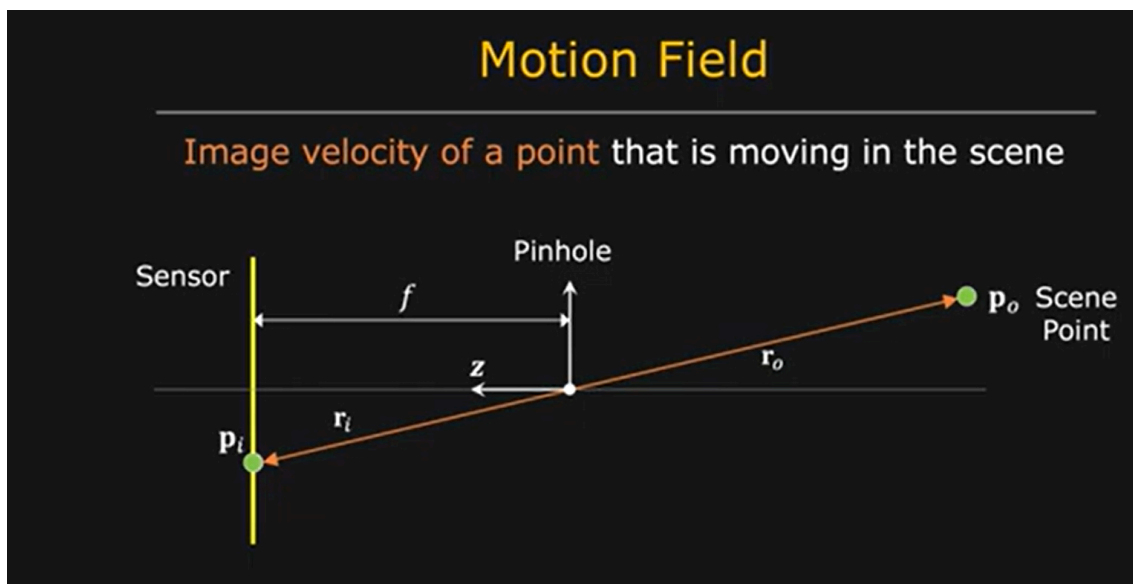


Motion Fields and Optical Flow

Motion Fields



p_o is a point in the 3d scene and it's location is given by the vector r_o . p_o projects onto the point p_i via perspective projection and it's location on the image plane is described by the vector r_i .

If p_o has some velocity in the 3d world, say v_o , then it's displacement is given by $v_o * dt$. So it's new location is $r_o + \Delta r_o$.

Also by definition, scene velocity v_o is the rate of change of r_o , so

$$\text{Scene Point Velocity: } v_o = \frac{dr_o}{dt}$$

What we are interested in is the Image point velocity:

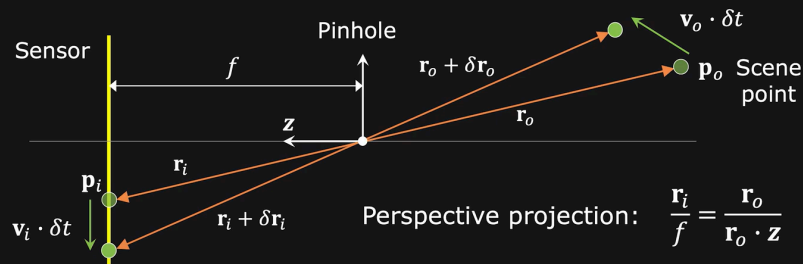
$$\text{Image Point Velocity: } v_i = \frac{dr_i}{dt}$$

(Motion Field)

We know v_o but we don't know v_i . So try to relate these to each other using perspective projection. Then simply take derivatives (using quotient rule) and then use cross product and get the answer.

Motion Field

Image velocity of a point that is moving in the scene



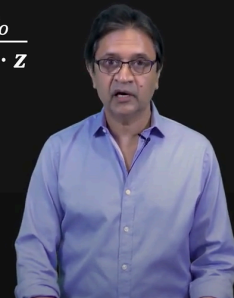
$$\frac{r_i}{f} = \frac{r_o}{r_o \cdot z}$$

Image Point Velocity: $\mathbf{v}_i = \frac{d\mathbf{r}_i}{dt} = f \frac{(\mathbf{r}_o \cdot \mathbf{z})\mathbf{v}_o - (\mathbf{v}_o \cdot \mathbf{z})\mathbf{r}_o}{(\mathbf{r}_o \cdot \mathbf{z})^2}$
(Motion Field)

$$\mathbf{v}_i = f \frac{(\mathbf{r}_o \times \mathbf{v}_o) \times \mathbf{z}}{(\mathbf{r}_o \cdot \mathbf{z})^2}$$

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[Horn 1981]



This \mathbf{v}_i is the motion field corresponding to the moving point in the 3D scene.

