

SHIFANG ZHAO

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<https://zzsf11.github.io/>

EDUCATION

Master | *Information and Communication Engineering*

Beijing Jiaotong University

Supervised by Prof. **Yunchao Wei**

Sep. 2023 – Now

Beijing, China

Bachelor | *Automation Engineering* | **GPA:3.74/4**

Beijing University of Technology

Sep. 2019 – Jul. 2023

Beijing, China

Relevant Coursework: Signal and system, Digital Signal Processing, Data Structures and Algorithms, Control Theory

PUBULICATION

OmniAD: Detect and Understand Industrial Anomaly via Multimodal Reasoning (Under review)

S. Zhao, Y. Lin, L. Han, Y. Zhao, Y. Wei

NeurIPS

AlignGen: Boosting Personalized Image Generation with Cross-Modality Prior Alignment (Under review)

Y. Lin*, **S. Zhao***, T. Liu, X. Qu, L. Liu, Y. Zhao, Y. Wei

ACM International Conference on Multimedia

WIDE: Make Railway Surveillance Anomaly Detection Right (Under revision)

S. Zhao, C. Ma, S. Su, X. Meng, Y. Zhao, Y. Wei

IEEE Trans. Intell. Transp. Syst.

Rethinking Data Imbalance in Class Incremental Surgical Instrument Segmentation

S. Zhao, L. Bai, K. Yuan, F. Li, J. Yu, W. Dong, G. Wang, M. Islam, N. Padoy, N. Navab, H. Ren

Medical Image Analysis

PROJECTS AND RESEARCH

Automatic Ping-Pong Ball Collection Robot Design

Aug. 2021 - Aug. 2022

Beijing University of Technology

- Led the development of an autonomous ping-pong ball collection robot, incorporating advanced target detection, path planning, and an innovative collection system using brushless motors and friction wheels.
- Designed and implemented a detection algorithm combining masking, Canny edge, and Hough circle techniques for rapid ball localization and efficient retrieval.

INTERN EXPERIENCE

Research Intern on Medical Image Analysis

Chinese University of Hong Kong

Fall 2024

Remote

HONORS AND AWARDS

The First Prize Scholarship

Recognition for to 10% of students in academics at Beijing University of Technology

2020 | 2021 | 2023

24th China Robot and Artificial Intelligence Competition National First Prize

Project: Automatic Ping-Pong Ball Collection Robot Design

Aug. 2022

SKILLS

Languages: English (CET6), Japanese (N2)

Programming: Python(Torch, CV2), C(STM32, ROS)