

# Linear Systems- Lab 1

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## Case 4. Mass-Spring-Damper system with free base

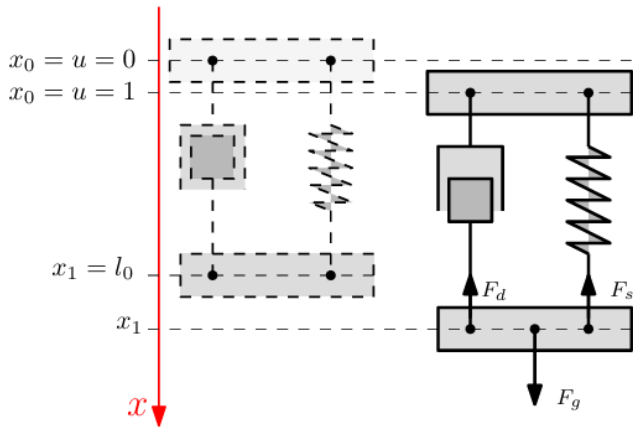


Figure 1: System scheme

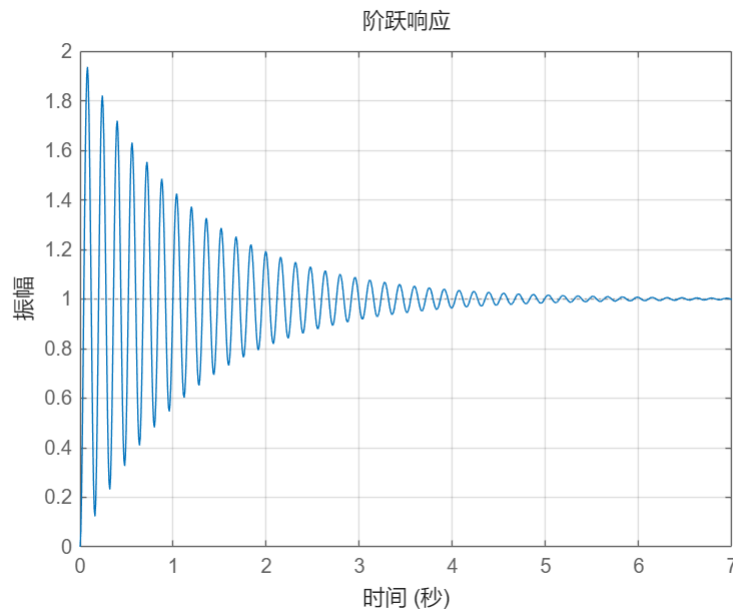
### System description:

- Block 0 position:  $x_0 = u$
- Gravity force:  $F_g = m_1 \cdot g$
- Damping force:  $F_d = K_d \cdot (\dot{x}_1 - \dot{x}_0)$
- Spring force:  $F_s = K_s \cdot (x_1 - x_0 - l_0)$

