

Demystifying Artificial Intelligence Sorcery

(Part 3: Deep Learning)^a

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^aAvailable @ <https://github.com/a-mhamdi/jlai/>



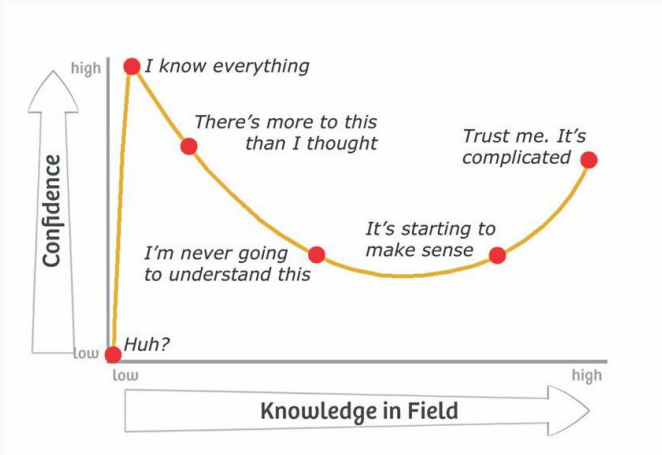
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DUNNING-KRUGER EFFECT



Kruger, J. and Dunning, D. (1999) *Unskilled and unaware of it: How difficulties in recognizing one's own incompetence lead to inflated self-assessments*. **J Pers Soc Psychol.** 77(6) pp. 1121–1134.

“Knowledge isn’t free. You have to pay attention.”

Richard P. Feynman



ROADMAP

1. An overview
2. CNN, VAE, GAN & NLP
3. Transfer Learning
4. Reinforcement Learning
5. Responsible AI
6. Quizzes
7. Azure AI Fundamentals

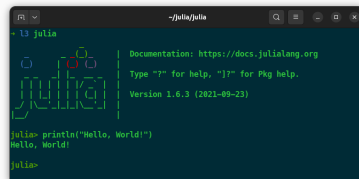
An overview

- CNNs** (*Convolutional Neural Networks*) are used for image classification and other computer vision tasks because they are able to automatically learn features from raw data. This is useful for tasks where manual feature engineering is difficult or impractical.
- VAEs** (*Variational Autoencoders*) are used for tasks such as image generation and anomaly detection because they are able to learn a compact representation of a dataset and generate new samples from this representation.
- GANs** (*Generative Adversarial Networks*) are used for tasks such as image generation and data augmentation because they are able to generate new data samples that are similar to a given dataset.
- NLP** (*Natural Language Processing*) is important for tasks such as language translation, text classification, and language generation because it allows computers to process and understand human language.



REMINDER

PROGRAMMING LANGUAGE

julia-lang.org/

DEVELOPMENT ENVIRONMENTS



Pluto.jl 

The Pluto.jl logo consists of the text "Pluto.jl" in a bold, black, sans-serif font, followed by three stacked circles in green, purple, and red.

▲ \$ docker compose up

▼ \$ docker compose down



JULIA IN A NUTSHELL

- ▲ **Fast:** native code for multiple platforms via LLVM;
- ▲ **Dynamic:** good support for interactive use (*like a scripting language*);
- ▲ **Reproducible:** environment recreation across platforms, with pre-built binaries;
- ▲ **Composable:** multiple dispatch as a paradigm (*oop & functional programming*);
- ▲ **General:** asynchronous I/O, metaprogramming, debugging, logging; profiling, pkg, ...
- ▲ **Open Source:** GitHub repository at <https://github.com/JuliaLang/julia>.



JULIA MICRO-BENCHMARKS (1/2)



<https://julialang.org/benchmarks>



JULIA MICRO-BENCHMARKS (2/2)

Geometric Means¹ of Micro-Benchmarks by Language

1	C	1.0
2	Julia	1.17006
3	LuaJIT	1.02931
4	Rust	1.0999
5	Go	1.49917
6	Fortran	1.67022
7	Java	3.46773
8	JavaScript	4.79602
9	Matlab	9.57235
10	Mathematica	14.6387
11	Python	16.9262
12	R	48.5796
13	Octave	338.704



¹Measure of central tendency expressed as $(x_1 \times x_2 \times \dots \times x_n)^{1/n}$



SOURCE CONTROL MANAGEMENT (SCM)

The screenshot shows the GitHub repository page for 'a-mhamdi/jlail'. The repository is public and has 2 stars and 3 forks. The main branch is 'main'. The repository contains a file tree with the following files and their commit dates:

