

Demystifying Artificial Intelligence Sorcery

(Part 2: Machine Learning)^a

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[&]quot;Available @ https://github.com/a-mhamdi/jlai/

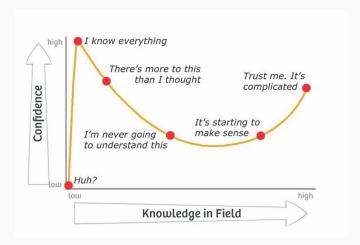


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DUNNING-KRUGER EFFECT

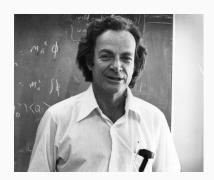


Kruger, J. and Dunning, D. (1999) *Unskilled and unaware of it: How difficulties in recognizing one's own incompetence lead to inflated self-assessments.* **J Pers Soc Psychol.** 77(6) pp. 1121–1134.

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"Knowledge isn't free. You have to pay attention."

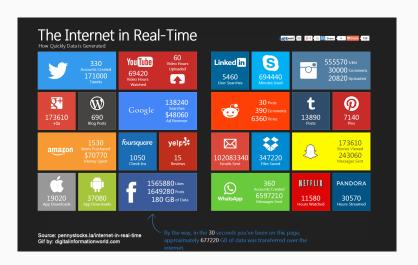
Richard P. Feynman



ROADMAP

- 1. An overview
- 2. Supervised Learning
- 3. Unsupervised Learning
- 4. Complementary Lab. Project
- 5. ML Landscape through Quizzes

An overview



Update on the internet in real time is available here.

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LITERATURE REVIEW (1/3)

"The field of machine learning is concerned with the question of how to construct computer programs that automatically improve with experience."

Mitchell, T. (1997) Machine Learning. McGraw-Hill International Editions. McGraw-Hill.

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LITERATURE REVIEW (2/3)

"Machine learning (ML) is a scientific discipline that concerns developing learning capabilities in computer systems. Machine learning is one of central areas of Artificial Intelligence (AI). It is an interdisciplinary area that combines results from statistics, logic, robotics, computer science, computational intelligence, pattern recognition, data mining, cognitive science, and more."

Wojtusiak, J. (2012) Machine learning. In Encyclopedia of the Sciences of Learning, pages 2082-2083. Springer US.

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LITERATURE REVIEW (3/3)

"Machine learning is an evolving branch of computational algorithms that are designed to emulate human intelligence by learning from the surrounding environment. They are considered the working horse in the new era of the so-called big data. Techniques based on machine learning have been applied successfully in diverse fields ranging from pattern recognition, computer vision, spacecraft engineering, finance, entertainment, and computational biology to biomedical and medical applications. [...] The ability of machine learning algorithms to learn from current context and generalize into unseen tasks would allow improvements in both the safety and efficacy of radiotherapy practice leading to better outcomes."

El Naqa, I. and Murphy, M. J. (2015) What Is Machine Learning?, pages 3–11. Springer International Publishing.

DEBRIFE

Arthur Samuel (1959)

Machine Learning: Field of study that gives computers the ability to learn without being explicitly programmed.

Tom Mitchell (1998)

Well-posed Learning Problem. A computer is said to learn from experience $\mathcal E$ with respect to some task $\mathcal T$ and some performance measure $\mathcal P$, if its performance on $\mathcal T$, as measured by \mathcal{P} , improves with experience \mathcal{E} .

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Task #1

Suppose your email program watches which emails you do or do not mark as spam, and based on that learns how to better filter spam. What is the task \mathcal{T} in this setting?

- 1. Classifying emails as spam or not spam;
- 2. Watching you label emails as spam or not spam:
- 3. The number (or fraction) of emails correctly classified as spam/not spam;
- 4. None of the above-this not a machine learning problem.

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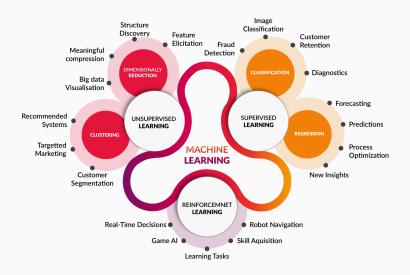
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OVERALL METHODOLOGY

- 1. Define the problem;
- 2. Gather dataset;
- 3. Choose measure of success;
- 4. Decide evaluation protocol;
- 5. Prepare the data;
- 6. Develop a model;
- 7. Iterate models.

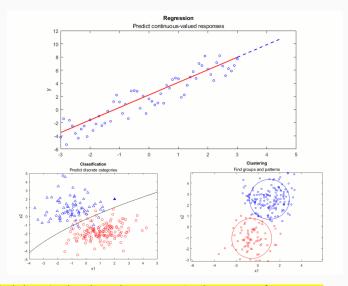


https://www.cognub.com/index.php/cognitive-platform/



https://vitalflux.com/great-mind-maps-for-learning-machine-learning/

REGRESSION | CLASSIFICATION | CLUSTERING



https://github.com/MathWorks-Teaching-Resources/Machine-Learning-for-Regression



PROGRAMMING LANGUAGE

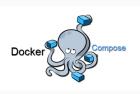




DEVELOPMENT ENVIRONMENTS







- ▲ \$ docker compose up
- ▼ \$ docker compose down





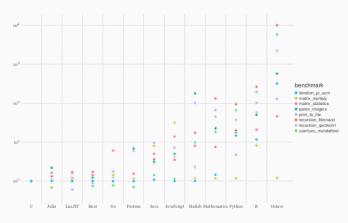


JULIA IN A NUTSHELL

- ▲ **Fast:** native code for multiple platforms via LLVM;
- **Dynamic:** good support for interactive use (like a a scripting language);
- **Reproducible:** environment recreation across platforms, with pre-built binaries;
- **Composable:** multiple dispatch as a paradigm (oop & functional programming);
- General: asynchronous I/O, metaprogramming, debugging, logging; profiling, pkg, ...
- Open Source: GitHub repository at https://github.com/JuliaLang/julia.



