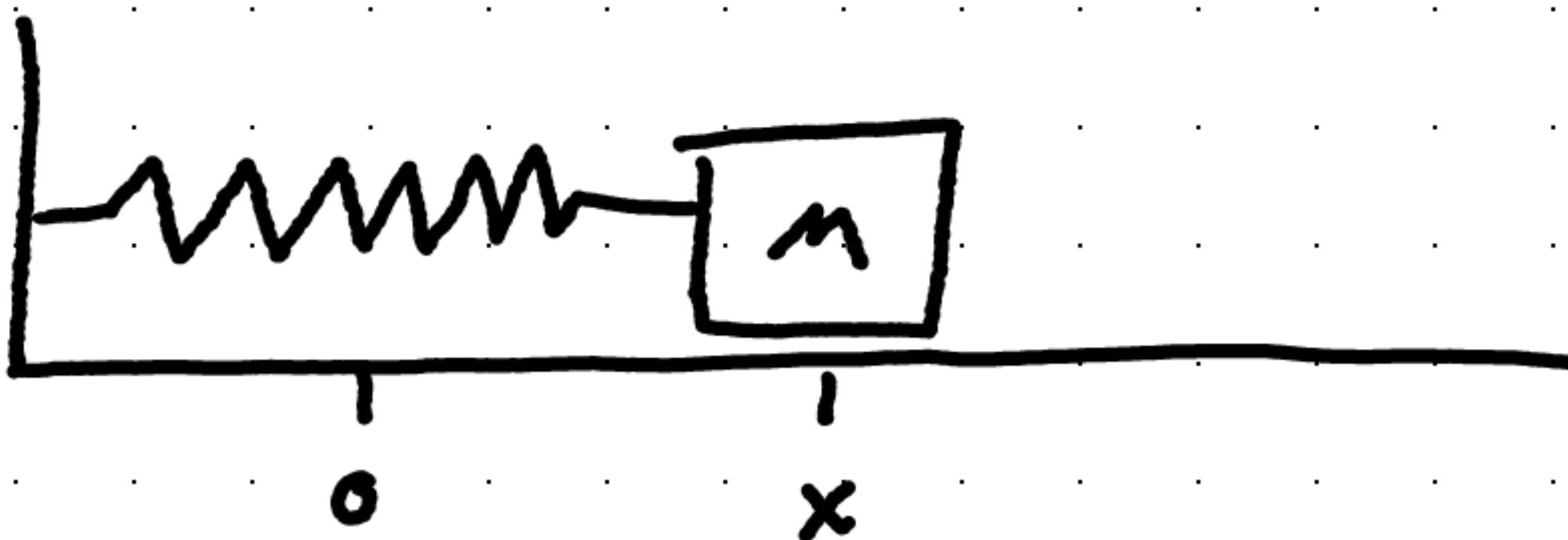


## Application: Vibrating Strings



(Equilibrium)

Newton's 2<sup>nd</sup>:  $F = ma$

$$a = \frac{d^2 x}{dt^2}$$

Let  $x(t)$  be the displacement of mass from the equilibrium.

Hooke's Law:

$F$  acting on mass, due to Spring, is proportional to  $x(t)$  (displacement from equilibrium)

$$F = -kx, k > 0$$

Plugging both in ends up with:

$$M \frac{d^2 x}{dt^2} = -Kx$$

or

$$M\ddot{x}(t) + Kx(t) = 0$$

Solve Homogeneous:

$$Mr^2 + K = 0, \quad r^2 = -\frac{K}{m}, \quad r = \pm \sqrt{-\frac{K}{m}} = \pm \sqrt{\frac{K}{m}}$$

