

3rd-exercise-2

8.

$$ds^2 = d\psi^2 + \sin^2\psi(d\theta^2 + \sin^2\theta d\phi)$$

$$g = \begin{pmatrix} 1 & & \\ & \sin^2\psi & \\ & & \sin^2\psi\sin^2\theta \end{pmatrix}$$

$$g^{-1} = \begin{pmatrix} 1 & & \\ & \frac{1}{\sin^2\psi} & \\ & & \frac{1}{\sin^2\psi\sin^2\theta} \end{pmatrix}$$

a.

$$[m_n] = \begin{pmatrix} 0 & 0 & 0 \\ 2\sin\psi\cos\psi & 0 & 0 \\ 2\sin\psi\cos\psi\sin^2\theta & 2\sin^2\psi\sin\theta\cos\theta & 0 \end{pmatrix}$$

$$\begin{aligned} \Gamma_{11}^0 &= -\frac{1}{2}g^{\psi\psi} \times 2\sin\psi\cos\psi = -\sin\psi\cos\psi \\ \Gamma_{10}^1 &= \frac{1}{2}g^{\theta\theta} \times 2\sin\psi\cos\psi = \frac{1}{\tan\psi} \\ \Gamma_{22}^0 &= -\frac{1}{2}g^{\psi\psi} \times 2\sin\psi\cos\psi\sin^2\theta = -\sin\psi\cos\psi\sin^2\theta \\ \Gamma_{20}^2 &= \frac{1}{2}g^{\phi\phi} \times 2\sin\psi\cos\psi\sin^2\theta = \frac{1}{\tan\psi} \\ \Gamma_{22}^1 &= -\frac{1}{2}g^{\theta\theta} \times 2\sin^2\psi\sin\theta\cos\theta = -\sin\theta\cos\theta \\ \Gamma_{21}^2 &= \frac{1}{2}g^{\phi\phi} \times 2\sin^2\psi\sin\theta\cos\theta = \frac{1}{\tan\theta} \end{aligned}$$

b.

$$\begin{aligned} R^1_{212} &= \partial_1\Gamma_{22}^1 - \partial_2\Gamma_{12}^1 + \Gamma_{1\lambda}^1\Gamma_{22}^\lambda - \Gamma_{2\lambda}^1\Gamma_{12}^\lambda \\ &= \partial_1(-\sin\theta\cos\theta) + \Gamma_{10}^1\Gamma_{22}^0 - \Gamma_{22}^1\Gamma_{21}^2 \\ &= -\cos^2\theta + \sin^2\theta + \frac{1}{\tan\psi} \times (-\sin\psi\cos\psi\sin^2\theta) + \sin\theta\cos\theta \times \frac{1}{\tan\theta} \\ &= \sin^2\theta - \cos^2\psi\sin^2\theta = \sin^2\psi\sin^2\theta \end{aligned}$$

$$\begin{aligned} R^2_{112} &= \partial_1\Gamma_{21}^2 - \partial_2\Gamma_{11}^2 + \Gamma_{1\lambda}^2\Gamma_{21}^\lambda - \Gamma_{2\lambda}^2\Gamma_{11}^\lambda \\ &= \partial_1\frac{1}{\tan\theta} + \Gamma_{21}^2\Gamma_{21}^2 - \Gamma_{20}^2\Gamma_{11}^0 \\ &= \frac{-1}{\sin^2\theta} + \frac{1}{\tan\theta} \times \frac{1}{\tan\theta} + \frac{1}{\tan\psi} \times \sin\psi\cos\psi \\ &= -1 + \cos^2\psi = -\sin^2\psi \end{aligned}$$

$$\begin{aligned} R^0_{202} &= \partial_0\Gamma_{22}^0 - \partial_2\Gamma_{02}^0 + \Gamma_{0\lambda}^0\Gamma_{22}^\lambda - \Gamma_{2\lambda}^0\Gamma_{02}^\lambda \\ &= \partial_0(-\sin\psi\cos\psi\sin^2\theta) - \Gamma_{22}^0\Gamma_{20}^2 \\ &= -\sin^2\theta(\cos^2\psi - \sin^2\psi) + \sin\psi\cos\psi\sin^2\theta \times \frac{1}{\tan\psi} \end{aligned}$$

$$\begin{aligned}
&= -\sin^2\theta\cos^2\psi + \sin^2\theta\sin^2\psi + \cos^2\psi\sin^2\theta \\
&= \sin^2\theta\cos^2\psi
\end{aligned}$$

$$\begin{aligned}
R^0_{101} &= \partial_0\Gamma^0_{11} - \partial_1\Gamma^0_{01} + \Gamma^0_{0\lambda}\Gamma^\lambda_{11} - \Gamma^0_{1\lambda}\Gamma^\lambda_{01} \\
&= \partial_0(-\sin\psi\cos\psi) + \Gamma^0_{11}\Gamma^1_{10} \\
&= -\cos^2\psi + \sin^2\psi - \sin\psi\cos\psi \times \frac{1}{\tan\psi} \\
&= \sin^2\psi
\end{aligned}$$

$$\begin{aligned}
R^1_{001} &= \partial_0\Gamma^1_{10} - \partial_1\Gamma^1_{00} + \Gamma^1_{0\lambda}\Gamma^\lambda_{10} - \Gamma^1_{1\lambda}\Gamma^\lambda_{00} \\
&= \partial_0\frac{1}{\tan\psi} + \Gamma^1_{10}\Gamma^1_{10} \\
&= \frac{-1}{\sin^2\psi} + \frac{\cos^2\psi}{\sin^2\psi} = -1
\end{aligned}$$

