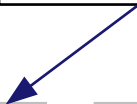


/home/zheng/robot_ws
_zheng/src/ros_wrap_safe
_motion/include/RosWrapconstraint
/RosWrapJointPosCst.h



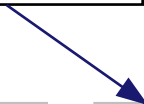
RosWrapconstraint/RosWrap
GenericCst.h



iostream



Eigen/Dense



Eigen/Core