File	Commit Message	Commit Date
.github/workflows	Update docker-image.yml	2 weeks ago
Codes	vgg and resnet transfer learning	yesterday
Docker	rm Docker cheat sheet	3 days ago
Exams	exam w/ answers	4 days ago
Slides-Labs	change colors	yesterday
.gitignore	change colors	yesterday
LICENSE	Initial commit	4 months ago
README.md	update Docker README file	2 weeks ago

The repository is titled 'An Introduction to Artificial Intelligence with Julia'. It includes a Readme, MIT license, 2 stars, 2 watching, and 3 forks. The languages section shows the following distribution:

Language	Percentage
Julia	94.3%
Dockerfile	3.4%
Batchfile	2.1%
TeX	0.2%

<https://github.com/a-mhamdi/jlail>



CONTINUOUS INTEGRATION (CI)


abmhamdi/jlai-p3 - Docker Image | Docker Hub - Brave

abmhamdi/jlai-p3 - Docker Image | Docker Hub - Brave

hub.docker.com/r/abmhamdi/jlai-p3

dockerhub Explore Repositories Organizations Usage Search Dock... [ctrl+K]

Explore / abmhamdi/jlai-p3

 **abmhamdi/jlai-p3**

By [abmhamdi](#) · Updated 1 minute ago

Artificial Intelligence Labs - Part 3 @ ISETBZ

[IMAGE](#)

[DATA SCIENCE](#) [LANGUAGES & FRAMEWORKS](#) [MACHINE LEARNING & AI](#)

☆0 ↓ 11

[Manage Repository](#)

Overview Tags

Deep Learning with Julia

This repository contains slides, labs and code examples for using [Julia](#) to implement some [artificial intelligence](#) related algorithms. Codes run on top of a [Docker](#) image, ensuring a consistent and reproducible environment.

Docker Pull Command

```
docker pull abmhamdi/jlai-p3
```

[Copy](#)

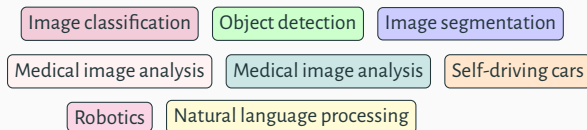
<https://hub.docker.com/r/abmhamdi/jlai-p3>

CNN, VAE, GAN & NLP

CNN

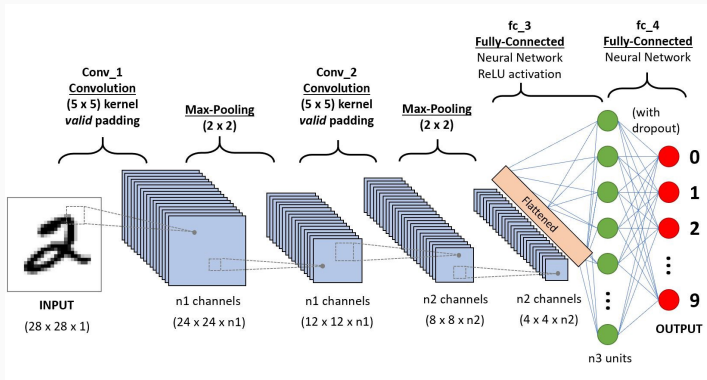
MOTIVATING FACTORS & USE CASES

- ▶ A **Convolutional Neural Network (CNN)** is a type of neural network that is particularly well-suited for image classification and object recognition tasks. It is designed to process data with a grid-like topology, such as an image.
- ▶ **CNNs** are composed of several types of layers, including convolutional layers, pooling layers, and fully connected layers:
 - ❶ The **convolutional layers** apply filters to the input data, which are used to detect patterns and features in the data.
 - ❷ The **pooling layers** reduce the spatial dimensions of the data, which helps to reduce the complexity of the model and make it more robust to small translations of the input data.
 - ❸ The **fully connected layers** combine the features learned by the convolutional and pooling layers to make a prediction.