and just for notation, let's say

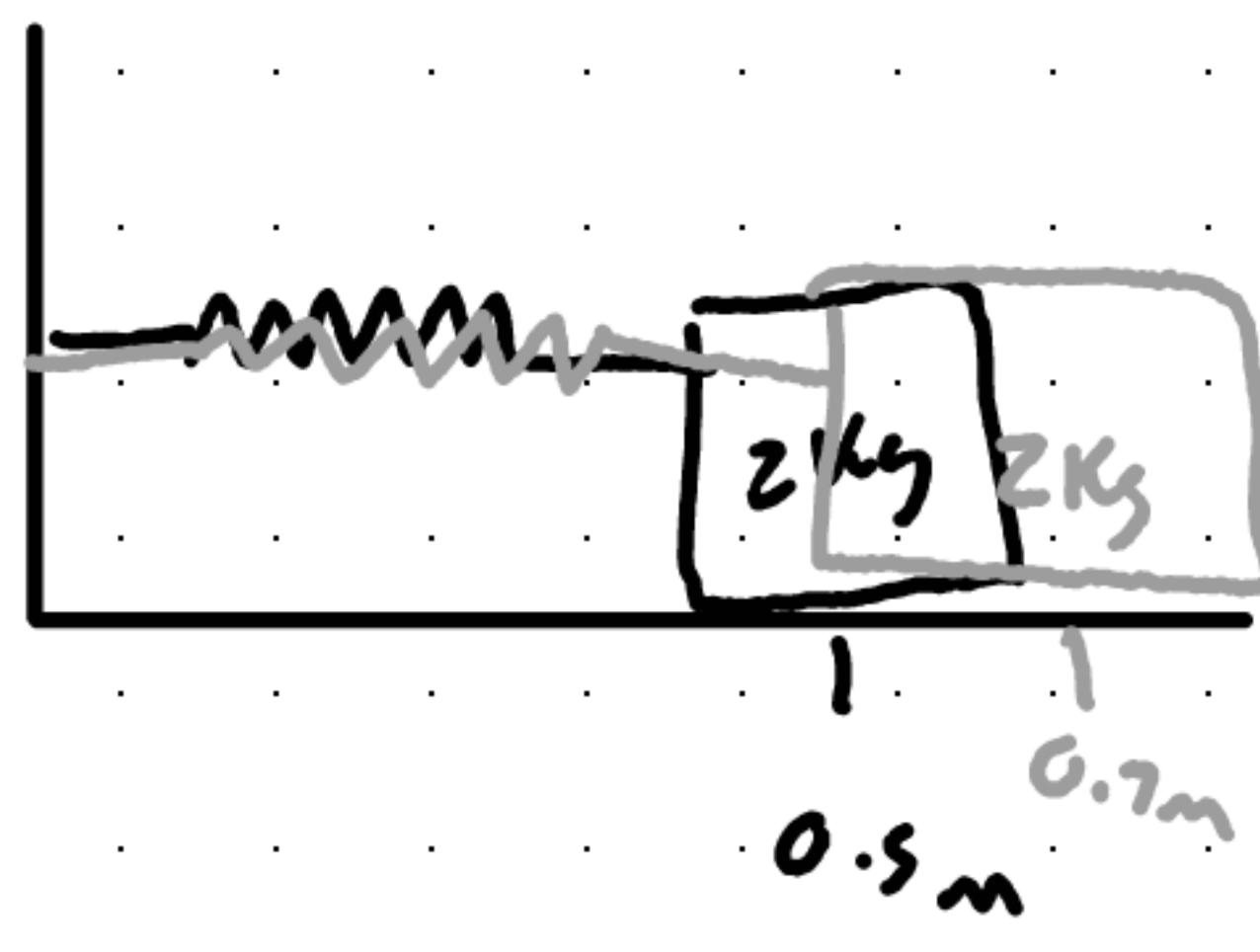
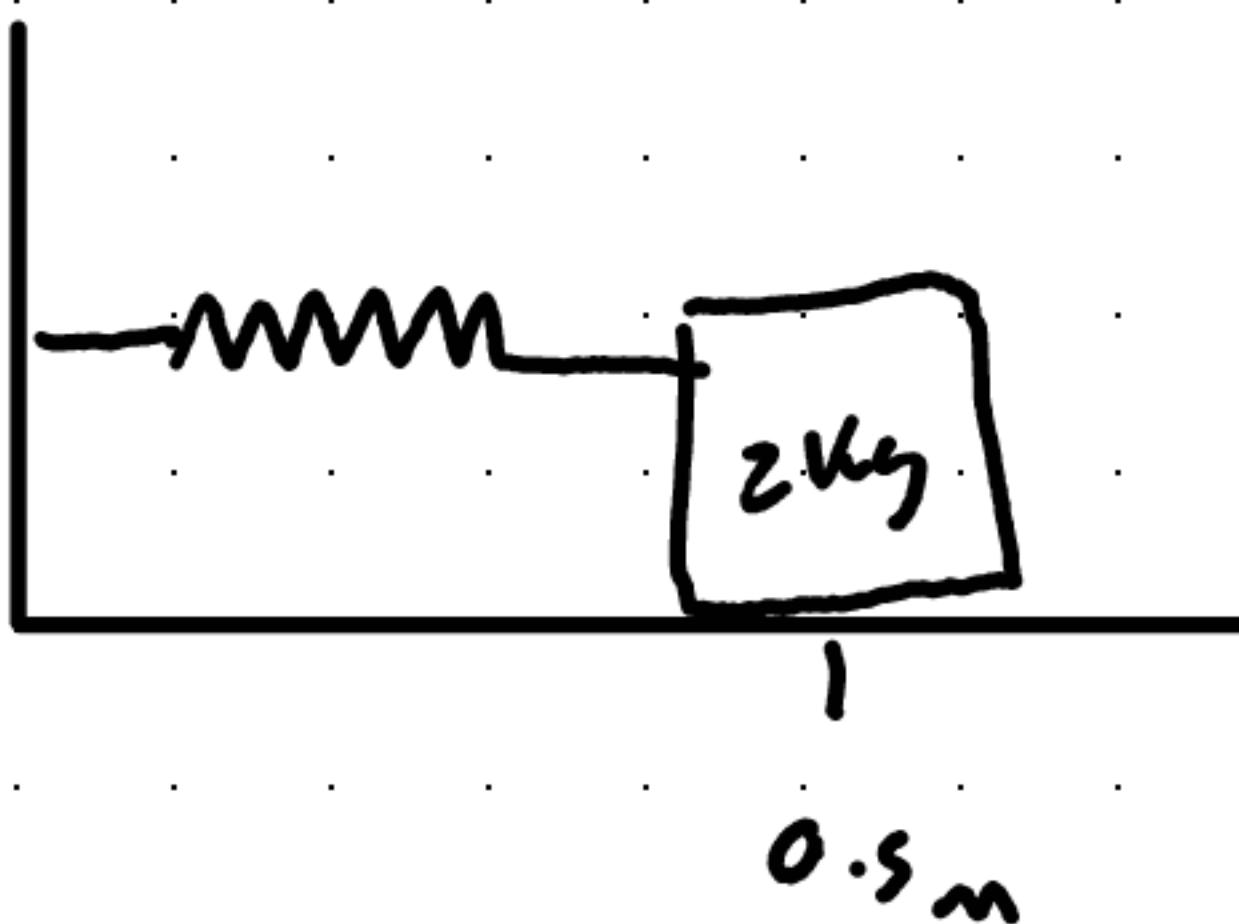
$$r = \pm \omega_i$$

