

## CS512 Assignment 3: Report

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### Abstract

Corner detection by implementing Harris Corner Detection algorithm with non-maximum suppression and thresholding is carried out in this project.

### Problem statement

- Harris Corner Detection algorithm implementation without using directly open cv method to detect corners
- Identification of proper corners by application of thresholding and non-maximum suppression

### Proposed solution

- Harris corner detection algorithm is done by taking into consideration the following equation

Handwritten equation for Harris corner detection on a chalkboard:

$$C(G) = \det(G) - k \operatorname{tr}^2(G)$$

Annotations:

- $C(G)$  is labeled "Corner measure".
- $G$  is labeled "Correlation matrix".
- $\det(G)$  is labeled "determinant".
- $\operatorname{tr}^2(G)$  is labeled "trace squared".
- $k$  is labeled "constant" and  $k \in [0, 0.5]$ .
- $\lambda_1, \lambda_2$  are labeled "eigenvalues".
- $k(\lambda_1 + \lambda_2)^2$  is written above the equation.

- Step over the whole image using a window defined by a scalar value
- Compute correlation matrix in the window by utilizing the following equation

Handwritten equation for computing the correlation matrix:

$$\sum p_i p_i^T = \sum \begin{bmatrix} x_i \\ y_i \end{bmatrix} \cdot \begin{bmatrix} x_i & y_i \end{bmatrix} = \begin{bmatrix} \sum x_i^2 & \sum x_i y_i \\ \sum y_i x_i & \sum y_i^2 \end{bmatrix}$$

- Utilize the corners measure to compute the possibility of a corner in the window using the Harris corner detection equation

- Apply thresholding
  - If the cornerness measure is lesser than a particular threshold value discard the corner
- Non maximum suppression is applied on corner list
  - Sort the corner list in descending order
  - Considering the corners one by one delete those corners which are in the vicinity having lesser cornerness measure
  - Perform the above until certain amount of corners are discovered
- Identify the discovered corners on the original image by highlighting it

## **Current Implementation**

- Implements Harris Corner Detection Algorithm
- Thresholding and Non-Maximum suppression is carried out
- Identification of corners by highlighting them on the original image

## **Future Enhancements**

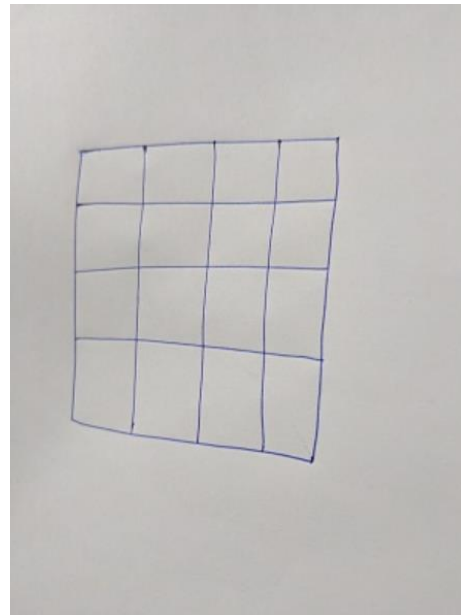
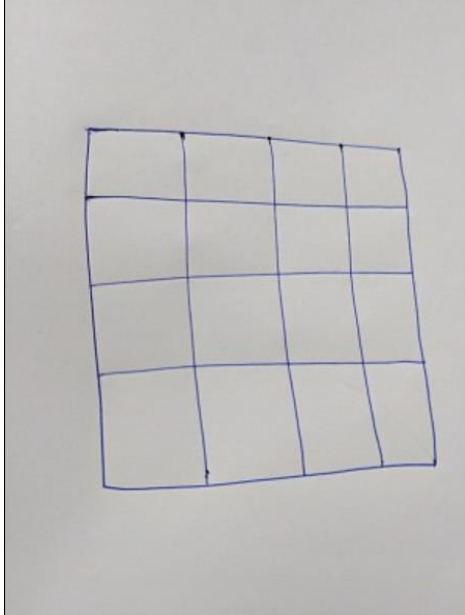
- Perform localization on the corners to improve the corner accuracy
- Compute feature vectors for each corners
- Perform stereo matching on images taken from different viewing angles
- Reduction of corner detection sensitivity to noise by utilizing better smoothing method
- Utilization of cython to improve the speed of execution