$$\begin{aligned}
R^2_{002} &= \partial_0\Gamma^2_{20} - \partial_2\Gamma^2_{00} + \Gamma^2_{0\lambda}\Gamma^\lambda_{20} - \Gamma^2_{2\lambda}\Gamma^\lambda_{00} \\
&= \partial_0\frac{1}{\tan\psi} + \Gamma^2_{20}\Gamma^2_{20} \\
&= \frac{-1}{\sin^2\psi} + \frac{\cos^2\psi}{\sin^2\psi} = -1
\end{aligned}$$

$$\begin{aligned}
R^0_{101} &= \sin^2\psi & R^1_{001} &= -1 \\
R^0_{202} &= \sin^2\psi\sin^2\theta & R^2_{002} &= -1 \\
R^1_{212} &= \sin^2\psi\sin^2\theta & R^2_{112} &= -\sin^2\psi
\end{aligned}$$

$$\begin{aligned}
R_{00} &= R^1_{010} + R^2_{020} = 1 + 1 = 2 \\
R_{11} &= R^0_{101} + R^2_{121} = \sin^2\psi + \sin^2\psi = 2\sin^2\psi \\
R_{22} &= R^0_{202} + R^1_{212} = \sin^2\psi\sin^2\theta + \sin^2\psi\sin^2\theta = 2\sin^2\psi\sin^2\theta
\end{aligned}$$

$$\begin{aligned}
R &= g^{00}R_{00} + g^{11}R_{11} + g^{22}R_{22} \\
&= 2 + \frac{1}{\sin^2\psi} \times 2\sin^2\psi + \frac{1}{\sin^2\psi\sin^2\theta} \times 2\sin^2\psi\sin^2\theta \\
&= 6
\end{aligned}$$

c.

$$\begin{aligned}
R_{\rho\sigma\mu\nu} &= \frac{6}{3(3-1)}(g_{\rho\mu}g_{\sigma\nu} - g_{\rho\nu}g_{\sigma\mu}) \\
&= g_{\rho\mu}g_{\sigma\nu} - g_{\rho\nu}g_{\sigma\mu}
\end{aligned}$$

$$\begin{aligned}
R_{0101} &= g_{0\lambda}R^\lambda_{101} = R^0_{101} = \sin^2\psi \\
R_{0102} &= g_{0\lambda}R^\lambda_{102} = R^0_{102} = 0 \\
R_{0112} &= g_{0\lambda}R^\lambda_{112} = 0 \\
R_{0202} &= g_{0\lambda}R^\lambda_{202} = R^0_{202} = \sin^2\psi\sin^2\theta \\
R_{0212} &= g_{0\lambda}R^\lambda_{212} = 0 \\
R_{1212} &= g_{1\lambda}R^\lambda_{212} = \sin^2\psi \times \sin^2\psi\sin^2\theta = \sin^4\psi\sin^2\theta
\end{aligned}$$

$$\begin{aligned}
R_{0101} &= g_{00}g_{11} - g_{01}g_{10} = \sin^2\psi \\
R_{0102} &= g_{00}g_{12} - g_{02}g_{10} = 0
\end{aligned}$$

$$\begin{aligned}
R_{0112} &= g_{01}g_{12} - g_{02}g_{11} = 0 \\
R_{0202} &= g_{00}g_{22} - g_{02}g_{20} = \sin^2\psi\sin^2\theta \\
R_{0212} &= g_{01}g_{22} - g_{02}g_{21} = 0 \\
R_{1212} &= g_{11}g_{22} - g_{12}g_{21} = \sin^4\psi\sin^2\theta
\end{aligned}$$

therefore it's maximally symmetric space

11.

$$ds^2 = f^2(r)dr^2 + r^2 f^2(r)d\theta^2$$

$$[m_n] = \begin{pmatrix} 2ff' & 0 \\ 2r^2ff' + 2rf^2 & 0 \end{pmatrix}$$

$$\Gamma_{11}^1 = \frac{1}{2f^2} \times 2ff' = \frac{f'}{f}$$

$$\Gamma_{22}^1 = -\frac{1}{2f^2} \times (2r^2ff' + 2rf^2) = -\left(\frac{r^2f'}{f} + r\right) = -r^2h$$

$$\Gamma_{21}^2 = \frac{1}{2r^2f^2} \times (2r^2ff' + 2rf^2) = \frac{f'}{f} + \frac{1}{r} = h$$

$$\begin{aligned}
R_{11} &= R^2_{121} = \partial_2\Gamma_{11}^2 - \partial_1\Gamma_{21}^2 + \Gamma_{2\lambda}^2\Gamma_{11}^\lambda - \Gamma_{1\lambda}^2\Gamma_{21}^\lambda \\
&= -\partial_1\Gamma_{21}^2 + \Gamma_{21}^2\Gamma_{11}^1 - \Gamma_{21}^2\Gamma_{21}^2 \\
&= -\partial_1\left(\frac{f'}{f} + \frac{1}{r}\right) + \left(\frac{f'}{f} + \frac{1}{r}\right)\frac{f'}{f} - \left(\frac{f'}{f} + \frac{1}{r}\right)^2 \\
R_{22} &= R^1_{212} = \partial_1\Gamma_{22}^1 - \partial_2\Gamma_{12}^1 + \Gamma_{1\lambda}^1\Gamma_{22}^\lambda - \Gamma_{2\lambda}^1\Gamma_{12}^\lambda \\
&= \partial_1\left(-\left(\frac{r^2f'}{f} + r\right)\right) - \left(\frac{r^2f'}{f} + r\right)\frac{f'}{f} + \left(\frac{r^2f'}{f} + r\right)\left(\frac{f'}{f} + \frac{1}{r}\right) \\
&= -\partial_1r^2\left(\frac{f'}{f} + \frac{1}{r}\right) - r^2\left(\frac{f'}{f} + \frac{1}{r}\right)\frac{f'}{f} + r^2\left(\frac{f'}{f} + \frac{1}{r}\right)^2
\end{aligned}$$