Solution

$$x(t) = C_1 \cos(\omega_i t) + C_2 \sin(\omega_i t), \quad \omega = \sqrt{\frac{K}{m}}$$

Example:

A Spring With a Mass of 2 Kg Has an Natural length 0.5m. A force of 25.6 N is required to stretch it to a length of 0.7m. The Spring is released with an initial velocity of 0. Find the position of the mass at any time t.



$$F = -Kx$$

$$-25.6 = -K(0.2)$$

$$K = 128$$

$$2 \frac{d^2x}{dt^2} + 128x = 0$$

$$x(t) = C_1 \cos 8t + C_2 \sin 8t$$

$$\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{128}{2}} = 8$$

$$2 \frac{d^2x}{dt^2} + 128x = 0$$

$$x(t) = C_1 \cos 8t + C_2 \sin 8t$$

$$x(0) = C_1 = 0.2$$

$$\dot{x}(0) = -8C_1 \sin 8t + 8C_2 \cos 8t \Big|_{t=0} = 8C_2 = 0$$

$$x(t) = 0.2 \cos 8t$$

Initial Conditions

$$x(0) = 0.2$$

$$\dot{x}(0) = 0$$

Distance

Velocity

## Damped Vibrations



Say, in damping fluid

Damping force: Proportional to velocity,  $\frac{dx}{dt}$



$$-C \frac{dx}{dt}$$

$$\frac{M \frac{d^2x}{dt^2}}{\text{Force}} = \text{Restoring Force} + \text{Damping Force} = -Kx - C \frac{dx}{dt}$$

