```
info: SampleBot, Symantec
main:
                            // select a random direction and distance to move
                [dir], 4
        rand
                            // computes a random number between 0 and max-1 inclusive and
                            // stores this random number into dest
        rand
                [count], 10
                [count], 1
        add
loop:
                        // check if I am on top of food and eat if so
        sense
                        // If the organism is on a square that contains sludge or a collection
                        // point, then dest is set to the ID type number of the sludge, or a
                        // value of 65535 if the organism is on a collection point. Dest will
                        // be set to 0 otherwise. Flags: If the organism is on a square that
                        // contains food or a collection point, the SUCCESS flag is set,
                        // otherwise the SUCCESS flag is cleared
                noFood // jumps to the specified address if the SUCCESS flag is NOT set
        jns
        eat
                        // If the organism is on a square that contains sludge/food then it
                        // eats the food and the food disappears from the current square. It
                        // then receives 2000 energy units. If eating the sludge will push it
                        // over 65535 energy units, then it will fail to eat it. Flags: If
                        // the organism successfully eats food, the SUCCESS flag is set,
                        // otherwise the SUCCESS flag is cleared
noFood:
                              // see if we're over a collection point and release some energy
        energy r0
                              // places the organism's current energy value into the dest
                              // register or memory location Flags: No effect on flags
        cmp
                r0, 2000
                notEnufEnergy // Jumps to the specified address if the LESS flag is set.
        jΊ
                              // Otherwise continue execution at the nxt instruction
                r5
        sense
                r5, 0xFFFF
        cmp
                             // are we on a collection point?
                notEnufEnergy // jumps to the address if the EQUAL flag is NOT set
        ine
        release 100
                              // drain my energy by 100, but get 100 points, assuming
                              // that we're releasing on a collection point if the release
                              // is successful, the SUCCESS flag is set, otherwise cleared
notEnufEnergy:
                              // move me
        cmp
                [count], 0
                              // moved enough in this direction; try a new one
                newDir
                              // jumps to the address if the EQUAL flag is set
        travel [dir]
                              // Moves the organism one slot in the specified direction
                              // assuming the space is not occupied by another organism or
                              // outside the sludge tank. This instruction costs 10 energy
                              // points if successful; otherwise it costs 1 energy point.
                              // When an organism moves: North: their y=y-1, South:
                              // their y=y+1 West: their x=x-1, East: their x=x+1. If it
                              // moves success, the SUCCESS flag is set, otherwise cleared
                              // travel 0 is N, travel 1 is N, travel 2 is E, travel 3 is W
        ins
                newDir
                              // bumped into another org or the wall
                              // jumps to the address if the SUCCESS flag is NOT set
        sub
                [count], 1
                              // sub dest, src // dest = dest - src
        jmp
                loop
newDir:
        rand
                [dirl. 4
                              // select a new direction
        rand
                [count], 10
                             // select a new count between 0 and 9
                1000
        jmp
dir:
        data { 0 }
                              // our initial direction
                              // our initial count of how far to move in the cur dir
count:
        data { 0 }
```

```
info: SashaBot01, Sasha
// changed how far to move in one firection before changing direction
main:
                            // select a random direction and distance to move
                [dir], 4
                           // computes a random number between 0 and max-1 inclusive and
        rand
                            // stores this random number into dest
        rand
                [count], 15
                [count], 1
        add
loop:
                        // check if I am on top of food and eat if so
        sense
                        // If the organism is on a square that contains sludge or a collection
                        // point, then dest is set to the ID type number of the sludge, or a
                        // value of 65535 if the organism is on a collection point. Dest will
                        // be set to 0 otherwise. Flags: If the organism is on a square that
                        // contains food or a collection point, the SUCCESS flag is set,
                        // otherwise the SUCCESS flag is cleared
                noFood // jumps to the specified address if the SUCCESS flag is NOT set
        jns
        eat
                        // If the organism is on a square that contains sludge/food then it
                        // eats the food and the food disappears from the current square. It
                        // then receives 2000 energy units. If eating the sludge will push it
                        // over 65535 energy units, then it will fail to eat it. Flags: If
                        // the organism successfully eats food, the SUCCESS flag is set,
                        // otherwise the SUCCESS flag is cleared
noFood:
                              // see if we're over a collection point and release some energy
        energy r0
                              // places the organism's current energy value into the dest
                              // register or memory location Flags: No effect on flags
        cmp
                r0, 2000
                notEnufEnergy // Jumps to the specified address if the LESS flag is set.
        j1
                              // Otherwise continue execution at the nxt instruction
        sense
                r5, 0xFFFF
        cmp
                             // are we on a colleciton point?
                notEnufEnergy // jumps to the address if the EQUAL flag is NOT set
        jne
        release 100
                              // drain my energy by 100, but get 100 points, assuming
                              // that we're releasing on a collection point if the release
                              // is successful, the SUCCESS flag is set, otherwise cleared
notEnufEnergy:
                              // move me
        cmp
                [count], 0
                              // moved enough in this direction; try a new one
                newDir
                              // jumps to the address if the EQUAL flag is set
        je
        travel [dir]
                              // Moves the organism one slot in the specified direction
                              // assuming the space is not occupied by another organism or
                              // outside the sludge tank. This instruction costs 10 energy
                              // points if successful; otherwise it costs 1 energy point.
                              // When an organism moves: North: their v=v-1. South:
                              // their v=v+1 West: their x=x-1, East: their x=x+1. If it
                              // moves success, the SUCCESS flag is set, otherwise cleared
                              // travel 0 is N, travel 1 is N, travel 2 is E, travel 3 is W
        jns
                newDir
                              // bumped into another org or the wall
                              // jumps to the address if the SUCCESS flag is NOT set
        sub
                [count], 1
                              // sub dest, src // dest = dest - src
                loop
        jmp
newDir:
        rand
                [dirl, 4
                              // select a new direction
        rand
                [count], 15 // select a new count between 0 and 14
        jmp
                loop
dir:
        data { 0 }
                              // our initial direction
                              // our initial count of how far to move in the cur dir
count:
```

data { 0 }