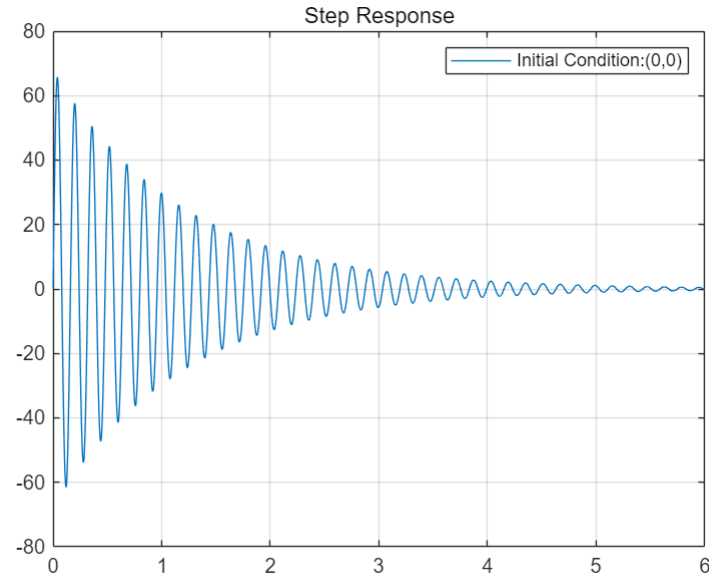
Connection established

## 0. Loading the initial data:

### 1. Transfer Function:



**2. Solve differential equation using zero initial conditions for  $u = 1$ .**



**3. Find the equilibrium point.**

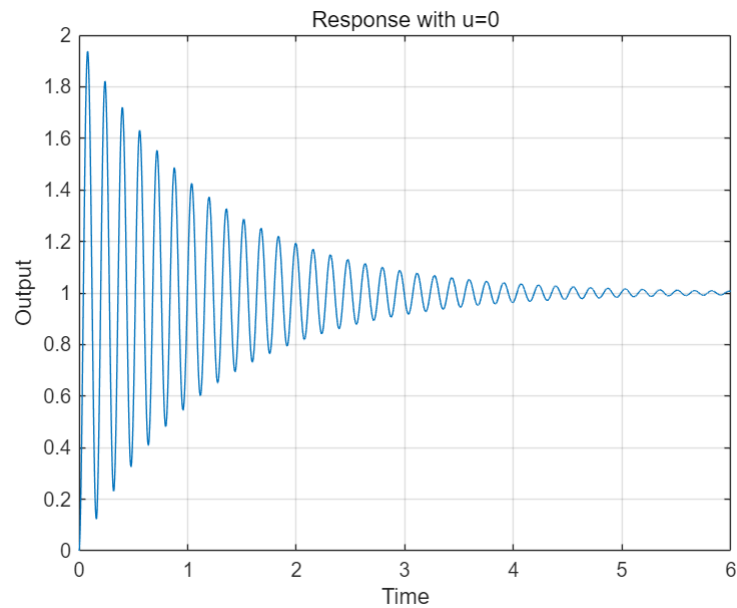
$$\begin{aligned} \frac{dx_1}{dt} &= x_2 = 0 \\ 1. \quad \frac{dx_2}{dt} &= -\frac{K_s}{m_1}x_1 - \frac{K_d}{m_1}x_2 + \frac{1}{m_1}u = 0 \\ 2. \quad u &= 0 \Rightarrow x_1 = x_2 = 0 \\ 3. \quad x &= \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, x^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

**4. Use change of state coordinates  $v = x - x^*$**

$$v = x - x^* = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

thus, it's the same with the step 3

**5. New differential equation zero with initial conditions for  $u = 1$**



## 6. Find transfer function of the system with equilibrium point $v^* = 0$

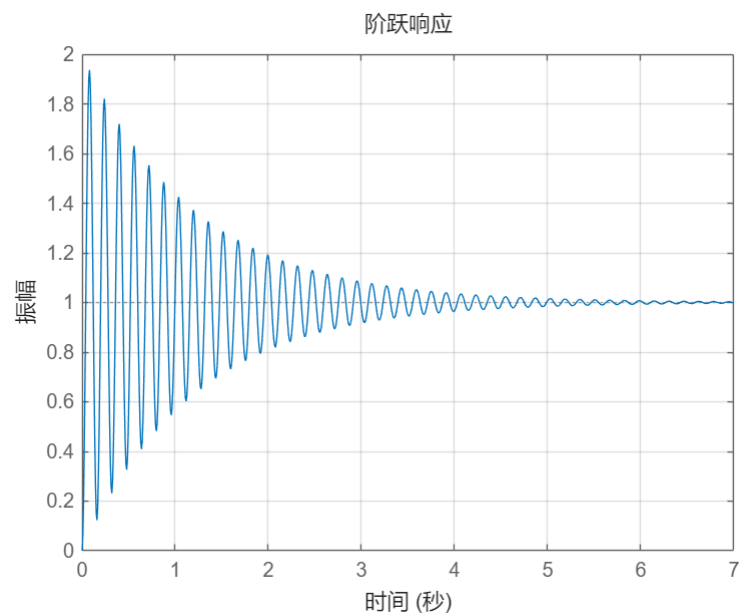
$$\frac{dx_1}{dt} = x_2 = 0$$

$$\frac{dx_2}{dt} = -\frac{K_s}{m_1}x_1 - \frac{K_d}{m_1}x_2 + \frac{1}{m_1}u = 0$$

