

Faster maximal clique enumeration in large real-world link streams

Alexis BAUDIN

January 30, 2024

IRIF – Graph seminar

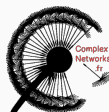


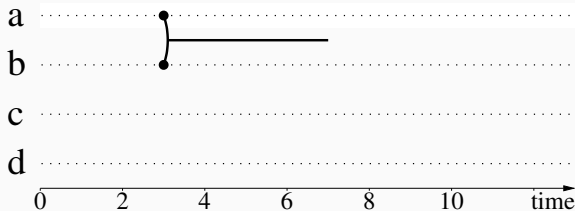
Table of contents

- 1 - Maximal clique enumeration in link streams
- 2 - New algorithm
- 3 - Complexity analysis
- 4 - Experimental study: performance gains
- 5 - Conclusion and perspectives

1 - Maximal clique enumeration in link streams

1 - Maximal clique enumeration in link streams

> Link stream: model temporal interactions



Link stream

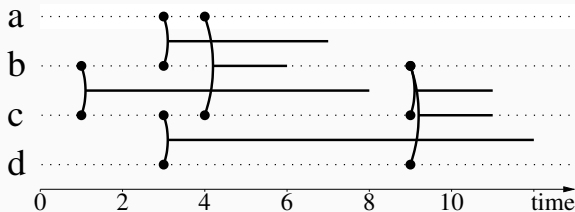
- Vertices : a , b , c et d
- Time period : $[0,12]$
- Interaction : temporal links
 - a , b linked over $[3,7]$

Advantages

- deals directly with the stream of interactions
- no arbitrary choice of time scale
- time is continuous

1 - Maximal clique enumeration in link streams

> Link stream: model temporal interactions



Link stream

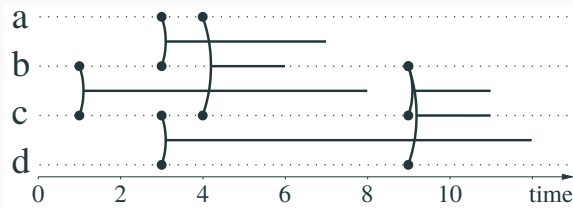
- Vertices : a , b , c et d
- Time period : $[0,12]$
- Interaction : temporal links
 - a , b linked over $[3,7]$
 - ...

Advantages

- deals directly with the stream of interactions
- no arbitrary choice of time scale
- time is continuous

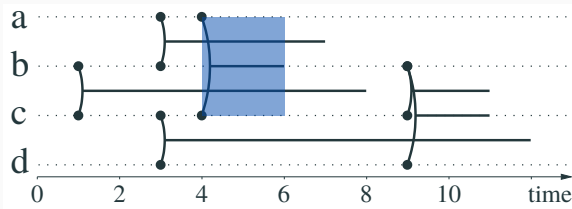
1 - Maximal clique enumeration in link streams

> Maximal cliques in link streams



1 - Maximal clique enumeration in link streams

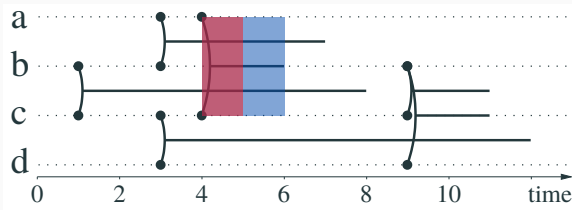
> Maximal cliques in link streams



$(\{a, b, c\}, [4, 6])$ is a clique

1 - Maximal clique enumeration in link streams

> Maximal cliques in link streams

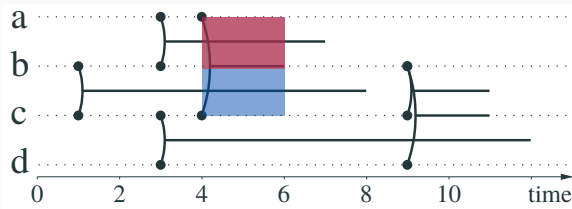


$(\{a, b, c\}, [4, 6])$ is a clique

$\rightarrow (\{a, b, c\}, \underline{[4, 5]})$ is not **time-maximal**

1 - Maximal clique enumeration in link streams

> Maximal cliques in link streams



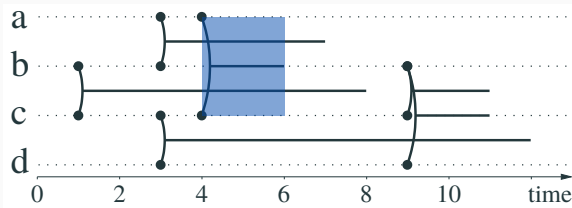
$(\{a, b, c\}, [4, 6])$ is a **clique**

→ $(\{a, b, c\}, [4, 5])$ is not **time-maximal**

→ $(\{a, b\}, [4, 6])$ is not **vertex-maximal**

1 - Maximal clique enumeration in link streams

> Maximal cliques in link streams



$(\{a, b, c\}, [4, 6])$ is a **clique**

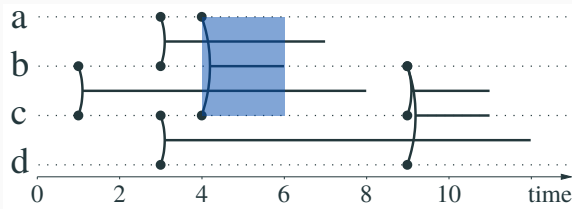
→ $(\{a, b, c\}, [4, 5])$ is not **time-maximal**

