## ASSIGNMENT #5

Please do not write your answers on a copy of this assignment. As with all assignments, there will conceptual and computational questions. For computational problems you may check your work using any tool you wish; however you must clearly explain each step that you make in your computation.

For this assignment I encourage you to work with others; however, you are expected to **submit your own work in your own words**. All questions except the true and false will be graded for completion. **If you would like feedback on a problem, please indicate it somehow.** You must make an honest attempt on each problem for full points on the completion aspect of your grade.

- (1) Answer each of the following questions. Also, the following parts are not related to one another.
  - (a) Let  $A = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$  and define  $T : \mathbb{R}^2 \to \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Find the images of  $\mathbf{u} = \begin{bmatrix} 1 \\ -3 \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} a \\ b \end{bmatrix}$  under T.
  - (b) Let  $A = \begin{bmatrix} 1 & -2 & 1 \\ 3 & -4 & 5 \\ 0 & 1 & 1 \\ -3 & 5 & 4 \end{bmatrix}$  and  $\mathbf{b} = \begin{bmatrix} 1 \\ 9 \\ 3 \\ -6 \end{bmatrix}$ . Define  $T : \mathbb{R}^3 \to \mathbb{R}^4$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Find a vector  $\mathbf{x}$  such that  $T(\mathbf{x}) = \mathbf{b}$ .
  - (c) Let  $A = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 7 & 1 & 1 & 2 \end{bmatrix}$ . Define  $T : \mathbb{R}^4 \to \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Find all vectors  $\mathbf{x} \in \mathbb{R}^4$  such that  $T(\mathbf{x}) = 0$ .
  - (d) Let  $T: \mathbb{R}^2 \to \mathbb{R}^2$  be a linear transformation that maps  $\mathbf{u} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$  to  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  to  $\begin{bmatrix} 1 \\ -3 \end{bmatrix}$ . Using what it means for T to be a linear transformation, find  $T(3\mathbf{u})$ ,  $T(2\mathbf{v})$ , and  $T(3\mathbf{u} + 2\mathbf{v})$ .
- (2) Assume  $T: \mathbb{R}^2 \to \mathbb{R}^2$  is a linear transformation. For each situation below find a matrix that represents T.
  - (a) T rotates points about the origin by  $\frac{-\pi}{4}$  radians
  - (b) T is a vertical shear that maps  $\mathbf{e}_1$  to  $3\mathbf{e}_1 + 2\mathbf{e}_2$  but leaves  $\mathbf{e}_2$  unchanged (i.e  $T(\mathbf{e}_2) = \mathbf{e}_2$ ). Recall that  $\mathbf{e}_1 = (1,0)$  and  $\mathbf{e}_2 = (0,1)$
  - (c) T first reflects points through the vertical  $x_2$  axis and then rotates points by  $\frac{3}{2\pi}$  radians about the origin. *Hint*: You might consider each transformation one at a time, and then multiply the matrices you find.
- (3) For each of the matrices below with \*'s for entries, fill in the \*'s with numbers that make each a true statement.

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(a) 
$$\begin{bmatrix} * & * & * \\ * & * & * \\ * & * & * \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_1 - 3x_3 \\ 4x_1 \\ x_1 - x_2 + x_3 \end{bmatrix} .$$

(b) 
$$\begin{bmatrix} * & * \\ * & * \\ * & * \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 - 3x_2 \\ x_1 \\ 7x_2 \end{bmatrix} .$$

(c) Find a matrix that realizes the linear tranformation  $T: \mathbb{R}^4 \to \mathbb{R}^2$ , where

$$T(x_1, x_2, x_3, x_4) = (2x_1 + x_3, x_2 - x_4).$$

Hint: What you did for parts (a) and (b) may be helpful here.

(4) Let 
$$A_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
,  $A_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$ , and  $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$ .

- (a) Find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_1$ . In other words, find all  $\mathbf{x} \in \mathbb{R}^3$  such that  $A_1\mathbf{x} = \mathbf{x}$
- (b) Find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_2$ . In other words, find all  $\mathbf{x} \in \mathbb{R}^3$  such that  $A_2\mathbf{x} = \mathbf{x}$
- (c) Find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_3$ . In other words, find all  $\mathbf{x} \in \mathbb{R}^3$  such that  $A_3\mathbf{x} = \mathbf{x}$
- (d) Use parts (a) through (c) to find all vectors in  $\mathbb{R}^3$  that are fixed by  $A_1$ ,  $A_2$ ,  $A_3$ .
- (e) Congratulate yourself! You have done a little bit of representation theory! These matrices generate the group of permutations of a three element set. This exercise is part of the steps you would take to find all irreducible representations of this permutation group (whatever that means).
- (5) Suppose that  $T: \mathbb{R}^3 \to \mathbb{R}^3$  is a linear transformation such that  $T(\mathbf{e}_1) = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ ,  $T(\mathbf{e}_2) = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ , and

$$T(\mathbf{e}_3) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$
. Answer the following questions.

- (a) Find a matrix A that represents T. In other words, find a matrix A such that  $T(\mathbf{x}) = A\mathbf{x}$  for all  $\mathbf{x} \in \mathbb{R}^3$ .
- (b) Describe the set of vectors,  $\mathbf{x}$ , that satisfy  $\mathbb{A}\mathbf{x} = 0$  in vector parametric notation.
- (c) Does A have an inverse? If so, what is it?
- (d) Is T an isomorphism? Why or why not?

- (6) Answer the following as true or false. No justification is needed.
  - (a) Every matrix determines a linear transformation.
  - (b) Every linear transformation is determined by a matrix.
  - (c) There is a linear transformation  $T: \mathbb{R}^2 \to \mathbb{R}^3$  that is surjective.
  - (d) There is a linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^2$  that is injective.
  - (e) If  $T: \mathbb{R}^m \to \mathbb{R}^n$  and  $S: \mathbb{R}^p \to \mathbb{R}^m$  are linear transformations, then  $T \circ S: \mathbb{R}^p \to \mathbb{R}^n$  is a linear transformation.
  - (f) If T is a linear transformation given by a  $n \times m$  matrix, then its codomain is  $\mathbb{R}^n$ .