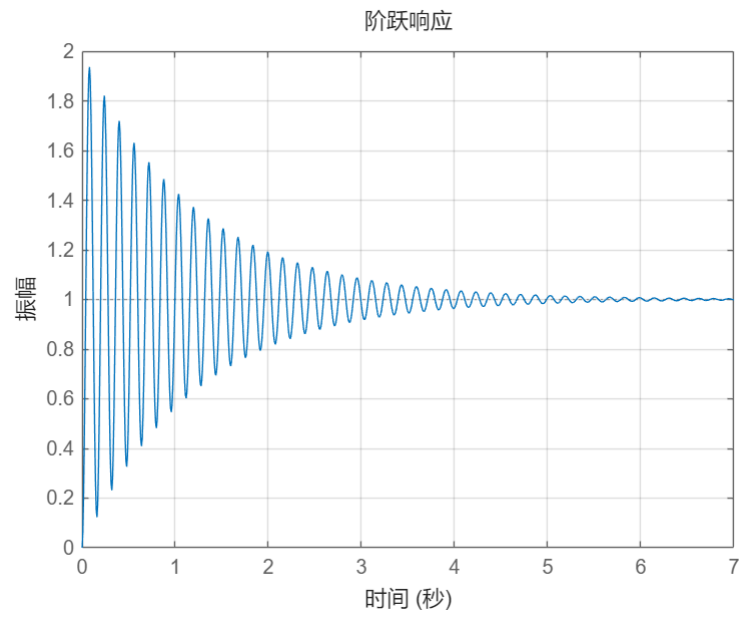
$$s \cdot x_1 = x_2$$

$$s \cdot x_2 = -\frac{K_s}{m_1}x_1 - \frac{K_d}{m_1}x_2 + \frac{1}{m_1}u$$

$$W(s) = \frac{X_1(s)}{U(s)} = \frac{K_d s + K_s}{m_1 s^2 + K_d s + K_s}$$

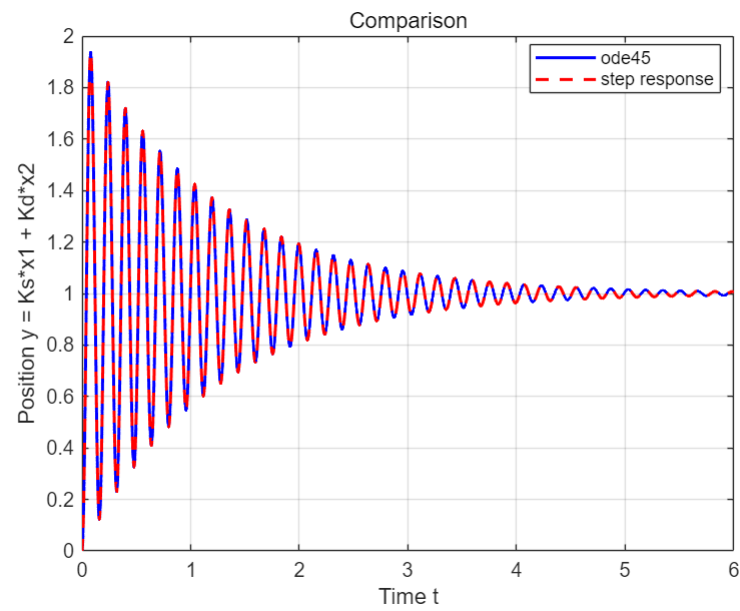


## 7. Construct state space model

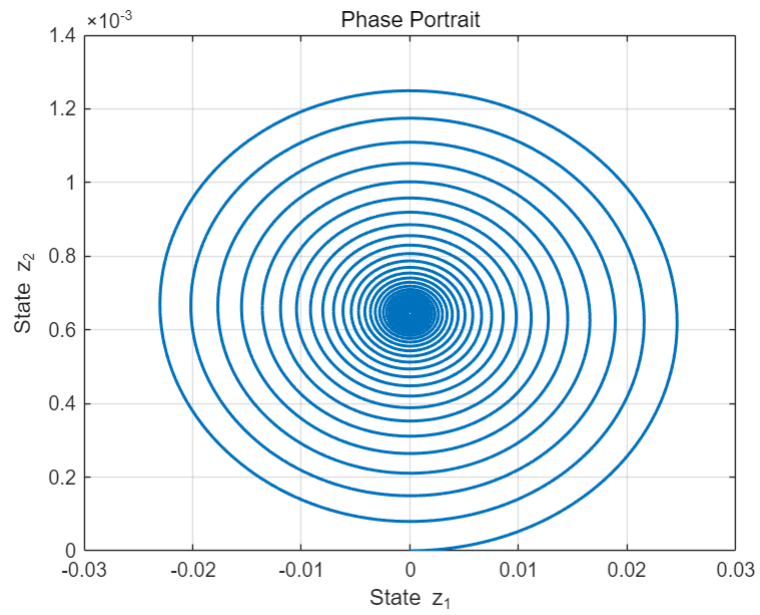


## 8. Plot the graphs

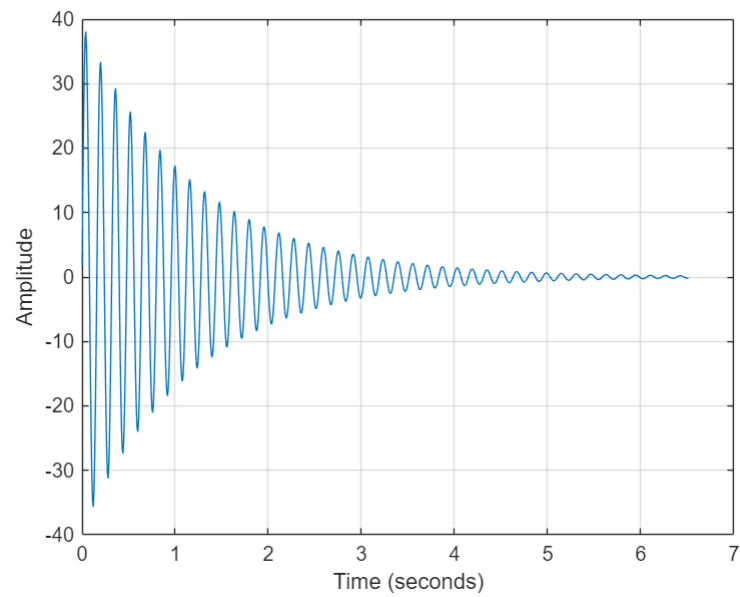
(a) Step response comparison & (b) Plot step response