→ $(\{a, b\}, [4, 6])$ is not **vertex-maximal**

maximal clique = *time-maximal* and *vertex-maximal*

1 - Maximal clique enumeration in link streams

> Maximal cliques in link streams



$(\{a, b, c\}, [4, 6])$ is a **clique** (maximal).

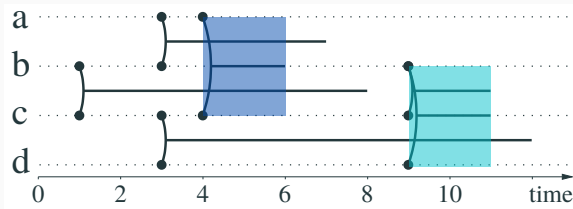
→ $(\{a, b, c\}, [4, 5])$ is not **time-maximal**

→ $(\{a, b\}, [4, 6])$ is not **vertex-maximal**

maximal clique = *time-maximal* and *vertex-maximal*

1 - Maximal clique enumeration in link streams

> Maximal cliques in link streams



$(\{a, b, c\}, [4, 6])$ is a **clique** (maximal).

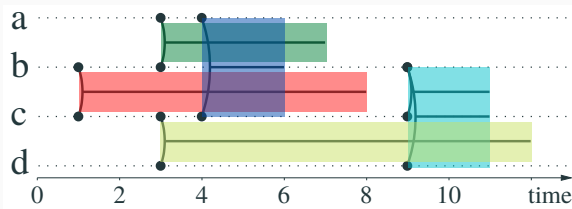
→ $(\{a, b, c\}, [4, 5])$ is not **time-maximal**

→ $(\{a, b\}, [4, 6])$ is not **vertex-maximal**

maximal clique = *time-maximal* and *vertex-maximal*

1 - Maximal clique enumeration in link streams

> Maximal cliques in link streams



$(\{a, b, c\}, [4, 6])$ is a **clique** (maximal).

→ $(\{a, b, c\}, [4, 5])$ is not **time-maximal**

→ $(\{a, b\}, [4, 6])$ is not **vertex-maximal**

maximal clique = *time-maximal* and *vertex-maximal*

1 - Maximal clique enumeration in link streams

> Enumeration problem

How to efficiently enumerate maximal cliques in massive real-world link streams?

Input: A link stream.

Output: List of all its maximal cliques.

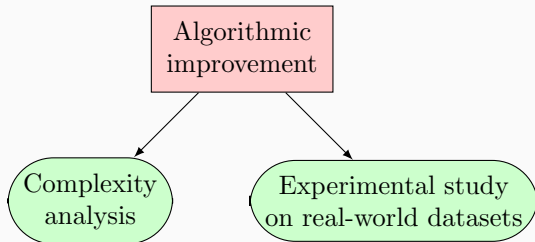
1 - Maximal clique enumeration in link streams

> Enumeration problem

How to efficiently enumerate maximal cliques in massive real-world link streams?

Input: A link stream.

Output: List of all its maximal cliques.

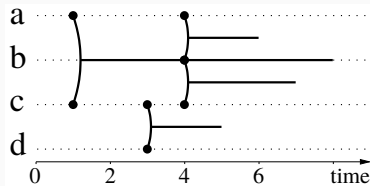


2 - New algorithm

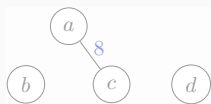
2 - New algorithm

- > Input datastructure

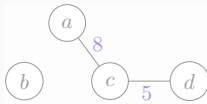
List of temporal links sorted chronologically



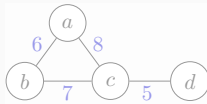
Evolving instantaneous graph G_t , with end dates



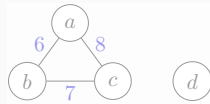
$G_1 : t = 1$



$G_3 : t = 3$



$G_4 : t = 4$

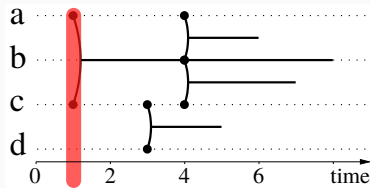


$G_5 : t = 5$

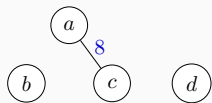
2 - New algorithm

- > Input datastructure

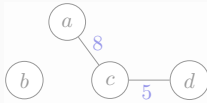
List of temporal links sorted chronologically