$$M \frac{d^2x}{dt^2} + C \frac{dx}{dt} + Kx = 0$$

Solve

$$m\omega^2 + cv + K = 0$$

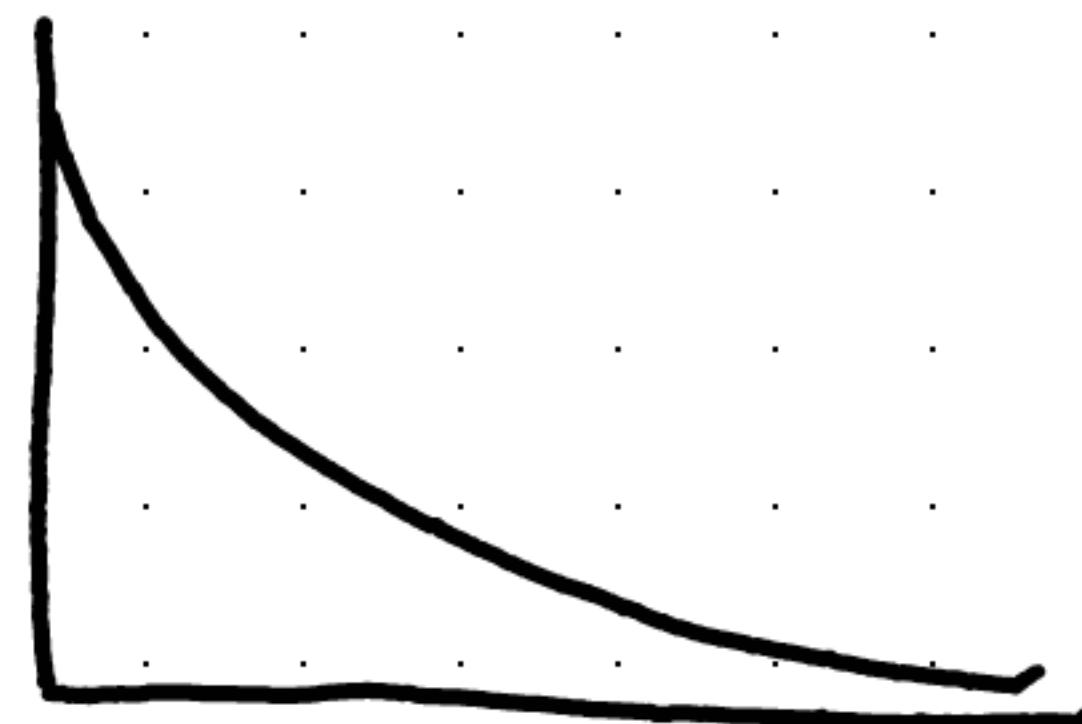
$$\tau = \frac{-C \pm \sqrt{C^2 - 4mK}}{2m}$$

