

# Math 135 Homework 6

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## 1. 19.1

Prove that, if  $p \neq q$ , then  $e^{px}$  and  $e^{qx}$  are linearly independent.

*Proof.* For a contradiction, assume that  $p \neq q$  and  $e^{px}$  and  $e^{qx}$  are linearly dependent and therefore satisfy

$$c_1 e^{px} + c_2 e^{qx} = 0 \quad (*)$$

for all  $x$  and  $c_1$  and  $c_2$  not both zero.

Assume that  $c_2 \neq 0$ .

Then,

$$\begin{aligned} c_1 e^{px} &= -c_2 e^{qx} \\ -\frac{c_1}{c_2} &= e^{(q-p)x}. \end{aligned}$$

But  $q - p \neq 0$  so  $e^{(q-p)x}$  cannot be constant for all  $x$ .

Therefore the assumption that  $e^{px}$  and  $e^{qx}$  were linearly dependent when  $p \neq q$  was false.

Thus, by contraction,  $e^{px}$  and  $e^{qx}$  are linearly independent when  $p \neq q$ .

Then,  $e^{(q-p)x} \neq 1$ .

So,  $e^{(q-p)x} \neq 1^x = 1$  cannot be constant for all  $x$ .

So,  $e^{(q-p)x} \neq c$  where  $c = -\frac{c_1}{c_2}$  such that  $c_2 \neq 0$ .

Then,

$$\begin{aligned} -\frac{c_1}{c_2} &\neq e^{(q-p)x} \\ -c_1 e^{px} &\neq c_2 e^{qx} \\ 0 &\neq c_1 e^{px} + c_2 e^{qx}. \end{aligned}$$

□

**19.2**

Prove that  $e^{ax}$  and  $xe^{ax}$  are linearly independent.

*Proof.* For a contradiction, assume that  $e^{ax}$  and  $xe^{ax}$  are linearly dependent.

Assume that  $c_2 \neq 0$ .

Then

$$c_1 e^{ax} + c_2 x e^{ax} = 0$$

for all  $x$ .

Since  $e^{ax} \neq 0$  for all  $x$ , then

$$c_1 + c_2 x = 0.$$

So

$$x = -\frac{c_1}{c_2}.$$

But, this statement cannot hold for all  $x$ .

So, the assumption that  $e^{ax}$  and  $xe^{ax}$  was false, therefore the two equations are linearly independent.  $\square$

**2. 20.24**

Find the general solution  $y'' - y' + y = 0$ .

The characteristic equation of this differential equation is

$$r^2 - r + 1 = 0.$$

This equation has roots

$$r = \frac{1 \pm \sqrt{3}i}{2}.$$

So, the general solution to the homogeneous equation is

$$y = e^{t/2} \left( c_1 \cos \frac{\sqrt{3}}{2} t + c_2 \sin \frac{\sqrt{3}}{2} t \right).$$

**3. 21.30**

Find the general solution to  $y''' - 2y'' + y' = 2e^x + 2x$  with the initial conditions  $y(0) = y'(0) = y''(0) = 0$ .

Then, via the characteristic equation, the homogeneous solution is

$$y_h = c_1 e^x + c_2 x e^x + c_3$$

Since the characteristic equation contains a root of degree two and the non-homogeneous equation contains an  $e^x$  term, the form of the particular solution is given by two degrees above the highest

degree present in the homogeneous solution,

$$y_p = A + Bx + Cx^2 + Ex^2e^x + Fx^3e^x.$$

Then, we also have

$$u'_p = B + 2Cx + (Ex^2 + 2Ex)e^x + (Fx^3 + 3Ex^2)e^x,$$

and

$$u''_p = 2C + (Ex^2 + 4Ex + 2x)e^x + (Fx^3 + 6Fx^2 + 6Fx)e^x.$$

Then,

$$\begin{aligned} u''_p - 2u'_p + u_p &= 2e^x + 2x \\ A + Bx + Cx^2 - 2B - 4Cx + 2C + 2Ee^x + 5Fxe^x &= 2e^x + 2x \\ (A - 2B + 2C) + (B - 4C)x + Cx^2 + 2Ee^x + 5Fxe^x &= 2e^x + 2x. \end{aligned}$$

The system of equations yields<sup>1</sup>...