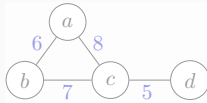
Evolving instantaneous graph G_t , with end dates



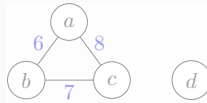
$G_1 : t = 1$



$G_3 : t = 3$



$G_4 : t = 4$

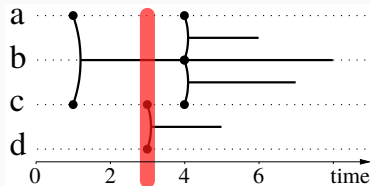


$G_5 : t = 5$

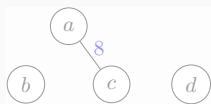
2 - New algorithm

- > Input datastructure

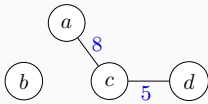
List of temporal links sorted chronologically



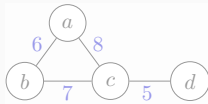
Evolving instantaneous graph G_t , with end dates



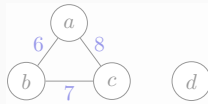
$G_1 : t = 1$



$G_3 : t = 3$



$G_4 : t = 4$

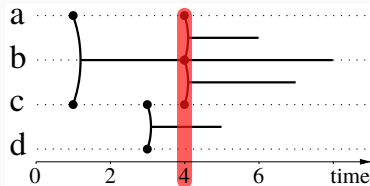


$G_5 : t = 5$

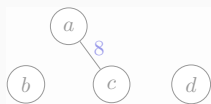
2 - New algorithm

- > Input datastructure

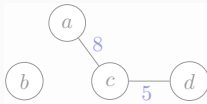
List of temporal links sorted chronologically



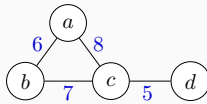
Evolving instantaneous graph G_t , with end dates



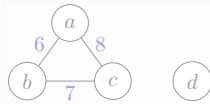
$G_1 : t = 1$



$G_3 : t = 3$



$G_4 : t = 4$

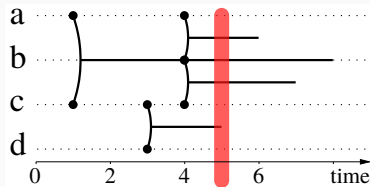


$G_5 : t = 5$

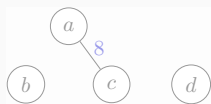
2 - New algorithm

- > Input datastructure

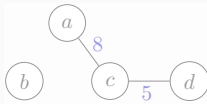
List of temporal links sorted chronologically



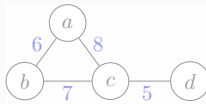
Evolving instantaneous graph G_t , with end dates



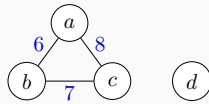
$G_1 : t = 1$



$G_3 : t = 3$



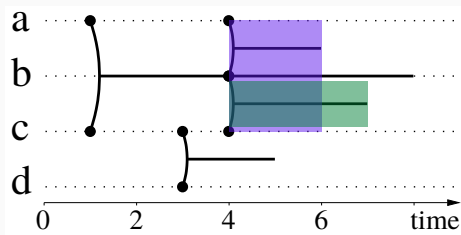
$G_4 : t = 4$



$G_5 : t = 5$

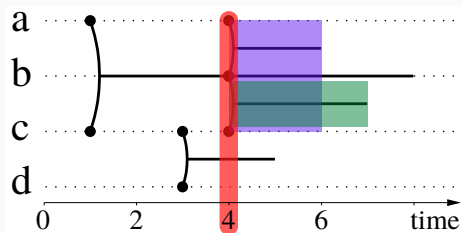
2 - New algorithm

> Maximal cliques that begin at each time t

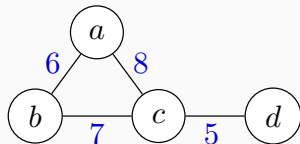


2 - New algorithm

> Maximal cliques that begin at each time t

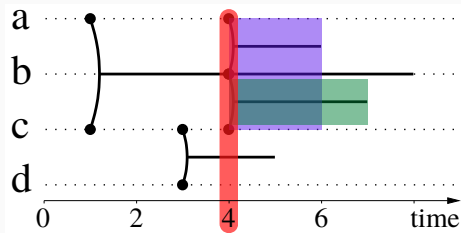


Instantaneous graph G_4

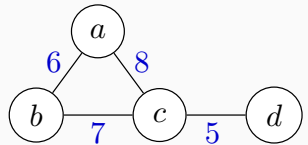


2 - New algorithm

> Maximal cliques that begin at each time t



Instantaneous graph G_4



Cliques of G_4
that contain
a new edge



Time-maximal cliques
that begin at $t = 4$

*Graph
algorithm*

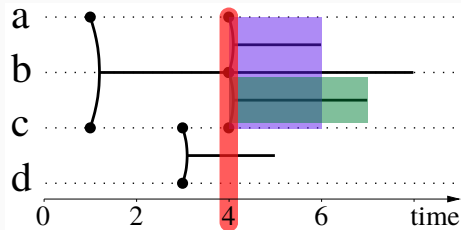
Instantaneous
graph G_4

Filter

Maximal cliques
that begin at $t = 4$

2 - New algorithm

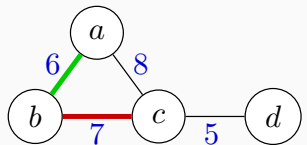
> Maximal cliques that begin at each time t



