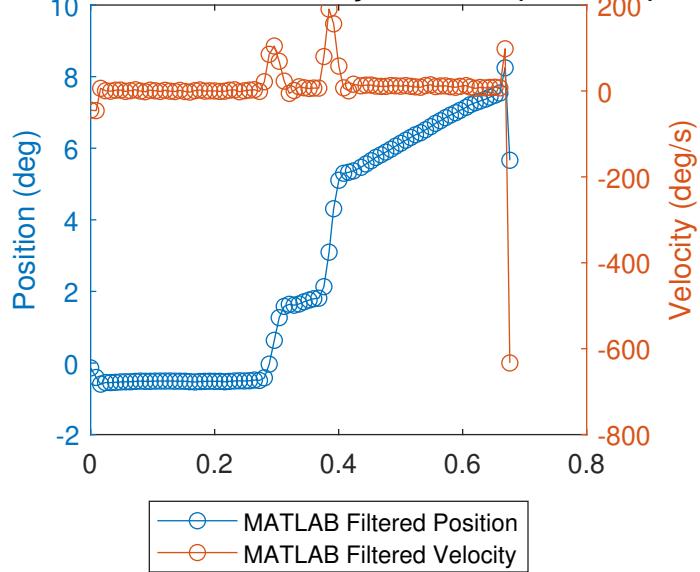
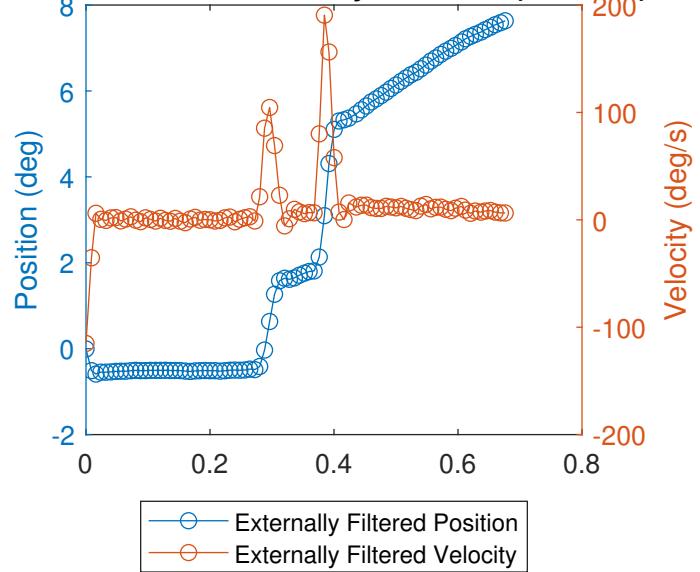


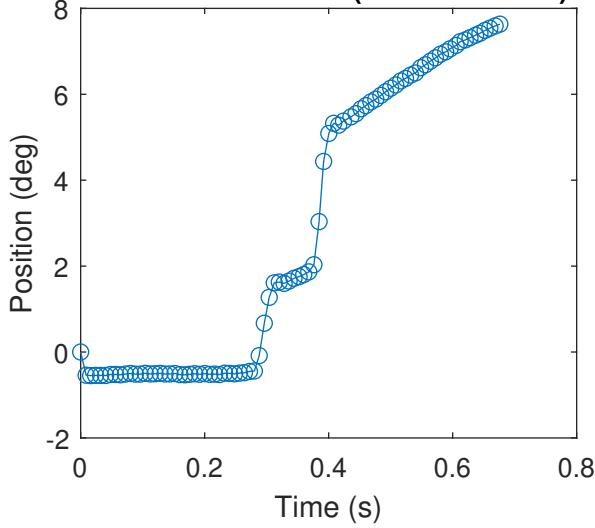
Filtered Position/Velocity: Trial 100 (MATLAB)



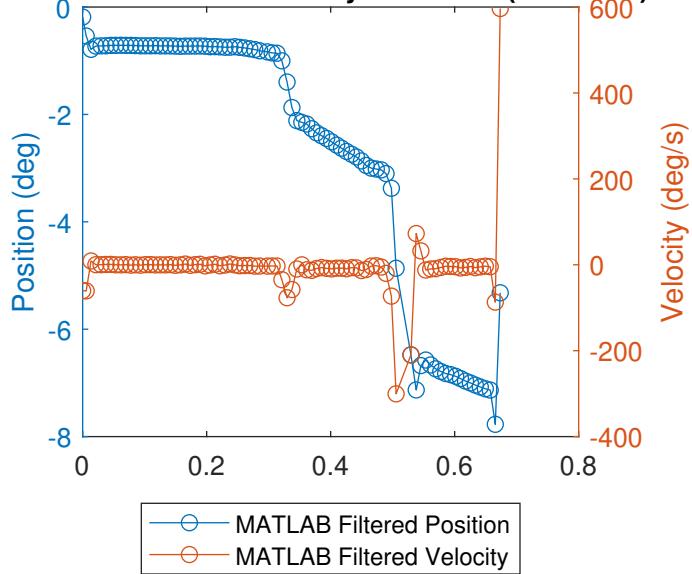
Filtered Position/Velocity: Trial 100 (External)



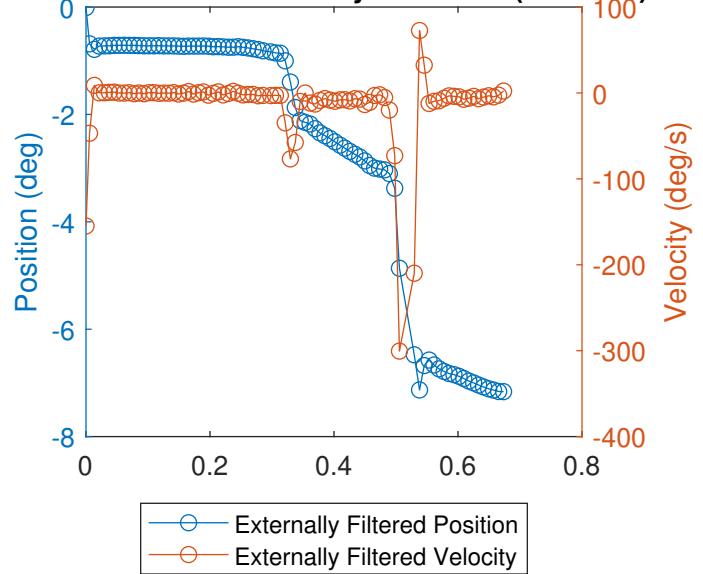
Raw Position Data (For Reference)



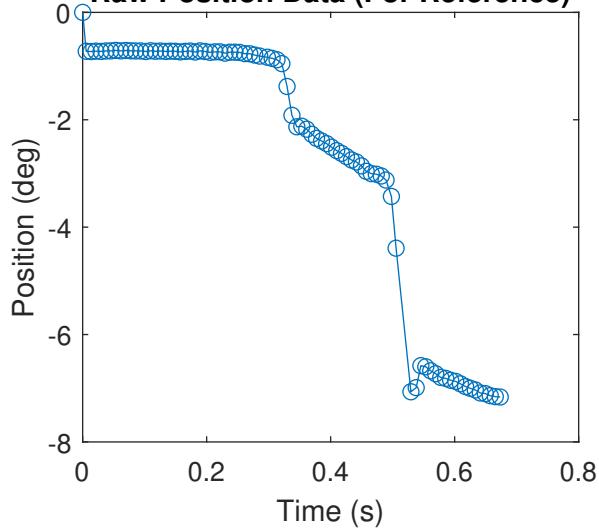
Filtered Position/Velocity: Trial 101 (MATLAB)

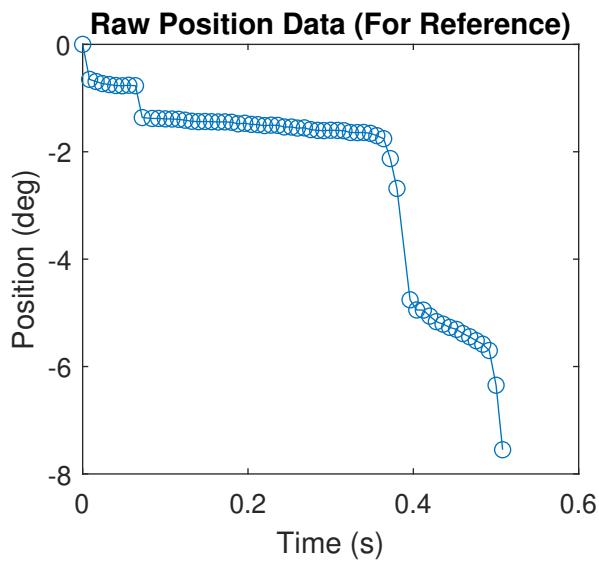
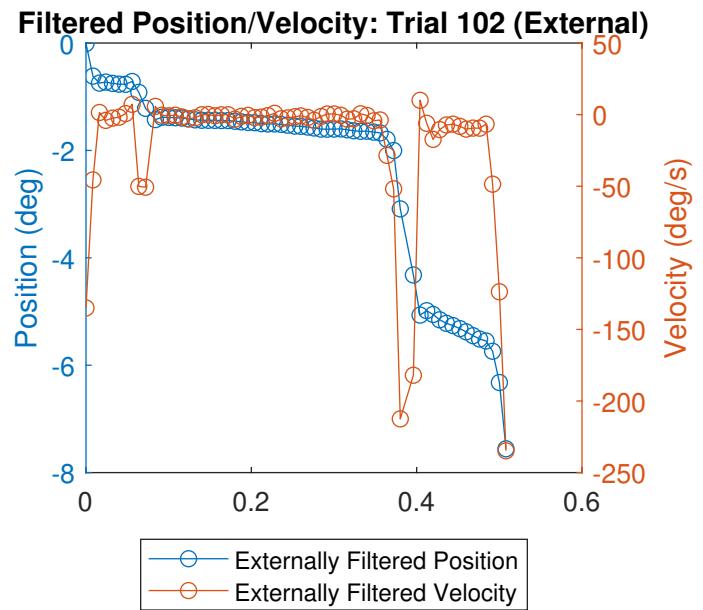
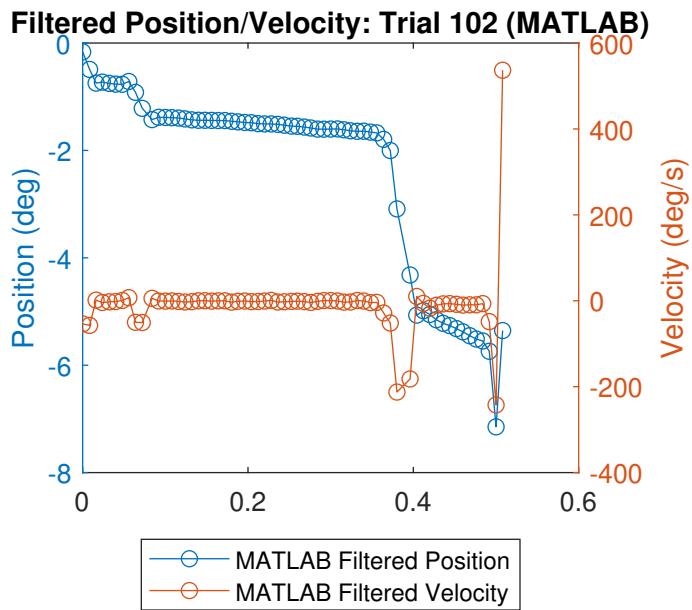


