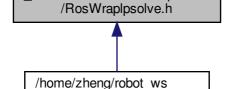
/home/zheng/robot_ws
_zheng/src/ros_wrap_safe
_motion/include/RosWrapsolver
/RosWraplpsolve.h



_zheng/src/ros_wrap_safe _motion/src/RosWrapsolver _/RosWraplpsolve.cpp