Caso I

$$c^2 > 4mk \quad (\text{Overdamping})$$

Two real roots to the Char eq

$$x(t) = C_1 e^{r_1 t} + C_2 e^{r_2 t}$$



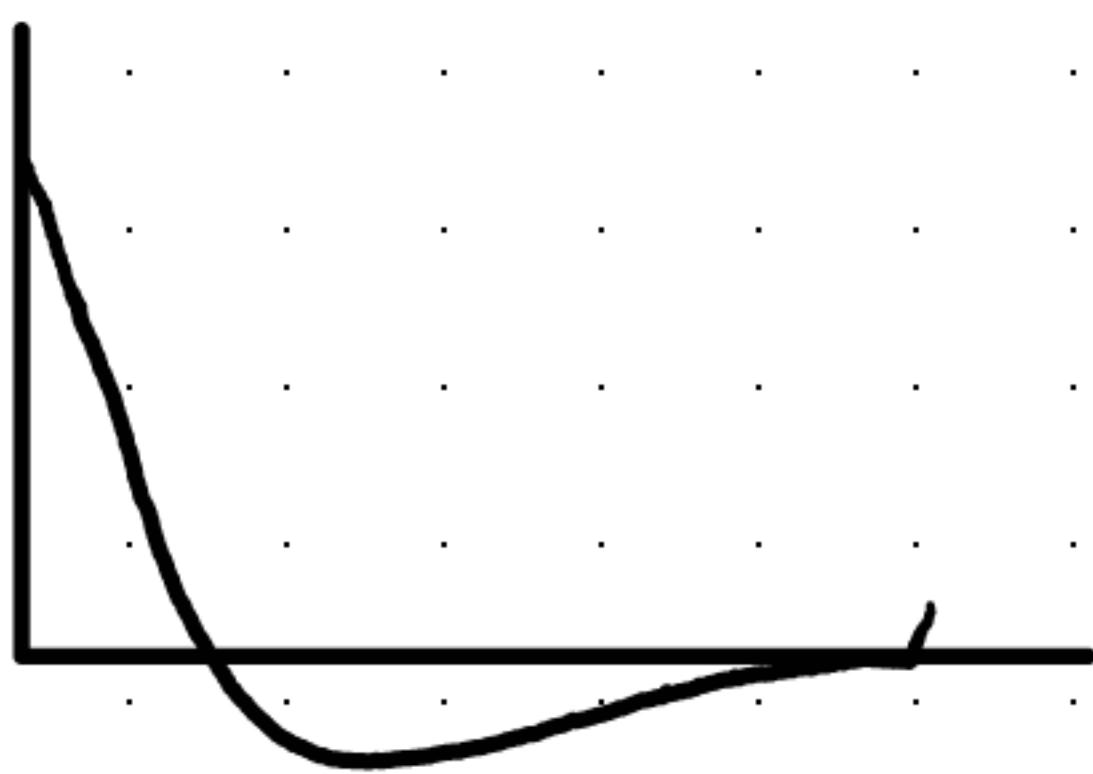
Caso II

$$c^2 - 4mk = 0$$

$$\text{One root: } r = -\frac{c}{2m}$$

Critical damping

$$x(t) = C_1 e^{-\frac{c}{2m}t} + C_2 t e^{-\frac{c}{2m}t}$$

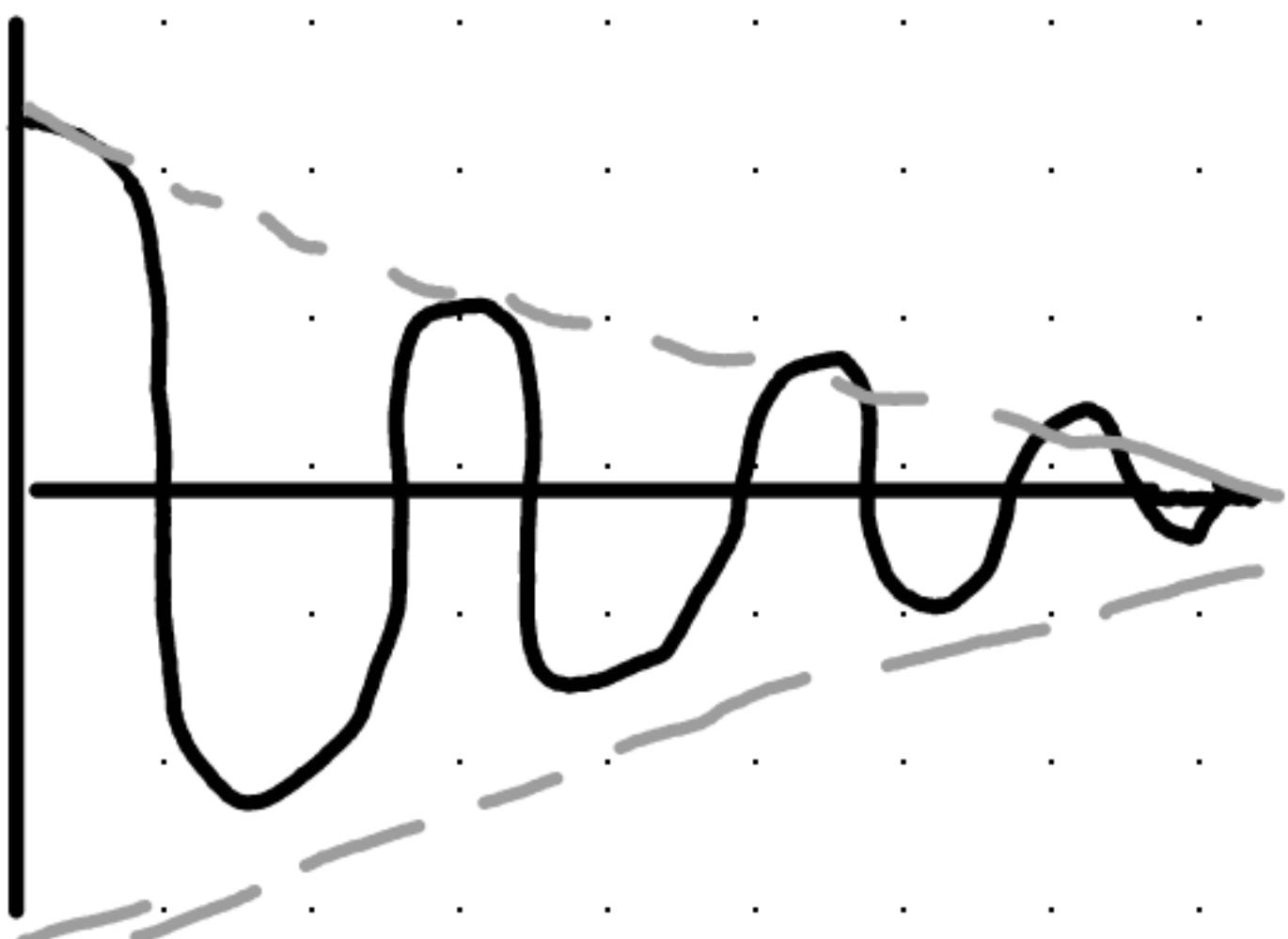


Caso III

$$c^2 - 4mk < 0$$

Underdamping

$$x(t) = C_1 e^{\frac{-c}{2m}t} (C_2 \cos \omega t + C_3 \sin \omega t)$$



Exponential decay on oscillating wave

Example: Suppose the spring from the previous example is immersed in a damping fluid with a coefficient  $C=40$ . (Recall,  $K=128$ ,  $M=2$ )

Find the position of the mass at any time  $t$  i.e. it starts from equilibrium and is given a push with initial velocity  $0.6 \text{ m/s}$