Filtered Position/Velocity: Trial 101 (External)

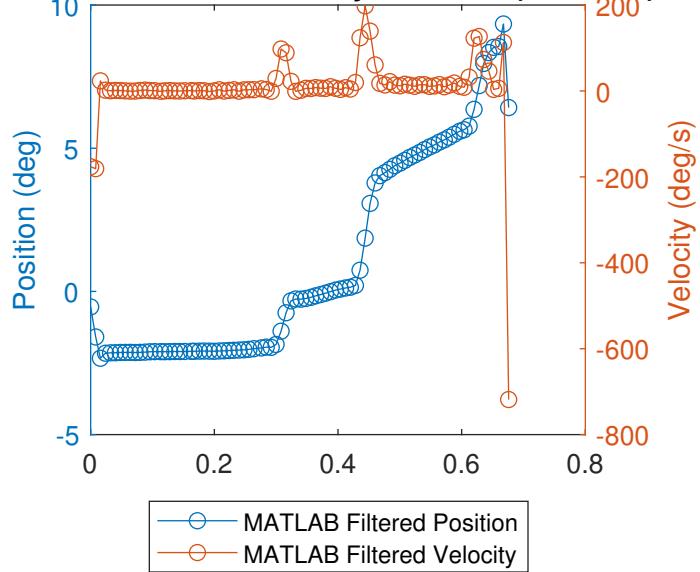


Raw Position Data (For Reference)

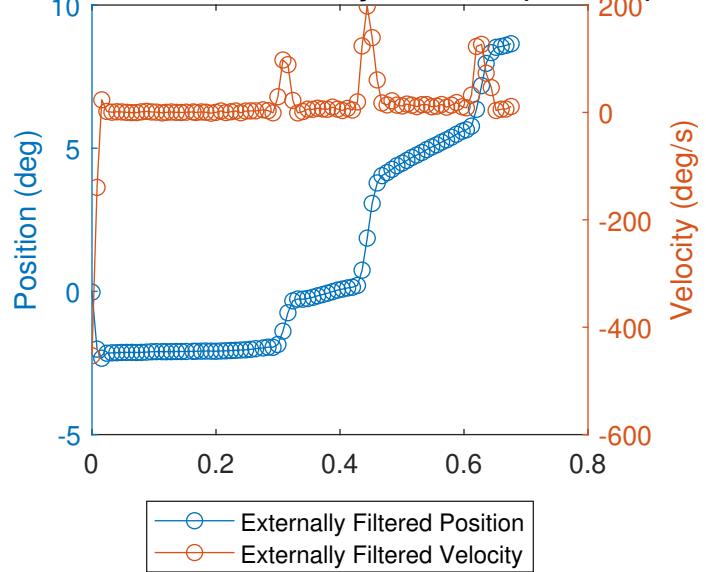




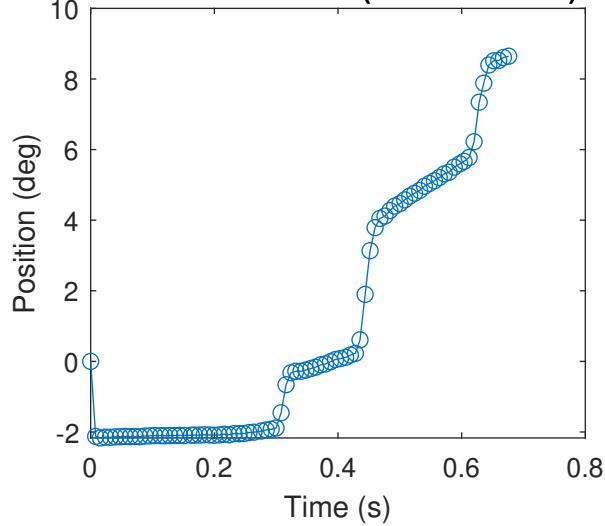
Filtered Position/Velocity: Trial 103 (MATLAB)



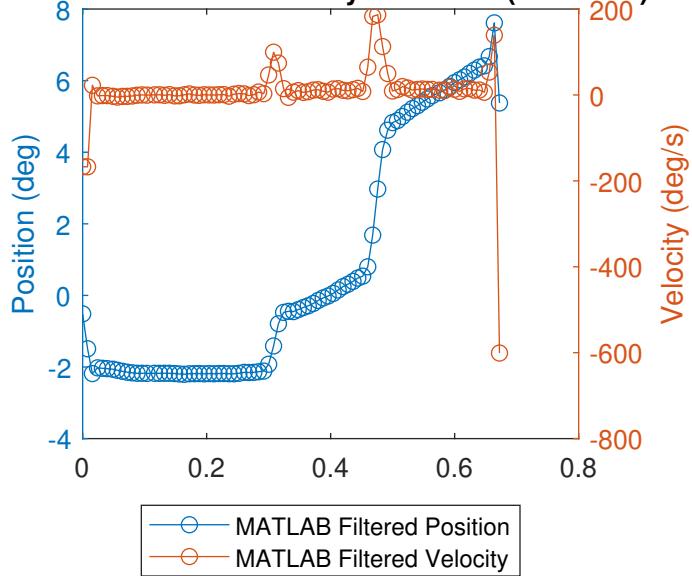
Filtered Position/Velocity: Trial 103 (External)



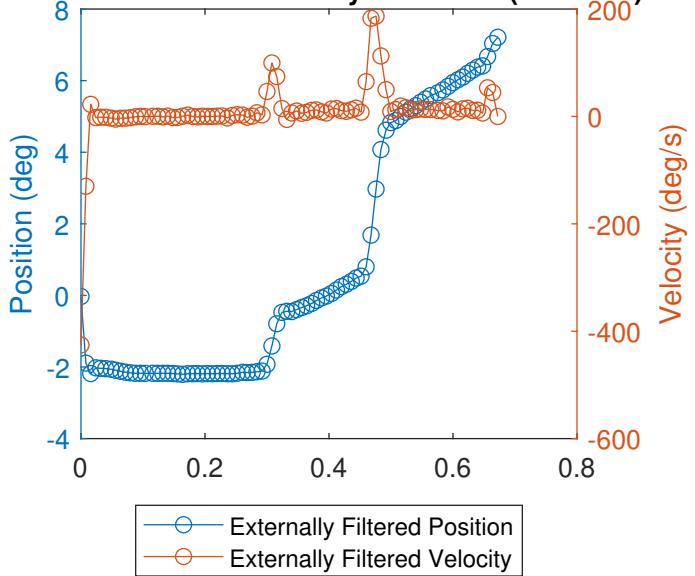
Raw Position Data (For Reference)



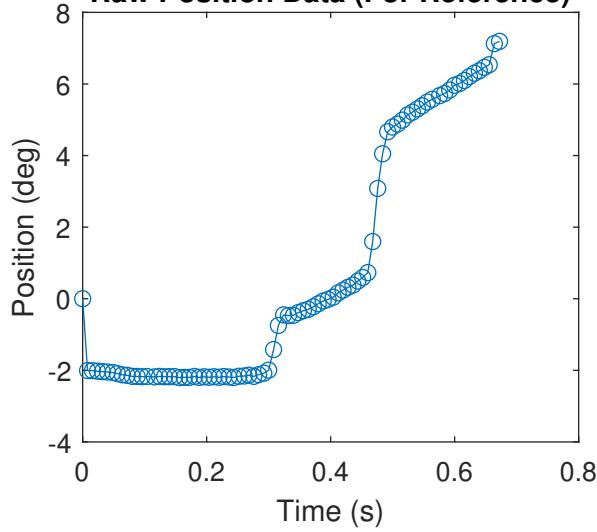
Filtered Position/Velocity: Trial 104 (MATLAB)



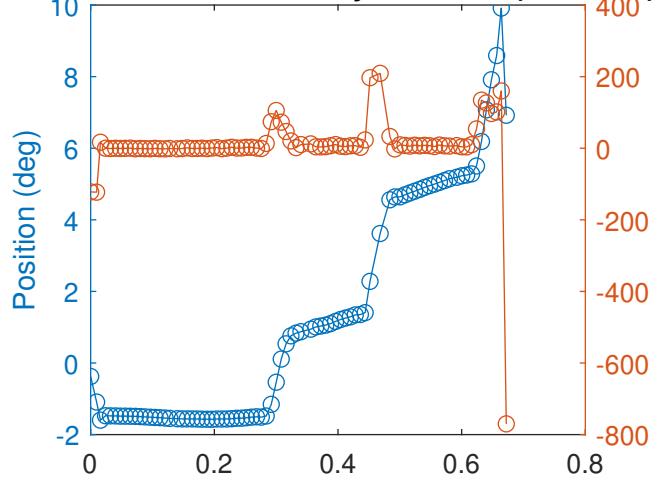
Filtered Position/Velocity: Trial 104 (External)



