An Efficient and Private ECG Classification System Using Split and Semi-Supervised learning

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Implementation Details

The following sections show the research pipeline overview that we used in our paper [1] and the implementation details that are left unmentioned in the paper.

1 Research Pipline Overview

[1]- A. Ayad, M. Barhoush, M. Frei, B. Vo" lker and A. Schmeink, "An Efficient and Private ECG Classification System Using Split and Semi-Supervised Learning," in IEEE Journal of Biomedical and Health Informatics, doi: 10.1109/JBHI.2023.3281977.

2 Test IoT setup

Table 1: Description of the hardware used in the experiments

1			
	Client	Server	
Description	Nvidia Jetson Nano Developer Kit	Dell Precision 3650	
CPU	Quad-core ARM A57 @ 1.43 GHz	Intel Core i9-10900K 3,7 GHz	
GPU	128-core Maxwell	Nvidia GeForce RTX 2080 Super 6GB	
RAM	4 GB LPDDR4	64 GB DDR4	

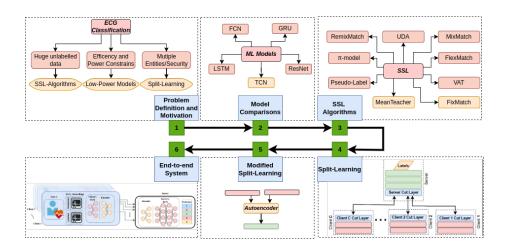


Figure 1: The ECG Pipeline Used in Our Paper [1]

3 SSL algorithms complexity

Table 2: Comparison of complexity between two SSL methods on the CIFR-10 data set to reach 80% accuracy [2]

$\begin{array}{c} {\rm SSL} \\ {\rm Algorithm} \end{array}$	Time [Sec]	$\begin{array}{c} \text{Memory} \\ [GB] \end{array}$	Batch Iteration	Time/Iteration [ms]	PFLOPS [10 ⁶ GFLOPS]
MeanTeacher (MT)	540	9.88	6183	87.4	3.4
FixMatch (FM)	1341	24.55	4242	316.1	9.1
MT/FM Ratio	40%	40%	146%	28%	37%

[2]- M. Barhoush, A. Ayad, and A. Schmeink, "Semi-supervised algorithms in resource-constrained edge devices: An overview and experimental comparison," in IEEE Int. Conf. on Smart Data (SmartData), 2022.

4 Model Hyper-parameters

Table 3: Training Parameters and General Values

Table 5. Training Larameters and General Value					
Parameter	Value				
Optimizer	Adam				
Learning Rate $(\alpha, \beta_1, \beta_2)$	(0.001, 0.9, 0.99)				
Batch Size	64				
Epochs	30				
Loss	Binary Cross Entropy				
Parameter	Value				
Kernal Size (K_T)	5				
Number of Features (F_T)	11				
Number of Timestamps (T)	250				
Number of Classes (C)	5				
	Parameter Optimizer Learning Rate $(\alpha, \beta_1, \beta_2)$ Batch Size Epochs Loss Parameter Kernal Size (K_T) Number of Features (F_T)				

Table 4: TCN5 Hyper-parameters, Block_0 to Block_2 reside in the Client's side, whereas Block_3 to Block_6 reside in the Server's Side

Block	Layer	Parameter	Value	
	Input	Size	$T \times F_T$	
Block_0	Padding	(Left, Right) Padding Size	$(K_T - 1, 0)$	
	Conv1D	(Input,Output) Channels	$(F_T, F_T + 1)$	
	Activation	Relu		
	BatchNorm1d	Size	L+1	
	-	Dialation1 (D1)	1	
	Padding	(Left, Right) Padding Size	$((K_T-1)\times D1,0)$	
	Conv1D	(Input,Output) Channels	$(L+1,F_T)$	
Block_1 (TCN1)	BatchNorm1d	Size	F_T	
	Activation Relu			
	Dropout	Dropout Rate	0.3	
	Padding	(Left, Right) Padding Size	$((K_T-1)\times D1,0)$	
	Conv1D	(Input,Output) Channels	(F_T,F_T)	
	BatchNorm1d Size		F_T	
	Activation	Relu		
	Dropout	Dropout Rate	0.3	
	-	Dialation (Dn)	2^{n-1}	
	Padding	(Left, Right) Padding Size	$((K_T-1)\times Dn,0)$	
	Conv1D	(Input,Output) Channels	(F_T,F_T)	
	BatchNorm1d	Size	F_T	
	Activation	n Relu		
Block_ n (TCN n),	Dropout	Dropout Rate	0.3	
n = 2, 3, 4, 5	Padding	(Left, Right) Padding Size	$((K_T-1)\times Dn,0)$	
	Conv1D	(Input,Output) Channels	(F_T,F_T)	
	BatchNorm1d	Size	F_T	
	Activation	Relu		
	Dropout	Dropout Rate	0.3	
	Flatten	Size	1	
Block_6	Linear	(Input,Output) Features	$(F_T \times 1000, C)$	
	Activation	Sigmoid		
	Output	Size	C	

Table 5: Autoencoder Hyper-parameters, The Encoder part resides in the Client's side, whereas The decoder part resides in the Server's Side

Autoecncoder	Layer	(Input,Output)	Kernal Size	Stride	Padding
Encoder	Conv1D	$(T_T, F_T) = (11, 11)$	4	2	1
	Conv1D	(8,11)	4	2	1
	Conv1D	(11,8)	4	2	1
Decoder	ConvTranspose1D	(5,8)	4	2	1
	ConvTranspose1D	(8,11)	4	2	1
	ConvTranspose1D	$(T_T, F_T) = (11, 11)$	4	2	1
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