

# SHIFANG ZHAO

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## EDUCATION

<b>Master</b>   <i>Information and Communication Engineering</i> Beijing Jiaotong University Supervised by Prof. <b>Yunchao Wei</b>	Sep. 2023 – Now Beijing, China
<b>Bachelor</b>   <i>Automation Engineering</i>   <b>GPA:3.74/4</b> Beijing University of Technology Relevant Coursework: Signal and system, Digital Signal Processing, Data Structures and Algorithms, Control Theory	Sep. 2019 – Jul. 2023 Beijing, China

## PUBULICATION

<b>OmniAD: Detect and Understand Industrial Anomaly via Multimodal Reasoning (Under review)</b> <b>S. Zhao</b> , Y. Lin, L. Han, Y. Zhao, Y. Wei <i>NeurIPS</i>	
<b>AlignGen: Boosting Personalized Image Generation with Cross-Modality Prior Alignment (Under review)</b> Y. Lin*, <b>S. Zhao*</b> , T. Liu, X. Qu, L. Liu, Y. Zhao, Y. Wei <i>ACM International Conference on Multimedia</i>	
<b>WIDE: Make Railway Surveillance Anomaly Detection Right (Under revision)</b> <b>S. Zhao</b> , C. Ma, S. Su, X. Meng, Y. Zhao, Y. Wei <i>IEEE Trans. Intell. Transp. Syst.</i>	
<b>Rethinking Data Imbalance in Class Incremental Surgical Instrument Segmentation</b> <b>S. Zhao</b> , L. Bai, K. Yuan, F. Li, J. Yu, W. Dong, G. Wang, M. Islam, N. Padoy, N. Navab, H. Ren <i>Medical Image Analysis</i>	

## PROJECTS AND RESEARCH

<b>Automatic Ping-Pong Ball Collection Robot Design</b> Beijing University of Technology	Aug. 2021 - Aug. 2022
<ul style="list-style-type: none"><li>Led the development of an autonomous ping-pong ball collection robot, incorporating advanced target detection, path planning, and an innovative collection system using brushless motors and friction wheels.</li><li>Designed and implemented a detection algorithm combining masking, Canny edge, and Hough circle techniques for rapid ball localization and efficient retrieval.</li></ul>	

## INTERN EXPERIENCE

<b>Research Intern on Medical Image Analysis</b> Chinese University of Hong Kong	Fall 2024 Remote
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## HONORS AND AWARDS

<b>The First Prize Scholarship</b> Recognition for to 10% of students in academics at Beijing University of Technology	2020   2021   2023
<b>24th China Robot and Artificial Intelligence Competition National First Prize</b> Project: Automatic Ping-Pong Ball Collection Robot Design	Aug. 2022

## SKILLS

**Languages:** English (CET6), Japanese (N2)  
**Programming:** Python(Torch, CV2), C(STM32, ROS)