JULIA MICRO-BENCHMARKS (1/2)



https://julialang.org/benchmarks



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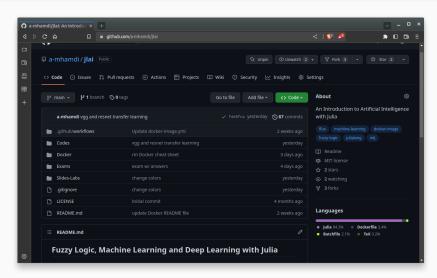
JULIA MICRO-BENCHMARKS (2/2)

Geometric Means¹ of Micro-Benchmarks by Language

1	С	1.0	
2	Julia	1.17006	
3	LuaJIT	1.02931	
4	Rust	1.0999	
5	Go	1.49917	
6	Fortran	1.67022	
7	Java	3.46773	
8	JavaScript	4.79602	
9	Matlab	9.57235	
10	Mathematica	14.6387	
11	Python	16.9262	
12	R	48.5796	
13	Octave	338.704	

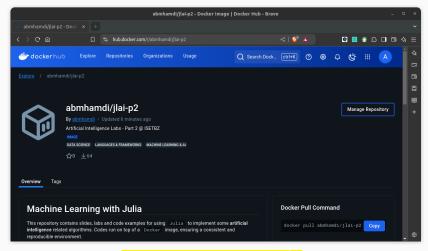






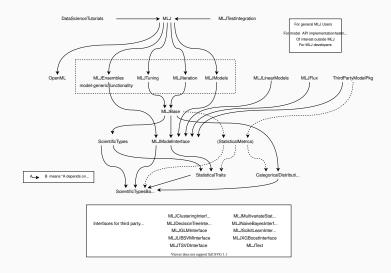
https://github.com/a-mhamdi/jlai

CONTINUOUS INTEGRATION (CI)



https://hub.docker.com/r/abmhamdi/jlai-p2

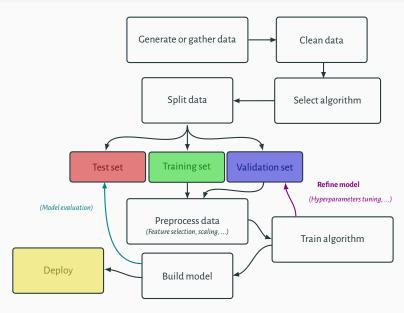
A MACHINE LEARNING FRAMEWORK FOR JULIA



https://docs.juliahub.com/MLJ/

Supervised Learning

WORKFLOW IN MACHINE LEARNING



DATA PREPROCESSING

How?

Cleaning Identifying and correcting or removing inaccuracies and inconsistencies in the data

Transformation Converting data from one format or structure to another.

Normalization Scaling the data so that it fits within a specific range. This is often done to make the data more amenable to certain operations or algorithms.

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DATA PREPROCESSING

- Raw data is often messy and may need to be cleaned and formatted before it can be used for machine learning.
 - (This may involve removing missing or invalid data, handling outliers, and encoding categorical variables.)
- Normalizing the data can help to scale the features so that they are on the same scale. (This can be important for algorithms that use distance measures, as features on different scales can dominate the distance measure.)
- Preprocessing techniques such as feature selection and feature extraction can help to reduce the dimensionality of the data.
 - (This may improve the performance of the model and reduce the risk of overfitting.)
- Preprocessing techniques such as feature selection can help to identify the most important features in the data
 - (This can make the model more interpretable and easier to understand.)

DATA PREPROCESSING

FEATURE SCALING

Normalization

$\frac{X - \min(X)}{\max(X) - \min(X)}$

▲ No assumption on data distribution

Standardization (Standardizer)

$$\langle \triangleq \frac{X - \mu}{\sigma}$$

▲ More recommended when following normal distribution

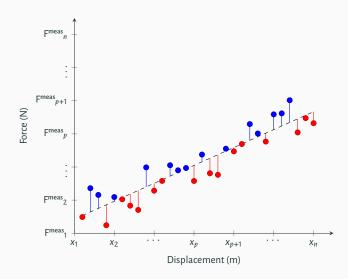
DATA PREPROCESSING TEMPLATE

CODE SNIPPET





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Consider the example of a spring. Our main goal is to determine the stiffness *k* of this spring, given some experimental data. The mathematical model (*Hooke's law*):

$$F = kx (1)$$

Restoring force is proportional to displacement.

Table 1: Measurements of couple (x_i, F^{meas}_i)

Xi	<i>x</i> ₁	 X _p	 Xn
F ^{meas}	F ^{meas} 1	 F ^{meas} _p	 F ^{meas} n

$$F^{\text{meas}}_{i} = F_{i} + \varepsilon_{i}$$
$$= kx_{i} + \varepsilon_{i}, \qquad (2)$$

where F_i denotes the unknown real value of the force applied to the spring. In order to estimate the stiffness value k, we can consider the quadratic criterion:

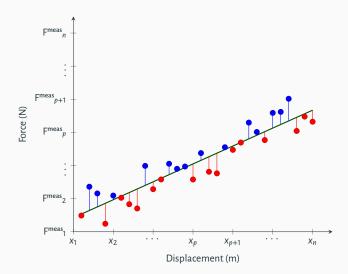
$$\mathcal{J} = \sum_{i=1}^{n} \varepsilon_i^2$$
$$= \sum_{i=1}^{n} (F^{\text{meas}}_i - kx_i)^2$$

$$\frac{\partial \mathcal{J}}{\partial k} = 0 \tag{3}$$

$$2\sum_{i=1}^{n} (F^{\text{meas}}_{i} - kx_{i}) \sum_{i=1}^{n} \frac{\partial (F^{\text{meas}}_{i} - kx_{i})}{\partial k} = 0$$

$$\sum_{i=1}^{n} (F^{\text{meas}}_{i} - kx_{i}) \sum_{i=1}^{n} x_{i} = 0$$

$$\sum_{i=1}^{n} \mathsf{F}^{\mathsf{meas}_{i}} x_{i} = k \sum_{i=1}^{n} x_{i}^{2} \iff \hat{k} = \frac{\sum_{i=1}^{n} \mathsf{F}^{\mathsf{meas}_{i}} x_{i}}{\sum_{i=1}^{n} x_{i}^{2}}$$



SIMPLE LINEAR REGRESSION

CODE SNIPPET





This example consists on determining the unknown couple (y_0, v_0) of a mobile solid. We assume that the trajectory is linear. The mathematical model that relates the position y to time t is given by this equation:

$$y = y_0 + v_0 t \tag{4}$$

Table 2: Measurements of position y

t _k	t_1	 t_p	 t _n
y ^{meas} k	y ^{meas}	 y ^{meas} _v	 y ^{meas} _n

$$y^{\text{meas}}_{k} = y_{k} + \varepsilon_{k}$$
$$= y_{0} + v_{0}t_{k} + \varepsilon_{k}, \tag{5}$$

where y_k denotes the unknown real value of the position y at time point t_k .

