AY: 2024-2025 M1-S2: Dept. of Electrical Engineering

EXAM | Al-ECUE221 Teacher: A. Mhamdi June 2025 Time Limit: $\mathbf{1}^{1}\!\!/_{2}$ h

This document contains 11 pages numbered from 1/11 to 11/11. As soon as it is handed over to you, make sure it is complete. The 3 tasks are independent and can be treated in the order that suits you.

The following rules apply:

- **1** A handwritten double-sided A4 sheet is permitted.
- 2 Any electronic material, except basic calculator, is prohibited.
- **18** Mysterious or unsupported answers will not receive full credit.
- **Q** Round results to the nearest thousandth (i.e., third digit after the decimal point).
- **6** Task N^o3: Each correct answer will grant a mark with no negative scoring.



Task Nº1

 $35mn \mid (7\frac{1}{2} \text{ points})$

Consider a binary classification problem in \mathbb{R}^2 with the following dataset consisting of five points:

$$\mathbf{D} = \{(\mathbf{x}_1, \mathbf{y}_1), (\mathbf{x}_2, \mathbf{y}_2), (\mathbf{x}_3, \mathbf{y}_3), (\mathbf{x}_4, \mathbf{y}_4), (\mathbf{x}_5, \mathbf{y}_5)\}$$

where:

$$\mathbf{x}_1 = (1, 2),$$
 $\mathbf{y}_1 = +1$ $\mathbf{x}_2 = (2, 3),$ $\mathbf{y}_2 = +1$ $\mathbf{x}_3 = (3, 3),$ $\mathbf{y}_3 = +1$ $\mathbf{x}_4 = (-1, -1),$ $\mathbf{y}_4 = -1$ $\mathbf{x}_5 = (-2, -2),$ $\mathbf{y}_5 = -1$

(a) (4 points) Find the optimal hard margin SVM classifier for this dataset¹.

By examining the data, we can identify that the support vectors are:

 $\mathbf{x}_1=(1,2)$ from the positive class $\mathbf{x}_4=(-1,-1)$ from the negative class

 $^{^{1}}x_{1}$ and x_{4} are the support vectors.

$$\mathcal{L}_{\mathsf{D}}(\boldsymbol{\alpha}) \ = \ \boldsymbol{\alpha}_1 + \boldsymbol{\alpha}_4 - \frac{1}{2} \left(\boldsymbol{\alpha}_1^2 \mathbf{x}_1^\mathsf{T} \mathbf{x}_1 - 2 \boldsymbol{\alpha}_1 \boldsymbol{\alpha}_4 \mathbf{x}_1^\mathsf{T} \mathbf{x}_4 + \boldsymbol{\alpha}_4^2 \mathbf{x}_4^\mathsf{T} \mathbf{x}_4 \right) \quad \text{s.t. } \boldsymbol{\alpha}_1 - \boldsymbol{\alpha}_4 = 0$$

 \mathcal{L}_{D} can be re-written as:

$$\mathcal{L}_{D}(\boldsymbol{\alpha}) = 2\alpha_{1} - \frac{1}{2}\alpha_{1}^{2} \left(\underbrace{x_{1}^{\mathsf{T}}x_{1}}_{5} - 2\underbrace{x_{1}^{\mathsf{T}}x_{4}}_{-3} + \underbrace{x_{4}^{\mathsf{T}}x_{4}}_{2} \right)$$
$$= 2\alpha_{1} - \frac{13}{2}\alpha_{1}^{2}$$

Compute $\frac{\partial \mathcal{L}_{D}(\boldsymbol{\alpha})}{\partial \alpha_{1}}$:

$$\frac{\partial \mathcal{L}_{\mathsf{D}}(\boldsymbol{\alpha})}{\partial \alpha_1} = 2 - 13\alpha_1$$

