Low-Rank Matrix Completion Project

Authors: Artem Bochkarev, Roman Isachenko Ilya Zharikov, Anne-Laure Ducroucq

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Problem Statement

Task

Given the amount of observed matrix entries to reconstruct low-rank matrix approximation.

Applications:

- recommender systems;
- image-processing;
- imputation of NAs for genomic data;
- rank estimation for SVD.

Problem Statement

Notations:

- M n × m unknown matrix;
- $\Omega \in \{1, ..., n\} \times \{1, ..., m\}$ indices of observed elements;

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$$P_{\Omega}(M) = egin{cases} M_{ij}, & ext{if } (i,j) \in \Omega; \ 0, & ext{otherwise}. \end{cases}$$

Optimization Task (NP-hard)

 $\begin{array}{ll}
\text{minimize} & \text{rank}(X) \\
X \in \mathbb{R}^{n \times m}
\end{array}$

subject to $P_{\Omega}(X) = P_{\Omega}(M)$



Relaxations

Original Task (NP-hard)

minimize
$$\operatorname{rank}(X)$$
, subject to $P_{\Omega}(X) = P_{\Omega}(M)$

SVP

$$\underset{X \in \mathbb{R}^{n \times m}}{\mathsf{minimize}} \quad \|P_{\Omega}(X) - P_{\Omega}(M)\|_F^2$$

subject to $rank(X) \leq k$

RISMF

$$\begin{array}{ll}
\text{minimize} & \|U\|_F^2 + \|V\|_F^2 \\
V \in \mathbb{R}^{k \times m}
\end{array}$$

subject to $P_{\Omega}(UV) = P_{\Omega}(M)$

SVT

$$\underset{X \in \mathbb{R}^{n \times m}}{\mathsf{minimize}} \quad \tau \|X\|_* + \|X\|_F^2$$

subject to
$$P_{\Omega}(X) = P_{\Omega}(M)$$

SoftImpute

$$\underset{X \in \mathbb{R}^{n \times m}}{\mathsf{minimize}} \quad \|X\|_*$$

subject to
$$||P_{\Omega}(X) - P_{\Omega}(M)||_F \leq \delta$$

Related Works

- Candes E. J., Recht B. Exact matrix completion via convex optimization. 2009.
- 2 Cai J. F., Candes E. J., Shen Z. A singular value thresholding algorithm for matrix completion. 2010.
- Mazumder R., Hastie T., Tibshirani R. Spectral regularization algorithms for learning large incomplete matrices. 2010.
- Jain P., Meka R., Dhillon I. S. Guaranteed rank minimization via singular value projection. 2010.
- Takacs G. et al. Scalable collaborative filtering approaches for large recommender systems. 2009.
- Vandereycken B. Low-rank matrix completion by Riemannian optimization. 2013.

SVP (Jain P., Meka R., Dhillon I. S., 2010)

Relaxation

```
Input: \Omega, P_{\Omega}(M), k, \eta;
Output: X;
1: X := 0
2: repeat
3: X := X - \eta P_{\Omega}^{-1} (P_{\Omega}(X) - P_{\Omega}(M))
4: U, \Sigma, V := SVD(X)
5: X := U_k \Sigma_k V_k^T
6: until \|P_{\Omega}(M) - P_{\Omega}(X)\|_E / \|P_{\Omega}(X)\|_E > \varepsilon
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SVT (Cai J. F., Candes E. J., Shen Z., 2010)

Relaxation

minimize
$$\lambda \|X\|_* + \|X\|_F^2$$
, subject to $P_{\Omega}(X) = P_{\Omega}(M)$

Input: $\Omega, M, \varepsilon, \lambda, \eta$;

Output: X;

- 1: $Y := \eta P_{\Omega}(M)$
- 2: repeat
- 3: $X := S_{\lambda}(Y)$
- 4: $P_{\Omega}(Y) := P_{\Omega}(Y) + \eta(M X)$
- 5: until $||P_{\Omega}(X-M)||_F/||P_{\Omega}(M)||_F > \varepsilon$

$$S_{\lambda}(W) = U[D - \lambda I]_{+}V^{*}; \quad U, D, V := SVD(W)$$



ROY team

SoftImpute (Hastie T., Tibshirani R., 2010)

Lagrangian Relaxation

$$\underset{X \in \mathbb{R}^{n \times m}}{\mathsf{minimize}} \quad \lambda \|X\|_* + \|P_{\Omega}(X) - P_{\Omega}(M)\|_F^2$$

Input: $M, \Omega, \varepsilon, \lambda_1 > \cdots > \lambda_k$; Output: sequence $X_{\lambda_1}, \dots, X_{\lambda_k}$; 1: X := 0; 2: for $i = 1, \dots, k$ do 3: repeat 4: $X := S_{\lambda_i}(P_{\Omega}(M) + P_{\Omega}^{\perp}(X))$ 5: until $\|P_{\Omega}(M) - P_{\Omega}(X)\|_F / \|P_{\Omega}(M)\|_F > \varepsilon$ 6: $X_{\lambda_i} := X$;

RIMSF

Relaxation

$$\underset{\substack{U \in \mathbb{R}^{n \times k} \\ V \in \mathbb{R}^{k \times m}}}{\mathsf{minimize}} \quad \|P_{\Omega}(UV) - P_{\Omega}(M)\|_F^2 + \lambda \left(\|U\|_F^2 + \|V\|_F^2\right)$$

Input: $M, \Omega, \varepsilon, \lambda, \eta$;

Output: U, V;

- 1: Initialization of U, V with small random numbers;
- 2: repeat
- 3: for $(i,j) \in \Omega$ do
- 4: Gradient step for U[i,:] and V[:,j] by regularized error function
- 5: **until** $||P_{\Omega}(M) P_{\Omega}(UV)||_F / ||P_{\Omega}(M)||_F > \varepsilon$



Numerical Experiments

- Synthetic data
 Low-rank matrices with random noise.
- Low-rank images
 Visual demonstration of algorithms.
- Assessment dataset
 Real dataset for collaborating filtering.

Synthetic Data

Images

Assessment data