The initial conditions reveal the final solution<sup>2</sup>...

So

$$y = x^2 + 4x + 4 + (x^2 - 4)e^x.$$

#### 4. 22.18

Use variation of parameters to find the general solution to

$$x^2y'' + xy' - 4y = x^3$$

given that  $y_1 = x^2$  and  $y_2 = x^{-2}$ .

The homogeneous solution is

$$y_h = c_1x^2 + c_2x^{-2}.$$

We will place the differential equation into standard form,

$$y'' + x^{-1}y' - 4x^{-2}y = x.$$

Let  $g(x) = x$ .

Then,  $y_p = u_1y_1 + u_2y_2$  where

$$\begin{aligned} u_1 &= \int \frac{-u_2g(x)}{W(y_1, y_2)} dx, \\ u_2 &= \int \frac{u_1g(x)}{W(y_1, y_2)} dx. \end{aligned}$$

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<sup>1</sup>Did not have time to finish typing up the solution.

<sup>2</sup>Same as above.

First, we compute the Wronskian of the two solutions,

$$\begin{aligned} W(x^2, x^{-2}) &= \begin{vmatrix} x^2 & x^{-2} \\ 2x & -2x^{-3} \end{vmatrix} \\ &= -2x^{-1} - 2x^{-1} \\ &= -4x^{-1}. \end{aligned}$$

So,

$$\begin{aligned} u_1 &= \int \frac{-x^{-2} \cdot x}{-4x^{-1}} dx = \frac{1}{4} \int dx = \frac{x}{4}, \\ u_2 &= \int \frac{x^2 \cdot x}{-4x^{-1}} dx = -\frac{1}{4} \int x^4 dx = -\frac{x^5}{20}. \end{aligned}$$

Assembling  $y_p$ , we obtain,

$$\begin{aligned} y_p &= \frac{x}{4}x^2 - \frac{x^5}{20}x^{-2} \\ &= \frac{x^3}{4} - \frac{x^3}{20} \\ &= \frac{5x^3 - x^3}{20} \\ &= \frac{x^3}{5}. \end{aligned}$$

Thus,

$$y = c_1x^2 + c_2x^{-2} + \frac{x^3}{5}.$$

## 5. 23.16

Find the general solution to  $x^2y'' - 2y = 2x^2$  given  $y_1 = x^2$ .

We proceed using the method of reduction of order.

With the form  $f_2(x)y'' + f_1(x)y' + f_0(x)y = 0$  from TP 23.14, we see that  $f_2(x) = x^2$ ,  $f_1(x) = 0$  and  $f_0(x) = -2$ .

Then, by TP 23.28,

$$y_2 = y_1 \int \frac{e^{-\int \frac{f_1(x)}{f_2(x)} dx}}{y_1^2} dx.$$

So, with  $y_1 = x^2$ ,

$$\begin{aligned} y_2 &= x^2 \int \frac{e^{-\int \frac{0}{x^2} dx}}{x^4} dx \\ &= x^2 \int \frac{dx}{x^4} \\ &= x^2 \frac{1}{-3x^3} \\ &= \frac{1}{-3x}. \end{aligned}$$

We construct the homogeneous solution with this  $y_2$ ,

$$y_h = c_1 x^2 + c_2 x^{-1}.$$

Then, we place the differential equation into standard form,

$$y'' - 2x^{-2}y = 2$$

and proceed with the technique of variation of parameters.

Let  $y_1 = x^2$ ,  $y_2 = x^{-1}$ , and  $g(x) = 2$ .