$$\begin{aligned}
R_{11} = R^2_{121} &= \partial_2\Gamma_{11}^2 - \partial_1\Gamma_{21}^2 + \Gamma_{2\lambda}^2\Gamma_{11}^\lambda - \Gamma_{1\lambda}^2\Gamma_{21}^\lambda \\
&= -\partial_r h + \Gamma_{21}^2\Gamma_{11}^1 - \Gamma_{21}^2\Gamma_{21}^2 \\
&= -h' + h\frac{f'}{f} - h^2
\end{aligned}$$

$$\begin{aligned}
R_{22} = R^1_{212} &= \partial_1\Gamma_{22}^1 - \partial_2\Gamma_{12}^1 + \Gamma_{1\lambda}^1\Gamma_{22}^\lambda - \Gamma_{2\lambda}^1\Gamma_{12}^\lambda \\
&= \partial_r(-r^2h) + \Gamma_{11}^1\Gamma_{22}^1 - \Gamma_{22}^1\Gamma_{21}^2 \\
&= -\partial_r(r^2h) - r^2h\frac{f'}{f} + r^2h^2
\end{aligned}$$

$$\begin{aligned}
R &= g^{11}R_{11} + g^{22}R_{22} \\
&= \frac{1}{f^2}\left(-h' + h\frac{f'}{f} - h^2\right) + \frac{1}{r^2f^2}\left(-\partial_r(r^2h) - r^2h\frac{f'}{f} + r^2h^2\right) \\
&= -\frac{h'}{f^2} - \frac{1}{r^2f^2}\partial_r(r^2h) \\
&= -\frac{h'}{f^2} - \frac{1}{r^2f^2}(r^2h' + 2rh) \\
&= -\frac{2h'}{f^2} - \frac{2rh}{r^2f^2}
\end{aligned}$$

$$\begin{aligned}
&= -\frac{2}{rf^2}(rh' + h) \\
&= -\frac{2}{rf^2}\left(r\left(\frac{f'}{f} + \frac{1}{r}\right)' + \left(\frac{f'}{f} + \frac{1}{r}\right)\right) \\
&= -\frac{2}{rf^2}\left(r\left(\frac{f''}{f} - \frac{f'^2}{f^2} - \frac{1}{r^2}\right) + \frac{f'}{f} + \frac{1}{r}\right) \\
&= -\frac{2}{rf^2}\left(r\left(\frac{f''}{f} - \frac{f'^2}{f^2}\right) + \frac{f'}{f}\right)
\end{aligned}$$

the differential equation

$$\begin{aligned}
R &= -\frac{2}{a^2} \\
-\frac{2}{rf^2}\left(r\left(\frac{f''}{f} - \frac{f'^2}{f^2}\right) + \frac{f'}{f}\right) &= -\frac{2}{a^2} \\
\frac{1}{rf^2}\left(r\left(\frac{f''}{f} - \frac{f'^2}{f^2}\right) + \frac{f'}{f}\right) &= \frac{1}{a^2} \\
\frac{1}{rf^2}\left(r\left(\frac{f'}{f}\right)' + \frac{f'}{f}\right) &= \frac{1}{a^2}
\end{aligned}$$

I'm not succeeded in solving the equation. orz

I got the answer form Mobius transformation

Refence: The road to reality[Penrose]chinese version P101

$$\begin{aligned}
x + iy &= \frac{z - 1}{iz + i} = \frac{u + iv - 1}{i(u + iv) + i} = \frac{u - 1 + iv}{-v + (u + 1)i} \\
&= \frac{(u - 1 + iv)(v + (u + 1)i)}{(-v + (u + 1)i)(v + (u + 1)i)} \\
&= \frac{(u - 1)v - v(u + 1) + i(v^2 + u^2 - 1)}{-v^2 - (u + 1)^2} \\
&= \frac{2v + i(1 - v^2 - u^2)}{v^2 + (u + 1)^2} \\
\Rightarrow \\
x &= \frac{2v}{v^2 + (u + 1)^2} \\
y &= \frac{1 - v^2 - u^2}{v^2 + (u + 1)^2}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial x}{\partial u} &= -\frac{4v(u + 1)}{(v^2 + (u + 1)^2)^2} \\
\frac{\partial x}{\partial v} &= \frac{2}{v^2 + (u + 1)^2} - \frac{2v \times 2v}{(v^2 + (u + 1)^2)^2} \\
&= \frac{2(v^2 + (u + 1)^2) - 4v^2}{(v^2 + (u + 1)^2)^2} = \frac{2((u + 1)^2 - v^2)}{(v^2 + (u + 1)^2)^2} \\
\frac{\partial y}{\partial u} &= \frac{-2u}{v^2 + (u + 1)^2} - \frac{(1 - v^2 - u^2) \times 2(u + 1)}{(v^2 + (u + 1)^2)^2} \\
&= \frac{-2u(v^2 + (u + 1)^2) - 2(u + 1)(1 - v^2 - u^2)}{(v^2 + (u + 1)^2)^2} \\
&= \frac{2(-uv^2 - u(u + 1)^2 - (u + 1) + u^2(u + 1) + v^2(u + 1))}{(v^2 + (u + 1)^2)^2} \\
&= \frac{2(v^2 - (u + 1)(u(u + 1) + 1 - u^2))}{(v^2 + (u + 1)^2)^2}
\end{aligned}$$