$(\{b, c\}, \quad), (\{a, b, c\}, \quad), (\{a, b\}, \quad)$

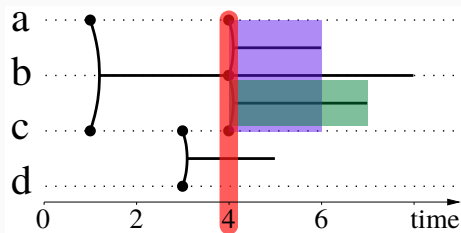
→ cliques of G_4 containing a new edge

Instantaneous graph G_4

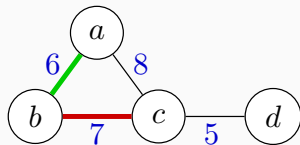


2 - New algorithm

> Maximal cliques that begin at each time t



Instantaneous graph G_4



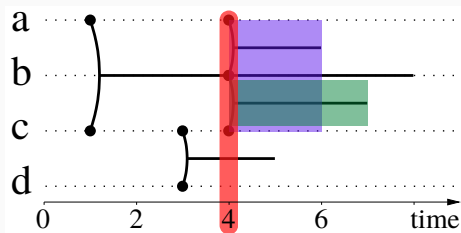
$(\{b, c\}, [4, \infty))$, $(\{a, b, c\}, [4, \infty))$, $(\{a, b\}, [4, \infty))$

→ cliques of G_4 containing a new edge

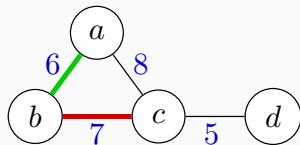
→ starting time: $t = 4$

2 - New algorithm

> Maximal cliques that begin at each time t



Instantaneous graph G_4



$(\{b, c\}, [4, 7]), (\{a, b, c\}, [4, 6]), (\{a, b\}, [4, 6])$

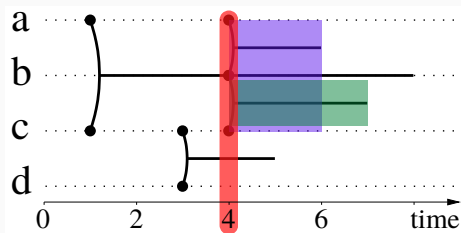
→ cliques of G_4 containing a new edge

→ starting time: $t = 4$

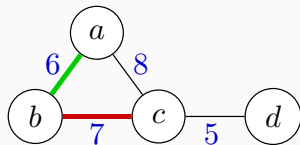
→ end time: min of edge end times

2 - New algorithm

> Maximal cliques that begin at each time t



Instantaneous graph G_4



$(\{b, c\}, [4, 7]), (\{a, b, c\}, [4, 6]), (\{a, b, c, d\}, [4, 5])$

→ cliques of G_4 containing a new edge

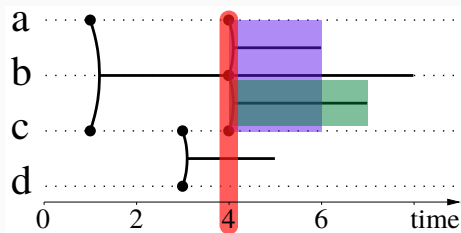
→ starting time: $t = 4$

→ end time: min of edge end times

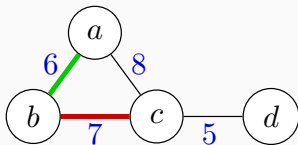
→ filter vertex-maximal cliques

2 - New algorithm

> Maximal cliques that begin at each time t



Instantaneous graph G_4



$(\{b, c\}, [4, 7]), (\{a, b, c\}, [4, 6]), (\{a, b\}, [4, 6])$

→ cliques of G_4 containing a new edge

→ starting time: $t = 4$

→ end time: min of edge end times

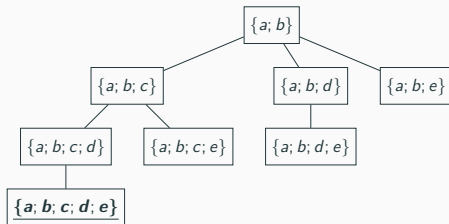
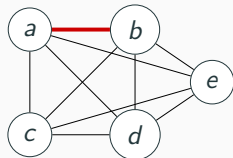
→ filter vertex-maximal cliques

Back to a graph problem: clique enumeration in G_t .