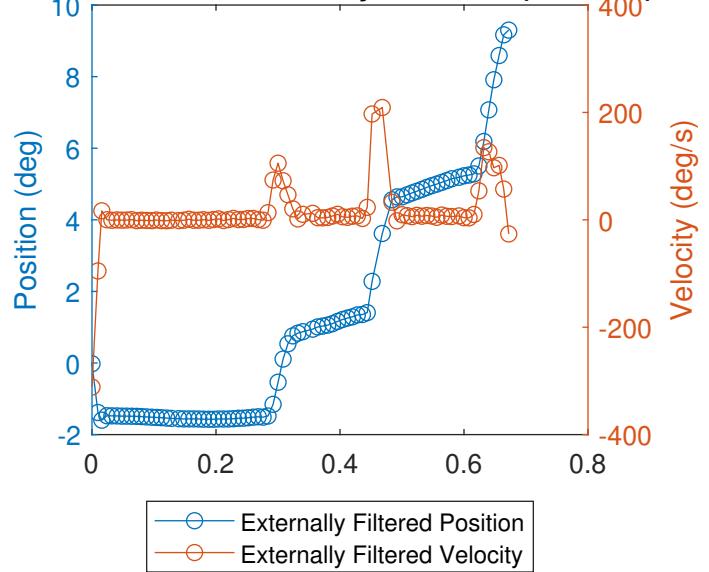
Raw Position Data (For Reference)



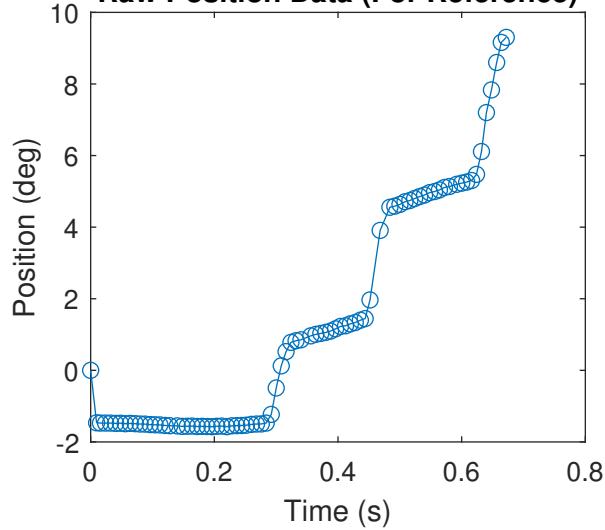
Filtered Position/Velocity: Trial 105 (MATLAB)

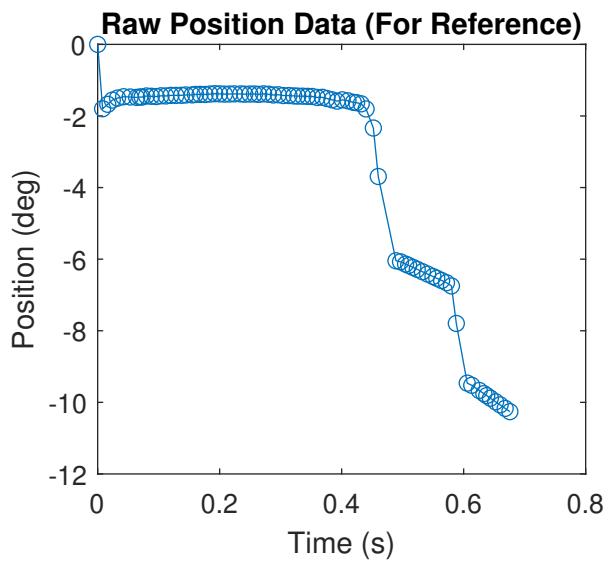
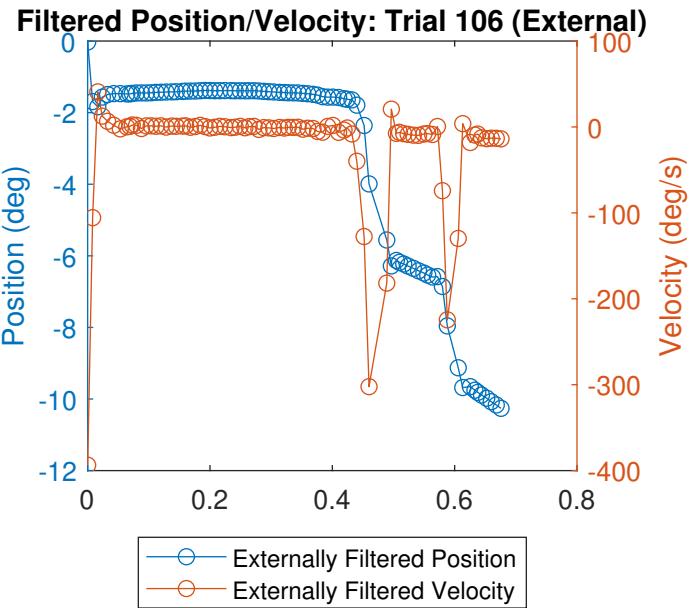
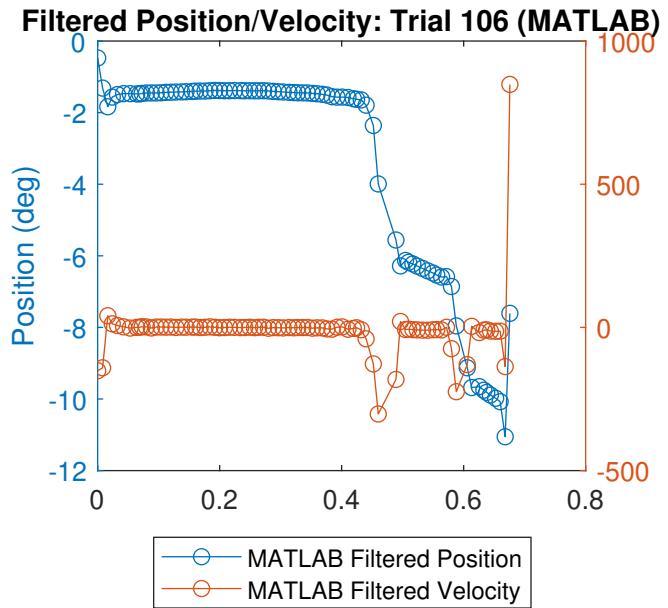


Filtered Position/Velocity: Trial 105 (External)

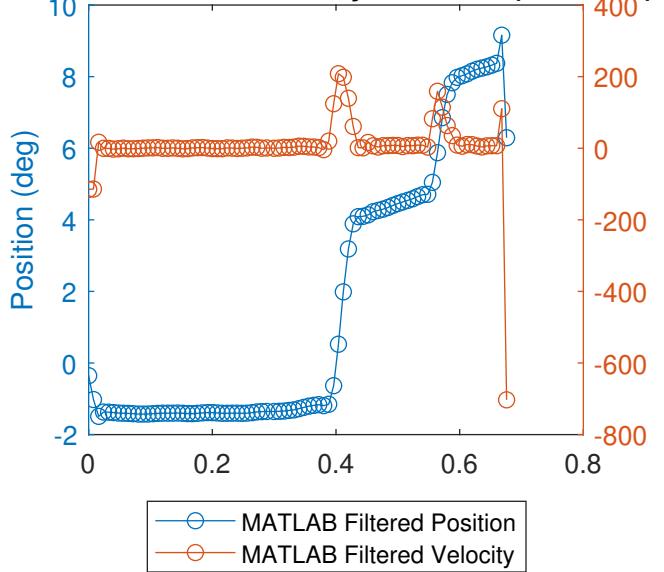


Raw Position Data (For Reference)

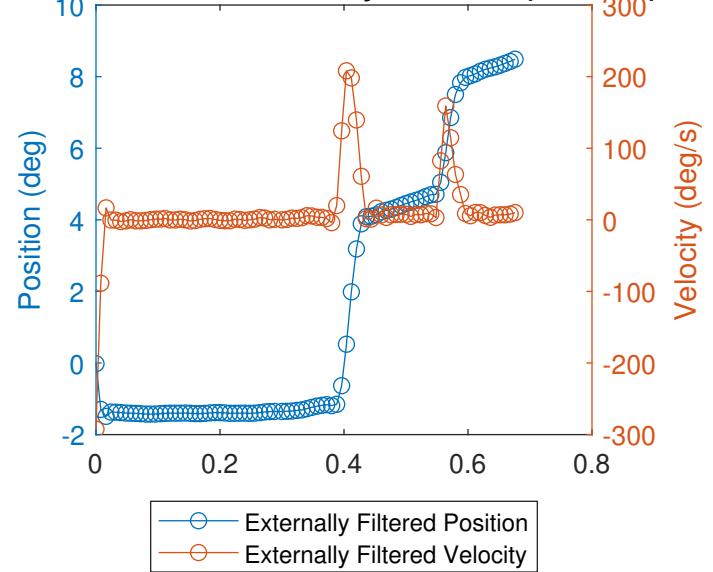




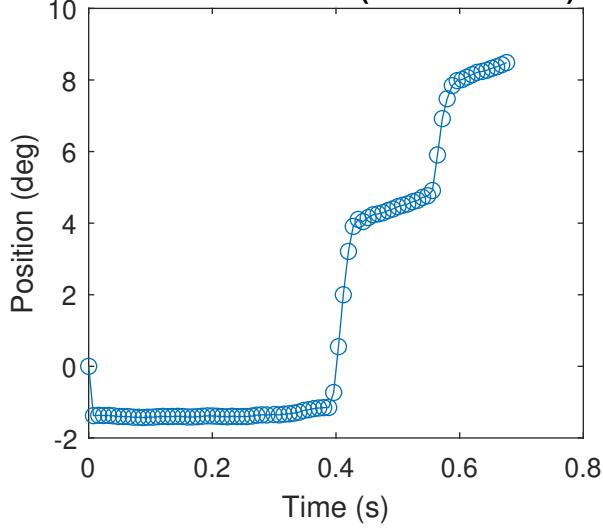
Filtered Position/Velocity: Trial 107 (MATLAB)