Then,

$$y_p = u_1 y_1 + u_2 y_2$$

where

$$\begin{aligned} u_1 &= \int \frac{-u_2 g(x)}{W(y_1, y_2)} dx, \\ u_2 &= \int \frac{u_1 g(x)}{W(y_1, y_2)} dx. \end{aligned}$$

First, we compute the Wronskian of the two solutions found in the homogeneous solution,

$$\begin{aligned} W(x^2, x^{-1}) &= \begin{vmatrix} x^2 & x^{-1} \\ 2x & -x^{-2} \end{vmatrix} \\ &= -x^2 \cdot x^{-2} - 2x \cdot x^{-1} \\ &= -1 - 2 \\ &= -3. \end{aligned}$$

Then, we compute  $u_1$ ,

$$\begin{aligned} u_1 &= \int \frac{-x^{-1} \cdot 2}{-3} dx \\ &= \frac{2}{3} \int \frac{dx}{x} \\ &= \frac{2}{3} \ln x. \end{aligned}$$

Similarly, we compute  $u_2$

$$\begin{aligned} u_2 &= \int \frac{x^2 \cdot 2}{-3} dx \\ &= -\frac{2}{9}x^3. \end{aligned}$$

So, we combine to get,

$$y_p = \frac{2}{3}x^2 \ln x - \frac{2}{9}x^2.$$

When combining  $y_h$  and  $y_p$ , we see that  $y_h$  already contains an arbitrary constant for an  $x^2$  term, so we only need to consider the  $\frac{2}{3}x^2 \ln x$  part of the particular solution.

Thus, our general solution is,

$$y = c_1x^2 + c_2x^{-1} + \frac{2}{3}x^2 \ln x.$$

6. Suppose that  $y_1$  and  $y_2$  form the fundamental set of solutions to

$$y'' + p(t)y' + q(t)y = 0 \tag{*}$$

on  $t \in \mathbb{R}$  such that  $p, q$  continuous for all  $t$ .

Prove that there is only one zero of  $y_1$  between two consecutive zeros of  $y_2$ .

*Proof.* Assume  $y_1$  and  $y_2$  form the fundamental set of solutions to (\*).

Since  $y_1$  and  $y_2$  form the fundamental set of solutions to the differential equation (\*), then they are twice differentiable, linearly independent, and their Wronskian is non-zero for all  $t$ .

$$0 \neq W(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_1' y_2.$$

For a contradiction, assume that there is no zero of  $y_1$  between two consecutive zeros of  $y_2$ .

Define  $c_1, c_2$  as consecutive roots of  $y_2$  such that  $y_2(c_1) = y_2(c_2) = 0$ .

Let  $I = [c_1, c_2]$ .

Then, by the assumption,  $y_1(t) \neq 0$  for all  $t \in I$ .

Let  $f(t) = \frac{y_2(t)}{y_1(t)}$ .

Since  $y_2(c_1) = y_2(c_2) = 0$ , then  $f(c_1) = f(c_2) = 0$ .

Since  $y_1(t) \neq 0$ ,  $\forall t \in I$ , then  $f(t)$  is continuous for all  $t \in I$ .

So, there exists an  $a \in (c_1, c_2)$  such that  $f'(a) = 0$  by Rolle's Theorem.

Then, with

$$f'(t) = \frac{d}{dt} \left[ \frac{y_2(t)}{y_1(t)} \right] = \frac{y_2' y_1 - y_2 y_1'}{y_1^2},$$

we see that

$$0 = f'(a) = \frac{y_2'(a)y_1(a) - y_2(a)y_1'(a)}{y_1^2(a)}.$$

But  $y_1 \neq 0$ ; so,

$$0 = y_2'(a)y_1(a) - y_2(a)y_1'(a),$$

which is the Wronskian of  $y_1$  and  $y_2$  evaluated at  $t = a$ .

But  $y_1$  and  $y_2$  form the fundamental set of solutions to (\*) and therefore their Wronskian is never zero by the assumption.