2 - New algorithm

> Pruning the enumeration in G_t

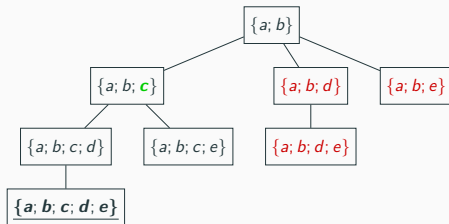
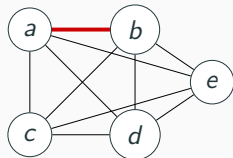
Clique enumeration
in some G_t



2 - New algorithm

> Pruning the enumeration in G_t

Clique enumeration
in some G_t

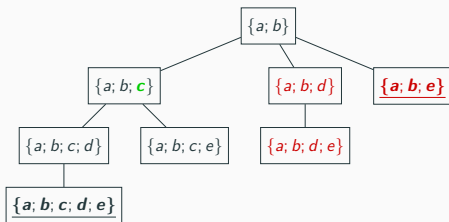
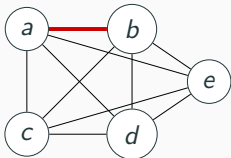


c chosen as pivot at first step

2 - New algorithm

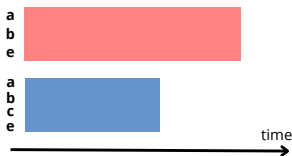
> Pruning the enumeration in G_t

Clique enumeration
in some G_t



c chosen as pivot at first step

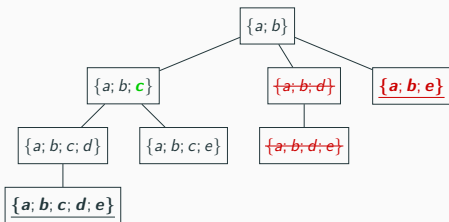
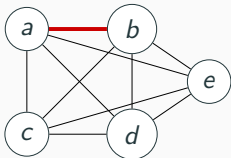
Example 1: do not prune $\{a; b; e\}$



2 - New algorithm

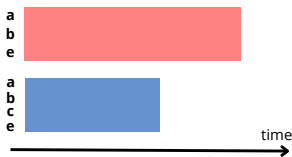
> Pruning the enumeration in G_t

Clique enumeration
in some G_t

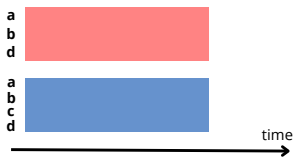


c chosen as pivot at first step

Example 1: do not prune $\{a; b; e\}$

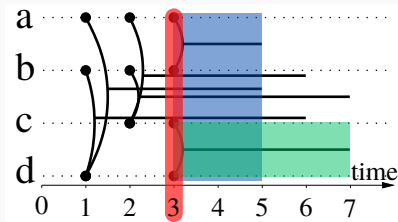


Example 2: prune $\{a; b; d\}$

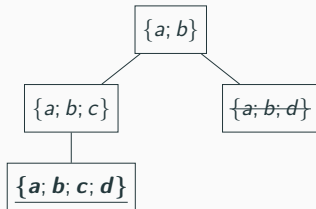
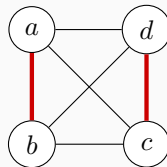


2 - New algorithm

> Pruning branches with already processed edges

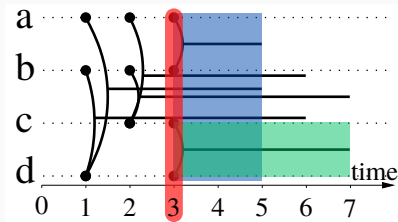


Instantaneous graph G_3

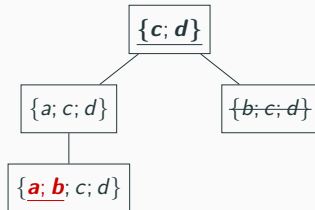
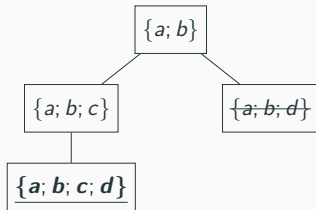
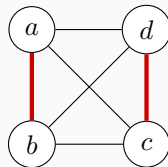


2 - New algorithm

> Pruning branches with already processed edges

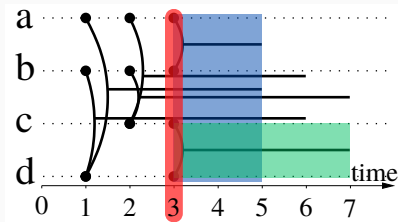


Instantaneous graph G_3

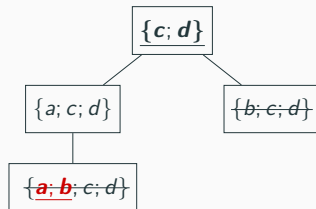
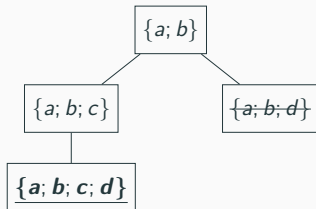
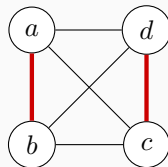


