This script presents an example of how to use python signal processing toolbox to calculate the inverse Z-transform of a discrete time signal by using power series expansion method. The code executes a long division (or polynomial division) algorithm to calculate the power series.

In this example, the same expression as the previous example is given:

$$X(z) = rac{1}{(1 - rac{1}{4}z^{-1})(1 - rac{1}{2}z^{-1})}, |z| > 0.5$$

and we will calculate its inverse Z-transform by power series expansion

This result is interpreted as follows: the output of the dimpulse function is an array of coefficients, starting with the constant term:

$$X(z) = x[0] + x[1]z^{-1} + x[2]z^{-2} + \dots$$

then the inverse transform of a polynomial series is

# import the necessary libraries

$$x[n] = [x[0], x[1], x[2], \dots]$$

Observe that;

In [ ]:

- The first argument of the dimpulse function is the system coeffs (with a constant 1) as a tuple which means it must be passed in parantheses ().
- The second argument x0 is initial state (usually zero)
- ullet The third argument k is the number of points we want to calculate the inverse transform. The outputs;
- n is the sample index vector from 0 to 10 for this example
- x is the inverse transform as an n-dimensional array, so we use the  $np.\ squeeze()$  function to reduce the redundant dimensions.

Note: if we do not reduce the dimensions of the output, the plotting function throws error.

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In [ ]: plt.stem(n, np.squeeze(x))
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