Front View





Speed:

26.79 km/h



Navigation:

Go straight on the current road

Reasoning under \mathcal{M}_{tool}

The vehicle is approaching a bus on the right side of the road.

The bus appears to be stationary or moving very slowly. There are no immediate obstacles in the lane ahead.

Reasoning Given the proximity of the bus and the moderate speed, it's necessary to decelerate to ensure safety. I need to confirm again if there are any immediate hazards on the road ahead.





{"view_index": "front", "object_text": "bus"}

The 3D object detection confirms the presence of a bus. At the same time, some pedestrians are detected in the immediate path. This supports

maintaining a straight trajectory while decelerating.

The initial action should be to decelerate and continue straight. Once it's confirmed that there are no immediate hazards, keep the current speed.