CNN

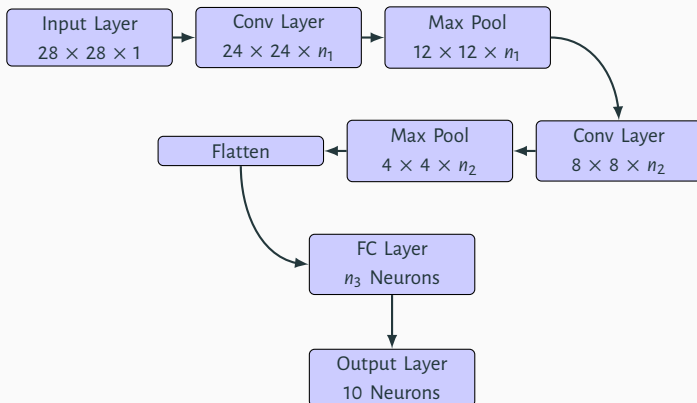
ARCHITECTURE

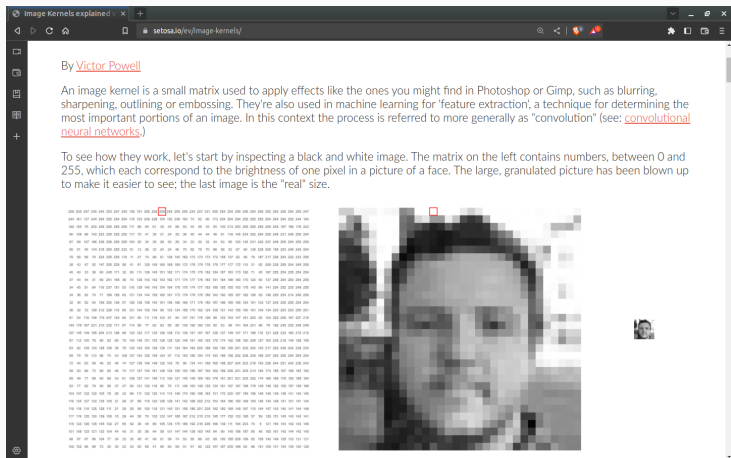


► Source

CNN

PIPELINE





<https://setosa.io/ev/image-kernels/>

CNN

WHAT IS PADDING

- ▶ involves adding extra pixels around the border of an image;
- ▶ prevents the shrinking of the input image;
- ▶ preserves information on the border.

$$\text{output_shape} = \frac{\text{input_shape} + 2 \times \overbrace{\text{padding}}^p - \overbrace{\text{filter_size}}^k}{\underbrace{\text{stride}}_s} + 1$$

Let's consider $s = 1$, which means that the filter moves one pixel at a time:

valid: ($p = 0$) no padding at all

$$\text{output_shape} = \text{input_shape} - k + 1$$

same: $\left(p = \frac{(k-1)}{2} \text{ \& } k \text{ is odd} \right)$ the output is the same dimension as the input

$$\text{output_shape} = \text{input_shape}$$

CNN

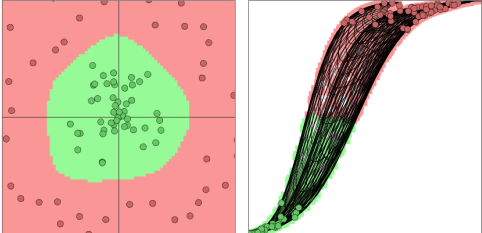
CONVNETJS DEMO

ConvNetJS demo: Classifi...

cs.stanford.edu/people/karpathy/convnetjs/demo/classify2d.html

Feel free to change this, the text area above gets eval()'d when you hit the button and the network gets reloaded. Every 10th of a second, all points are fed to the network multiple times through the trainer class to train the network. The resulting predictions of the network are then "painted" under the data points to show you the generalization.

On the right we visualize the transformed representation of all grid points in the original space and the data, for a given layer and only for 2 neurons at a time. The number in the bracket shows the total number of neurons at that level of representation. If the number is more than 2, you will only see the two visualized but you can cycle through all of them with the cycle button.



simple data circle data spiral data random data

Controls:
 CLICK: Add red data point
 SHIFT+CLICK: Add green data point
 CTRL+CLICK: Remove closest data point

Go [back to ConvNetJS](https://cs.stanford.edu/people/karpathy/convnetjs/)

drawing neurons 0 and 1 of layer with index 4 (tanh)