Setting $\frac{\partial \mathcal{L}_{D}(\boldsymbol{\alpha})}{\partial \boldsymbol{\alpha}_{1}} = 0$ yields:

$$\alpha_1 = \alpha_4 = \frac{2}{13}$$

The optimal value for \mathbf{w}^{\star} is:

$$\mathbf{w}^{\star} = \alpha_1 \mathbf{x}_1 - \alpha_4 \mathbf{x}_4$$
$$= \left[\frac{4}{13}, \frac{6}{13} \right]^{\mathsf{T}}$$

Using the support vector \mathbf{x}_1 , we get:

$$b^{\star} = 1 - \mathbf{x}_1^{\mathsf{T}} \mathbf{w}^{\star}$$
$$= -\frac{3}{13}$$

The hyperplane is therefore given by:

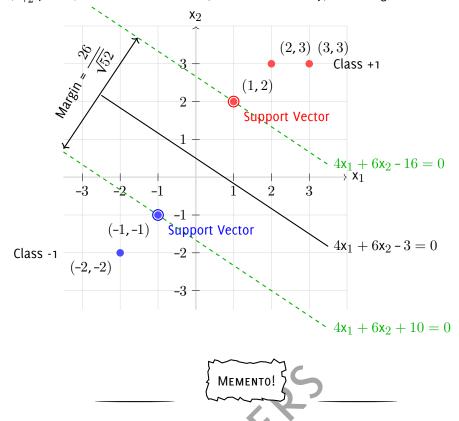
$$4x_1 + 6x_2 - 3 = 0$$

(b) (1 point) Calculate the margin of the classifier.

The margin width is calculated as:

Margin Width
$$=\frac{2}{\|\mathbf{w}\|}=\frac{2}{\sqrt{(4/13)^2+(6/13)^2}}=\frac{26}{\sqrt{52}}$$

(c) (2 $\frac{1}{2}$ points) Visualize the dataset, decision boundary, and margin.



• The dual problem is given by:

$$\mathcal{L}_{D}(\pmb{\alpha}) \ = \ \sum_{k=1}^{n} \pmb{\alpha}_k - \frac{1}{2} \sum_{k,l=1}^{n} \pmb{\alpha}_k \pmb{\alpha}_l \mathbf{y}_k \mathbf{y}_l \mathbf{x}_k^{\top} \mathbf{x}_l \quad \text{s.t. } \sum_{k=1}^{n} \pmb{\alpha}_k \mathbf{y}_k = 0$$

• The optimal \mathbf{w}^* is a linear combination of support vectors:

$$\textbf{w}^{\star} = \sum_{k \in \text{SV}} \alpha_k \textbf{y}_k \textbf{x}_k$$

• The bias b^* is computed using any support vector \mathbf{x}_k :

$$b^{\bigstar} = y_k - \boldsymbol{w}^{\bigstar\top} \boldsymbol{x}_k$$

Our dataset consists of four points in a 2D (x, y) plane:

$$A = (1, 3)$$

$$B = (2, 5)$$

$$C = (3, 4)$$

$$D = (5, 6)$$

(a) Perform PCA on the dataset:

i. (1 point) Center the data.

Mean of each feature:

Mean of x-coordinates
$$=$$
 $\frac{1+2+3+5}{4} = \frac{11}{4} = 2.75$
Mean of y-coordinates $=$ $\frac{3+5+4+6}{4} = \frac{18}{4} = 4.5$

In order to center the data, we need to subtract the mean from each data point:

Centered Point
$$1 = (1 - 2.75, 3 - 4.5) = (-1.75, -1.5)$$

Centered Point
$$2 = (2 - 2.75, 5 - 4.5) = (-0.75, 0.5)$$

Centered Point
$$3 = (3 - 2.75, 4 - 4.5) = (0.25, -0.5)$$

Centered Point 4 =
$$(5$$
 – 2.75 , 6 – $4.5) = (2.25, 1.5)$

ii. (2 points) Compute the covariance matrix.