$$\begin{aligned}
&= \frac{2(v^2 - (u+1)^2)}{(v^2 + (u+1)^2)^2} \\
\frac{\partial y}{\partial v} &= \frac{-2v}{v^2 + (u+1)^2} - \frac{(1 - v^2 - u^2) \times 2v}{(v^2 + (u+1)^2)^2} \\
&= \frac{2(-v(v^2 + (u+1)^2) - (v - v^3 - u^2v))}{(v^2 + (u+1)^2)^2} \\
&= \frac{2(-v(u+1)^2 - v + u^2v)}{(v^2 + (u+1)^2)^2} \\
&= \frac{2(-v(u^2 + 2u + 1) - v + u^2v)}{(v^2 + (u+1)^2)^2} = \frac{2(-2uv - 2v)}{(v^2 + (u+1)^2)^2} \\
&= \frac{-4v(u+1)}{(v^2 + (u+1)^2)^2}
\end{aligned}$$

$$\text{set } \rho = v^2 + (u+1)^2 \quad \frac{\partial(x, y)}{\partial(u, v)} = \begin{pmatrix} \frac{c}{\rho^2} & \frac{b}{\rho^2} \\ -\frac{b}{\rho^2} & \frac{c}{\rho^2} \end{pmatrix}$$

$$\text{put into the metric } ds^2 = \frac{a^2}{y^2} dx^2 + \frac{a^2}{y^2} dy^2$$

$$b^2 + c^2 = (4v(u+1))^2 + (2(v^2 - (u+1)^2))^2 = 4(4v^2(u+1)^2 + (v^2 - (u+1)^2)^2) = 4(v^2 + (u+1)^2)^2$$

$$\begin{aligned}
ds^2 &= \frac{a^2}{\left(\frac{1-v^2-u^2}{v^2+(u+1)^2}\right)^2} ((\partial_u x du + \partial_v x dv)^2 + (\partial_u y du + \partial_v y dv)^2) \\
&= \frac{a^2 \rho^2}{(1-v^2-u^2)^2} \left(\left(\frac{c}{\rho^2} du + \frac{b}{\rho^2} dv \right)^2 + \left(-\frac{b}{\rho^2} du + \frac{c}{\rho^2} dv \right)^2 \right) \\
&= \frac{a^2}{\rho^2 (1-v^2-u^2)^2} (c^2 du^2 + b^2 dv^2 + 2cb du dv + b^2 du^2 + c^2 dv^2 - 2bcd du dv) \\
&= \frac{a^2}{\rho^2 (1-v^2-u^2)^2} ((c^2 + b^2) du^2 + (c^2 + b^2) dv^2) \\
&= \frac{a^2}{\rho^2 (1-v^2-u^2)^2} (4\rho^2 du^2 + 4\rho^2 dv^2) \\
&= \frac{4a^2}{(1-r^2)^2} (du^2 + dv^2) \\
&= \frac{4a^2}{(1-r^2)^2} (dr^2 + r^2 d\theta^2)
\end{aligned}$$

$$\text{check the differential equation: solution } f(r) = \frac{2a}{1-r^2} \quad f' = -\frac{2a}{(1-r^2)^2} \times (-2r) = \frac{4ar}{(1-r^2)^2}$$

$$\begin{aligned}
\frac{1}{r f^2} \left(r \left(\frac{f'}{f} \right)' + \frac{f'}{f} \right) &= \frac{1}{r \left(\frac{2a}{1-r^2} \right)^2} \left(r \left(\frac{\frac{4ar}{(1-r^2)^2}}{\frac{2a}{1-r^2}} \right)' + \frac{\frac{4ar}{(1-r^2)^2}}{\frac{2a}{1-r^2}} \right) \\
&= \frac{(1-r^2)^2}{4a^2 r} \left(r \left(\frac{2r}{1-r^2} \right)' + \frac{2r}{1-r^2} \right) \\
&= \frac{(1-r^2)^2}{4a^2 r} \left(r \left(\frac{2(1-r^2) - 2r \times (-2r)}{(1-r^2)^2} \right) + \frac{2r}{1-r^2} \right) \\
&= \frac{(1-r^2)^2}{4a^2 r} \left(r \left(\frac{2-2r^2+4r^2}{(1-r^2)^2} \right) + \frac{2r}{1-r^2} \right) \\
&= \frac{(1-r^2)^2}{4a^2} \left(\frac{2+2r^2}{(1-r^2)^2} + \frac{2(1-r^2)}{(1-r^2)^2} \right) \\
&= \frac{(1-r^2)^2}{4a^2} \left(\frac{4}{(1-r^2)^2} \right)
\end{aligned}$$

$$= \frac{1}{a^2}$$

therefore when require $y > 0 \Rightarrow y = \frac{1-v^2-u^2}{v^2+(u+1)^2} > 0$ then $1-v^2-u^2 > 0 \Leftrightarrow r^2 = u^2 + v^2 < 1$

namely the range of r is $(0, 1)$

13.

killing equation upper indice version

$$(g_{\sigma\mu}\partial_\nu + g_{\sigma\nu}\partial_\mu)K^\sigma + (g_{\sigma\mu}\Gamma_{\nu\lambda}^\sigma + g_{\sigma\nu}\Gamma_{\mu\lambda}^\sigma)K^\lambda = 0$$

a.