2 - New algorithm

> Pruning branches with already processed edges



Instantaneous graph G_3



2 - New algorithm

> State of the art

Summary of the new algorithm

- cliques not stored in memory ✓
- interactions reduced at each time step ✓

2 - New algorithm

> State of the art

Summary of the new algorithm

- cliques not stored in memory ✓
- interactions reduced at each time step ✓

State of the art : four main works

- Viard *et al.* 2016
 - Viard *et al.* 2018
 - Himmel *et al.* 2017
 - Bentert *et al.* 2019
- } Store all cliques
⇒ too costly in memory
- } Need all past and future interactions
when processing a vertex.

3 - Complexity analysis

3 - Complexity analysis

> From input characteristics

Input characteristics

d: maximal instantaneous degree

m: number of links

3 - Complexity analysis

> From input characteristics

Input characteristics

d: maximal instantaneous degree

m: number of links

Algorithm: for each link $(u \xrightarrow{[t_0, t_1]} v)$:

- List and process cliques in G_{t_0} that contain $\{u, v\}$
 - Number of those cliques: $\mathcal{O}(2^d)$
 - Cost of computing and processing: $\mathcal{O}(d^2)$

3 - Complexity analysis

> From input characteristics

Input characteristics

d : maximal instantaneous degree

m : number of links

Algorithm: for each link $(u \xrightarrow{[t_0, t_1]} v)$:

→ List and process cliques in G_{t_0} that contain $\{u, v\}$

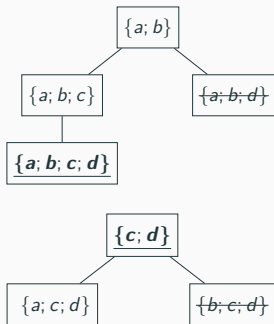
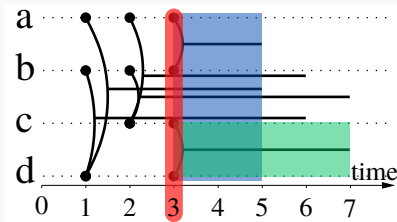
- Number of those cliques: $\mathcal{O}(2^d)$

- Cost of computing and processing: $\mathcal{O}(d^2)$

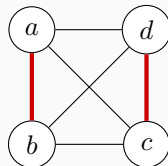
⇒ **Complexity:** $\boxed{\mathcal{O}(m \cdot d^2 \cdot 2^d)}$

3 - Complexity analysis

> From output characteristics

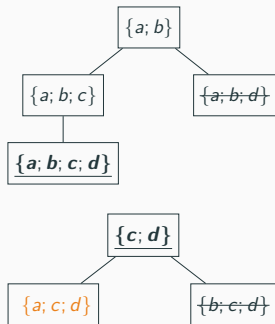
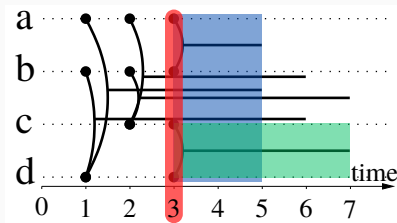


Instantaneous graph G_3

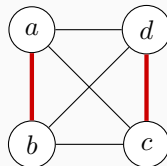


3 - Complexity analysis

> From output characteristics

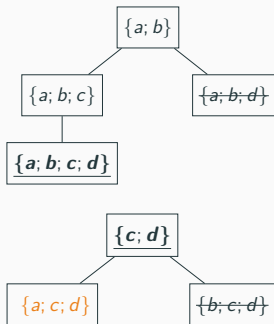
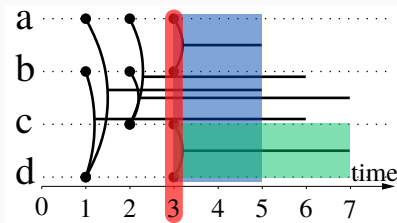


Instantaneous graph G_3

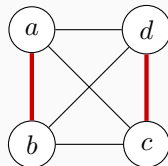


3 - Complexity analysis

> From output characteristics



Instantaneous graph G_3



Ratio “good” leaves

$$r = \frac{\text{nb maximal clique leaves}}{\text{nb leaves}}$$

Here: $r = \frac{1}{4}$; optimal: $r = 1$.