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In order to estimate the values taken by the couple $\begin{bmatrix} y_0, v_0 \end{bmatrix}^T$, we consider the quadratic criterion again, as follows:

$$\mathcal{J} = \sum_{k=1}^{n} \varepsilon_k^2$$
$$= \varepsilon^{\mathsf{T}} \times \varepsilon$$

The vector ε is set by ε_k , $\forall k \geq 1$:

$$\varepsilon = \begin{bmatrix} \varepsilon_1 & \cdots & \varepsilon_n \end{bmatrix}^T$$

$$\frac{\partial \mathcal{J}}{\partial \left[\begin{array}{c} y_0 \\ \end{array}\right]} = 0 \tag{6}$$



MULTIPLE LINEAR REGRESSION



Consider the following multivariable equation:

$$y = \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_m x_m \tag{7}$$

For a particular single measurement, eq. (7) can be updated as

$$y_k = \theta_1 x_{(1,k)} + \theta_2 x_{(2,k)} + \cdots + \theta_m x_{(m,k)} + \varepsilon_k$$

We denote hereafter by θ the vector $\begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_m \end{bmatrix}$. The function y_k becomes:

$$y_k = \underbrace{\left[x_{(1,k)}, x_{(2,k)}, \cdots, x_{(m,k)}\right]}_{X_b^T} \theta + \varepsilon_k$$

We assume that we have n measurements for y. Then we can transform the previous equation into

$$y = H\theta + \varepsilon$$

where
$$\mathbf{y}^{\mathsf{T}} = [y_1, y_2, \cdots, y_n], X = \begin{bmatrix} x_1^{\mathsf{T}} \\ x_2^{\mathsf{T}} \\ \vdots \\ \mathbf{y}^{\mathsf{T}} \end{bmatrix}$$
, and $\boldsymbol{\varepsilon}^{\mathsf{T}} = [\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n]$.

$$\mathcal{J} = \sum_{k=1}^{n} \varepsilon_k^2$$
$$= \varepsilon^{\mathsf{T}} \varepsilon$$

The best well estimated value of $\hat{\theta}$ corresponds to the absolute minimum of \mathcal{J} . This leads to calculate the gradient of \mathcal{J} with respect to θ :

$$\frac{\partial \mathcal{J}}{\partial \theta} = \frac{\partial (\varepsilon^{\mathsf{T}} \varepsilon)}{\partial \theta}$$

$$\frac{\partial \left(\boldsymbol{\varepsilon}^{\mathsf{T}}\boldsymbol{\varepsilon}\right)}{\partial \boldsymbol{\theta}} \quad = \quad 2 \left(\frac{\partial \boldsymbol{\varepsilon}}{\partial \boldsymbol{\theta}}\right)^{\mathsf{T}} \boldsymbol{\varepsilon}$$

Recall that $\varepsilon = y - X\theta$, the term $\frac{\partial \varepsilon}{\partial \theta}$ hence becomes:

$$\frac{\partial \varepsilon}{\partial \theta} = -X$$

$$\frac{\partial J}{\partial \theta} = 2(-X)^{\mathsf{T}} (y - X\theta)$$
$$= 0$$

The vector $\hat{\theta}$ is given by

$$\hat{\theta} = \left(X^T X\right)^{-1} X^T y$$



 X^TX is not invertible (singular/degenerate)

▼ Redundant Features

Some features are linearly dependent, i.e, \exists some $x_p \propto \text{some } x_l$, e.g., x_p in feet and x_l in m.

▼ Too many features

Fewer observations compared to the number of features, i.e, $m \ge n$.

- ▲ Delete some features
- ▲ Add extra observations

Use regularization:
$$\underbrace{\lambda \sum_{i=2}^{m} |\theta_i|}_{\text{LASSO}} \underbrace{\frac{1}{2} \lambda \sum_{i=2}^{m} \theta_i^2}_{\text{RIDGE}} \underbrace{r \lambda \sum_{i=2}^{m} |\theta_i| + \frac{(1-r)}{2} \lambda \sum_{i=2}^{m} \theta_i^2}_{\text{ELASTIC NET}}$$

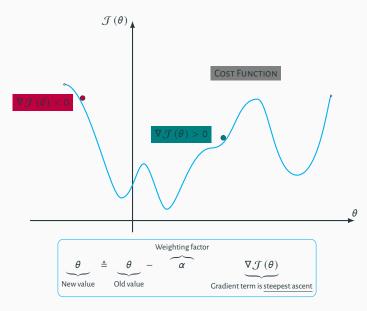
$$\hat{\theta} = \begin{bmatrix} 0 & \cdots & \cdots & 0 \\ \vdots & 1 & \ddots & \vdots \\ \vdots & \ddots & 1 & \ddots & \vdots \\ \vdots & \ddots & 1 & 0 \\ 0 & \cdots & \cdots & 0 & 1 \end{bmatrix}_{r}^{-1}$$

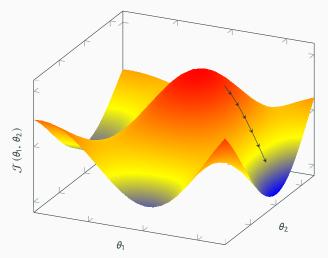
POLYNOMIAL REGRESSION

CODE SNIPPET









- ① Start with some random values of θ_1 and θ_2
- ② Keep changing θ_1 and θ_2 to reduce \mathcal{J} (θ_1 , θ_2) until we hopefully end up at minimum

$$\theta_i \triangleq \theta_i - \underbrace{\alpha}_{\text{Learning Rate}} \frac{\partial \mathcal{J}}{\partial \theta_i}$$

