## **Front View**





## Speed:

3.07 km/h

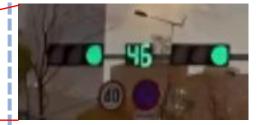


## Navigation:

Turn right at the current intersection

## Reasoning under $\mathcal{M}_{tool}$

Description The scene shows an intersection with multiple vehicles and pedestrians. There are motorcyclists and cars nearby, requiring careful navigation. I need check the traffic light status.





{"view\_index": "front", "bbox": [80, 140, 120, 160], "description": "the traffic light at the intersection"}

The traffic light is green and there are 46 seconds left, which means I need to wait cautiously for pedestrians to cross. I will check front-right next.





{"frame\_index": "current", "view\_index": "front\_right"}

The front-right view captures motorcyclists and pedestrians crossing the intersection, indicating a busy area.

Reasoning Given that the current speed is low and road condition is busy, stopping is necessary before proceeding with the turn. After ensuring that there are no pedestrians in front of the vehicle, accelerating with a right turn aligns with the navigation command.

Prediction The initial actions involve stopping and assessing the environment. After ensuring safety, accelerating with a right turn.

