

Object::getMatrix

Object::updateRotationMatrixY

translateMatrix

```
graph LR; A[Object::getMatrix] --> C[translateMatrix]; B[Object::updateRotationMatrixY] --> C;
```

The diagram illustrates a dependency or mapping relationship. Two source methods, 'Object::getMatrix' and 'Object::updateRotationMatrixY', are shown in white boxes on the left. Two blue arrows originate from the right side of these boxes and point towards a single target method, 'translateMatrix', which is shown in a gray box on the right.