Recall that

$$\mathcal{J} = \frac{1}{2n} \sum_{k=1}^{n} (y_k - h_{\theta}(x_k))^2 \quad \Longrightarrow \quad \frac{\partial \mathcal{J}}{\partial \theta_i} = -\frac{1}{n} \sum_{k=1}^{n} (y_k - h_{\theta}(x_k)) x_{(i,k)}$$

$$\theta_{1} \triangleq \theta_{1} + \alpha \frac{1}{n} \sum_{k=1}^{n} (y_{k} - h_{\theta}(x_{k})) x_{(1,k)}$$

$$\theta_{2} \triangleq \theta_{2} + \alpha \frac{1}{n} \sum_{k=1}^{n} (y_{k} - h_{\theta}(x_{k})) x_{(2,k)}$$

$$\cdot$$

$$\theta_{m} \triangleq \theta_{m} + \alpha \frac{1}{n} \sum_{k=1}^{n} (y_{k} - h_{\theta}(x_{k})) x_{(m,k)}$$

$$\theta_i \triangleq \theta_i - \underbrace{\alpha}_{\text{Learning Rate}} \frac{\partial \mathcal{J}}{\partial \theta_i}$$

Recall that with L2 regularization term

$$\mathcal{J} = \frac{1}{2n} \sum_{k=1}^{n} (y_k - h_{\theta}(x_k))^2 + \frac{\lambda}{2n} \sum_{i=2}^{m} \theta_i^2 \quad \Longrightarrow \quad \frac{\partial \mathcal{J}}{\partial \theta_i} = -\frac{1}{n} \sum_{k=1}^{n} (y_k - h_{\theta}(x_k)) x_{(i,k)} + \frac{\lambda}{n} \theta_i \text{ iff } i \neq 1$$

$$\theta_{1} \triangleq \left(1 - \alpha \frac{1}{n}\right) \theta_{1} + \alpha \frac{1}{n} \sum_{k=1}^{n} \left(y_{k} - h_{\theta}\left(x_{k}\right)\right) x_{(1,k)}$$

$$\theta_{2} \triangleq \left(1 - \alpha \frac{\lambda}{n}\right) \theta_{2} + \alpha \frac{1}{n} \sum_{k=1}^{n} \left(y_{k} - h_{\theta}\left(x_{k}\right)\right) x_{(2,k)}$$

$$\theta_{m} \triangleq \left(1 - \alpha \frac{\lambda}{n}\right) \theta_{m} + \alpha \frac{1}{n} \sum_{k=1}^{n} \left(y_{k} - h_{\theta}\left(x_{k}\right)\right) x_{(m,k)}$$

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Task #2

The yield y of a chemical process is a random variable whose value is considered to be a linear function of the temperature x. The following data of corresponding values of x and y is found:

Temperature in °C (x)	0	25	50	75	100
Yield in grams (y)	14	38	54	76	95

The linear regression model $y = \theta_1 + \theta_2 x$ is used. Determine the values of θ_0 , θ_1 .

- 1. Using normal equation,
- 2. Using gradient descent for 5 iterations, given the following initial settings:

$$\alpha = 0.01$$
 and $\theta = \begin{bmatrix} 1 \\ 0.5 \end{bmatrix}$

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1 Normal Equation

$$y = \begin{bmatrix} 14 \\ 38 \\ 54 \\ 76 \\ 95 \end{bmatrix} \text{ and } X = \begin{bmatrix} 1 & 0 \\ 1 & 25 \\ 1 & 50 \\ 1 & 75 \\ 1 & 100 \end{bmatrix} \implies \hat{\theta} = \begin{bmatrix} \hat{\theta}_1 \\ \hat{\theta}_2 \end{bmatrix} = \begin{bmatrix} 15.4 \\ 0.8 \end{bmatrix}$$

② Stochastic Gradient Descent

k	1	2	3 4		5	
у	14	38	54	76	95	
$h_{\theta}(x_k)$	1	13.63	330.999	-9894.410 734688.376		
$\hat{\theta} = \begin{bmatrix} \hat{\theta}_1 \\ \hat{\theta}_2 \end{bmatrix}$	1.13 0.5	1.374 6.592	-1.396 -131.907	98.308 7345.901	-7247.626 -727247.475	

```
X = [1 \ 0; \ 1 \ 25; \ 1 \ 50; \ 1 \ 75; \ 1 \ 100] \# Features
     y = [14, 38, 54, 76, 95] # Target
 3
     alpha, n, theta = 0.01, 5, [1; .5]
 4
     J = \Gamma I
 5
     for k in 1:5
         h_{th} = X[k, :]' * theta
         println("h_th is $(h_th)")
         cost = (v[k] - h_th)^2
 9
         push!(J, cost);
10
          theta += alpha * (v[k] - h_th) * X[k, :]
11
          println("theta is $(theta)")
12
     end
13
```



Code is available at https://github.com/a-mhamdi/jlai/

 $\rightarrow {\sf Codes} \rightarrow {\sf Julia} \rightarrow {\sf Part-2} \rightarrow {\sf gradient-descent.jl}$



Assumptions of Linear Regression



1. Linearity

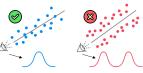
(Linear relationship between Y and each X)



2. Homoscedasticity



3. Multivariate Normality (Normality of error distribution)



4. Independence

(of observations. Includes "no autocorrelation")



5. Lack of Multicollinearity
(Predictors are not correlated with each other)





6. The Outlier Check
(This is not an assumption, but an "extra")



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EVALUATION METRICS (1/2)

Mean Absolute Error (MAE) measures the average difference of absolute values between predicted and actual targets.

MAE =
$$\frac{1}{n} \sum_{k=1}^{n} |y_k - \hat{y}_k|$$

A lower MAE indicates a better fit of the model to the data.

Root Mean Squared Error (RMSE) measures the difference between predicted and actual values.

RMSE =
$$\sqrt{\frac{1}{n} \sum_{k=1}^{n} (y_k - \hat{y}_k)^2}$$

A lower RMSE indicates a better fit of the model to the data.