(c) Plot phase portrait

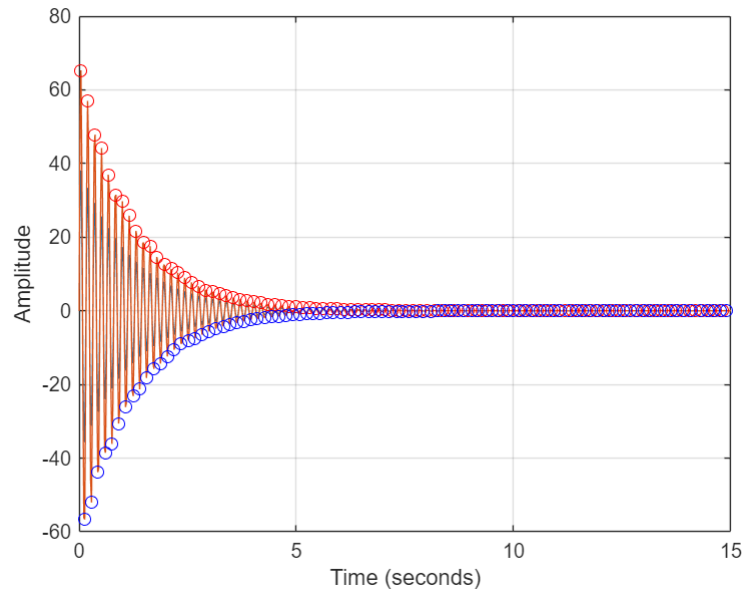


(d) Plot impulse response

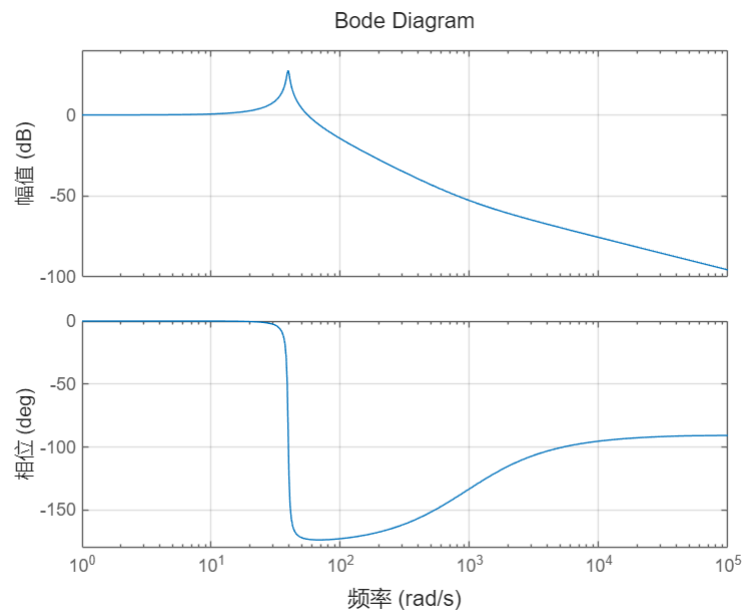


(e) For both models plot response

The amplitude of the output signal  $y(t)$  changed 188 times with respect to the input  $u(t)$  when system oscillations stabilized.



(f) Plot Magnitude and Phase data



## Answers

ans = 包含以下字段的 struct:

```

Bode_Plot_Peak_gain_of_resonance: 24
Bode_Plot_Phase_crossover_frequency: [0 58.8000]
Bode_Plot_Resonance_frequency: 39.4000
Impulse_Response_SettlingTime: 5
Step_Response_RiseTime: 0.0267
Bode_Plot_Gain_crossover_frequency: 0
Impulse_Response_MaxTime: 0.0399
Step_Response_Peak: 1.9363

```

ans =

包含以下字段的 [struct](#):

```

Bode_Plot_Peak_gain_of_resonance: 1
Bode_Plot_Phase_crossover_frequency: 1
Bode_Plot_Resonance_frequency: 1
Impulse_Response_SettlingTime: 1
Step_Response_RiseTime: 1
total_score: 5

```