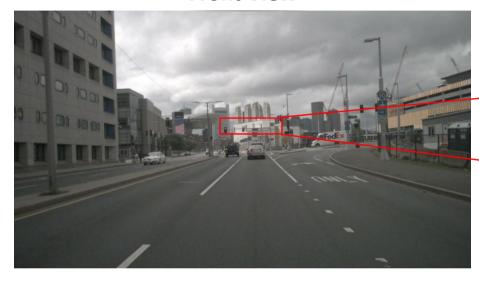
Front View





Speed:

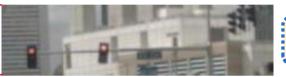


Navigation:

Continue straight

Reasoning under \mathcal{M}_{tool}

Description The scene shows an urban intersection with multiple lanes and traffic signals. Several vehicles are visible ahead, including a car directly in front of us. I need to use 'Rol Inspection' to check the traffic light status.





{"view_index": "front", "bbox": [300, 150, 400, 175], "description": "the traffic light at the intersection"}

The Rol Inspection image shows that the traffic light is red or yellow, indicating a need to stop.

Given the red or yellow traffic light and the presence of Reasoning vehicles ahead, it's logical to decelerate and prepare to stop. As we approach closer, further deceleration will be necessary until we come to a complete stop.

Prediction Based on the observed conditions and traffic signals, the appropriate actions are to decelerate and then stop. This sequence ensures safety and adherence to traffic rules.