3 - Complexity analysis

> From output characteristics

Output characteristics

α : number of maximal cliques

q : maximal number of vertices in a clique

3 - Complexity analysis

> From output characteristics

Output characteristics

α : number of maximal cliques

q : maximal number of vertices in a clique

Complexity: $\mathcal{O}((\text{nb nodes in the trees}) \cdot (\text{cost of a node}))$

3 - Complexity analysis

> From output characteristics

Output characteristics

α : number of maximal cliques

q : maximal number of vertices in a clique

Complexity: $\mathcal{O}((\text{nb nodes in the trees}) \cdot (\text{cost of a node}))$

→ **Nb nodes:** $\mathcal{O}((\text{max depth}) \cdot (\text{nb leaves}))$

- max depth = q
- nb leaves = $\frac{1}{r} \cdot (\text{nb maximal clique leaves}) = \mathcal{O}\left(\frac{1}{r} \cdot \alpha\right)$

3 - Complexity analysis

> From output characteristics

Output characteristics

α : number of maximal cliques

q : maximal number of vertices in a clique

Complexity: $\mathcal{O}((\text{nb nodes in the trees}) \cdot (\text{cost of a node}))$

→ **Nb nodes:** $\mathcal{O}((\text{max depth}) \cdot (\text{nb leaves}))$

- max depth = q
- nb leaves = $\frac{1}{r} \cdot (\text{nb maximal clique leaves}) = \mathcal{O}\left(\frac{1}{r} \cdot \alpha\right)$

→ **Cost of a node:** $\mathcal{O}(d^2)$

3 - Complexity analysis

> From output characteristics

Output characteristics

α : number of maximal cliques

q : maximal number of vertices in a clique

Complexity: $\mathcal{O}((\text{nb nodes in the trees}) \cdot (\text{cost of a node}))$

→ **Nb nodes:** $\mathcal{O}((\text{max depth}) \cdot (\text{nb leaves}))$

- max depth = q
- nb leaves = $\frac{1}{r} \cdot (\text{nb maximal clique leaves}) = \mathcal{O}\left(\frac{1}{r} \cdot \alpha\right)$

→ **Cost of a node:** $\mathcal{O}(d^2)$

⇒ Complexity of the algorithm: $\boxed{\mathcal{O}\left(\frac{1}{r} \cdot \alpha \cdot q \cdot d^2\right)}$

3 - Complexity analysis

> Summary

From input characteristics

$$\mathcal{O}(m \cdot d^2 \cdot 2^d)$$

From output characteristics

$$\mathcal{O}\left(\frac{1}{r} \cdot d^2 \cdot q \cdot \alpha\right)$$

3 - Complexity analysis

> Summary

From input characteristics

$$\mathcal{O}(m \cdot d^2 \cdot 2^d)$$

- Viard *et al.* 2018: $\mathcal{O}(n^3 \cdot m^2 \cdot 2^n)$
- Himmel *et al.* 2018: $\mathcal{O}(m \cdot n \cdot |T| \cdot 3^{c/3} \cdot 2^c)$
- Bentert *et al.* 2019: $\mathcal{O}(n^4 \cdot |T|^2 \cdot 2^c)$

($c \leq d$ degeneracy, $|T|$ number of time steps)

From output characteristics

$$\mathcal{O}\left(\frac{1}{r} \cdot d^2 \cdot q \cdot \alpha\right)$$

3 - Complexity analysis

> Summary

From input characteristics

$$\mathcal{O}(m \cdot d^2 \cdot 2^d)$$

- Viard *et al.* 2018: $\mathcal{O}(n^3 \cdot m^2 \cdot 2^n)$
- Himmel *et al.* 2018: $\mathcal{O}(m \cdot n \cdot |T| \cdot 3^{c/3} \cdot 2^c)$
- Bentert *et al.* 2019: $\mathcal{O}(n^4 \cdot |T|^2 \cdot 2^c)$

($c \leq d$ degeneracy, $|T|$ number of time steps)

From output characteristics

$$\mathcal{O}\left(\frac{1}{r} \cdot d^2 \cdot q \cdot \alpha\right)$$

- output size = $\mathcal{O}(q \cdot \alpha) \Rightarrow$ factor $\frac{1}{r} \cdot d^2$ from output size

3 - Complexity analysis

> Summary

From input characteristics

$$\mathcal{O}(m \cdot d^2 \cdot 2^d)$$

- Viard *et al.* 2018: $\mathcal{O}(n^3 \cdot m^2 \cdot 2^n)$
- Himmel *et al.* 2018: $\mathcal{O}(m \cdot n \cdot |T| \cdot 3^{c/3} \cdot 2^c)$
- Bentert *et al.* 2019: $\mathcal{O}(n^4 \cdot |T|^2 \cdot 2^c)$

($c \leq d$ degeneracy, $|T|$ number of time steps)

From output characteristics

$$\mathcal{O}\left(\frac{1}{r} \cdot d^2 \cdot q \cdot \alpha\right)$$

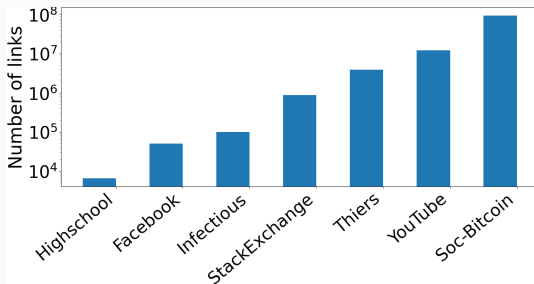
- output size = $\mathcal{O}(q \cdot \alpha) \Rightarrow$ factor $\frac{1}{r} \cdot d^2$ from output size
- $1 \leq \frac{1}{r} \leq 2^q$ but $\frac{1}{r} \approx 1.1$ in practice (experiments)