EVALUATION METRICS (2/2)

R-squared is a statistical measure that quantifies the proportion of the variance in the dependent variable that is explained by the independent variables in the model.

$$\mathcal{R}^{2} = 1 - \frac{SS_{\text{residuals}}}{SS_{\text{total}}} = 1 - \frac{\sum_{k=1}^{n} (y_{k} - \hat{y}_{k})^{2}}{\sum_{k=1}^{n} (y_{k} - \bar{y})^{2}}$$

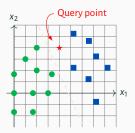
1 indicates that the model explains ALL the variance in the dependent variable

• O indicates that the model explains **NONE** of the variance in the dependent variable

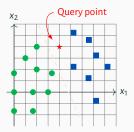
Adjusted R-squared is a modified version of R-squared that accounts for the number of independent variables in the model.

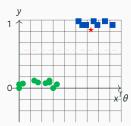
Adjusted
$$\mathcal{R}^2 = 1 - (1 - \mathcal{R}^2) \frac{n-1}{n-m-1}$$

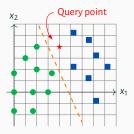
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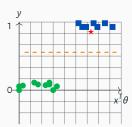


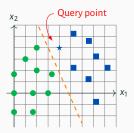


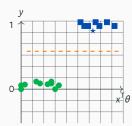




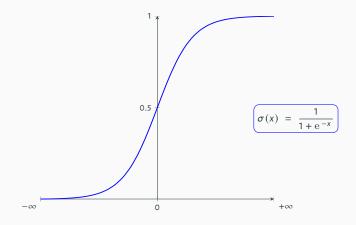








Logistic or S-shaped function σ



- σ squashes range of distance from $]-\infty, +\infty[$ to [0, 1]
- σ is differentiable and easy to compute: $(\dot{\sigma} = \sigma \times (1 \sigma))$

$$y = \sigma (\theta_1 x_1 + \theta_2 x_2 + \dots + \theta_m x_m)$$
$$y = \frac{1}{1 + e^{-x^T \theta}}$$

Hypothesis

$$h_{\theta}(x) = P(y = 1|x; \theta) = \frac{1}{1 + e^{-x^{T}\theta}}$$

For some given x_k

$$h_{\theta}(x_k) = P(y = 1 | x_k; \theta) = \frac{1}{1 + e^{-x_k^T \theta}}$$

Cost function

$$\mathcal{J} = \left\{ \begin{array}{ll} -\ln\left(h_{\theta}(x)\right) & \text{if} \quad y = 1 \\ \\ -\ln\left(1 - h_{\theta}(x)\right) & \text{if} \quad y = 0 \end{array} \right.$$

$$\mathcal{J} = -y \ln \left(h_{\theta}(x) \right) - (1 - y) \ln \left(1 - h_{\theta}(x) \right)$$

$$\theta_i \triangleq \theta_i - \underbrace{\alpha}_{\text{Learning Rate}} \frac{\partial \mathcal{J}}{\partial \theta_i}$$

Generalizing \mathcal{J} yields:

$$\mathcal{J} = -\frac{1}{n} \sum_{k=1}^{n} (y_k \ln (h_{\theta}(x_k)) + (1 - y_k) \ln (1 - h_{\theta}(x_k)))$$

$$\implies \frac{\partial \mathcal{J}}{\partial \theta_i} = -\frac{1}{n} \sum_{k=1}^{n} (y_k - h_{\theta}(x_k)) x_{(i,k)}$$

$$\theta_1 \triangleq \theta_1 + \alpha \frac{1}{n} \sum_{k=1}^{n} (y_k - h_{\theta}(x_k)) x_{(1,k)}$$

$$\left[\theta_{1} \triangleq \theta_{1} + \alpha \frac{1}{n} \sum_{k=1}^{n} (y_{k} - h_{\theta}(x_{k})) x_{(1,k)}\right] \left[\theta_{2} \triangleq \theta_{2} + \alpha \frac{1}{n} \sum_{k=1}^{n} (y_{k} - h_{\theta}(x_{k})) x_{(2,k)}\right]$$

$$\theta_{m} \triangleq \theta_{m} + \alpha \frac{1}{n} \sum_{k=1}^{n} (y_{k} - h_{\theta}(x_{k})) x_{(m,k)}$$

$$\theta_i \triangleq \theta_i - \underbrace{\alpha}_{\text{Learning Rate}} \frac{\partial \mathcal{J}}{\partial \theta_i}$$

Generalizing \mathcal{J} with L_2 regularization term yields:

$$\mathcal{J} = -\frac{1}{n} \sum_{k=1}^{n} (y_k \ln (h_{\theta}(x_k)) + (1 - y_k) \ln (1 - h_{\theta}(x_k))) + \frac{\lambda}{2n} \sum_{i=2}^{m} \theta_i^2$$

$$\implies \frac{\partial \mathcal{J}}{\partial \theta_i} = -\frac{1}{n} \sum_{k=1}^{n} (y_k - h_{\theta}(x_k)) x_{(i,k)} + \frac{\lambda}{n} \theta_i \quad \text{iff } i \neq 1$$

$$\theta_{1} \triangleq \left(1 - \alpha \frac{1}{n}\right) \theta_{1} + \alpha \frac{1}{n} \sum_{k=1}^{n} \left(y_{k} - h_{\theta}\left(x_{k}\right)\right) x_{(1,k)}$$

$$\theta_{2} \triangleq \left(1 - \alpha \frac{\lambda}{n}\right) \theta_{2} + \alpha \frac{1}{n} \sum_{k=1}^{n} \left(y_{k} - h_{\theta}\left(x_{k}\right)\right) x_{(2,k)}$$

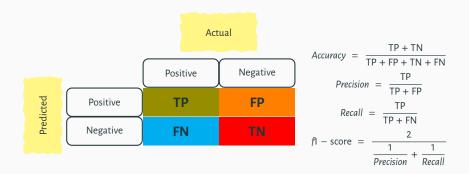
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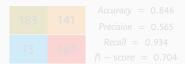
$$\theta_{m} \triangleq \left(1 - \alpha \frac{\lambda}{n}\right) \theta_{m} + \alpha \frac{1}{n} \sum_{k=1}^{n} \left(y_{k} - h_{\theta}\left(x_{k}\right)\right) x_{(m,k)}$$



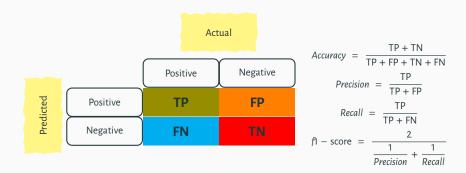


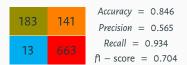
CONFUSION MATRIX





CONFUSION MATRIX





320	20	Accuracy = 0.932 Precision = 0.941
43	538	Recall = 0.882 f1 - score = 0.910

