

```
controller_interface  
::MultiInterfaceController  
< franka_hw::FrankaModelInterface,  
  hardware_interface::PositionJointInterface,  
  hardware_interface::VelocityJointInterface,  
  hardware_interface::EffortJointInterface,  
  franka_hw::FrankaStateInterface >
```



```
graph RL; panda_mpc::PandaMPCController --> controller_interface
```

panda\_mpc::PandaMPCController