For a 2D dataset, the covariance matrix C is:

$$C = \begin{bmatrix} var(x) & cov(x, y) \\ \\ cov(x, y) & var(y) \end{bmatrix}$$

Computing each element:

$$\begin{aligned} \text{var}(\mathbf{x}) &= \frac{(-1.75)^2 + (-0.75)^2 + (0.25)^2 + (2.25)^2}{3} \\ &= \frac{8.75}{3} \\ &\approx 2.917 \end{aligned}$$

$$\begin{aligned} \text{var}(\mathbf{y}) &= \frac{(-1.5)^2 + (0.5)^2 + (-0.5)^2 + (1.5)^2}{4} \\ &= \frac{5}{3} \\ &\approx 1.667 \end{aligned}$$

$$cov(x, y) = \frac{(-1.75)(-1.5) + (-0.75)(0.5) + (0.25)(-0.5) + (2.25)(1.5)}{4}$$
$$= \frac{5.5}{3}$$
$$\approx 1.833$$

$$\therefore \qquad C = \begin{bmatrix} 2.917 & 1.833 \\ \\ 1.833 & 1.667 \end{bmatrix}$$

iii. (2 points) Find the eigenvalues and the eigenvectors of the covariance matrix.

To find the eigenvalues, we solve: $\det \left(\mathbf{\textit{C}} - \lambda \mathbf{I}_2 \right) = 0$

$$\det\left(\mathbf{C} - \lambda \mathbf{I}_2\right) = 0$$

For our covariance matrix:

$$\det \begin{pmatrix} 2.917 - \lambda & 1.833 \\ 1.833 & 1.667 - \lambda \end{pmatrix} = 0$$
$$(2.917 - \lambda)(1.667 - \lambda) - 1.833^2 = 0$$
$$\lambda^2 - 4.584\lambda + 1.503 = 0$$

Using the quadratic formula:

$$\lambda = \frac{4.584 \pm \sqrt{(4.584)^2 - 4 \cdot 1 \cdot 1.503}}{2 \cdot 1}$$
$$= \frac{4.584 \pm \sqrt{15.001}}{2}$$
$$= \frac{4.584 \pm 3.873}{2}$$

Therefore:

 $\lambda_1 = 4.228$ (larger eigenvalue) and $\lambda_2 = 0.355$ (smaller eigenvalue)

For the eigenvector $\mathbf{v}_1 = \left[\mathbf{v}_{11}, \ \mathbf{v}_{12} \right]^\mathsf{T}$ corresponding to $\lambda_1 = 4.228$:

$$\begin{cases} (2.917 - 4.228) \mathsf{v}_{11} + 1.833 \mathsf{v}_{12} &= 0 \\ 1.833 \mathsf{v}_{11} + (1.667 - 4.228) \mathsf{v}_{12} &= 0 \end{cases} \Longrightarrow \begin{cases} -1.311 \mathsf{v}_{11} + 1.833 \mathsf{v}_{12} &= 0 \\ 1.833 \mathsf{v}_{11} - 2.561 \mathsf{v}_{12} &= 0 \end{cases}$$

If we set $v_{11} = 1$, then $v_{12} = 0.715$, giving us $\mathbf{v}_1 = [1, 0.715]^T$. Normalizing:

$$\begin{vmatrix} \mathbf{v}_1 \end{vmatrix} = \sqrt{1^2 + (0.715)^2} \approx 1.229$$

 $\mathbf{v}_1 = \frac{[1, 0.715]^\mathsf{T}}{1.229} \approx [0.814, 0.582]^\mathsf{T}$