fc(6) tanh(6) fc(2) **tanh(2)**

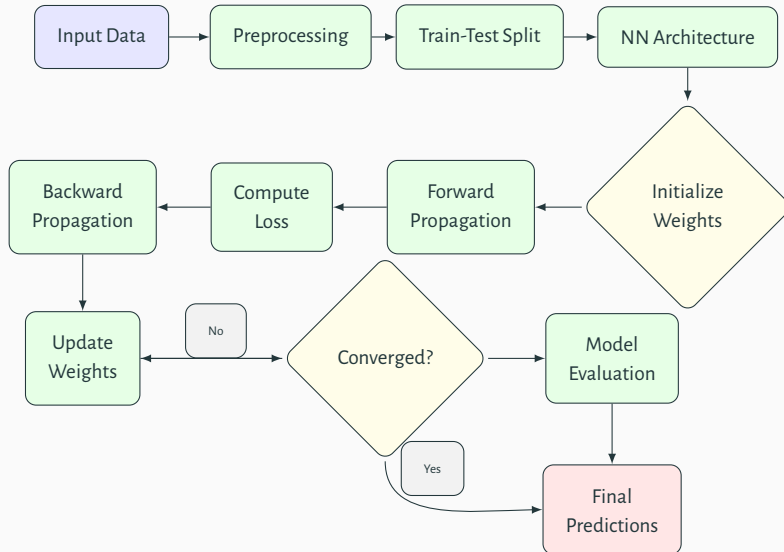
fc(2)

cycle through visualized neurons at selected layer (if more than 2)

<https://cs.stanford.edu/people/karpathy/convnetjs/demo/classify2d.html>

CNN

NEURAL NETWORK LEARNING ALGORITHM



CNN

CNN EXPLAINER



<https://poloclub.github.io/cnn-explainer/>

CNN



The code is available @ github.com/a-mhamdi/jlai → *Codes* → *Julia* → *Part-3*

→ *cnn* → *cnn.jl*

Pluto.jl 

→ *cnn* → *cnn.ipynb*



VAE

MOTIVATING FACTORS & USE CASES

- ▶ A **Variational Autoencoder (VAE)** is a type of deep learning model that is used to learn latent representations of data. It is a generative model, which means that it can generate new samples of data that are similar to the training data.
- ▶ **VAEs** are trained to encode the data into a low-dimensional latent space and then decode the latent representation back into the original data space. During training, the **VAE** learns to reconstruct the input data, while also trying to enforce a constraint on the latent space that encourages it to represent the data in a meaningful way.
- ▶ The constraint that is used in a **VAE** is called the variational lower bound. This lower bound is maximized during training, which encourages the latent space to be structured in a way that is useful for generating samples that are similar to the training data.