This is what we hope to measure, but there is no guarantee that we can measure this.

Optical Flow

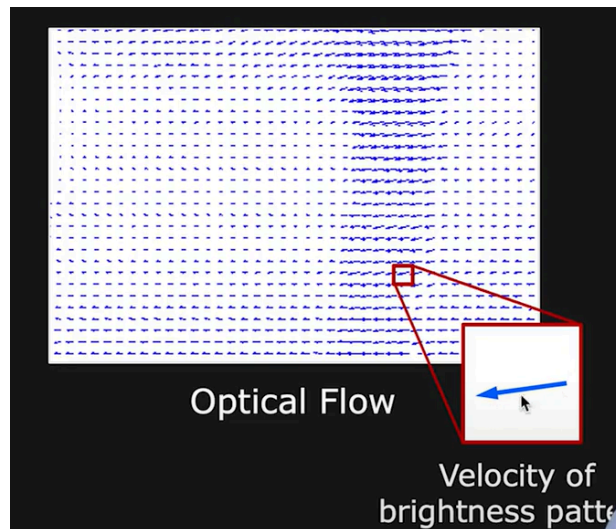
Instead, what we hope to measure is the motion of brightness patterns in the image.



(Here, if you take each point in the first frame and try to figure out where the point landed in the second image, that would be the motion field)

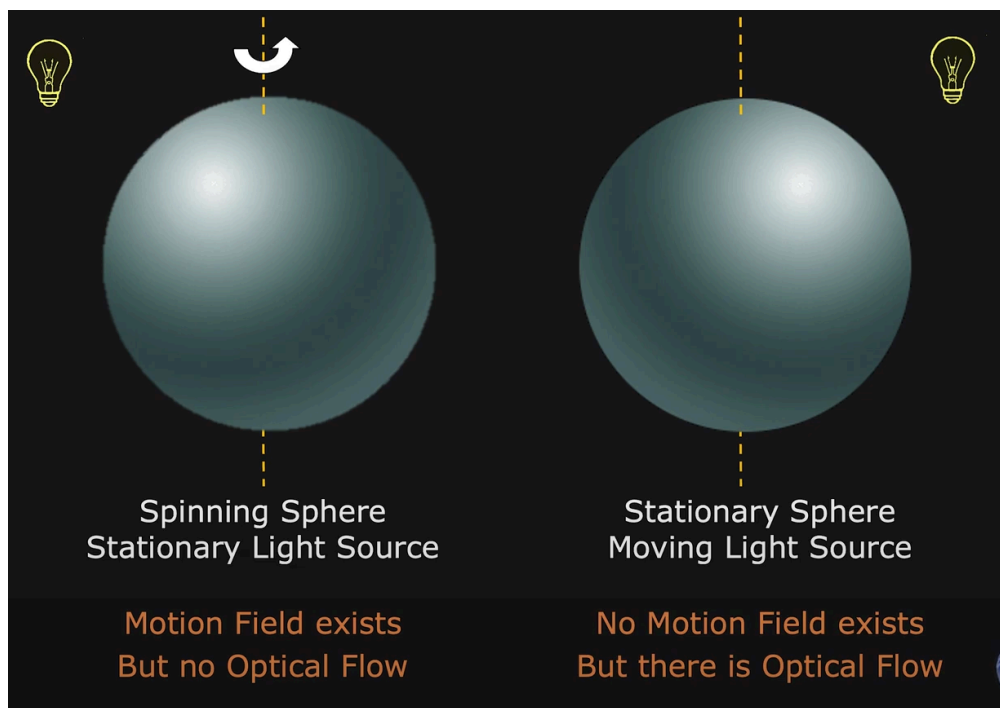
But what we can do is take a brightness pattern in one image and figure out where the brightness pattern is in the second image.

And if you have a successful algorithm that can do that, we can get a result that looks like this:



At each pixel, you have a vector that tells you what the optical flow at the point is. So, the motion of brightness patterns is the optical flow. And the optical flow vector's length tells you how fast its moving and direction tells you direction it's moving in the IMAGE PLANE.

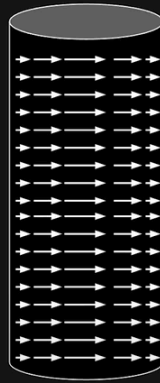
Ideally Optical Flow = Motion Field. Unfortunately, not most of the time.



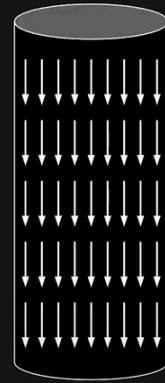
Another case where motion field and optical flow exists, but not the same



Barber Pole
Illusion



Motion Field



Optical Flow