$$(\eta_{\sigma\mu}\partial_\nu + \eta_{\sigma\nu}\partial_\mu)K^\sigma = 0$$

$$\left\{ \begin{array}{l} 2\eta_{\sigma t}\partial_t K^\sigma = 0 \\ (\eta_{\sigma t}\partial_x + \eta_{\sigma x}\partial_t)K^\sigma = 0 \\ (\eta_{\sigma t}\partial_y + \eta_{\sigma y}\partial_t)K^\sigma = 0 \\ (\eta_{\sigma t}\partial_z + \eta_{\sigma z}\partial_t)K^\sigma = 0 \\ 2\eta_{\sigma x}\partial_x K^\sigma = 0 \\ (\eta_{\sigma y}\partial_x + \eta_{\sigma x}\partial_y)K^\sigma = 0 \\ (\eta_{\sigma x}\partial_z + \eta_{\sigma z}\partial_x)K^\sigma = 0 \\ 2\eta_{\sigma y}\partial_y K^\sigma = 0 \\ (\eta_{\sigma y}\partial_z + \eta_{\sigma z}\partial_y)K^\sigma = 0 \\ 2\eta_{\sigma z}\partial_z K^\sigma = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} -\partial_t K^t = 0 \\ -\partial_x K^t + \partial_t K^x = 0 \\ -\partial_y K^t + \partial_t K^y = 0 \\ -\partial_z K^t + \partial_t K^z = 0 \\ \partial_x K^x = 0 \\ \partial_x K^y + \partial_y K^x = 0 \\ \partial_z K^x + \partial_x K^z = 0 \\ \partial_y K^y = 0 \\ \partial_z K^y + \partial_y K^z = 0 \\ \partial_z K^z = 0 \end{array} \right.$$

claim the solution as an order one expansion $K^\mu = a^\mu_\nu x^\nu + c^\mu$

$$\left\{ \begin{array}{l} a^0_\nu \partial_0 x^\nu = 0 \\ -a^0_\nu \partial_1 x^\nu + a^1_\nu \partial_0 x^\nu = 0 \\ -a^0_\nu \partial_2 x^\nu + a^2_\nu \partial_0 x^\nu = 0 \\ -a^0_\nu \partial_3 x^\nu + a^3_\nu \partial_0 x^\nu = 0 \\ a^1_\nu \partial_1 x^\nu = 0 \\ a^2_\nu \partial_1 x^\nu + a^1_\nu \partial_2 x^\nu = 0 \\ a^1_\nu \partial_3 x^\nu + a^3_\nu \partial_1 x^\nu = 0 \\ a^2_\nu \partial_2 x^\nu = 0 \\ a^2_\nu \partial_3 x^\nu + a^3_\nu \partial_2 x^\nu = 0 \\ a^3_\nu \partial_3 x^\nu = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} a^0_0 = 0 \\ -a^0_1 + a^1_0 = 0 \\ -a^0_2 + a^2_0 = 0 \\ -a^0_3 + a^3_0 = 0 \\ a^1_1 = 0 \\ a^2_1 + a^1_2 = 0 \\ a^1_3 + a^3_1 = 0 \\ a^2_2 = 0 \\ a^2_3 + a^3_2 = 0 \\ a^3_3 = 0 \end{array} \right.$$

therefore

$$K^\mu = a^\mu_\nu x^\nu + c^\mu$$

$$\begin{pmatrix} K^1 \\ K^2 \\ K^3 \\ K^4 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 & a^0_1 & a^0_2 & a^0_3 & c^1 \\ a^0_1 & 0 & a^1_2 & a^1_3 & c^2 \\ a^0_2 & -a^1_2 & 0 & a^2_3 & c^3 \\ a^0_3 & -a^1_3 & -a^2_3 & 0 & c^4 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x^1 \\ x^2 \\ x^3 \\ x^4 \\ 1 \end{pmatrix}$$

could see explicitly ,there are 10 independent killing vector.cause of 10 free paramenters.

b.

$$ds^2 = -dudv - dvdu + a^2(u)dx^2 + b^2(u)dy^2$$

$$g = \begin{pmatrix} 0 & -1 & & \\ -1 & 0 & & \\ & & a^2 & \\ & & & b^2 \end{pmatrix}$$

$$g^{-1} = \begin{pmatrix} 0 & -1 & & \\ -1 & 0 & & \\ & & \frac{1}{a^2} & \\ & & & \frac{1}{b^2} \end{pmatrix}$$

$$\begin{aligned} \Gamma_{\mu\nu}^u &= \frac{1}{2}g^{uv}(\partial_\mu g_{\nu v} + \partial_\nu g_{\mu v} - \partial_v g_{\mu\nu}) = 0 \\ \Gamma_{\mu\nu}^v &= \frac{1}{2}g^{vu}(\partial_\mu g_{\nu u} + \partial_\nu g_{\mu u} - \partial_u g_{\mu\nu}) \\ &= \frac{1}{2}\partial_u g_{\mu\nu} \\ &= \begin{cases} \Gamma_{xx}^v = aa' \\ \Gamma_{yy}^v = bb' \\ 0 & \text{others} \end{cases} \end{aligned}$$

$$\begin{aligned} \Gamma_{\mu\nu}^x &= \frac{1}{2}g^{xx}(\partial_\mu g_{\nu x} + \partial_\nu g_{\mu x} - \partial_x g_{\mu\nu}) \\ &= \frac{1}{2a^2}(\partial_\mu g_{\nu x} + \partial_\nu g_{\mu x}) \\ &= \begin{cases} \Gamma_{xu}^x = \frac{1}{2a^2}\partial_u g_{xx} \\ 0 & \text{others} \end{cases} = \begin{cases} \Gamma_{ux}^x = \frac{a'}{a} \\ 0 & \text{others} \end{cases} \end{aligned}$$