Generative modeling

Anomaly detection

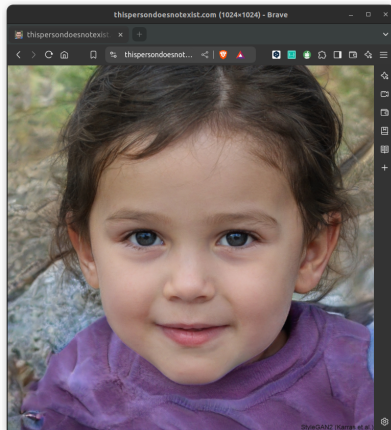
Data compression

Representation learning

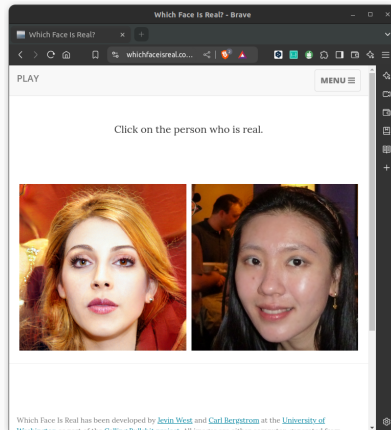
Semi-supervised learning

VAE

DEMOS



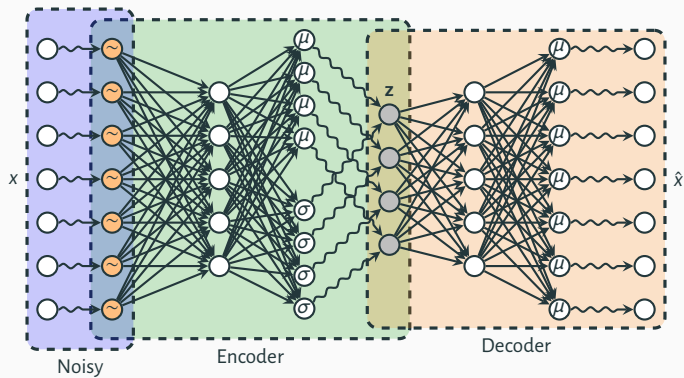
<https://thispersondoesnotexist.com/>



<https://www.whichfaceisreal.com>

VAE

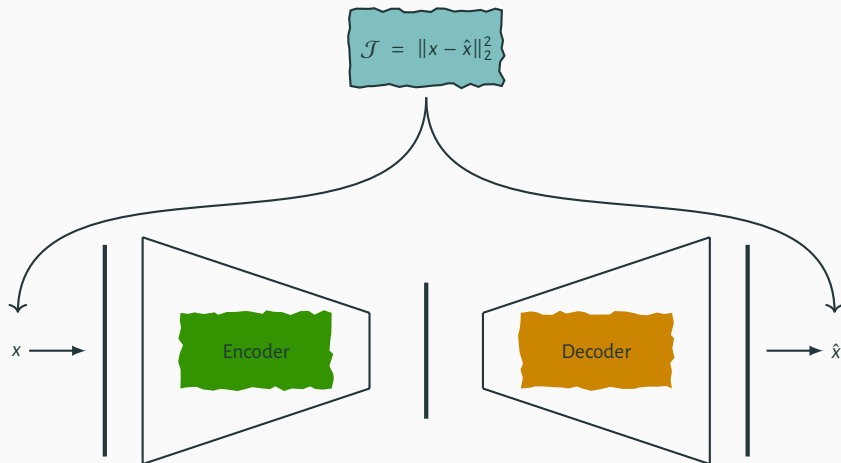
ARCHITECTURE OF VARIATIONAL AUTOENCODER



VAE

LOSS OF VANILLA AUTOENCODER

MINIMIZE SQUARED ERROR LOSS



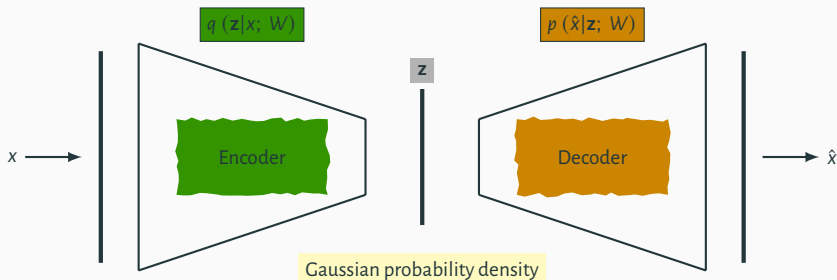
VAE

LOSS OF VARIATIONAL AUTOENCODER

$$\mathcal{J} = - \mathbb{E}_{\mathbf{z} \sim q(\mathbf{z}|\mathbf{x}^{(i)}; W)} \left[\log p(\hat{\mathbf{x}}^{(i)} | \mathbf{z}; W) \right] + \mathcal{KL} \left(q(\mathbf{z}|\mathbf{x}^{(i)}; W) \parallel p(\mathbf{z}) \right)$$

Expected negative log likelihood term wrt to encoder distribution

Kullback-Leiber divergence term where $p(\mathbf{z}) \sim \mathcal{N}(\mu = 0, \sigma^2 = 1)$



VAE

 \mathcal{KL} LOSS DERIVATION

In a VAE, the latent vector \mathbf{z} is calculated by:

$$\mathbf{z} = \mu + \sigma \odot \epsilon \quad \text{where } \epsilon \sim \mathcal{N}(0_{\mathbf{z}}, \mathbb{1}_{\mathbf{z} \times \mathbf{z}})$$

μ and σ denote respectively the mean and variances for the latent vector \mathbf{z} . The encoder learns to output the two vectors $\mu \in \mathbb{R}^z$, and $\sigma \in \mathbb{R}^z$. The encoder distribution is

$$q(\mathbf{z} | x^{(i)}) = \mathcal{N}(\mathbf{z} | \mu(x^{(i)}), \Sigma(x^{(i)})) \quad \text{where } \Sigma = \begin{bmatrix} \sigma_1^2 & 0 & 0 & \cdots \\ 0 & \sigma_2^2 & 0 & \cdots \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_l^2 \end{bmatrix}$$

The latent prior is given by

$$p(\mathbf{z}) = \mathcal{N}(0_{\mathbf{z}}, \mathbb{1}_{\mathbf{z} \times \mathbf{z}})$$

$$\mathcal{KL}(q(\mathbf{z} | x^{(i)}; W) \| p(\mathbf{z})) = \frac{1}{2} \left[- \sum_i (\log \sigma_i^2 + 1) + \sum_i \sigma_i^2 + \sum_i \mu_i^2 \right]$$