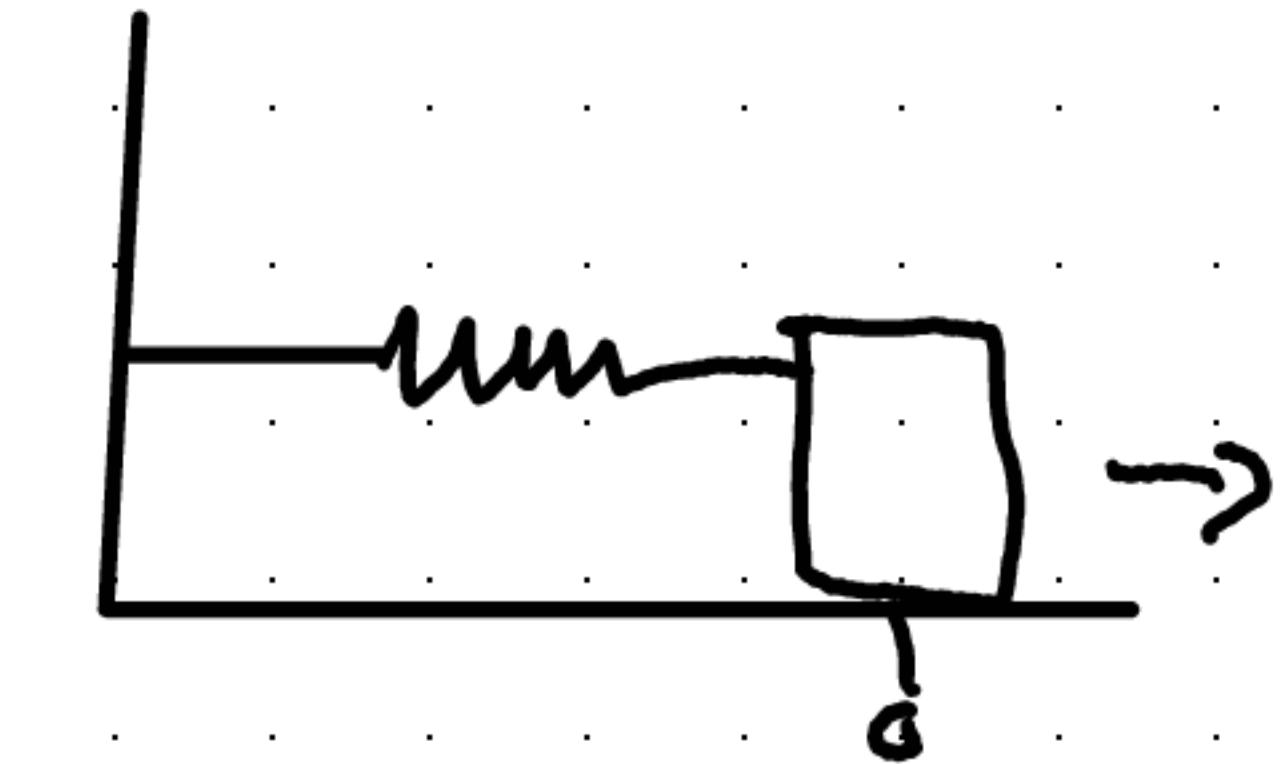
$$x(0)=0, \quad x'(0) = 0.6 \text{ m/s}$$

$$2 \frac{d^2x}{dt^2} + 40 \frac{dx}{dt} + 128x = 0$$

$$\frac{d^2x}{dt^2} + 20 \frac{dx}{dt} + 64x = 0$$

$$r^2 + 20r + 64 = 0$$

$$(r+4)(r+16)$$



$$r = -4, \quad r = -16$$

$$x(t) = C_1 e^{-4t} + C_2 e^{-16t}$$

Apply IC's

$$x(0)=0$$

$$x(0) = C_1 + C_2 = 0$$

$$x'(0) = 0$$

$$C_2 = 4$$

## Forced Vibrations

External Force:  $F(t)$

$$m \frac{d^2x}{dt^2} = \text{restoring + damping + external forces}$$

$$= Kx - c \frac{dx}{dt} + F(t)$$

$\ddot{mx} + c\dot{x} + Kx = F(t)$

Non-Homogeneous

## Common Situation

External Force is oscillatory:  $F(t) = F_0 \cos \omega_0 t$

(Where  $\omega_0 \neq \omega = \sqrt{\frac{k}{m}}$ )  
(Frequency)

If  $c=0$

$$m \ddot{x} + Kx = F_0 \cos \omega t$$

Can express solution as:

$$x(t) = C_1 \cos \omega t + C_2 \sin \omega t + \frac{F_0}{m(\omega^2 - \omega_0^2)} \cos(\omega_0 t)$$

If it turns out that the driving force frequency is the same as the natural frequency

