partial_r \Phi \left(\frac{dt}{d\lambda} \right)^2 - R \left(\frac{d\phi}{d\lambda} \right)^2 = 0 \end{array} \right. \end{aligned}$$

therefore

$$\begin{aligned} \frac{\left(\frac{d\phi}{d\lambda} \right)^2}{\left(\frac{dt}{d\lambda} \right)^2} &= \frac{\partial_r \Phi}{R} \\ \left(\frac{d\phi}{dt} \right)^2 &= \frac{1}{R} \times \left(\frac{GM}{R^2} \right) \\ \frac{d\phi}{dt} &= \sqrt{\frac{GM}{R^3}} \end{aligned}$$

the geodesic

$$\begin{cases} t &= \lambda + t_0 \\ r &= R \\ \theta &= \frac{\pi}{2} \\ \phi &= \sqrt{\frac{GM}{R^3}}\lambda + \phi_0 \end{cases}$$

c. two different curve.

form (b) satellite

$$\begin{aligned} \frac{\Delta\phi}{\Delta t} &= \sqrt{\frac{GM}{R^3}} \\ \frac{2\pi}{\Delta t} &= \sqrt{\frac{GM}{R^3}} \end{aligned}$$

$$\Delta t = 2\pi\sqrt{\frac{R^3}{GM}}$$

proper time:

$$\begin{aligned} d\tau^2 &= -\frac{1}{c^2}ds^2 \\ &= -\frac{1}{c^2}(-(c^2 + 2\Phi)dt^2 + r^2\sin^2\theta d\phi) \\ &= \left(1 + \frac{2}{c^2}\Phi\right)(2\pi)^2\left(-\frac{R^2}{\Phi}\right) - \frac{R^2}{c^2}(2\pi)^2 \\ &= (2\pi)^2\left(-\frac{R^2}{\Phi} - \frac{2R^2}{c^2} - \frac{R^2}{c^2}\right) \\ &= (2\pi)^2\frac{R^2}{c^2}\left(-\frac{c^2}{\Phi} - 3\right) \\ &= (2\pi)^2\frac{R^2}{-\Phi}\left(1 + \frac{3\Phi}{c^2}\right) \end{aligned}$$

$$\begin{aligned} \Delta t &= 2\pi\frac{R_2}{\sqrt{-\Phi}} = 2\pi \times 6.371 \times 10^6 m \times \sqrt{\frac{6.371 \times 10^6 m}{6.674 \times 10^{-11} m^3 kg^{-1} s^{-2} \times 5.972 \times 10^{24} kg}} \\ &= 5.061 \times 10^3 s \end{aligned}$$

$$\begin{aligned} \Delta\tau &= 2\pi\frac{R_2}{\sqrt{-\Phi}}\sqrt{1 + \frac{3\Phi}{c^2}} \\ &= \Delta t \times \sqrt{1 - \frac{3 \times 6.674 \times 10^{-11} m^3 kg^{-1} s^{-2} \times 5.972 \times 10^{24} kg}{6.371 \times 10^6 m \times (2.998 \times 10^8 m s^{-1})^2}} \\ &= \Delta t \times \sqrt{1 - 2.088 \times 10^{-9}} \\ &= 5.0609 \times 10^3 s \end{aligned}$$