Contact

Ali Jahani Amiri

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Youtube Channel

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Education

2016- now M.Sc. in Computer Science

University of Alberta, Canada

GPA: 3.9/4 Expected Gradutation Date: Jan, 2018

Thesis: "Deep Learning in Simultaneous Localization and Mapping"

Improving accuracy of the state-of-art SLAM using semi-supervised single

image depth estimation neural networks"

Supervisor: Prof. Hong Zhang

2011 - 2016 B.Sc. in Electrical Engineering

University of Tehran, Iran

GPA: 15.59/20

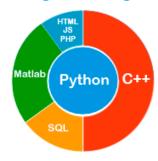
Thesis: "Real-time Video Stabilization and Mosaicing".

Implementing a framework in C++ using OpenCV to stabilize the video stream

by mosaicing

Supervisor: Dr. Hadi Moradi

Programming



Technologies

Tensorflow, Caffe, ROS, Unreal Engine4, OpenCV, OpenGL, Wireshark, Linux, Windows

Voluntary

IROS 2017 Conference

Al-Gl-CRV 2017 Conference

Leader of our convocation video clips team

Hobbies

Dancing, Chess, Playing Video Games

Publications

2018 SY Loo, A Jahani, S Mashohor, SH Tang and H Zhang

CNN-SVO: Improving the Mapping in Semi-Direct Visual Odometry Using

Single-Image Depth Prediction submitted to ICRA 2019

2016 A Jahani, H Moradi

Real-time video stabilization and mosaicking for monitoring and surveillance 2016 4th International Conference on *Robotics and Mechatronics (ICROM)*,

613-618

Certificates

11/18	Structuring Machine Learning Projects	deeplearning.ai on Coursera
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01/18 Convolutional Neural Networks deeplearning.ai on Coursera

12/17 Improving Deep Neural Networks: Hyperparameter tuning, Regulariza-

tion and Optimization deeplearning.ai on Coursera

12/17 **Neural Networks and Deep Learning** deeplearning.ai on Coursera

Work Experience

11/17 - 09/18 **3D Game Developer Intern**

vrCAVE Inc., Canada

Implemented an rule-based AI and automated hint system using Unreal Engine 4 in the Multiplayer Virtual Reality escape room game. We used agile

methodology and GIT

09/16 - Now **Teaching Assistant**

University of Alberta, Canada

Introduction to Computing Science

05/17 - 08/17 Research Assistant

CIMS LAB

Integrating deep learning methods with current state of art of Simultaneous Localization and Mapping(SLAM)

Notable Projects

Winter 2017	2D Grid Mapping and Navigation using Monocular Ca Improving state of art ORBSLAM 2 framework for navigareal-time	
Winter 2017	Direct Sparse Odometry vs ORB-SLAM Comparing direct and indirect methods in Simultaneou mapping algorithms	Computer Vision us Localization and
Fall 2016	Image Segmentation of Choroideremia Disease Implementing machine learning algorithms such as SV Deep Neural Networks for pixelwise classification of retin	
Fall 2016	3D Animation and Model Viewer Implementing an animation loader using C++ and OpenC	Computer Graphics
Fall 2015	2D Prison Break Game Implementing a 2D game using SDL in C++	Advanced Programming