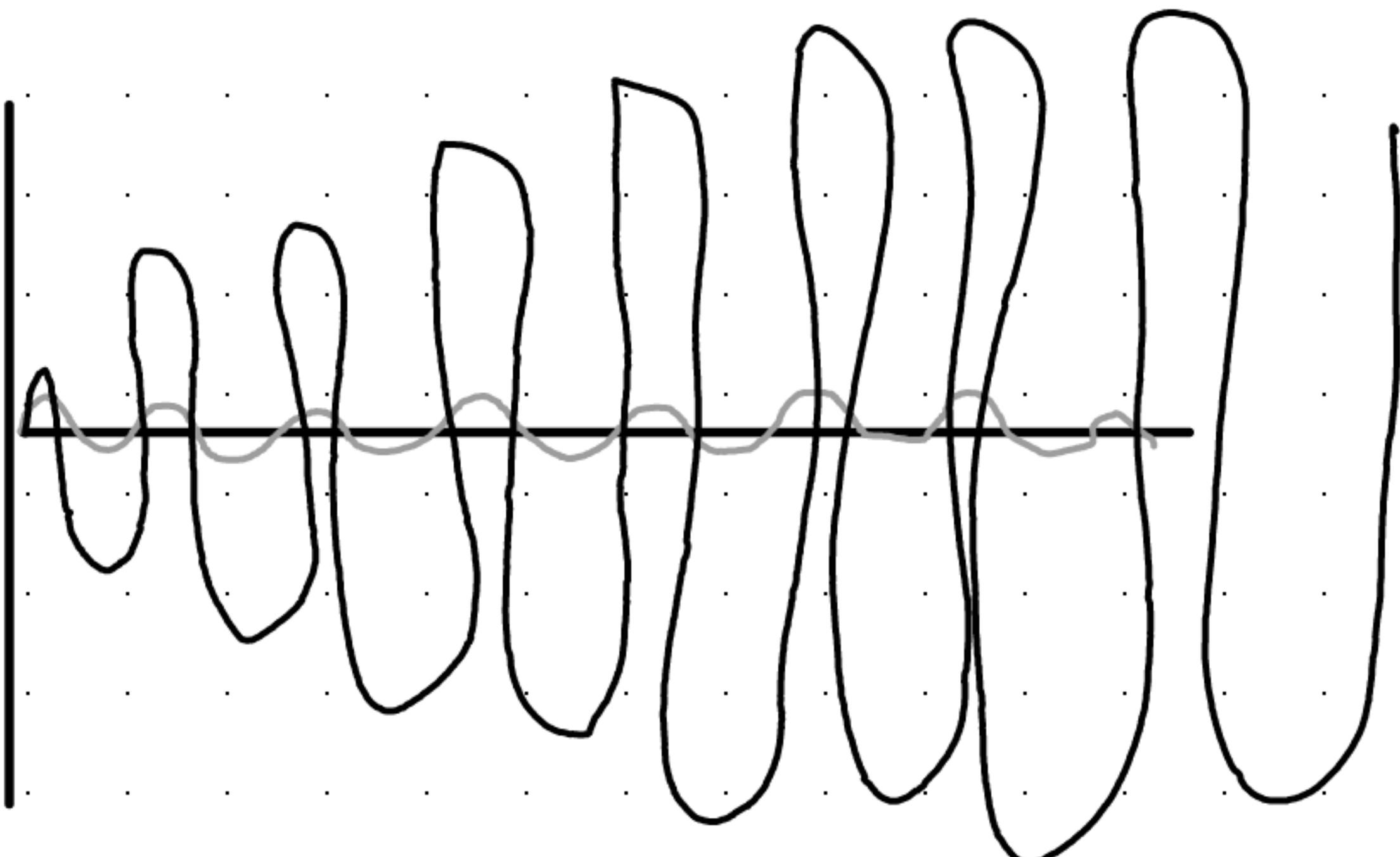
$$\omega_0 = \omega$$

$\omega_0$  can show

...Duplic Shows Up!

