Front View

⏱ **Speed:**
5.20 km/h

📍 **Navigation：**
Continue straightafter passing the barrier gate

Reasoning under $\mathcal{M}_{tool}$

Description The vehicle is approaching a barrier gate at the intersection. There are traffic cones on the left side, indicating a controlled entry point.

Reasoning Given the low speed and the presence of traffic cones, it's necessary to decelerate initially to ensure safety as the vehicle approaches the barrier gate. Once safely past the gate, maintaining a steady speed while continuing straight aligns with the navigation command.

🚗 {"view_index": "front"}

The depth map shows that the barrier gate and traffic cones are relatively close, reinforcing the need to decelerate initially. The road ahead appears clear after the gate.

Prediction The vehicle should decelerate initially, once past the gate, maintain a steady speed and continue straight.

["Decelerate, Straight", "Decelerate, Straight", "Keep Speed, Straight", "Accelerate, Straight"] ✅