Demystifying Al Sorcery A. MHAMDI

EVALUATION METRICS









Accuracy denotes the ratio of how much we got right over all cases:

$$Accuracy = \frac{TP + TN}{TP + FP + TN + FN}$$

Precision designates how much positives do we get right over all positive predictions:

$$Precision = \frac{TP}{TP + FP}$$

Recall is the ratio of how much positives we got right over all actual positive cases:

$$Recall = \frac{TP}{TP + FN}$$

f1 − score denotes the Harmonic Mean of Precision & Recall:

$$f1 - score = \frac{2}{\frac{1}{Precision} + \frac{1}{Recall}}$$

EVALUATION METRICS

FOLLOW UP

$$f_{\beta}$$
-score = $\frac{1+\beta^2}{1-\beta^2}$

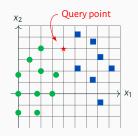
Case #1: Prioritize Precision over Recall, e.g., $\beta = 0.5$

- ► Mail spam detection
- Predicting appropriate day to launch a satellite

Case #2: Prioritize Recall over Precision, e.g., $\beta = 2$

- ► Detection of life threatening diseases like cancer
- ► Fraud detection

k-Nearest Neighbors (1/6)



$$d(x; y) = \left(\sum_{i=1}^{n} |y_i - x_i|^p\right)^{1/p}$$

$$d(x; y) = \sum_{i=1}^{n} |y_i - x_i|$$

$$d(x; y) = \sum_{i=1}^{n} |y_i - x_i|$$

$$d(x; y) = \sqrt{\sum_{i=1}^{n} (y_i - x_i)^2}$$

k-NEAREST NEIGHBORS (2/6)

► Evelyn Fix and Joseph Hodges, 1951 ► Thomas Cover, 1966

Algorithm 1 Summary Construction

1: **procedure** How does *k*-NN work? (Finding Nearest Neighbors)

Input: A query point;

Output: Assign a class label to that point.

- 2: Define how many neighbors will be checked to classify the specific query point;
- 3: Compute the distance d(x; y) of the query point to other data points;
- 4: Count the number of the data points in each category;
- 5: Assign the query point to the class with most frequent neighbors.
- 6: end procedure

Task#3

Let be the following coordinate points:

$$A(1, 6)$$
; $B(2, 6)$; $C(3, 1)$; $D(4, 2)$; $E(6, 0)$; $F(7, 5)$; $G(7, 3)$; $H(10, 3)$; $I(-4, -1)$

Using the Euclidean distance, what are the two closest neighbors of point P(5, 5)?

$$d(A; P) = \sqrt{17} \approx 4.12$$
 $d(B; P) = \sqrt{10} \approx 3.16$ $d(C; P) = \sqrt{20} \approx 4.47$

$$d(D; P) = \sqrt{10} \approx 3.16$$
 $d(E; P) = \sqrt{26} \approx 5.1$ $d(F; P) = \sqrt{4} = 2$

$$d(G; P) = \sqrt{8} \approx 2.83$$
 $d(H; P) = \sqrt{29} \approx 5.38$ $d(I; P) = \sqrt{117} \approx 10.82$

end

k-Nearest Neighbors (4/6)

Task #42

We try to predict the color of a fruit according to its width (w) and height (h). The following training data is available:

Fruit	F ₁	F ₂	F ₃	F ₄	F_5	F ₆	F ₇	F ₈
w	2	5	2	6	1	4	2	6
h	6	6	5	5	2	2	1	1
Color	Red	Yellow	Orange	Purple	Red	Blue	Violet	Green

The goal here is to study the influence of neighbors on the color property of a fruit. Let U be the new fruit of width w = 1 and height h = 4

- 1. What is its color if we consider 1 neighbor?
- 2. What is its color if we consider 3 neighbors?
- 3. Rather than majority voting, we would like to consider the vote of neighbors weighted by the distance. Each neighbor votes according to a weight inversely proportional to the square of its distance: $\frac{1}{42}$. We take 3 neighbors, what is the color of *U*? Compare your results to those in question 2.

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$$d(U; F_1) = \sqrt{5} \approx 2.24$$

$$d(U; F_1) = \sqrt{5} \approx 2.24$$
 $d(U; F_2) = \sqrt{20} \approx 4.47$ $d(U; F_3) = \sqrt{2} \approx 1.41$

$$d(U; F_3) = \sqrt{2} \approx 1.4$$

$$d(U; F_4) = \sqrt{26} \approx 5$$

$$d(U; F_5) = \sqrt{4} =$$

$$d(U; F_4) = \sqrt{26} \approx 5.1$$
 $d(U; F_5) = \sqrt{4} = 2$ $d(U; F_6) = \sqrt{13} \approx 3.6$

$$d(U; F_7) = \sqrt{10} \approx 3.16$$
 $d(U; F_8) = \sqrt{34} \approx 5.83$

- 1. Color of U is Orange because $d(U; F_3)$ is the smallest.
- 2. Color of U is Red: F_1 and F_5 (+2 to Red class), F_3 (+1 to Orange class)
- 3. Color of *U* is Orange

$$S(\text{Red}) = \frac{1}{d^2(U; F_1)} + \frac{1}{d^2(U; F_5)} = 0.45 S(\text{Orange}) = \frac{1}{d^2(U; F_3)} = 0.5$$

$$S(\text{Orange}) = \frac{1}{d^2(U; F_3)} = 0.$$

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k-Nearest Neighbors (6/6)

```
function dds(w, h) # 'w' and 'h' are width and height of some fruit
    d_squared = (w-1)^2+(h-4)^2
    (d_squared, sqrt(d_squared))
end

dds(2, 6) # Fruit 'F_1'
dds(5, 6) # Fruit 'F_2'
```

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²From Prof Winston's hook



CODE SNIPPET





RULE OF THUMB TO CHOOSE k

k is even if the number of classes is odd

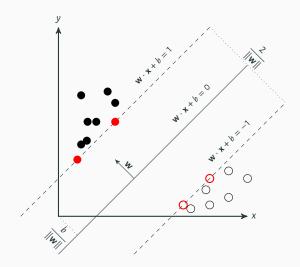
k is odd if the number of classes is even

k is an important hyperparameter that can affect the performance of the model.