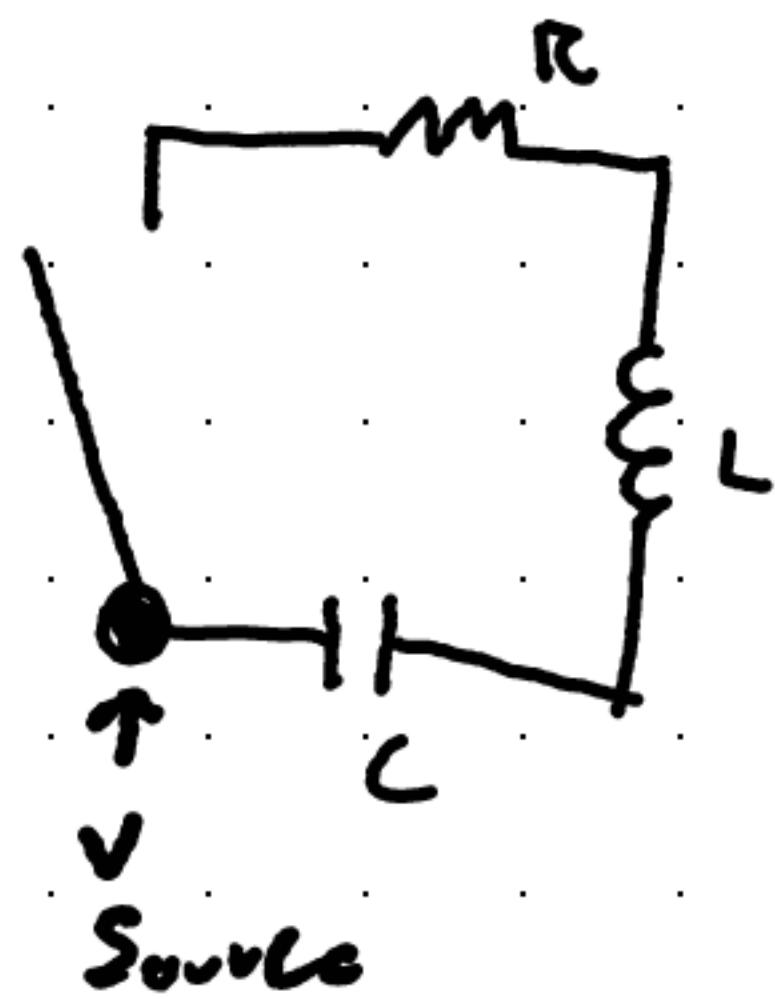
$$x(t) = C_1 \cos \omega t + C_2 \sin \omega t + \frac{F_0}{2M\omega} t \sin \omega t$$

When the driving force frequency matches the natural frequency, you get resonance



Picture Pushing on a swing in the absence of any damping force...

# Electric Circuits



Electromotive Force,  $E(t)$  (e.g battery)

Resistor  $R$  (Resistance)

Inductor  $L$  (inductance)

Capacitor  $C$  (Capacitance)

$Q(t)$ : Charge on Capacitor at time  $t$ .

$I(t)$ : Current at time  $t$ .

$$I(t) = \frac{dQ}{dt}$$

$$E(t) = L\ddot{Q} + R\dot{Q} + \frac{1}{C}Q$$

Example :

Find  $Q(t)$  and Current ( $I(t)$ ) at time  $t$

if  $R = 40\Omega$ ,  $L = 1H$ ,  $C = 16 \times 10^{-4} F$ ,

$E(t) = 100 \cos 10t$  and initial Charge and Current are both zero.

$$1\ddot{Q} + 40\dot{Q} + \frac{1}{1.6 \times 10^{-4}} Q = 100 \cos 10t$$

$$\ddot{Q} + 40\dot{Q} + 625Q = 100 \cos 10t$$

$$r^2 + 40r + 625 = 0$$

$$r = -20 \pm \sqrt{1600 - 2500}$$

$$r = -20 \pm 15i$$

$$Q(t) = e^{-20t} (C_1 \cos 15t + C_2 \sin 15t)$$

Next, find  $Q_p(t)$

Guess

No Dope!

$$Q_p(t) = A \cos \omega t + B \sin \omega t$$

$$\dot{Q}_p(t) = -10A \sin \omega t + 10B \cos \omega t$$

$$\ddot{Q}_p(t) = -100A \cos \omega t - 100B \sin \omega t$$

Plug into

$$Q''_p + 40Q'_p + 625Q_p$$

= ...

=

$$(525A + 400B) \cos \omega t + (-400A + 525B) \sin \omega t = 100 \cos \omega t$$

Determine  $A, B$ :

cos:

$$525A + 400B = 100$$

sin:

$$-400A + 525B = 0$$

$$A = \frac{84}{697}$$

$$B = \frac{64}{697}$$

$$Q_p(t) = \frac{84}{697} \cos \omega t + \frac{64}{697} \sin \omega t$$

So:

$$Q(t) = \frac{84}{697} \cos(\omega t) + \frac{64}{697} \sin(\omega t) + e^{-2\omega t} (C_1 \cos(\omega t) + C_2 \sin(\omega t))$$

Apply IC's

$$Q(0) = 0, I(0) = 0$$

$$\hookrightarrow Q'(0) = 0$$

$$Q(0) = (C_1 + 0) + \frac{84}{697} + 0 = 0, C_1 = -\frac{84}{697}$$

$$Q'(0) = \dots = -2\omega C_1 + 15C_2 + \frac{64\omega}{697} = 0$$

$$C_2 = -\frac{464}{2091}$$

$$Q(t) = \frac{84}{697} \cos(\omega t) + \frac{64}{697} \sin(\omega t) + e^{-2\omega t} \left( \frac{-464}{2091} \cos(\omega t) + \frac{-84}{697} \sin(\omega t) \right)$$

Steady State Solution

(Always sticks around)

Transient Solution

(eventually goes away)