For the eigenvector \mathbf{v}_2 corresponding to $\lambda_2=0.355$:

$$\begin{cases} (2.917 - 0.355) \mathsf{v}_{21} + 1.833 \mathsf{v}_{22} &= 0 \\ 1.833 \mathsf{v}_{21} + (1.667 - 0.355) \mathsf{v}_{22} &= 0 \end{cases} \begin{cases} 2.562 \mathsf{v}_{21} + 1.833 \mathsf{v}_{22} &= 0 \\ 1.833 \mathsf{v}_{21} + 1.312 \mathsf{v}_{22} &= 0 \end{cases}$$
 If we set $\mathsf{v}_{21} = 1$, then $\mathsf{v}_{22} = -1.398$, giving us $\mathsf{v}_2 = [1, -1.398]^\mathsf{T}$. Normalizing:
$$|\mathsf{v}_2| = \sqrt{1^2 + (1.398)^2} \approx 1.719$$

$$\begin{vmatrix} \mathbf{v}_2 \end{vmatrix} = \sqrt{1^2 + (1.398)^2} \approx 1.719$$

 $\mathbf{v}_2 = \frac{[1, -1.398]^T}{1.719} \approx [0.582, -0.813]^T$

(b) (2 points) Identify the principal components and explain which one captures the most variance.

The eigenvalues tell us how much variance is explained by each principal compo-

nent:

Total variance =
$$\lambda_1 + \lambda_2 = 4.228 + 0.355 = 4.583$$

Proportion explained by PC
$$_1=\frac{\lambda_1}{\text{Total variance}}\approx\frac{4.228}{4.583}\approx0.922$$
 or 92.2%

Proportion explained by PC₂ =
$$\frac{\lambda_2}{\text{Total variance}} \approx \frac{0.355}{4.583} \approx 0.078 \text{ or } 7.8\%$$

To project the centered data points onto the principal components, we multiply each centered data point by the eigenvectors.

Projection onto PC₁ ($\mathbf{v}_1 = [0.814, \ 0.582]^{\mathsf{T}}$):

Projection of A =
$$(-1.75 \times 0.814) + (-1.5 \times 0.582) = -2.298$$

Projection of B =
$$(-0.75 \times 0.814) + (0.5 \times 0.582) = -0.32$$

Projection of C =
$$(0.25 \times 0.814) + (-0.5 \times 0.582) = -0.088$$

Projection of D =
$$(2.25 \times 0.814) + (1.5 \times 0.582) = 2.704$$

Projection onto PC_2 ($\mathbf{v}_2 = [0.582, -0.813]^{\mathsf{T}}$):

Projection of A =
$$(-1.75 \times 0.582) + (-1.5 \times -0.813) = 0.2$$

Projection of B = $(-0.75 \times 0.582) + (0.5 \times -0.813) = -0.843$
Projection of C = $(0.25 \times 0.582) + (-0.5 \times -0.813) = 0.552$

Projection of B =
$$(-0.75 \times 0.582) + (0.5 \times -0.813) = -0.843$$

Projection of
$$\mathbf{C} = (0.25 \times 0.582) + (-0.5 \times -0.813) = 0.552$$

Projection of D =
$$(2.25 \times 0.582) + (1.5 \times -0.813) = 0.09$$

The transformed data points in the new PC coordinate system are:

$$P_{A} = (-2.298, 0.2)$$
 $P_{B} = (-0.32, -0.843)$

$$P_{C} = (-0.088, 0.552)$$
 $P_{D} = (2.704, 0.09)$

Since PC_1 captures approximately 92% of the variance, we could reduce our dimensionality by keeping only the first principal component:

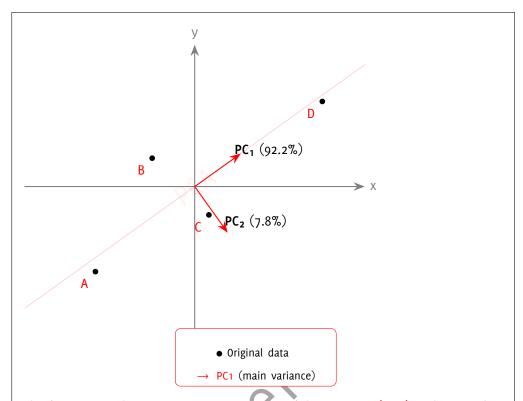
Point A (reduced)
$$\equiv P_A = -2.298$$

Point B (reduced)
$$\equiv P_B = -0.32$$

Point C (reduced)
$$\equiv P_C = -0.088$$

Point D (reduced)
$$\equiv P_D = 2.704$$

(c) (2 points) Draw the principal components on a scatter plot and describe their relationship to the spread of data.