So, the statement that  $y_1$  has no zero between  $c_1$  and  $c_2$  is false.

So, by contradiction,  $y_1$  must have at least one zero between the two consecutive zeros of  $y_2$  at  $c_1$  and  $c_2$ .

Then, for a contraction, assume that  $y_1$  has more than one zero between two consecutive zeros of  $y_2$ . This statement is equivalent to stating that  $y_2$  has no zeros between two consecutive zeros of  $y_2$ .

We will repeat the above part of the proof by defining the utility function  $g(t) = \frac{y_1(t)}{y_2(t)}$ .

Let  $J = [b_1, b_2]$

So, by the assumption, there exists  $b_1, b_2$  such that  $y_1(b_1) = y_1(b_2) = 0$ .

Then, by the assumption,  $y_2(t) \neq 0$  for all  $t \in J$ .

So,  $g$ , the quotient of two continuous functions, whose denominator is not zero, is continuous.

Since  $g(b_1) = g(b_2) = 0$  and  $g$  continuous, then there exists a  $k \in J$  such that  $g'(k) = 0$  by Rolle.

Then, with

$$g'(t) = \frac{y_1' y_2 - y_1 y_2'}{y_2^2},$$

$$0 = g'(k) = \frac{y_1'(k)y_2(k) - y_1(k)y_2'(k)}{y_2^2(k)}.$$

But  $y_2 \neq 0$ ; so,

$$0 = y_1'(k)y_2(k) - y_1(k)y_2'(k),$$

which is the Wronskian of  $y_1$  and  $y_2$  evaluated at  $t = k$ .

But, the Wronskian of  $y_1$  and  $y_2$  is never zero by the assumption that they form the fundamental set of solutions.

So  $W(y_1(k), y_2(k)) = 0$  is a contradiction.

Thus  $y_1$  has no more than one zero between two consecutive zeros of  $y_2$ .

Since  $y_1$  has at least one zero and no more than one zero between two consecutive zeros of  $y_2$ , then  $y_1$  has exactly one zero between two consecutive zeros of  $y_2$ .

□

7. Let  $y_1$  and  $y_2$  be solutions to

$$y'' + py' + qy = 0 \quad (*)$$

where  $p, q$  continuous on  $I = (a, b)$ .

Show that if there is a point in  $I$  where  $y_1$  and  $y_2$  are both zero or where both have maxima or minima, then  $y_1$  and  $y_2$  are linearly dependent.

We will show that there exists a  $c \in I$  such that, if either

$$y_1(c) = y_2(c) = 0, \quad (a)$$

or

$$y_1'(c) = y_2'(c) = 0 \quad (a)$$

and  $y_1''(c) \neq 0$  and  $y_2''(c) \neq 0$ , then  $y_1$  and  $y_2$  are linearly dependent.

For a contradiction, assume that  $y_1$  and  $y_2$  are linearly independent solutions to (\*).

So, the Wronskian of  $y_1$  and  $y_2$  is non zero for all  $t \in I$ .

$$0 \neq W(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_1' y_2.$$

Then, for case (a),

$$y_1(c) = y_2(c) = 0$$

implies that

$$y_1(c)y_2'(c) - y_1'(c)y_2(c) = 0.$$

But,

$$y_1 y_2' - y_1' y_2 \neq 0$$

for all  $t \in I$  by the assumption that the solutions  $y_1$  and  $y_2$  were linearly independent.

Therefore  $y_1$  and  $y_2$  are linearly dependent and also constant multiples of each other.

Next, for case (b),

$$y_1'(c) = y_2'(c) = 0$$

implies that

$$y_1(c)y_2'(c) - y_1'(c)y_2(c) = 0.$$

But, this contradicts the assumption of the linear independence of the solutions.

The non-zero second derivative condition was not necessary.

So, we have shown that if there exists a  $c$  such that the solutions are both zero at  $c$ , or both attain a critical point at  $c$ , then the two solutions are linearly dependent and therefore constant multiples of one another.