► Source

VAE



The code is available @ github.com/a-mhamdi/jlai → *Codes* → *Julia* → *Part-3*

→ *vae* → *vae.jl*

Pluto.jl

→ *vae* → *vae.ipynb*



GAN

AN OVERVIEW

- ▶ A **Generative Adversarial Network (GAN)** is a type of deep learning model designed to generate new, synthetic samples of data. It consists of two networks: a **generator network** and a **discriminator network**. The **generator network** generates synthetic samples, while the **discriminator network** tries to distinguish between the synthetic samples and real samples of data.
- ▶ During training, the **generator and discriminator networks** are trained concurrently, with the **generator** trying to generate synthetic samples that are indistinguishable from real samples, and the **discriminator** trying to correctly classify the samples as either real or synthetic. The **generator** is trained to improve its synthetic samples based on the feedback from the **discriminator**, and the **discriminator** is trained to become more sensitive to synthetic samples.
- ▶ The goal of a **GAN** is to learn a generative model that can produce synthetic samples that are similar to the training data.

Image generation

Image style transfer

Text-to-image synthesis

Video prediction

Text-to-speech synthesis

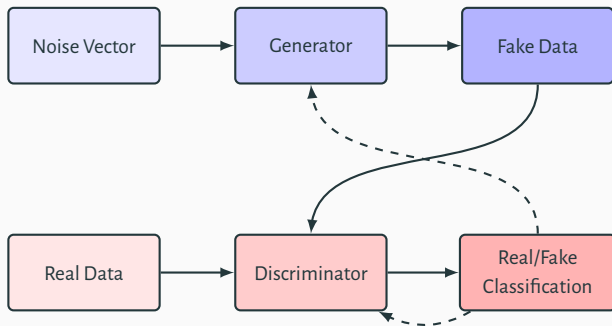
Super-resolution

Data augmentation

Domain adaptation

GAN

ARCHITECTURE & USE CASES



GAN



The code is available @ github.com/a-mhamdi/jlai → *Codes* → *Julia* → *Part-3*

→ *gan* → *gan.jl*

Pluto.jl

→ *gan* → *gan.ipynb*



NLP

PURPOSE & USE CASES

- ▶ **Natural Language Processing (NLP)** is a field of artificial intelligence and computer science that focuses on the interaction between computers and humans using natural language.
- ▶ **NLP** involves the development of algorithms and models that can understand, interpret, and generate human language.
- ▶ **NLP** is used in a wide range of applications, including machine translation, question answering, text summarization, text classification, and sentiment analysis.

Part-of-speech tagging

Named entity recognition

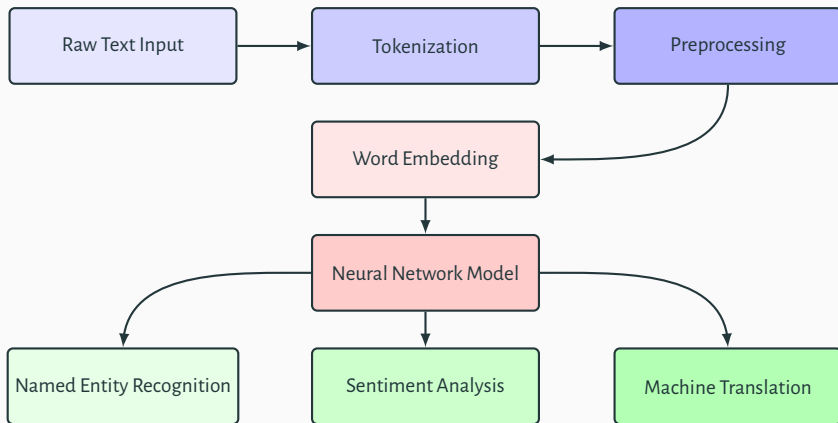
Sentiment analysis

Machine translation

Text summarization

NLP

PIPELINE



NLP

GENERAL PROCESS IN JULIA

1. Preprocess the text data by lowercasing, removing punctuation, and splitting the text into individual tokens (*e.g.*, words or subwords).
2. Build a vocabulary of the most common tokens in the text data.
3. Encode the text data as a sequence of integers using the vocabulary.
4. Pad the encoded sequences to the same length to make them suitable for input to a model.
5. Define the NLP model using a library such as `Flux.jl` or `Knet.jl`.
6. Train the model using gradient descent and a suitable loss function.
7. Use the trained model to make predictions on new data.