$$\begin{aligned} \Gamma_{\mu\nu}^y &= \frac{1}{2}g^{yy}(\partial_\mu g_{\nu y} + \partial_\nu g_{\mu y} - \partial_y g_{\mu\nu}) \\ &= \frac{1}{2b^2}(\partial_\mu g_{\nu y} + \partial_\nu g_{\mu y}) \\ &= \begin{cases} \Gamma_{yu}^y = \frac{1}{2b^2}\partial_u g_{yy} \\ 0 & \text{others} \end{cases} = \begin{cases} \Gamma_{yu}^y = \frac{b'}{b} \\ 0 & \text{others} \end{cases} \end{aligned}$$

$$(g_{\sigma\mu}\partial_\nu + g_{\sigma\nu}\partial_\mu)K^\sigma + (g_{\sigma\mu}\Gamma_{\nu\lambda}^\sigma + g_{\sigma\nu}\Gamma_{\mu\lambda}^\sigma)K^\lambda = 0$$

$$\left\{ \begin{array}{l} -2g_{\sigma u}\partial_u K^\sigma + (g_{\sigma u}\Gamma_{u\lambda}^\sigma + g_{\sigma u}\Gamma_{u\lambda}^\sigma)K^\lambda = 0 \\ -2g_{\sigma v}\partial_v K^\sigma + (g_{\sigma v}\Gamma_{v\lambda}^\sigma + g_{\sigma v}\Gamma_{v\lambda}^\sigma)K^\lambda = 0 \\ -2g_{\sigma x}\partial_x K^\sigma + (g_{\sigma x}\Gamma_{x\lambda}^\sigma + g_{\sigma x}\Gamma_{x\lambda}^\sigma)K^\lambda = 0 \\ -2g_{\sigma y}\partial_y K^\sigma + (g_{\sigma y}\Gamma_{y\lambda}^\sigma + g_{\sigma y}\Gamma_{y\lambda}^\sigma)K^\lambda = 0 \\ (g_{\sigma u}\partial_v + g_{\sigma v}\partial_u)K^\sigma + (g_{\sigma u}\Gamma_{v\lambda}^\sigma + g_{\sigma v}\Gamma_{u\lambda}^\sigma)K^\lambda = 0 \\ (g_{\sigma u}\partial_x + g_{\sigma x}\partial_u)K^\sigma + (g_{\sigma u}\Gamma_{x\lambda}^\sigma + g_{\sigma x}\Gamma_{u\lambda}^\sigma)K^\lambda = 0 \\ (g_{\sigma u}\partial_y + g_{\sigma y}\partial_u)K^\sigma + (g_{\sigma u}\Gamma_{y\lambda}^\sigma + g_{\sigma y}\Gamma_{u\lambda}^\sigma)K^\lambda = 0 \\ (g_{\sigma v}\partial_x + g_{\sigma x}\partial_v)K^\sigma + (g_{\sigma v}\Gamma_{x\lambda}^\sigma + g_{\sigma x}\Gamma_{v\lambda}^\sigma)K^\lambda = 0 \\ (g_{\sigma v}\partial_y + g_{\sigma y}\partial_v)K^\sigma + (g_{\sigma v}\Gamma_{y\lambda}^\sigma + g_{\sigma y}\Gamma_{v\lambda}^\sigma)K^\lambda = 0 \\ (g_{\sigma x}\partial_y + g_{\sigma y}\partial_x)K^\sigma + (g_{\sigma x}\Gamma_{y\lambda}^\sigma + g_{\sigma y}\Gamma_{x\lambda}^\sigma)K^\lambda = 0 \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} 2\partial_u K^v = 0 \\ 2\partial_v K^u = 0 \\ -2a^2\partial_x K^x + 2a^2\frac{a'}{a}K^u = 0 \\ -2b^2\partial_y K^y + 2b^2\frac{b'}{b}K^u = 0 \\ -\partial_v K^v - \partial_u K^u = 0 \\ -\partial_x K^v + a^2\partial_u K^x - aa'K^x + a^2\frac{a'}{a}K^x = 0 \\ -\partial_y K^v + b^2\partial_u K^y - bb'K^y + b^2\frac{b'}{b}K^y = 0 \\ -\partial_x K^u + a^2\partial_v K^x = 0 \\ -\partial_y K^u + b^2\partial_v K^y = 0 \\ a^2\partial_y K^x + b^2\partial_x K^y = 0 \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} \partial_u K^v = 0 \\ \partial_v K^u = 0 \\ -a\partial_x K^x + a'K^u = 0 \\ -b\partial_y K^y + b'K^u = 0 \\ -\partial_v K^v - \partial_u K^u = 0 \\ -\partial_x K^v + a^2\partial_u K^x = 0 \\ -\partial_y K^v + b^2\partial_u K^y = 0 \\ -\partial_x K^u + a^2\partial_v K^x = 0 \\ -\partial_y K^u + b^2\partial_v K^y = 0 \\ a^2\partial_y K^x + b^2\partial_x K^y = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} \partial_u K^v = 0 \\ 0 = 0 \\ \partial_x K^x = 0 \\ \partial_y K^y = 0 \\ \partial_v K^v = 0 \\ -\partial_x K^v + a^2\partial_u K^x = 0 \\ -\partial_y K^v + b^2\partial_u K^y = 0 \\ \partial_v K^x = 0 \\ \partial_v K^y = 0 \\ a^2\partial_y K^x + b^2\partial_x K^y = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} \partial_u K^v = 0 \\ \partial_v K^v = 0 \\ \partial_v K^x = 0 \\ \partial_x K^x = 0 \\ \partial_v K^y = 0 \\ \partial_y K^y = 0 \\ -\partial_x K^v + a^2\partial_u K^x = 0 \\ -\partial_y K^v + b^2\partial_u K^y = 0 \\ a^2\partial_y K^x + b^2\partial_x K^y = 0 \end{array} \right.$$

