

## Contact

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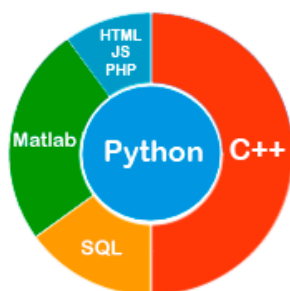
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## Programming



## Technologies

Tensorflow, Keras,  
Caffe, ROS,  
Unreal Engine4,  
OpenCV, OpenGL,  
Scikit-learn, GIT,  
Power BI, Plotly

## Voluntary

IROS 2017  
Conference

AI-GI-CRV 2017  
Conference

Leader of our  
convocation video clips  
team

## Hobbies

Dancing, Swimming,  
Playing Video Games

# Ali Jahani Amiri

## Education

- 2016- now **M.Sc. in Computer Science** [University of Alberta, Canada](#)  
GPA: 3.9/4 Expected Graduation Date: **June, 2018**  
*Thesis: "Semi-Supervised Monocular Depth Estimation with Left-Right Consistency Using Deep Neural Network"*  
*Improving accuracy of the state-of-art single image depth estimation by 3%. We used LiDAR (as supervised) and stereo images (as unsupervised) simultaneously in our training using **Tensorflow**."*  
*Supervisor: Prof. Hong Zhang*
- 2011 - 2016 **B.Sc. in Electrical Engineering** [University of Tehran, Iran](#)  
GPA: 15.59/20  
*Thesis: "Real-time Video Stabilization and Mosaicing".*  
Implementing a framework in C++ using OpenCV to stabilize the video stream by mosaicing  
*Supervisor: Dr. Hadi Moradi*

## Publications

- 2019 **A Jahani, SY Loo, and H Zhang**  
Semi-Supervised Monocular Depth Estimation with Left-Right Consistency Using Deep Neural Network  
*submitted to IROS 2019*
- 2018 **SY Loo, A Jahani, S Mashohor, SH Tang, and H Zhang**  
CNN-SVO: Improving the Mapping in Semi-Direct Visual Odometry Using Single-Image Depth Prediction  
*ICRA 2019*
- 2016 **A Jahani, H Moradi**  
Real-time video stabilization and mosaicking for monitoring and surveillance  
2016 4th International Conference on *Robotics and Mechatronics (ICROM)*, 613-618

## Work Experience

- 01/19 - Now **Research Assistant** [Robotics-vision Lab, UoA](#)  
Applying **conditional generative adversarial networks** for semi-supervised single image depth estimation framework  
3D reconstruction of the environment using deep learning and Simultaneous Localization and Mapping (SLAM) for polarized cameras (Funded by Huawei)
- 11/17 - 09/18 **3D Game Developer Intern** [vrCAVE Inc., Edmonton](#)  
Implemented a **rule-based AI** and automated/manual in-game hint system using Unreal Engine 4 in Multiplayer Virtual Reality escape room games. We used **agile methodology** and **GIT**
- 09/16 - 12/18 **Teaching Assistant** [UoA](#)  
Introduction to Computing Science
- 05/17 - 08/17 **Research Assistant** [Robotics-vision Lab, UoA](#)  
Integrating deep learning methods with current state of art of Simultaneous Localization and Mapping (SLAM)

## Certificates

11/18	<b>Structuring Machine Learning Projects</b> <a href="#">deeplearning.ai on Coursera</a> Learned to diagnose error and prioritize the most promising direction for error reduction
01/18	<b>Convolutional Neural Networks</b> <a href="#">deeplearning.ai on Coursera</a> Built a convolutional neural network, including recent variations e.g. residual networks.
12/17	<b>Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization</b> <a href="#">deeplearning.ai on Coursera</a> Learned to effectively use initialization, L2 and dropout regularization, batch normalization Learned about different optimization algorithms, e.g. gradient descent, Momentum, RMSprop and Adam
12/17	<b>Neural Networks and Deep Learning</b> <a href="#">deeplearning.ai on Coursera</a> Implemented fully connected deep neural networks and backpropagation

## Notable Projects

March 2019	<b>Crop Growth Stage Classification</b> <a href="#">Finalist Group @ATB DATATHON, Edmonton</a> Developed a real-time deep neural network to classify the growth stages of the crop using <b>Keras</b> and <b>Tensorflow</b> to help farmers, and performed a live demo on the stage.
Winter 2017	<b>2DGrid Mapping and Navigation using Monocular Camera</b> <a href="#">Robotics Course</a> Improved state of art ORBSLAM 2 framework for navigation tasks in C++ in real-time
Winter 2017	<b>Direct Sparse Odometry vs ORB-SLAM</b> <a href="#">Computer Vision Course</a> Compared direct and indirect methods in Simultaneous Localization and mapping algorithms
Fall 2016	<b>Image Segmentation of Choroideremia Disease</b> <a href="#">Machine Learning Course</a> Implemented machine learning algorithms such as <b>SVM</b> , <b>Random Forest</b> , <b>Deep Neural Network (UNet)</b> for pixelwise classification of retina images
Fall 2016	<b>3D Animation and Model Viewer</b> <a href="#">Computer Graphics Course</a> Implemented an animation loader using C++ and OpenGL
Fall 2015	<b>2D Prison Break Game</b> <a href="#">Advanced Programming Course</a> Implemented a 2D game using SDL in C++