NLP



The code is available @ github.com/a-mhamdi/jlai → *Codes* → *Julia* → *Part-3*

→ *nlp* → *nlp.jl*

Pluto.jl 

→ *nlp* → *nlp.ipynb*



Transfer Learning

TRANSFER LEARNING

DRIVING FORCES & USE CASES

- ▶ **Transfer Learning** is a machine learning technique in which a model that has been trained on one task is re-purposed on a second related task. **Transfer Learning** can be used to improve the performance of the second task by leveraging the knowledge learned from the first task.
- ▶ One common use of **Transfer Learning** is to fine-tune a pre-trained model on a new dataset. For example, a pre-trained image classification model that has been trained on a large dataset such as ImageNet can be fine-tuned on a smaller dataset of a different but related task, such as detecting objects in medical images. Fine-tuning the pre-trained model on the new dataset can lead to improved performance compared to training a model from scratch on the smaller dataset.
- ▶ **Transfer Learning** is useful because it allows a machine learning model to learn from a large amount of data, even if the data is not directly related to the task at hand. It can also be used to speed up the training process, since the model does not need to be trained from scratch.

Image classification

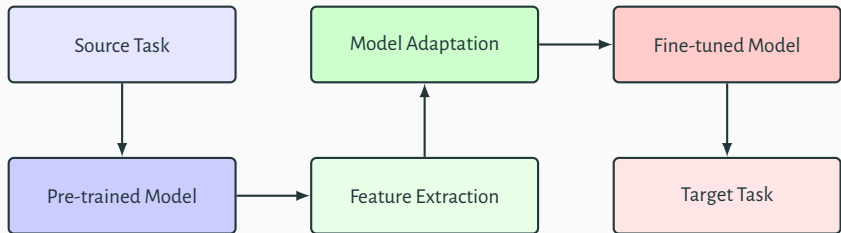
Computer vision

Natural language processing

Robotics

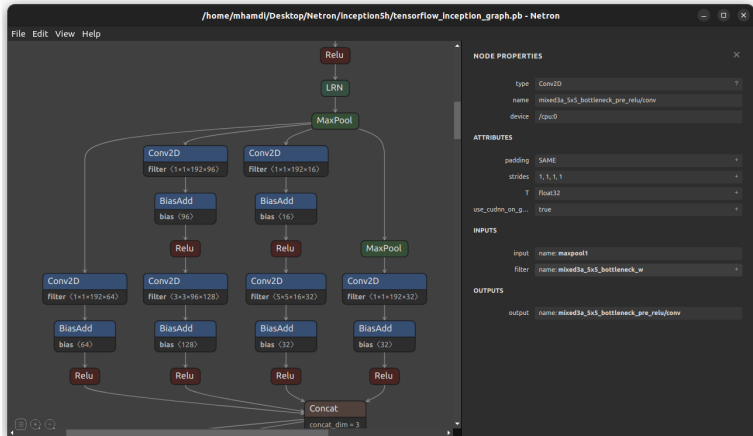
TRANSFER LEARNING

PIPELINE



TRANSFER LEARNING

NETRON



<https://github.com/lutzroeder/netron>

TRANSFER LEARNING

GENERAL PROCESS IN JULIA

1. Load the pre-trained model (*e.g.*, a convolutional neural network trained on ImageNet).
2. Replace the final layer (or layers) of the pre-trained model with a new, untrained layer (or layers) that is suitable for your target task.
3. Freeze the weights of the pre-trained layers to prevent them from being updated during training.
4. Load your dataset and split it into training and validation sets.
5. Use the training set to fine-tune the weights of the new layer (or layers) using gradient descent and a suitable loss function.
6. Monitor the performance of the model on the validation set and adjust the hyperparameters (*e.g.*, *learning rate*) as needed.
7. When you're satisfied with the performance of the model on the validation set, you can use it to make predictions on the test set or on new data.