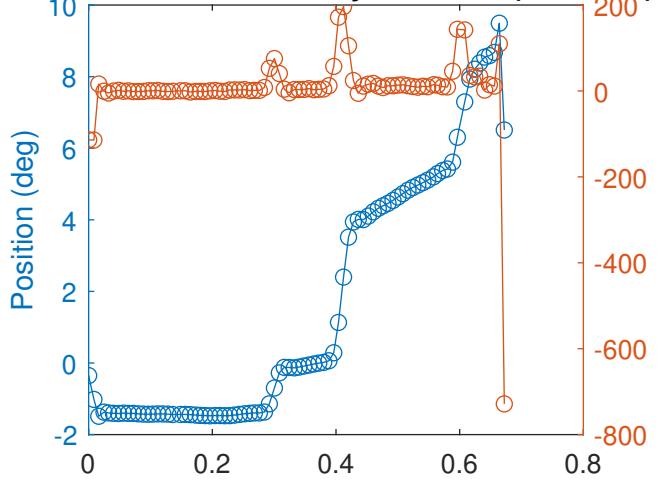
Filtered Position/Velocity: Trial 107 (External)



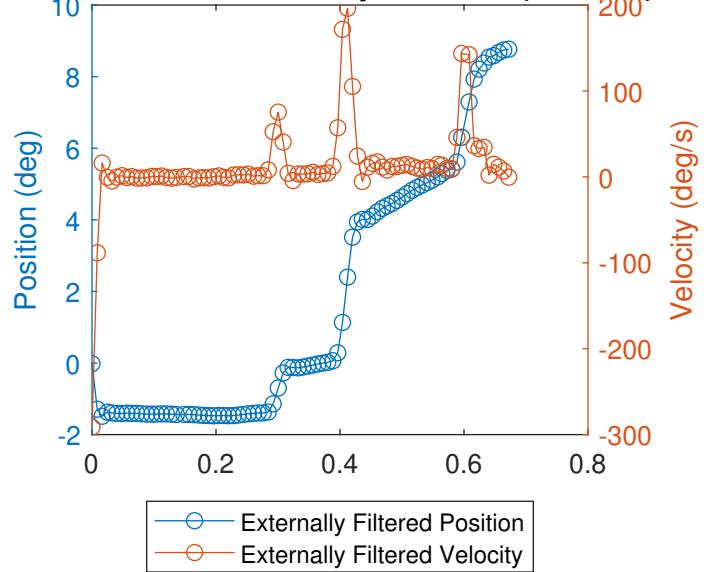
Raw Position Data (For Reference)



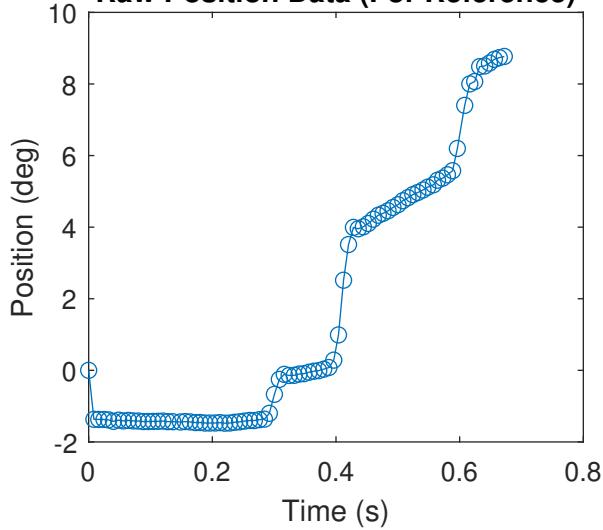
Filtered Position/Velocity: Trial 108 (MATLAB)

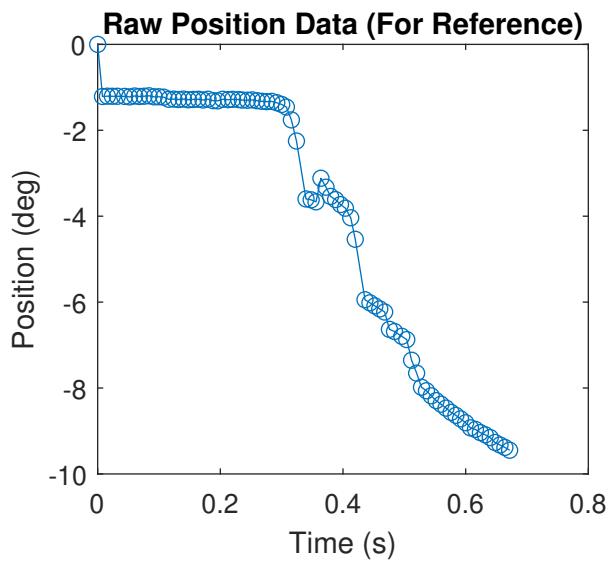
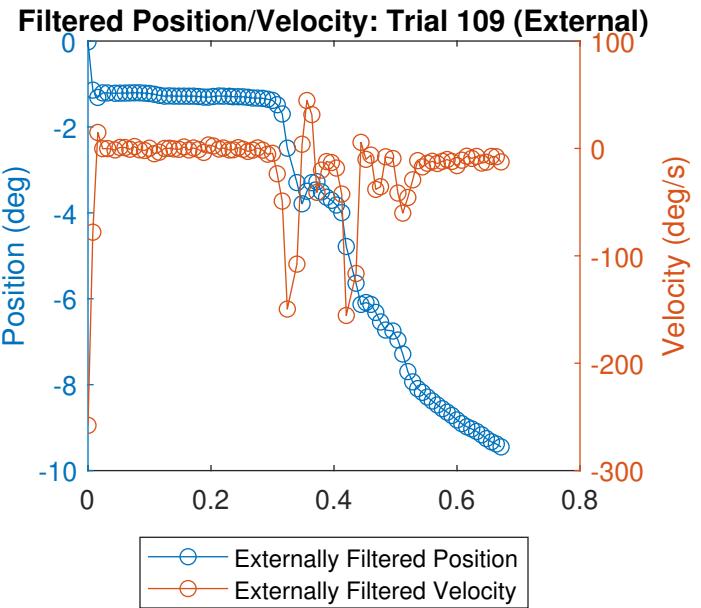
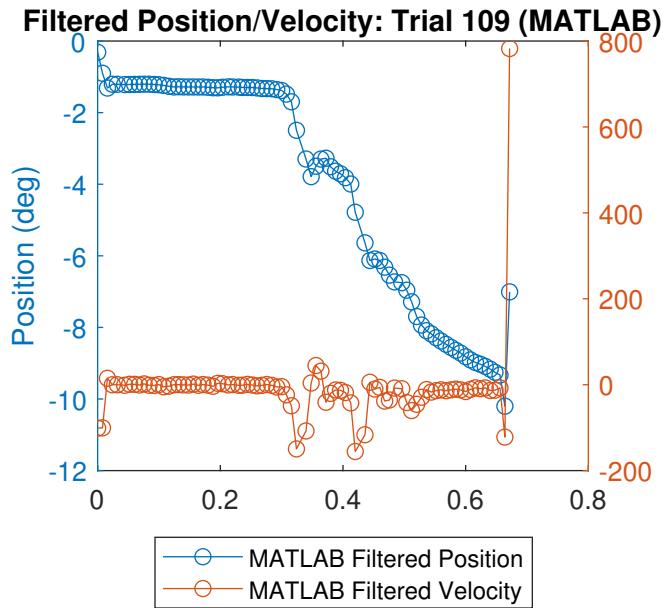