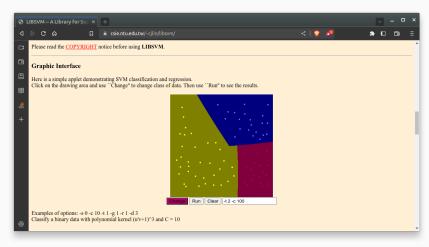
- 1. Larger values of k will result in a smoother decision boundary, which can lead to a more generalized model.
- 2. Smaller values of k will result in a more complex decision boundary, which can lead to a model that is more prone to overfitting.
- 3. The optimal value of k may depend on the specific dataset and the characteristics of the data.

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SUPPORT VECTOR MACHINE (SVM) (1/2)



SUPPORT VECTOR MACHINE (SVM) (2/2)



https://www.csie.ntu.edu.tw/~cjlin/libsvm/

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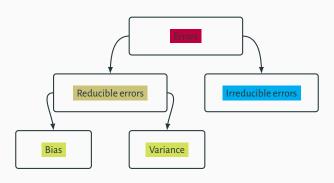
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SUMMARY

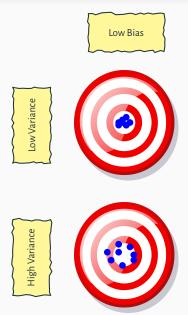
Method	Pros	Cons
Logistic Regression	▲ Probabilistic	 Almost linearly separable data
k-NN	Fast and efficient	# of neighbors k
K-ININ	a l'ast and emclent	 Detecting outliers³
	▲ Memory efficient	▼ Kernel's choice
SVM	▲ Versatile	Large datasets
SVIVI	Noise and outliers	Overlapping classes
	High dimension	Interpretability
Naive Bayes	▲ Simplicity and efficiency	▼ Independence between features
ivalve bayes	High dimension	▼ ∃ of irrelevant features
	▲ Interpretability	▼ Overfitting
Decision Tree	 Numerical and categorical data 	Unstable
Decision tree	Robust to outliers	Continuous variables
	▲ High accuracy	▼ # of input features
Random Forest	▲ Less prone to overfitting	▼ Computation
kanaom Forest	▲ High dimension	▼ Interpretability

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³Points that differ significantly from the rest of the data points.



BIAS-VARIANCE TRADEOFF



High Bias





Unsupervised Learning

K-MEANS CLUSTERING (1/3)

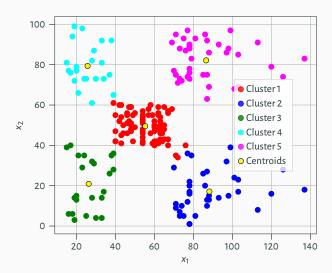
The algorithm *K***-Means** allows to display regularities or patterns in unlabeled data.

- ► The term 'means' refers to averaging the data when computing each centroid;
- A centroid is the arithmetic mean of all the data points belonging to a particular cluster.

This technique identifies a certain number of centroids within a data set. The algorithm then allocates every data point to the nearest cluster as it attempts to keep the clusters as small as possible. At the same time, K-Means attempts to keep the other clusters as different as possible.

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K-MEANS CLUSTERING (2/3)



K-Means Clustering (3/3)

Algorithm 2 Summary Construction

1: **procedure** How does K-Means work? (Discovering similarities)

Input: Unlabeled data sets;

Output: Grouping into clusters.

- 2: Define how many clusters will be used to group the data sets;
- Initialize all the coordinates of the k cluster centers
- 4: repeat
- 5: Assign each point to its nearest cluster;
- 6: Update the centroids coordinates;
- 7: **until** No changes to the centers of the clusters
- 8: Assign new cases to one of the clusters
- 9: end procedure

Of the following examples, which would you address using an <u>unsupervised learning</u> algorithms? (Check all that apply.)

- 1. Given email labeled as spam/not spam, learn a spam filter
- 2. Given a set of news articles found on the web, group them into set of articles about the same story
- Given a database of customer data, automatically discover market segments and group customers into different market segments
- 4. Given a dataset of patients diagnosed as either having diabetes or not, learn to classify new patients as having diabetes or not.

⁴From 'Machine Learning' course on 'Coursera'

Of the following examples, which would you address using an <u>unsupervised learning</u> algorithms? (Check all that apply.)

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⁴From 'Machine Learning' course on 'Coursera'

$$A(2, 10)$$
; $B(2, 5)$; $C(8, 4)$; $D(5, 8)$; $E(7, 5)$; $F(6, 4)$; $G(1, 2)$ and $H(4, 9)$.

- Initial cluster centers are: $\alpha(2, 10)$; $\beta(5, 8)$ and $\gamma(1, 2)$
- The distance between two points: $M(x_m, y_m)$ and $N(x_n, y_n)$ is defined as

$$d(M; N) = |x_m - x_n| + |y_m - y_n|$$

⁵Credit: Shokoufeh Mirzaei, PhD

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$$d(M; N) = |x_m - x_n| + |y_m - y_n| \quad y$$

$$\beta * D$$

$$\beta * D$$

$$F = C$$

⁵Credit: Shokoufeh Mirzaei. PhD

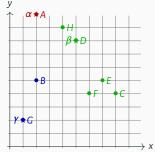
Use K-Means algorithm to cluster the following eight points intro three clusters:

$$A(2, 10); B(2, 5); C(8, 4); D(5, 8); E(7, 5); F(6, 4); G(1, 2)$$
 and $H(4, 9)$.