TRANSFER LEARNING



The code is available @ github.com/a-mhamdi/jlai → *Codes* → *Julia* → *Part-3*

→ *transfer-learning* → *transfer-learning.jl*

Pluto.jl 

→ *transfer-learning* → *transfer-learning.ipynb*



Reinforcement Learning

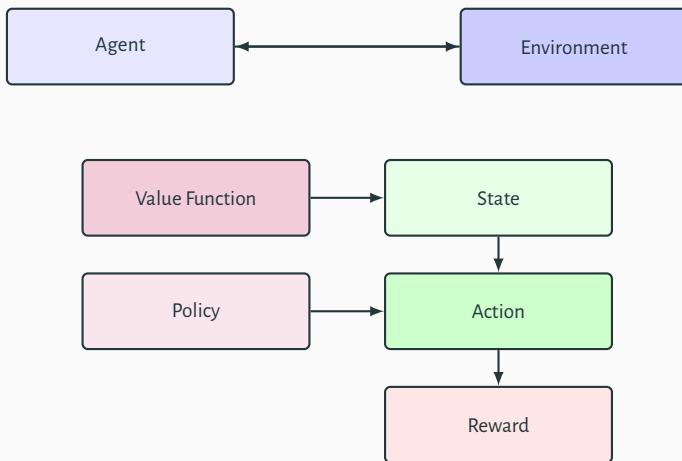
REINFORCEMENT LEARNING

SYNOPSIS

- ▶ **Reinforcement Learning** is a type of machine learning in which an agent learns to interact with its environment in order to maximize a reward. It involves learning to map situations (called states) to actions that will maximize a reward. The agent receives feedback in the form of rewards and penalties for its actions, which it uses to adjust its behavior accordingly.
- ▶ In **reinforcement Learning**, the goal is to learn a policy that maximizes the cumulative reward over time. The agent learns this policy through **trial and error**, by exploring different actions in different states and receiving feedback in the form of rewards or penalties.
- ▶ **Reinforcement Learning** is used in a variety of applications, including control systems, game playing, and natural language processing. It has been successful in a number of tasks, including teaching a computer to play chess and Go at a high level.

REINFORCEMENT LEARNING

PIPELINE



REINFORCEMENT LEARNING



The code is available @ github.com/a-mhamdi/jlai → Codes → Julia → Part-3

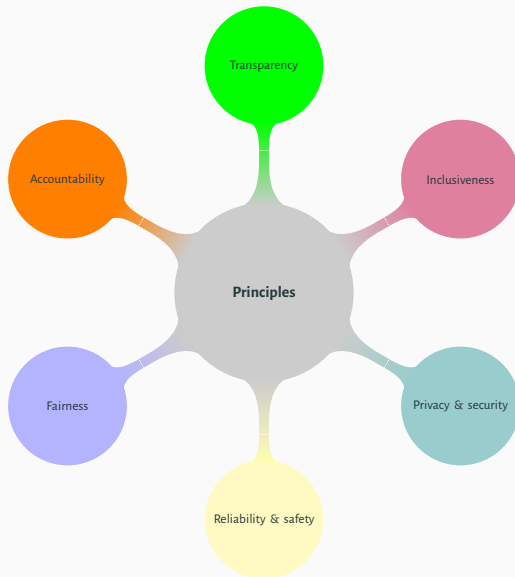
→ *reinforcement-learning* → *reinforcement-learning.jl*

Pluto.jl 

→ *reinforcement-learning* → *reinforcement-learning.ipynb*



Responsible AI



Quizzes

KNOWLEDGE CHECK



1

Go to wooclap.com

2

Enter the event code in the top banner

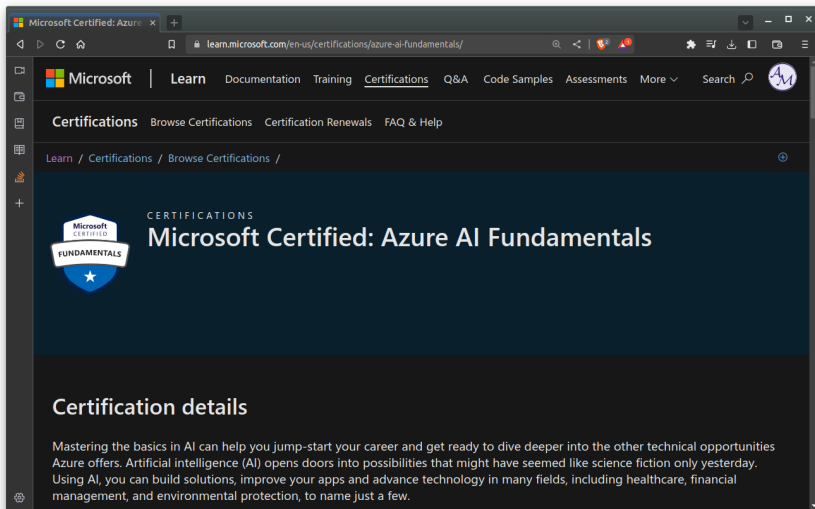
Event code

JLAI3

<https://app.wooclap.com/JLAI3>

Azure AI Fundamentals

EXAM PREP AI-900



<https://learn.microsoft.com/en-us/certifications/azure-ai-fundamentals/>

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FURTHER READING (2/2)

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- [SR] J. Silge and D. Robinson. ***Text Mining with R: A Tidy Approach.*** O'Reilly Media, p. 194.