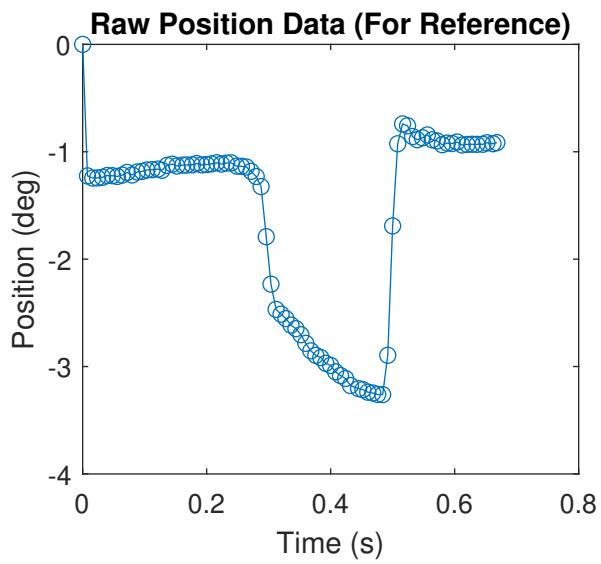
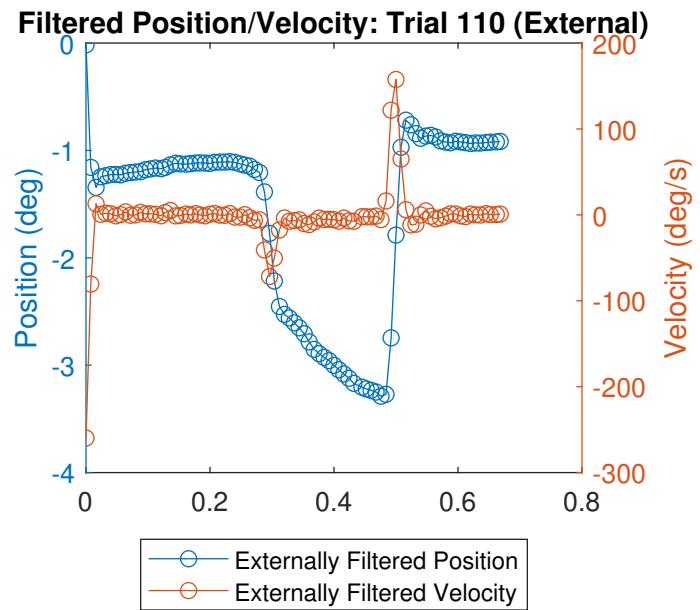
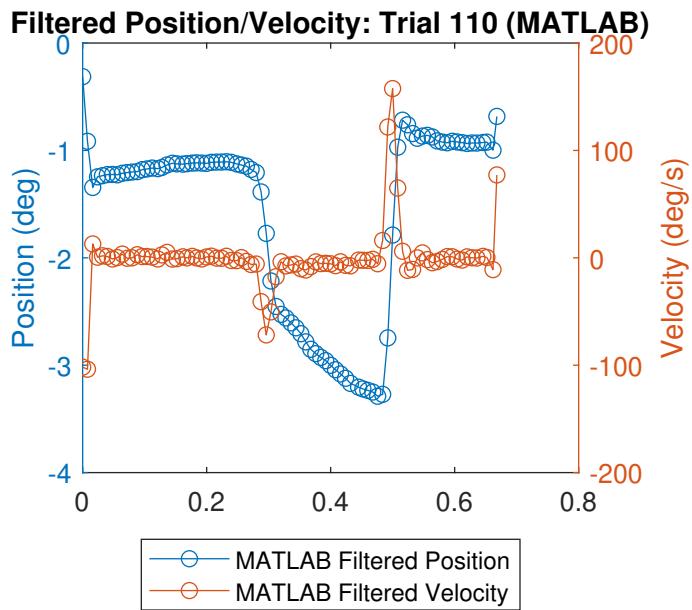
Filtered Position/Velocity: Trial 108 (External)

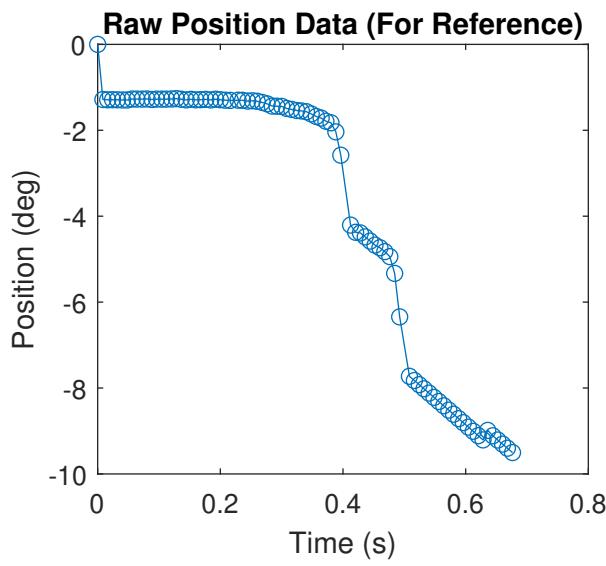
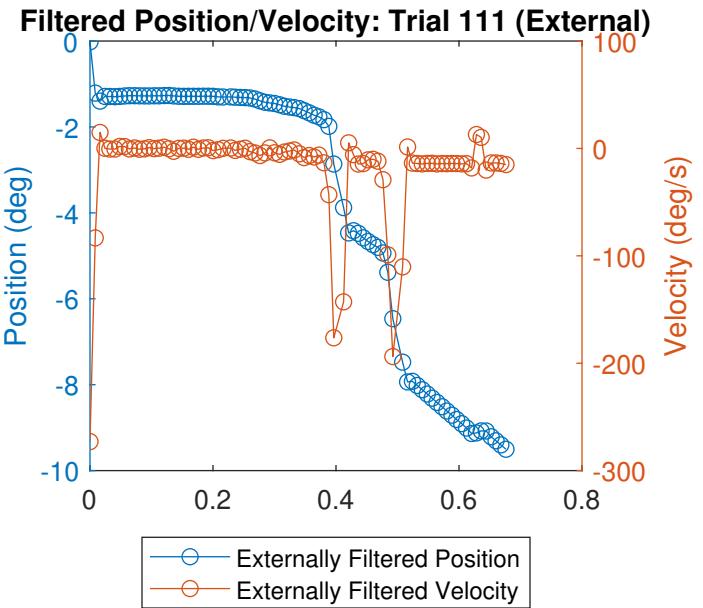
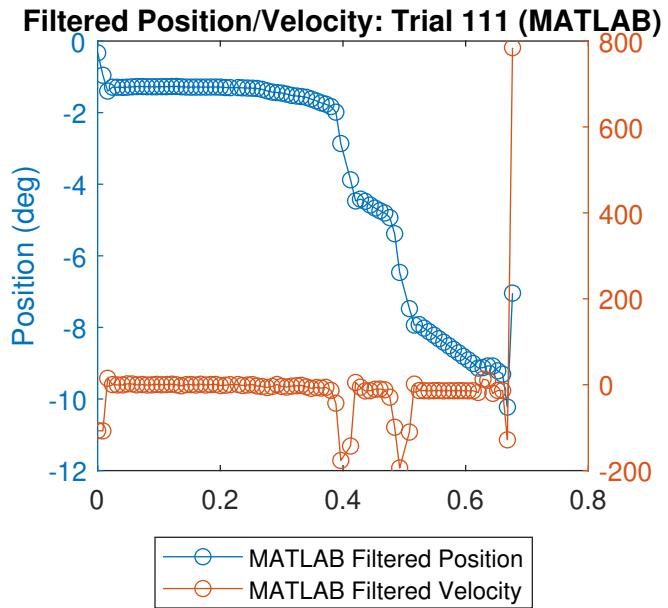


Raw Position Data (For Reference)

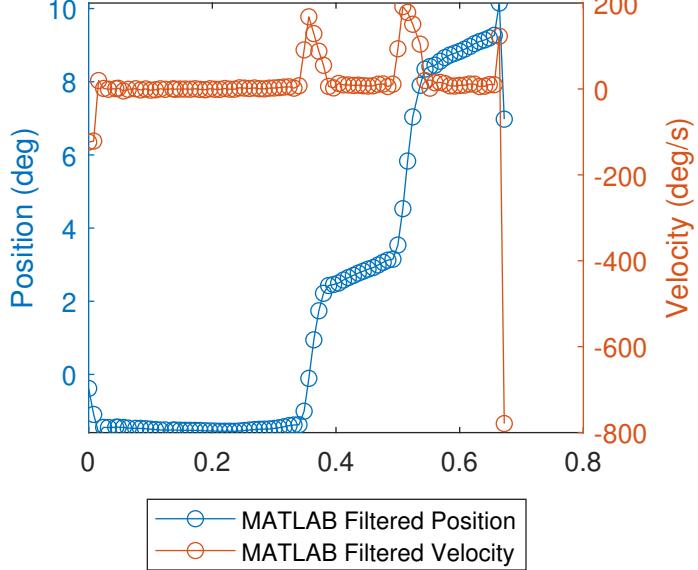




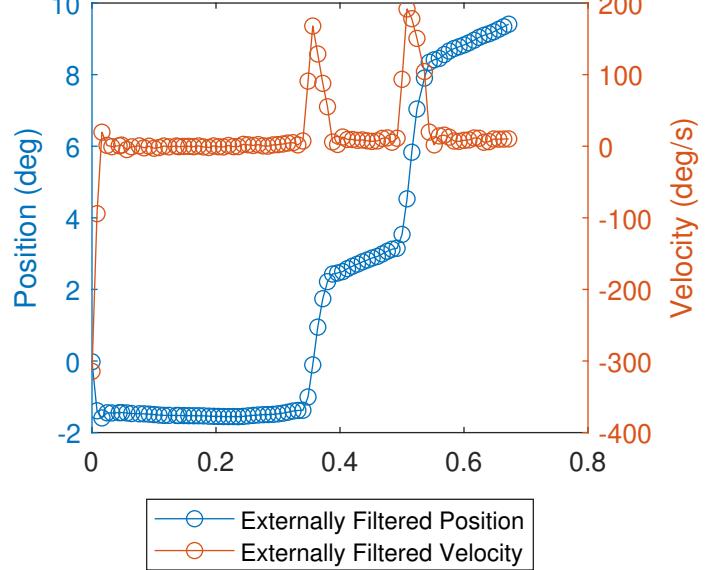




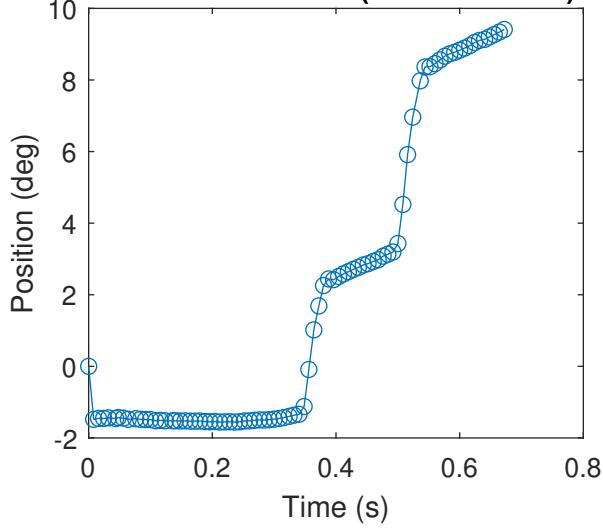
Filtered Position/Velocity: Trial 112 (MATLAB)