The first principal component captures most of the variance (92%), indicating that our 2D dataset can be effectively represented in a single dimension with minimal loss of information.

julia

```
using DataFrames, MLJ
   X = DataFrame(x=[1., 2, 3, 5], y=[3., 5, 4, 6])
   4×2 DataFrame
    Row | x
        | Float64 Float64
      1 |
              1.0
                       3.0
      2 |
              2.0
                       5.0
      3 |
              3.0
                       4.0
              5.0
                       6.0
      4
13
```

```
# Load and fit 'PCA'
   PCA = @load PCA pkg="MultivariateStats"
   mach = machine(PCA(), X)
   fit!(mach)
   # Compute explained variance for each dimension
   explained_variance = report(mach).principalvars
   2-element Vector{Float64}:
    4.228606549861576
    0.3547267834717567
   =#
25
26
   explained_variance ./= sum(explained_variance)
   explained_variance .*= 100
   2-element Vector{Float64}:
    92.2605065424344
     7.739493457565602
32
   =#
33
34
   # Transform data to get components
   components = MLJ.transform(mach,
   4×2 DataFrame
    Row | x1
                      x2
        | Float64
                      Float64
      1 | 2.29607
                       0.201431
      2 | 0.318946
                      -0.843074
      3 | 0.0876672
                        0.5521
      4 | -2.70268
                        0.0895427
   =#
```

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Answer S	SHEET }	
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a) $(\frac{1}{2}$ point) What is being calculated here?		
using MLJ		
LR = @load LinearRegressor pkg=GLM	1 6	
<pre>mach = machine(LR(), X, y)</pre>		
evaluate!(mach, resampling=Holdout → measure=[rms, rsquared])	(fraction_t	crain=0.8),
√ Train-test split with 80% training	data, reportir	ng RMSE and R ²
5-fold cross-validation using RMS		
 Bootstrapped confidence interva 		nts
Feature importance scores using		
o) $(\frac{1}{2}$ point) What happens when executing	this code?	
struct Point		
x::Int		
y::Int		
<pre>end p = Point(1, 2)</pre>		
p = Point(1, 2) $p.x = 3$		
Creates a new Point (3, 2)		
Creates a copy with updated x-v		
√ Throws an error: setfield!: i	mmutable st	ruct
\bigcirc Modifies p.x to 3 successfully c) ($\frac{1}{2}$ point) What does the following code of		

mutable struct Box content::String end b1 = Box("Apple") b2 = b1b2.content = "Orange" println(b1.content) √ "Orange" ○ Throws an error ○ Undefined beavior (d) $(\frac{1}{2}$ point) Which of the following impurity measures is NOT differentiable with respect to class probabilities? O Gini impurity Entropy All of the above $\sqrt{}$ None of the above (e) $(\frac{1}{2}$ point) In PCA, what is the relationship between the eigenvalues of the covariance matrix and the variance explained? O Eigenvalues are unrelated to variance in PCA. O Eigenvalues represent the correlation between original features and principal components. O Eigenvalues are inversely proportional to the variance explained. $\sqrt{}$ Eigenvalues correspond to the variance along each principal component. (f) $(\frac{1}{2}$ point) In DBSCAN, which of the following statements about core points is FALSE? \bigcirc A core point has at least MinPts points within its ϵ -neighborhood (including itself). A core point can be part of multiple clusters. $\sqrt{\ }$ A core point can be a noise point if it lies in a low-density region. O A core point always belongs to a cluster. (g) $(\frac{1}{2}$ point) Which is not an assumption of linear regression?

DO NOT WRITE ANYTHING HERE

√ Standardization ○ Linearity ○ Homoscedasticity ○ Multivariate Normality