guess

$$\left\{ \begin{array}{l} K^v(x, y) = c_1x + c_2y + c_3 \\ K^x(u, y) = c_4 \int_0^u \frac{1}{a^2} dt + c_5 \\ K^y(u, x) = c_6 \int_0^u \frac{1}{b^2} dt + c_7 \end{array} \right.$$

$$\left\{ \begin{array}{l} \partial_u K^v = 0 \\ \partial_v K^v = 0 \\ \partial_v K^x = 0 \\ \partial_x K^x = 0 \\ \partial_v K^y = 0 \\ \partial_y K^y = 0 \\ -\partial_x K^v + a^2\partial_u K^x = 0 \\ -\partial_y K^v + b^2\partial_u K^y = 0 \\ a^2\partial_y K^x + b^2\partial_x K^y = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} 0 = 0 \\ 0 = 0 \\ 0 = 0 \\ 0 = 0 \\ 0 = 0 \\ 0 = 0 \\ -c_1 + c_4a^2 \times \frac{1}{a^2} = 0 \\ -c_2 + c_6b^2 \times \frac{1}{b^2} = 0 \\ 0 = 0 \end{array} \right. = \left\{ \begin{array}{l} c_1 = c_4 \\ c_2 = c_6 \end{array} \right.$$

then

$$\begin{pmatrix} K^u \\ K^\nu \\ K^x \\ K^y \end{pmatrix} = \begin{pmatrix} 0 \\ c_1x + c_2y + c_3 \\ c_1 \int_0^u \frac{1}{a^2} dt + c_5 \\ c_2 \int_0^u \frac{1}{b^2} dt + c_7 \end{pmatrix}$$

could see there are 5 free parameters ,namely 5 five independent killing vector.

could see form the metric $K^u = 0$

guess evidence here:

$$\begin{cases} \partial_u K^\nu = 0 \\ -\partial_x K^\nu + a^2 \partial_u K^x = 0 \\ \partial_\nu K^x = 0 \\ \partial_x K^x = 0 \end{cases} \Rightarrow \partial_u (a^2 \partial_u K^x) = 0$$

$$\Rightarrow a^2 \partial_u K^x = C_1(y)$$

$$\Rightarrow K^x = C_1(y) \int_0^u \frac{1}{a^2(t)} dt + C_2(y)$$

similarly

$$K^y = C_3(x) \int_0^u \frac{1}{b^2(t)} dt + C_4(x)$$

16.

a.

$$\begin{aligned} ds^2 &= d^2\psi + \sin^2\psi d\theta^2 + \sin^2\psi \sin^2\theta d\phi^2 \\ &= d^2\psi + (\sin\psi d\theta)(\sin\psi d\theta) + (\sin\psi \sin\theta d\phi)(\sin\psi \sin\theta d\phi) \\ &= \hat{\theta}^1 \otimes \hat{\theta}^1 + \hat{\theta}^2 \otimes \hat{\theta}^2 + \hat{\theta}^3 \otimes \hat{\theta}^3 \end{aligned}$$

therefore

$$[e_a^\mu] = \begin{pmatrix} 1 & & \\ & \frac{1}{\sin\psi} & \\ & & \frac{1}{\sin\psi \sin\theta} \end{pmatrix}$$

$$[e_\mu^a] = \begin{pmatrix} 1 & & \\ & \sin\psi & \\ & & \sin\psi \sin\theta \end{pmatrix}$$

$$e^0 = d\psi \quad e^1 = \sin\psi d\theta \quad e^2 = \sin\psi \sin\theta d\phi$$

b.

$$\begin{aligned} de^0 &= 0 \\ de^1 &= \partial_\nu \sin\psi dx^\nu \wedge d\theta = \cos\psi d\psi \wedge d\theta \\ de^2 &= \partial_\nu \sin\psi \sin\theta dx^\nu \wedge d\phi = \cos\psi \sin\theta d\psi \wedge d\phi + \sin\psi \cos\theta d\theta \wedge d\phi \end{aligned}$$

$$\begin{aligned} w_b^0 \wedge e^b &= -de^0 \\ w_1^0 \wedge e^1 + w_2^0 \wedge e^2 &= 0 \\ w_1^0 \wedge \sin\psi d\theta + w_2^0 \wedge \sin\psi \sin\theta d\phi &= 0 \end{aligned}$$

$$\begin{aligned}\sin\psi w^0_1 \wedge d\theta + \sin\psi \sin\theta w^0_2 \wedge d\phi &= 0 \\ w^0_1 \wedge d\theta + \sin\theta w^0_2 \wedge d\phi &= 0\end{aligned}$$

$$\begin{aligned}w^1_b \wedge e^b &= -de^1 \\ w^1_0 \wedge e^0 + w^1_2 \wedge e^2 &= -(\cos\psi d\psi \wedge d\theta) \\ w^1_0 \wedge d\psi + w^1_2 \wedge \sin\psi \sin\theta d\phi &= -\cos\psi d\psi \wedge d\theta\end{aligned}$$

$$\begin{aligned}w^2_b \wedge e^b &= -de^2 \\ w^2_0 \wedge e^0 + w^2_1 \wedge e^1 &= -\cos\psi \sin\theta d\psi \wedge d\phi \\ w^2_0 \wedge d\psi + \sin\psi w^2_1 \wedge d\theta &= -\cos\psi \sin\theta d\psi \wedge d\phi - \sin\psi \cos\theta d\theta \wedge d\phi\end{aligned}$$