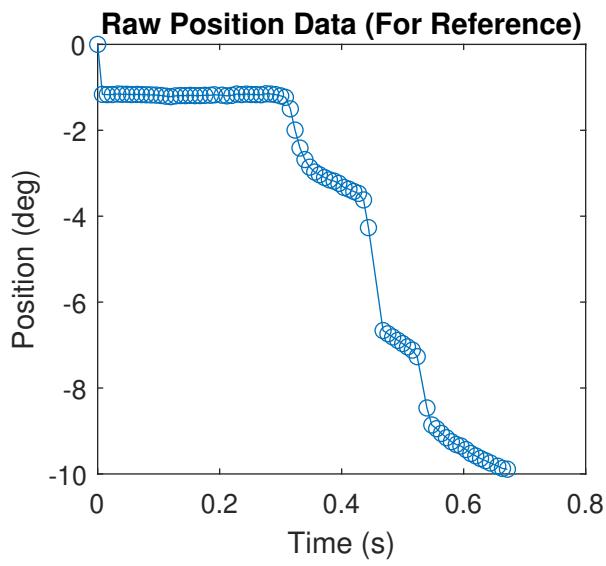
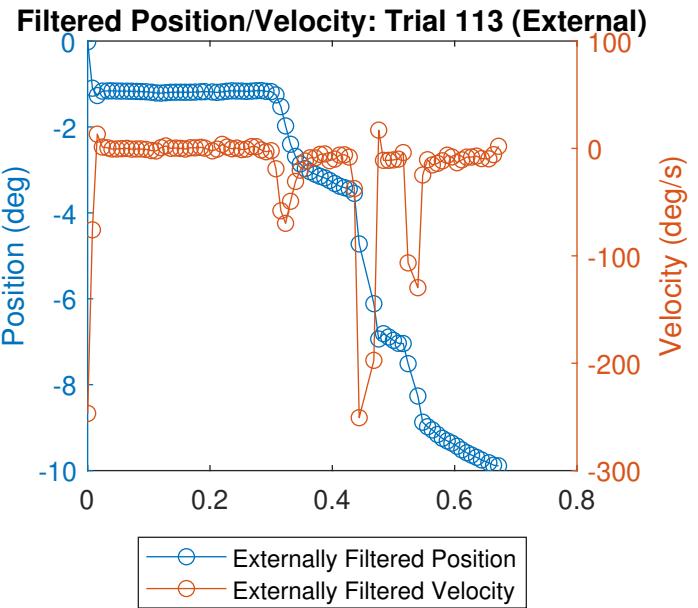
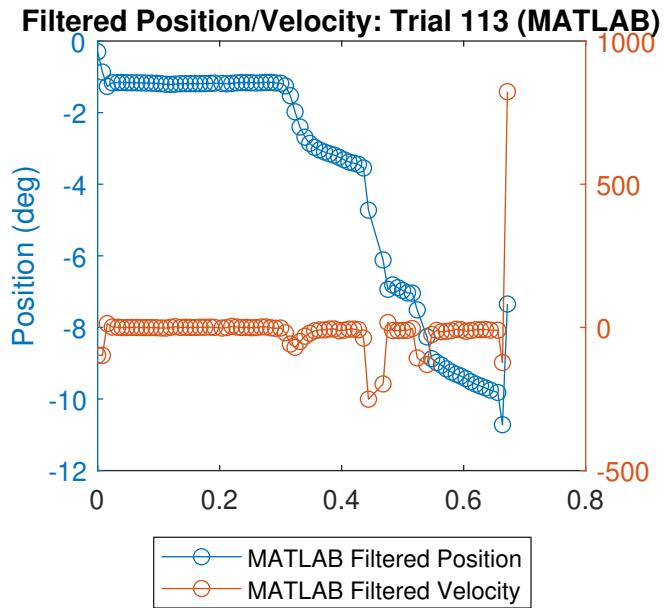


Filtered Position/Velocity: Trial 112 (External)

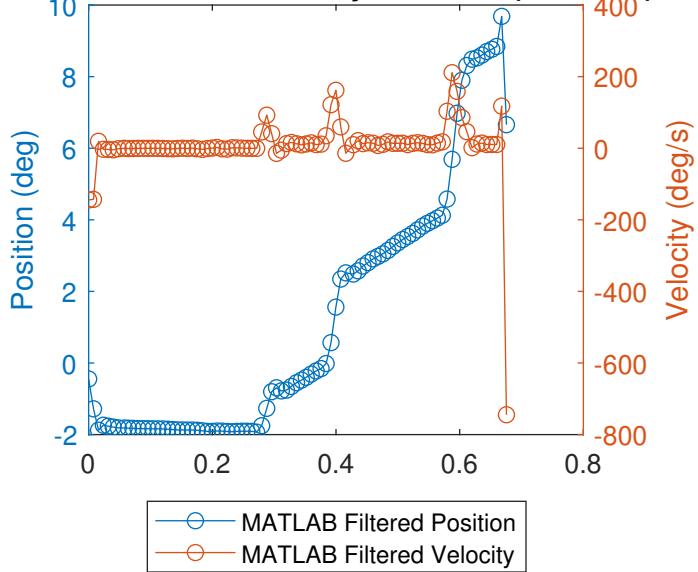


Raw Position Data (For Reference)

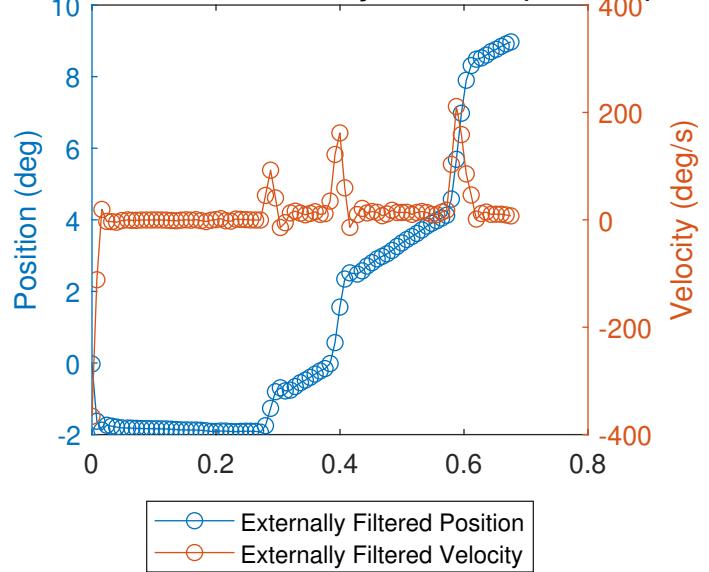




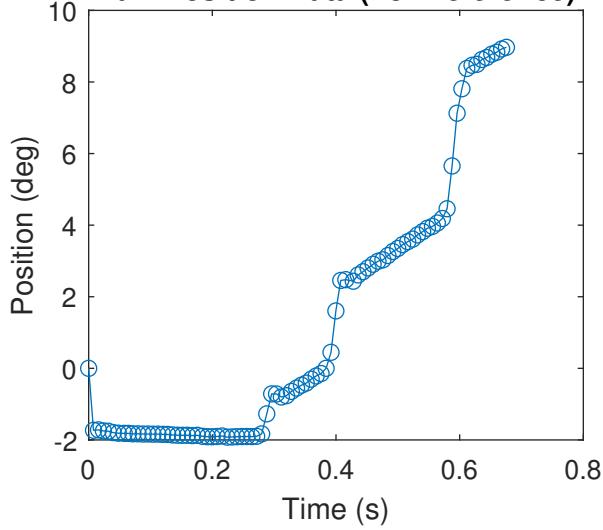
Filtered Position/Velocity: Trial 114 (MATLAB)

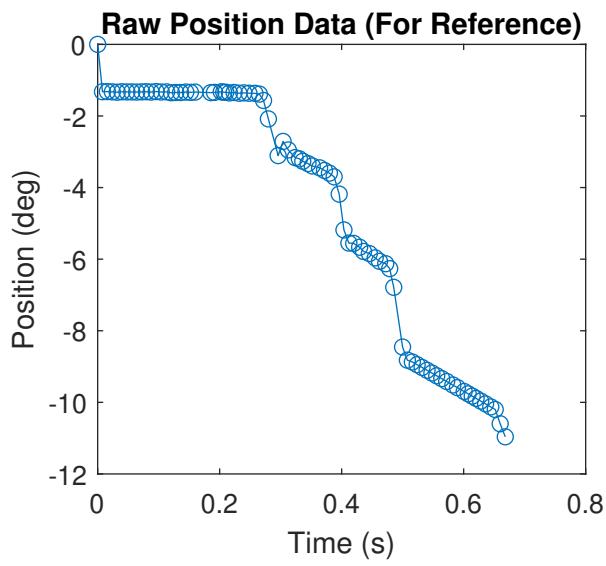
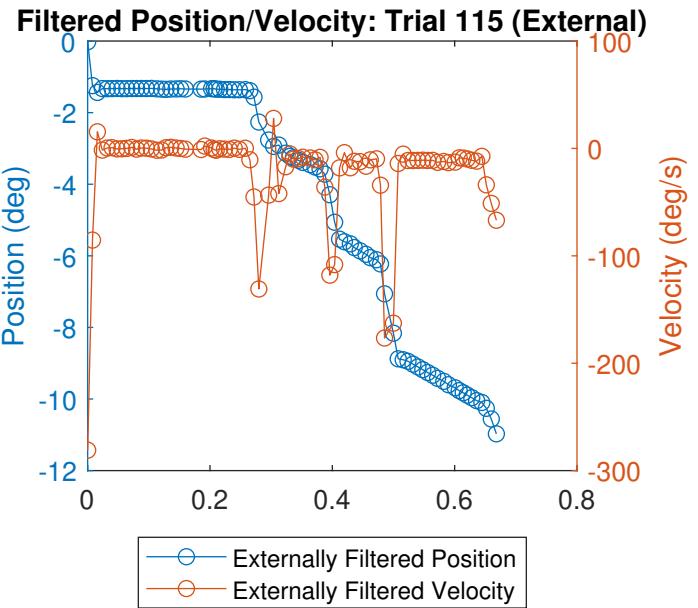
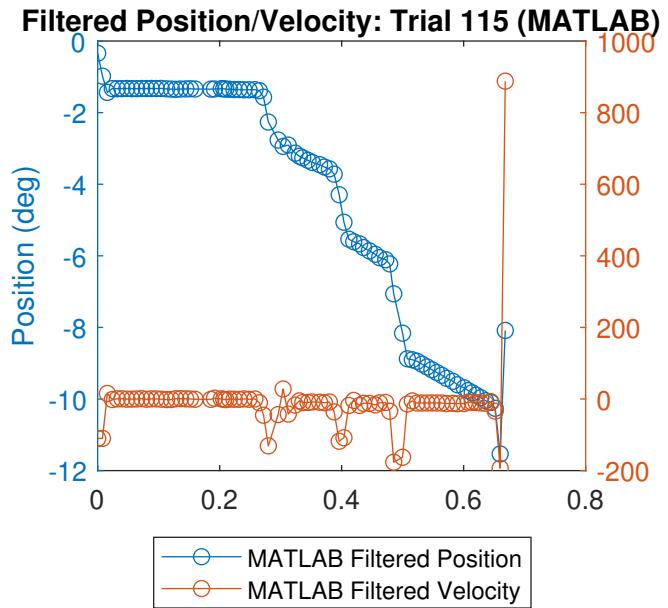


