

## ASSIGNMENT #5

**Please do not write your answers on a copy of this assignment.** As with all assignments, there will be conceptual and computational questions. For computational problems you may check your work using any tool you wish; however **you must clearly explain each step that you make in your computation.**

For this assignment I encourage you to work with others; however, you are expected to **submit your own work in your own words**. I will grade a subset of these problems and will take completion of the ungraded problems into account for the final grade of this assignment. Completion is worth 20% of the final grade of this assignment. To emphasize: **you must make an honest attempt on each problem for full points on the completion aspect of your grade.**

- (1) Answer each of the following questions. Also, the following parts are not related to one another.

(a) Let  $A = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$  and define  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Find the images of  $\mathbf{u} = \begin{bmatrix} 1 \\ -3 \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} a \\ b \end{bmatrix}$  under  $T$ .

(b) Let  $A = \begin{bmatrix} 1 & -2 & 1 \\ 3 & -4 & 5 \\ 0 & 1 & 1 \\ -3 & 5 & 4 \end{bmatrix}$  and  $\mathbf{b} = \begin{bmatrix} 1 \\ 9 \\ 3 \\ -6 \end{bmatrix}$ . Define  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Find a vector  $\mathbf{x}$  such that  $T(\mathbf{x}) = \mathbf{b}$ .

(c) Let  $A = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 7 & 1 & 1 & 2 \end{bmatrix}$ . Define  $T : \mathbb{R}^4 \rightarrow \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Find all vectors  $\mathbf{x} \in \mathbb{R}^4$  such that  $T(\mathbf{x}) = \mathbf{0}$ .

(d) Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a linear transformation that maps  $\mathbf{u} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$  to  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  to  $\begin{bmatrix} 1 \\ -3 \end{bmatrix}$ . Using what it means for  $T$  to be a linear transformation, find  $T(3\mathbf{u})$ ,  $T(2\mathbf{v})$ , and  $T(3\mathbf{u} + 2\mathbf{v})$ .

- (2) Assume  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a linear transformation. For each situation below find a matrix that represents  $T$ .

(a)  $T$  rotates points about the origin by  $\frac{-\pi}{4}$  radians

(b)  $T$  is a vertical shear that maps  $\mathbf{e}_1$  to  $3\mathbf{e}_1 + 2\mathbf{e}_2$  but leaves  $\mathbf{e}_2$  unchanged (i.e.  $T(\mathbf{e}_2) = \mathbf{e}_2$ ). Recall that  $\mathbf{e}_1 = (1, 0)$  and  $\mathbf{e}_2 = (0, 1)$

(c)  $T$  first reflects points through the vertical  $x_2$  axis and then rotates points by  $\frac{3}{2\pi}$  radians about the origin. *Hint:* You might consider each transformation one at a time, and then multiply the matrices you find.

- (3) For each of the matrices below with \*'s for entries, fill in the \*'s with numbers that make each a true statement.

$$(a) \begin{bmatrix} * & * & * \\ * & * & * \\ * & * & * \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_1 - 3x_3 \\ 4x_1 \\ x_1 - x_2 + x_3 \end{bmatrix}.$$

$$(b) \begin{bmatrix} * & * \\ * & * \\ * & * \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 - 3x_2 \\ x_1 \\ 7x_2 \end{bmatrix}.$$

(c) Find a matrix that realizes the linear transformation  $T : \mathbb{R}^4 \rightarrow \mathbb{R}^2$ , where

$$T(x_1, x_2, x_3, x_4) = (2x_1 + x_3, x_2 - x_4).$$

*Hint:* What you did for parts (a) and (b) may be helpful here.

$$(4) \text{ Let } A_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, A_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \text{ and } \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}.$$

(a) Find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_1$ . In other words, find all  $\mathbf{x} \in \mathbb{R}^3$  such that  $A_1\mathbf{x} = \mathbf{x}$

(b) Find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_2$ . In other words, find all  $\mathbf{x} \in \mathbb{R}^3$  such that  $A_2\mathbf{x} = \mathbf{x}$

(c) Find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_3$ . In other words, find all  $\mathbf{x} \in \mathbb{R}^3$  such that  $A_3\mathbf{x} = \mathbf{x}$

(d) Use parts (a) through (c) to find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_1, A_2, A_3$ .

(e) Congratulate yourself! You have done a little bit of representation theory! These matrices generate the group of permutations of a three element set. This exercise is part of the steps you would take to find all irreducible representations of this permutation group (whatever that means).

$$(5) \text{ Suppose that } T : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ is a linear transformation such that } T(\mathbf{e}_1) = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, T(\mathbf{e}_2) = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \text{ and}$$

$$T(\mathbf{e}_3) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}. \text{ Answer the following questions.}$$

(a) Find a matrix  $A$  that represents  $T$ . In other words, find a matrix  $A$  such that  $T(\mathbf{x}) = A\mathbf{x}$  for all  $\mathbf{x} \in \mathbb{R}^3$ .

(b) Describe the set of vectors,  $\mathbf{x}$ , that satisfy  $A\mathbf{x} = 0$  in vector parametric notation.

(c) Does  $A$  have an inverse? If so, what is it?

(d) Is  $T$  an isomorphism? Why or why not?

- (6) Answer the following as true or false. No justification is needed.
- (a) Every matrix determines a linear transformation.
  - (b) Every linear transformation is determined by a matrix.
  - (c) There is a linear transformation  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  that is surjective.
  - (d) There is a linear transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  that is injective.
  - (e) If  $T : \mathbb{R}^m \rightarrow \mathbb{R}^n$  and  $S : \mathbb{R}^p \rightarrow \mathbb{R}^m$  are linear transformations, then  $T \circ S : \mathbb{R}^p \rightarrow \mathbb{R}^n$  is a linear transformation.
  - (f) If  $T$  is a linear transformation given by a  $n \times m$  matrix, then its codomain is  $\mathbb{R}^n$ .