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$$d(M; N) = |x_m - x_n| + |y_m - y_n|$$

Point	$\alpha(2, 10)$	β (5, 8)	γ(1, 2)	#
A(2, 10)	0	5	9	1
B(2, 5)	5	6	4	3
C(8, 4)	12	7	9	2
D(5, 8)	5	0	10	2
E(7, 5)	10	5	9	2
F(6, 4)	10	5	7	2
G(1, 2)	9	10	0	3
H(4, 9)	3	2	10	2



5Credit: Shokoufeh Mirzaei, PhD

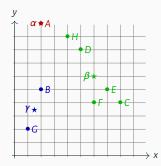
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$$A(2,\,10);\,B(2,\,5);C(8,\,4);D(5,\,8);E(7,\,5);F(6,\,4);G(1,\,2)\,and\,H(4,\,9).$$

- Initial cluster centers are: $\alpha(2, 10)$; $\beta(5, 8)$ and $\gamma(1, 2)$
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A(2, 10)	0	5	9	1
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D(5, 8)	5	0	10	2
E(7, 5)	10	5	9	2
F(6, 4)	10	5	7	2
G(1, 2)	9	10	0	3
H(4, 9)	3	2	10	2
α(2	, 10)	B(6, 6)	γ(1.5, 3.5	5))



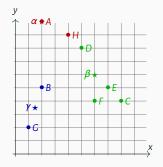
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Doint	~(2 10)	0((()	w(1 F 2 F)	1 "
Point	$\alpha(2, 10)$	β (6, 6)	$\gamma(1.5, 3.5)$	#
A(2, 10)	0	8	7	1
B(2, 5)	5	5	2	3
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F(6, 4)	10	2	5	2
G(1, 2)	9	9	2	3
H(4, 9)	3	5	8	1



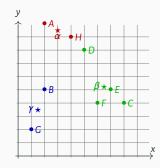
⁵Credit: Shokoufeh Mirzaei, PhD

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Point	$\alpha(2, 10)$	β (6, 6)	$\gamma(1.5, 3.5)$	#
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E(7, 5)	10	2	7	2
F(6, 4)	10	2	5	2
G(1, 2)	9	9	2	3
H(4, 9)	3	5	8	1
(x(3 9	S) (B(6	5 5 25)	v(15 35)	<u> </u>



⁵Credit: Shokoufeh Mirzaei, PhD

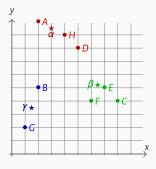
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$$d(M; N) = |x_m - x_n| + |y_m - y_n|$$

5	()	0(1)	()	I
Point	$\alpha(3, 9.5)$	β (6.5, 5.25)	γ (1.5, 3.5)	#
A(2, 10)	1.5	9.25	7	1
B(2, 5)	5.5	4.75	2	3
C(8, 4)	10.5	2.75	7	2
D(5, 8)	3.5	4.25	8	1
E(7, 5)	8.5	0.75	7	2
F(6, 4)	8.5	1.75	5	2
G(1, 2)	9.5	8.75	2	3
H(4, 9)	1.5	6.25	8	1



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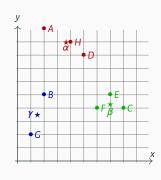
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E(7, 5)	8.5	0.75	7	2
F(6, 4)	8.5	1.75	5	2
G(1, 2)	9.5	8.75	2	3
H(4, 9)	1.5	6.25	8	1
α(3	.67, 9)	β(7, 4.3)	γ(1.5, 3.5)	



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⁵Credit: Shokoufeh Mirzaei, PhD

Use K-Means algorithm to cluster the following eight points intro three clusters:

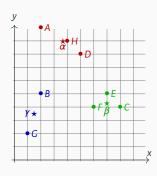
$$A(2, 10)$$
; $B(2, 5)$; $C(8, 4)$; $D(5, 8)$; $E(7, 5)$; $F(6, 4)$; $G(1, 2)$ and $H(4, 9)$.

 $d(M; N) = |x_m - x_n| + |y_m - y_n|$

- Initial cluster centers are: $\alpha(2, 10)$; $\beta(5, 8)$ and $\gamma(1, 2)$
- The distance between two points: $M(x_m, y_m)$ and $N(x_n, y_n)$ is defined as

Point	$\alpha(3.67, 9)$	β (7, 4.3)	$\gamma(1.5, 3.5)$	#
A(2, 10)	2.67	10.7	7	1
B(2, 5)	5.67	5.7	2	3
C(8, 4)	9.33	1.3	7	2
D(5, 8)	2.33	5.7	8	1
E(7, 5)	7.33	0.7	7	2
F(6, 4)	7.33	1.3	5	2
G(1, 2)	9.67	8.3	2	3

7.7



0.33

H(4, 9)

8

⁵Credit: Shokoufeh Mirzaei, PhD

$$A(2, 10)$$
; $B(2, 5)$; $C(8, 4)$; $D(5, 8)$; $E(7, 5)$; $F(6, 4)$; $G(1, 2)$ and $H(4, 9)$.

- Initial cluster centers are: $\alpha(2, 10)$; $\beta(5, 8)$ and $\gamma(1, 2)$
- The distance between two points: $M(x_m, y_m)$ and $N(x_n, y_n)$ is defined as

$$d(M; N) = |x_m - x_n| + |y_m - y_n|$$

Point	$\alpha(3.67, 9)$	$\beta(7, 4.3)$	$\gamma(1.5, 3.5)$	#
A(2, 10)	2.67	10.7	7	1
B(2, 5)	5.67	5.7	2	3
C(8, 4)	9.33	1.3	7	2
D(5, 8)	2.33	5.7	8	1
E(7, 5)	7.33	0.7	7	2
F(6, 4)	7.33	1.3	5	2
G(1, 2)	9.67	8.3	2	3
H(4, 9)	0.33	7.7	8	1
(x(3	67 9) B	(7 / 3)	v(15 35)	



⁵Credit: Shokoufeh Mirzaei, PhD



CODE SNIPPET

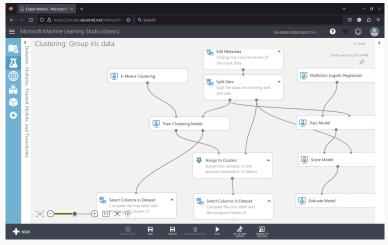




Complementary Lab. Project

On the day of assignment, you will be informed about the **dataset to consider**, **specific features to keep**, and **name of machine learning model to build**. You will be asked to:

- ① conduct the experiment successfully (pipeline, featurization, split, etc.);
- ② deploy a fully functional web service app that meets the given specifications.



https://studio.azureml.net/

■DEMO!

ML Landscape through Quizzes

KNOWLEDGE CHECK



https://app.wooclap.com/JLAI2

74/74 A. Mhambi Demystifying Al Sorcery

FURTHER READING (1/2)

2021, 420 pp.

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