

An Efficient and Private ECG Classification System Using Split and Semi-Supervised learning

Ahmad Ayad, Mahdi Barhoush, Marian Frei, Benedikt Völker
and Anke Schmeink

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Implementation Details

The following sections show the research pipeline overview that we used in our paper [1] and the implementation details that are left unmentioned in the paper.

1 Research Pipeline Overview

[1]- A. Ayad, M. Barhoush, M. Frei, B. Völker and A. Schmeink, "An Efficient and Private ECG Classification System Using Split and Semi-Supervised Learning," in IEEE Journal of Biomedical and Health Informatics, doi: 10.1109/JBHI.2023.3281977.

2 Test IoT setup

Table 1: Description of the hardware used in the experiments

	Client	Server
Description	Nvidia Jetson Nano Developer Kit	Dell Precision 3650
CPU	Quad-core ARM A57 @ 1.43 GHz	Intel Core i9-10900K 3,7 GHz
GPU	128-core Maxwell	Nvidia GeForce RTX 2080 Super 6GB
RAM	4 GB LPDDR4	64 GB DDR4

3 SSL algorithms complexity

Table 2: Comparison of complexity between two SSL methods on the CIFR-10 data set to reach 80% accuracy [2]

SSL Algorithm	Time [Sec]	Memory [GB]	Batch Iteration	Time/Iteration [ms]	PFLOPS [10 ⁶ GFLOPS]
MeanTeacher (MT)	540	9.88	6183	87.4	3.4
FixMatch (FM)	1341	24.55	4242	316.1	9.1
MT/FM Ratio	40%	40%	146%	28%	37%

[2]- M. Barhoush, A. Ayad, and A. Schmeink, “Semi-supervised algorithms in resource-constrained edge devices: An overview and experimental comparison,” in IEEE Int. Conf. on Smart Data (SmartData), 2022.

4 Model Hyper-parameters

Table 3: Training Parameters and General Values

Training	Parameter	Value
	Optimizer	Adam
	Learning Rate (α, β_1, β_2)	(0.001,0.9,0.99)
	Batch Size	64
	Epochs	30
	Loss	Binary Cross Entropy
General Values	Parameter	Value
	Kernal Size (K_T)	5
	Number of Features (F_T)	11
	Number of Timestamps (T)	250
	Number of Classes (C)	5

Table 4: TCN5 Hyper-parameters, Block_0 to Block_2 reside in the Client’s side, whereas Block_3 to Block_6 reside in the Server’s Side

Block	Layer	Parameter	Value
Block_0	Input	Size	$T \times F_T$
	Padding	(Left, Right) Padding Size	$(K_T - 1, 0)$
	Conv1D	(Input,Output) Channels	$(F_T, F_T + 1)$
	Activation	Relu	
	BatchNorm1d	Size	$L+1$
Block_1 (TCN1)	–	Dialation1 (D1)	1
	Padding	(Left, Right) Padding Size	$((K_T - 1) \times D1, 0)$
	Conv1D	(Input,Output) Channels	$(L + 1, F_T)$
	BatchNorm1d	Size	F_T
	Activation	Relu	
	Dropout	Dropout Rate	0.3
	Padding	(Left, Right) Padding Size	$((K_T - 1) \times D1, 0)$
	Conv1D	(Input,Output) Channels	(F_T, F_T)
	BatchNorm1d	Size	F_T
	Activation	Relu	
	Dropout	Dropout Rate	0.3
Block- n (TCN n), $n = 2, 3, 4, 5$	–	Dialation (Dn)	2^{n-1}
	Padding	(Left, Right) Padding Size	$((K_T - 1) \times Dn, 0)$
	Conv1D	(Input,Output) Channels	(F_T, F_T)
	BatchNorm1d	Size	F_T
	Activation	Relu	
	Dropout	Dropout Rate	0.3
	Padding	(Left, Right) Padding Size	$((K_T - 1) \times Dn, 0)$
	Conv1D	(Input,Output) Channels	(F_T, F_T)
	BatchNorm1d	Size	F_T
	Activation	Relu	
	Dropout	Dropout Rate	0.3
Block_6	Flatten	Size	1
	Linear	(Input,Output) Features	$(F_T \times 1000, C)$
	Activation	Sigmoid	
	Output	Size	C

Table 5: Autoencoder Hyper-parameters, The Encoder part resides in the Client's side, whereas The decoder part resides in the Server's Side

Autoecncoder	Layer	(Input,Output)	Kernal Size	Stride	Padding
Encoder	Conv1D	$(T_T, F_T) = (11, 11)$	4	2	1
	Conv1D	$(8, 11)$	4	2	1
	Conv1D	$(11, 8)$	4	2	1
Decoder	ConvTranspose1D	$(5, 8)$	4	2	1
	ConvTranspose1D	$(8, 11)$	4	2	1
	ConvTranspose1D	$(T_T, F_T) = (11, 11)$	4	2	1