## Usage Information

Script name – test.py

Package requirements – cv2, numpy

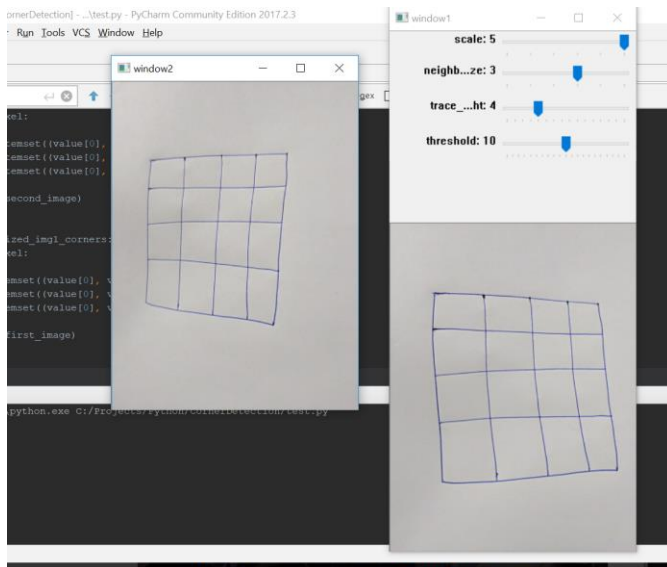
Images being considered – “11.jpg” and “12.jpg”



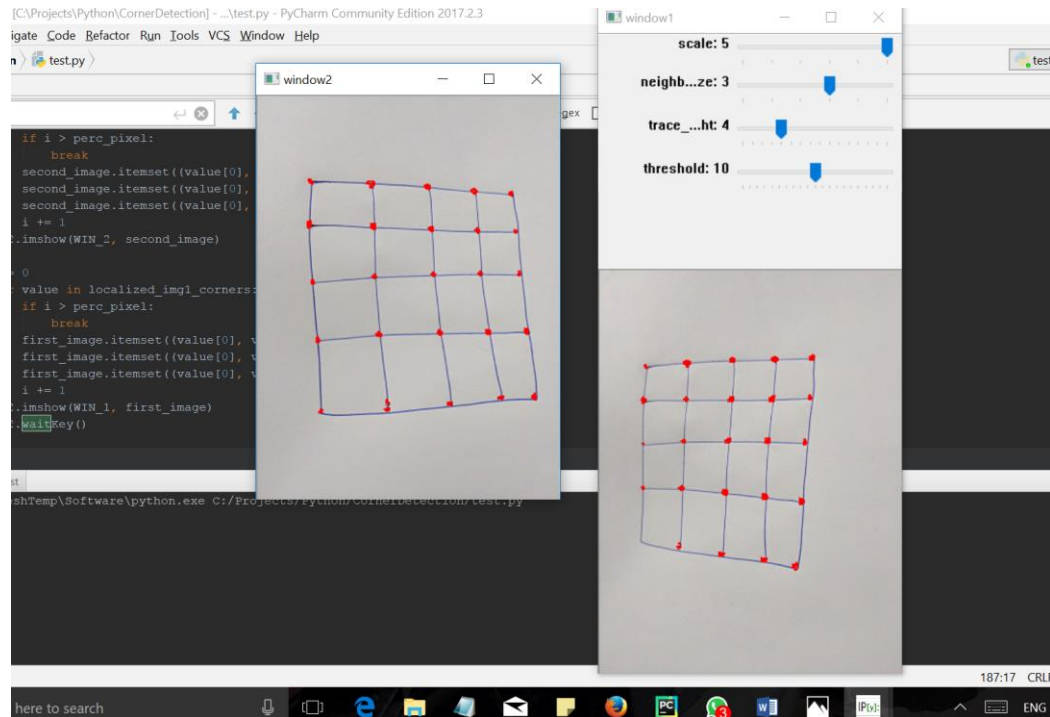
Run command – python test.py

## Results and discussion

- On startup of the script  
Original images are displayed



- Enter any letter, corner detection will be performed and resulting corners are displayed on the same windows



## References

- <https://docs.python.org/3/tutorial/>
- <https://docs.opencv.org/3.1.0/index.html>