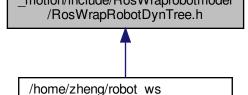
/home/zheng/robot\_ws
\_zheng/src/ros\_wrap\_safe
\_motion/include/RosWraprobotmodel
/RosWrapRobotDynTree.h



\_zheng/src/ros\_wrap\_safe \_motion/src/RosWraprobotmodel \_/RosWrapRobotDynTree.cpp