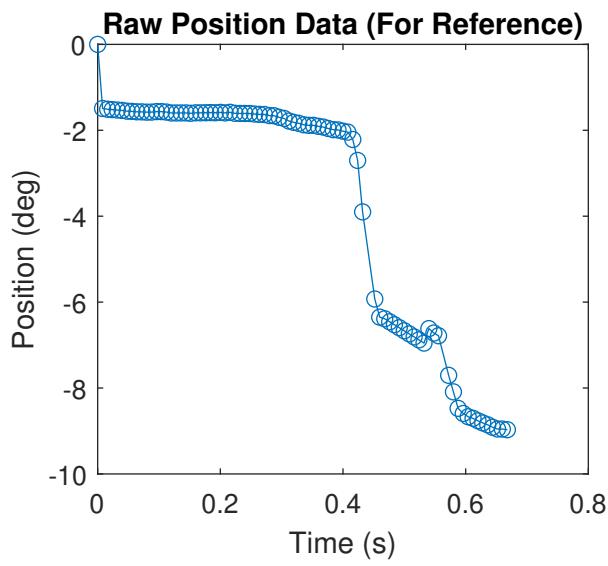
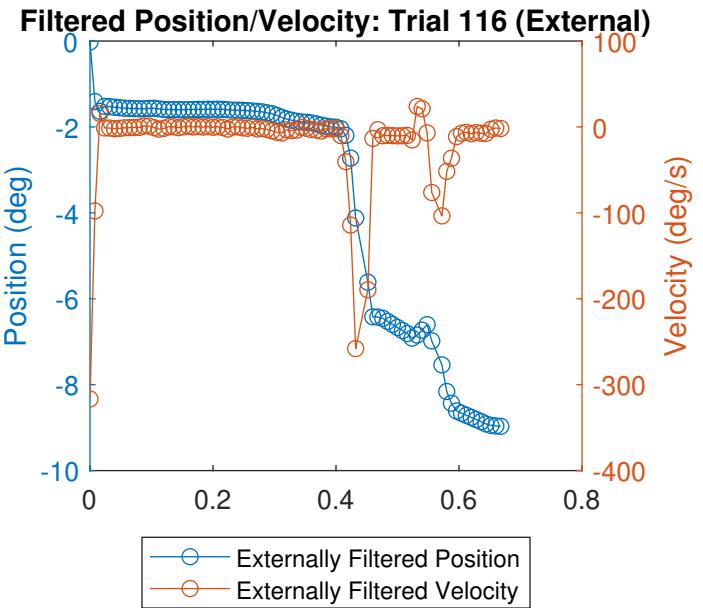
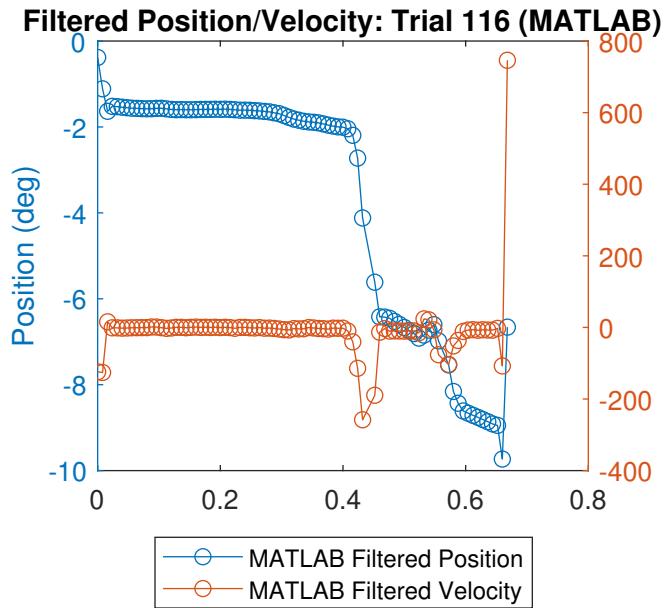
Filtered Position/Velocity: Trial 114 (External)

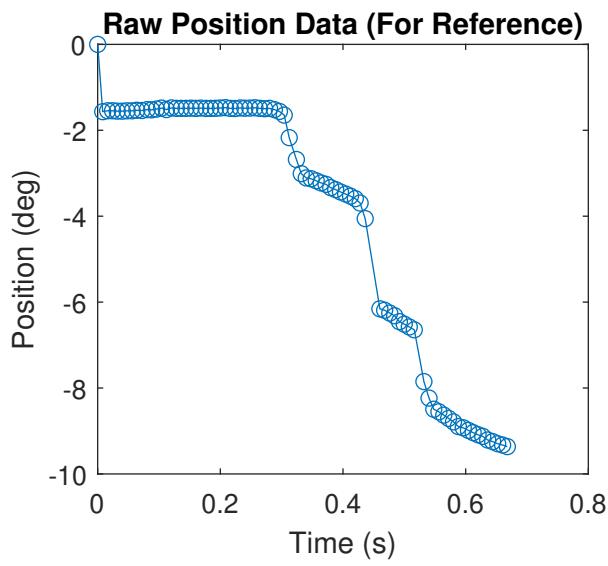
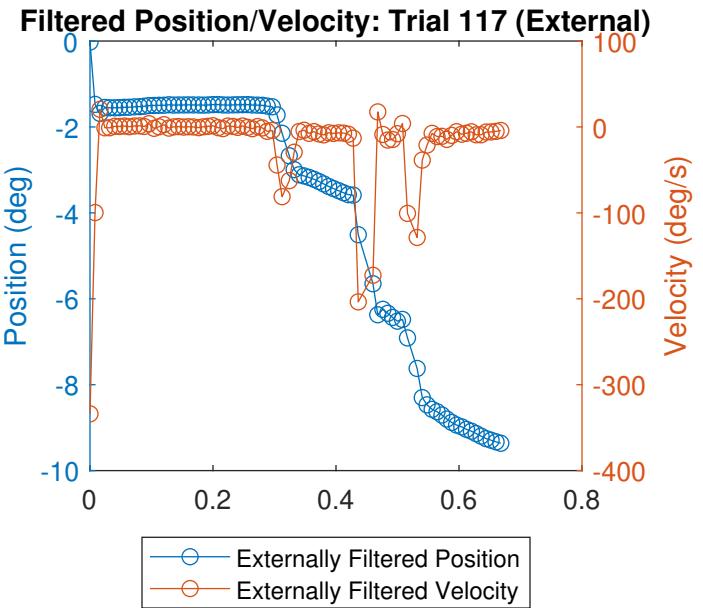
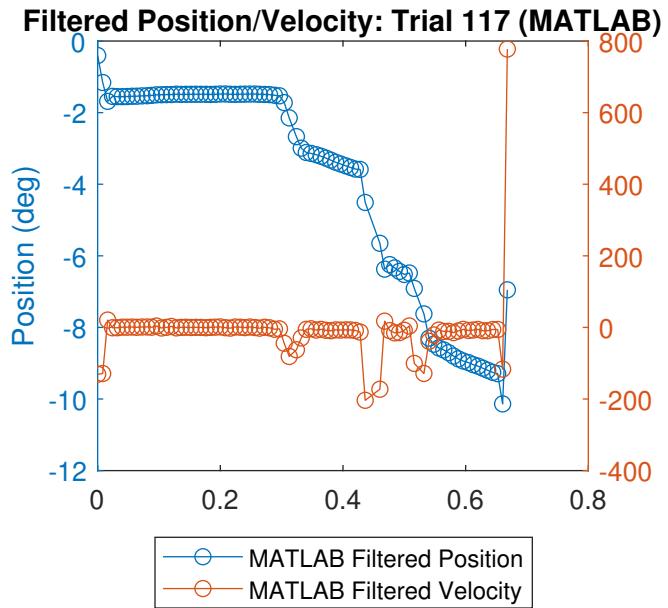


Raw Position Data (For Reference)