$$\begin{cases} w^0_1 = \alpha d\theta \\ w^0_2 = \beta d\phi \\ w^1_0 = \cos\psi d\theta \\ w^1_2 = \gamma d\phi \\ w^2_0 = \cos\psi \sin\theta d\phi \\ w^2_1 = \cos\theta d\phi \end{cases} \Rightarrow \begin{cases} w^0_1 = -\cos\psi d\theta \\ w^0_2 = -\cos\psi \sin\theta d\phi \\ w^1_2 = -\cos\theta d\phi \end{cases}$$

$$\begin{aligned}R^0_0 &= dw^0_0 + w^0_b \wedge w^b_0 = 0 \\ R^0_1 &= dw^0_1 + w^0_b \wedge w^b_1 \\ &= \sin\psi d\psi \wedge d\theta + w^0_2 \wedge w^2_1 \\ &= \sin\psi d\psi \wedge d\theta - \cos\psi \sin\theta \cos\theta d\phi \wedge d\phi \\ &= \sin\psi d\psi \wedge d\theta\end{aligned}$$

$$\begin{aligned}R^0_2 &= dw^0_2 + w^0_b \wedge w^b_2 \\ &= -\partial_\nu(\cos\psi \sin\theta) dx^\nu \wedge d\phi + w^0_1 \wedge w^1_2 \\ &= \sin\psi \sin\theta d\psi \wedge d\phi - \cos\psi \cos\theta d\theta \wedge d\phi + (-\cos\psi d\theta) \wedge (-\cos\theta d\phi) \\ &= \sin\psi \sin\theta d\psi \wedge d\phi\end{aligned}$$

$$\begin{aligned}R^1_1 &= 0 \\ R^1_2 &= dw^1_2 + w^1_b \wedge w^b_2 \\ &= -d\cos\theta \wedge d\phi + w^1_0 \wedge w^0_2 \\ &= \sin\theta d\theta \wedge d\phi + \cos\psi d\theta \wedge (-\cos\psi \sin\theta d\phi) \\ &= (\sin\theta - \cos^2\psi \sin\theta) d\theta \wedge d\phi \\ &= \sin\theta \sin^2\psi d\theta \wedge d\phi\end{aligned}$$

$$R^2_2 = 0$$

$$\begin{aligned}R^\sigma_\rho &= e^a R^b_a e_b \\ &= e_b R^b_a e^a \\ &= \begin{pmatrix} 1 & & \\ \frac{1}{\sin\psi} & & \\ & \frac{1}{\sin\psi \sin\theta} & \end{pmatrix} \begin{pmatrix} & R^0_1 & R^0_2 \\ -R^0_1 & & R^1_2 \\ -R^0_2 & -R^1_2 & \end{pmatrix} \begin{pmatrix} 1 & & \\ & \sin\psi & \\ & & \sin\psi \sin\theta \end{pmatrix} \\ &= \begin{pmatrix} 1 & & \\ \frac{1}{\sin\psi} & & \\ & \frac{1}{\sin\psi \sin\theta} & \end{pmatrix} \begin{pmatrix} & \sin\psi R^0_1 & \sin\psi \sin\theta R^0_2 \\ -R^0_1 & & \sin\psi \sin\theta R^1_2 \\ -R^0_2 & -\sin\psi R^1_2 & \end{pmatrix} \\ &= \begin{pmatrix} & \sin\psi R^0_1 & \sin\psi \sin\theta R^0_2 \\ -\frac{1}{\sin\psi} R^0_1 & & \frac{1}{\sin\psi} \times \sin\psi \sin\theta R^1_2 \\ -\frac{1}{\sin\psi \sin\theta} R^0_2 & -\frac{1}{\sin\psi \sin\theta} \times \sin\psi R^1_2 & \end{pmatrix}\end{aligned}$$

$$\begin{aligned}
&= \begin{pmatrix} \sin\psi R^0_1 & \sin\psi\sin\theta R^0_2 \\ -\frac{1}{\sin\psi}R^0_1 & \sin\theta R^1_2 \\ -\frac{1}{\sin\psi\sin\theta}R^0_2 & -\frac{1}{\sin\theta}R^1_2 \end{pmatrix} \\
&= \begin{pmatrix} \sin^2\psi d\psi \wedge d\theta & \sin^2\psi\sin^2\theta d\psi \wedge d\phi \\ -d\psi \wedge d\theta & \sin^2\psi\sin^2\theta d\theta \wedge d\phi \\ -d\psi \wedge d\phi & -\sin^2\psi d\theta \wedge d\phi \end{pmatrix}
\end{aligned}$$

$$\begin{aligned}
R^0_{101} &= \sin^2\psi & R^1_{001} &= -1 \\
R^0_{202} &= \sin^2\psi\sin^2\theta & R^2_{002} &= -1 \\
R^1_{212} &= \sin^2\psi\sin^2\theta & R^2_{112} &= -\sin^2\psi
\end{aligned}$$

$$\begin{aligned}
R_{00} &= R^1_{010} + R^2_{020} = 1 + 1 = 2 \\
R_{11} &= R^0_{101} + R^2_{121} = \sin^2\psi + \sin^2\psi = 2\sin^2\psi \\
R_{22} &= R^0_{202} + R^1_{212} = \sin^2\psi\sin^2\theta + \sin^2\psi\sin^2\theta = 2\sin^2\psi\sin^2\theta
\end{aligned}$$