4 - Experimental study: performance gains

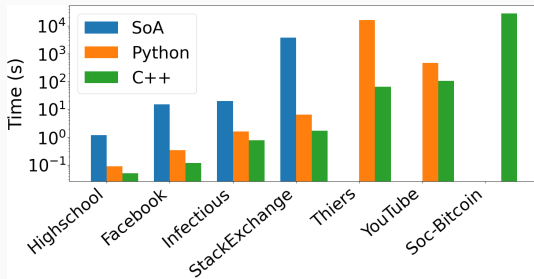
4 - Experimental study: performance gains

Datasets: state of the art + massive link streams

- communication networks
- human interactions



4 - Experimental study: performance gains



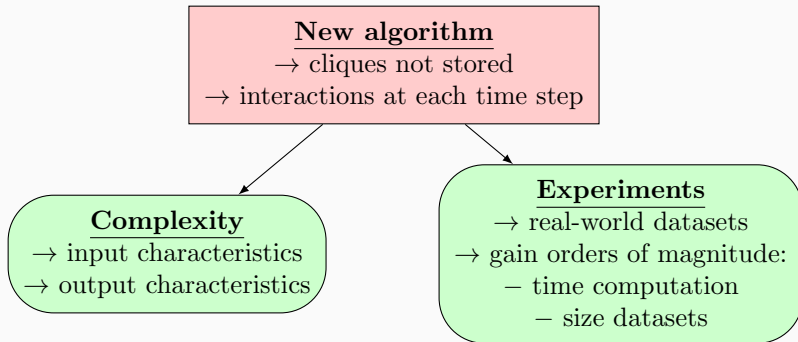
Experimental protocol

- Code in Python and C++
- Maximum 24h and 390Gb RAM.

5 - Conclusion and perspectives

5 - Conclusion and perspectives

> Contributions

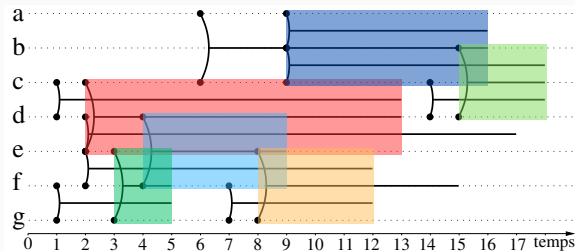


5 - Conclusion and perspectives

> Application

Communities in link streams by clique percolation

[Baudin et al. 2023]



→ temporal data analysis

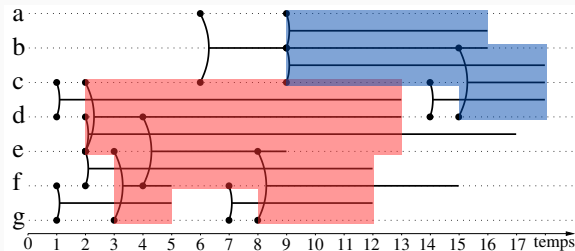
→ anomaly detection

5 - Conclusion and perspectives

> Application

Communities in link streams by clique percolation

[Baudin et al. 2023]



→ temporal data analysis

→ anomaly detection

5 - Conclusion and perspectives

> Perspectives

Improve enumeration by ordering nodes

Ordering the nodes of each instantaneous graph G_t .

[Eppstein *et al.* 2010]: core ordering of vertices.

5 - Conclusion and perspectives

> Perspectives

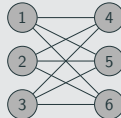
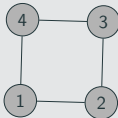
Improve enumeration by ordering nodes

Ordering the nodes of each instantaneous graph G_t .

[Eppstein *et al.* 2010]: core ordering of vertices.

Other temporal enumeration using a same framework

Enumerate other motifs in each instantaneous graph G_t .



Thank you for your attention!

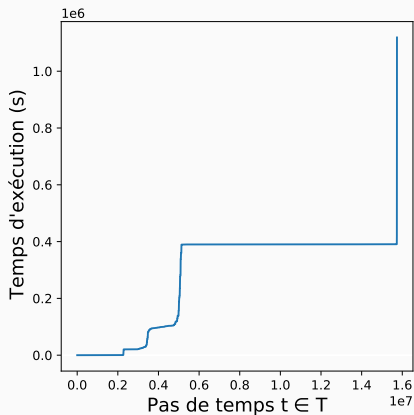
Code in open-access:

`https://gitlab.lip6.fr/baudin/maxcliques-linkstream`

Contact: `alexis.baudin@lip6.fr`

Appendix

Study the limits of computation



Study the limits of computation