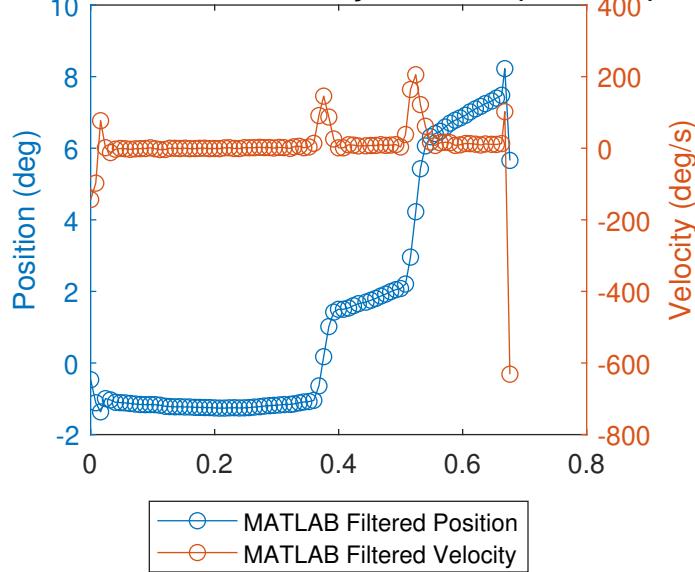




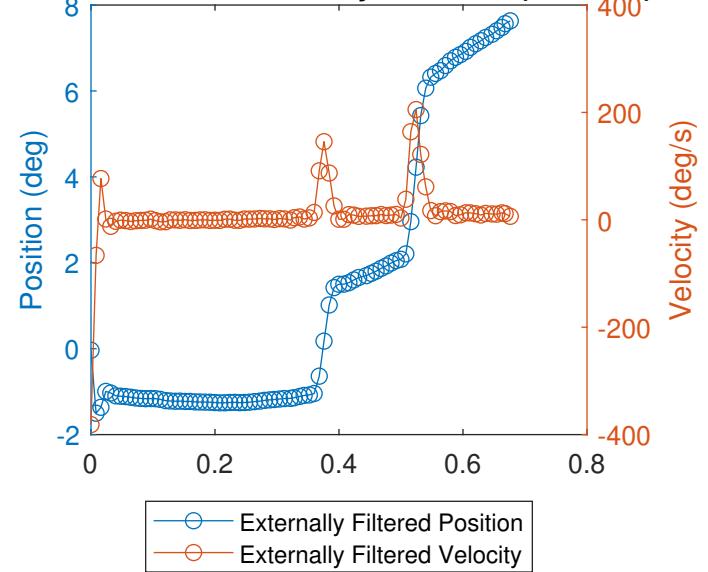




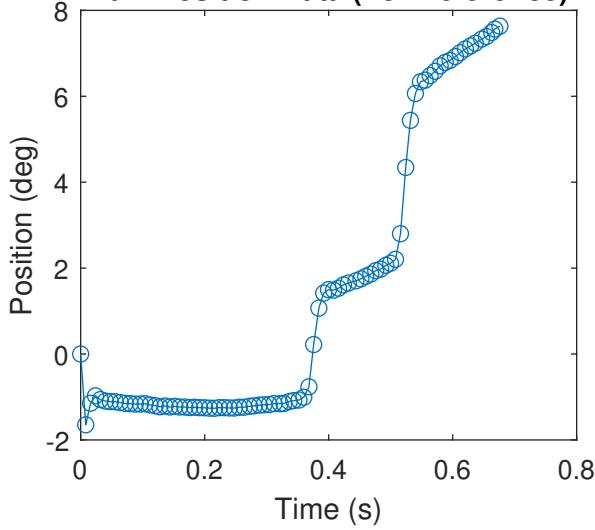
Filtered Position/Velocity: Trial 118 (MATLAB)



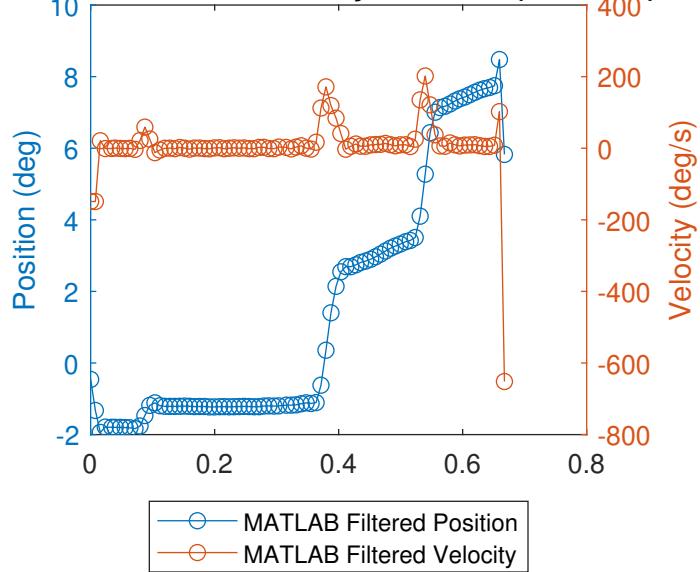
Filtered Position/Velocity: Trial 118 (External)



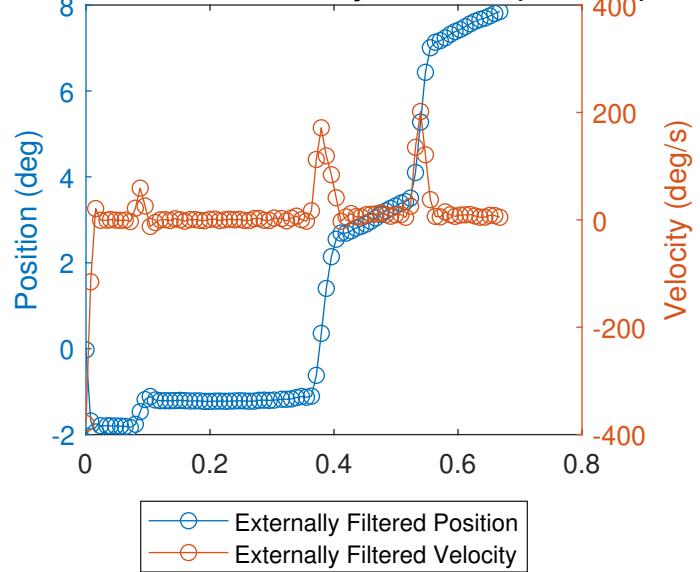
Raw Position Data (For Reference)



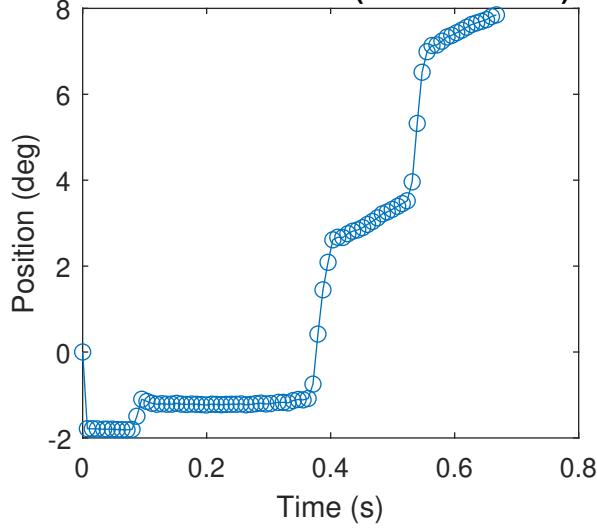
Filtered Position/Velocity: Trial 119 (MATLAB)



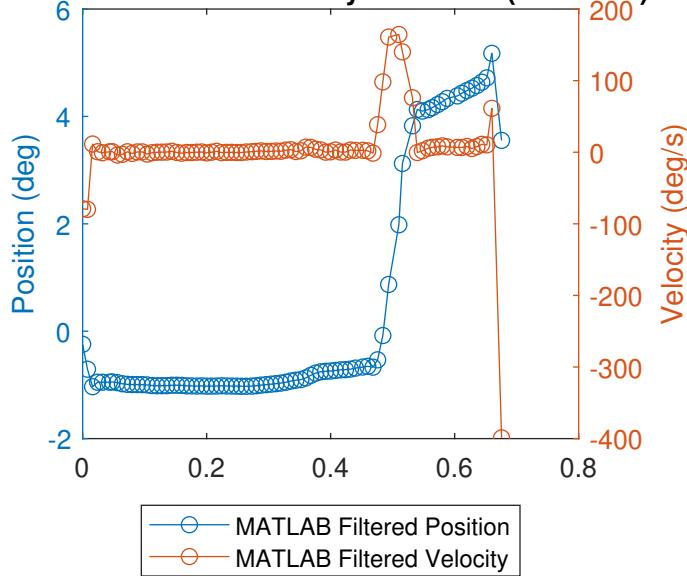
Filtered Position/Velocity: Trial 119 (External)



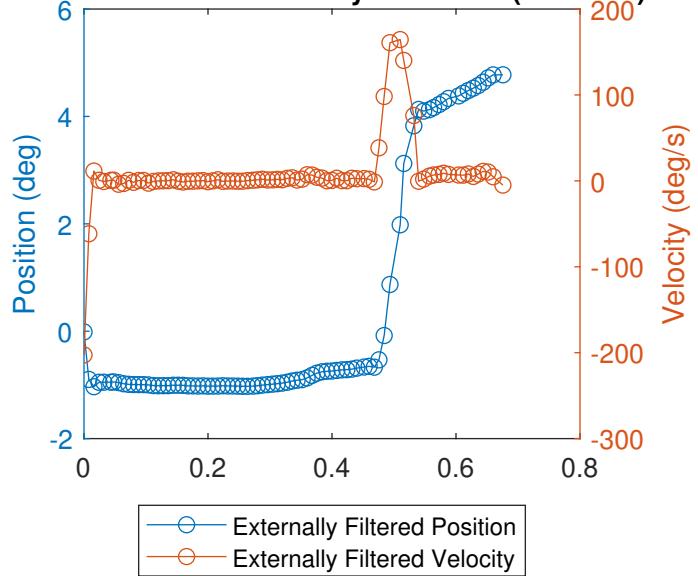
Raw Position Data (For Reference)



Filtered Position/Velocity: Trial 120 (MATLAB)



Filtered Position/Velocity: Trial 120 (External)



Raw Position Data (For Reference)

