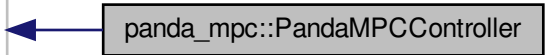


```
controller_interface  
::MultiInterfaceController  
< franka_hw::FrankaModelInterface,  
  hardware_interface::VelocityJointInterface,  
  hardware_interface::EffortJointInterface,  
  franka_hw::FrankaStateInterface >
```



```
graph LR; A[panda_mpc::PandaMPCController] --> B[controller_interface::MultiInterfaceController];
```

panda_mpc::PandaMPCController