
Problem Set #1

Reading Assignment

- Unit I: 1. Introduction to Numerical Methods for ODEs.
 - Unit I: 2. Convergence of Numerical Methods.
 - Unit I: 3. Accuracy of Numerical Methods.
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Problem 1.1 *Truncation error analysis*

Consider the following numerical integration schemes:

1.

$$u^{n+1} = 2u^n - u^{n-1} + \Delta t F(u^n)$$

2.

$$u^{n+1} = u^n + \frac{1}{4}\Delta t F(u^n) + \frac{3}{4}\Delta t F(u^{n-1})$$

- Determine the leading term of the local truncation error and identify the local order of accuracy.
- For the ODE

$$\frac{du}{dt} = c - u, \quad 0 \leq t \leq 1$$

with conditions $c = u = 0$ for $t < 0$, and $c = 1$ for $0 \leq t \leq 1$. Use numerical experiments to determine the global order of accuracy of these two schemes.

2 Solutions

Taylor expansion of necessary factors

$$\begin{aligned}
u^{n+1} &= u^n + \Delta t \left. \frac{du}{dt} \right|_{t^n} + \frac{1}{2} \Delta t^2 \left. \frac{d^2u}{dt^2} \right|_{t^n} + O(\Delta t^3) \\
u^{n-1} &= u^n - \Delta t \left. \frac{du}{dt} \right|_{t^n} + \frac{1}{2} \Delta t^2 \left. \frac{d^2u}{dt^2} \right|_{t^n} + O(\Delta t^3) \\
F(u^n) &= F^n \\
F(u^{n-1}) &= \left. \frac{du}{dt} \right|_{t^{n-1}} = \left. \frac{du}{dt} \right|_{t^n} - \Delta t \left. \frac{d^2u}{dt^2} \right|_{t^n} + O(\Delta t^2)
\end{aligned}$$

2.1 Scheme 1

$$\begin{aligned}
e &= u^{n+1} - 2u^n + u^{n-1} - \Delta t F(u^n) \\
&= u^n + \Delta t \left. \frac{du}{dt} \right|_{t^n} + \frac{1}{2} \Delta t^2 \left. \frac{d^2u}{dt^2} \right|_{t^n} + O(\Delta t^3) \\
&\quad - 2u^n \\
&\quad + \left(u^n - \Delta t \left. \frac{du}{dt} \right|_{t^n} + \frac{1}{2} \Delta t^2 \left. \frac{d^2u}{dt^2} \right|_{t^n} + O(\Delta t^3) \right) \\
&\quad - \Delta t F^n \\
&= (u^n - 2u^n + u^n) + \Delta t (F^n - F^n - F^n) + O(\Delta t^2) \\
&= -\Delta t F^n \\
&= o(\Delta t)
\end{aligned}$$

$$e = O(\Delta t^{p+1}) = O(\Delta t) \Rightarrow p = 0 \quad (1)$$

The local truncation error is $O(\Delta t)$ and the local order of accuracy is $p = 0$.

2.2 Scheme 2

$$\begin{aligned}
e &= u^{n+1} - u^n - \frac{1}{4} \Delta t (F^n + 3F^{n-1}) \\
&= u^n + \Delta t \left. \frac{du}{dt} \right|_{t^n} + \frac{1}{2} \Delta t^2 \left. \frac{d^2u}{dt^2} \right|_{t^n} + O(\Delta t^3) \\
&\quad - u^n \\
&\quad - \frac{\Delta t}{4} \left(F^n + 3F^n - 3\Delta t \left. \frac{d^2u}{dt^2} \right|_{t^n} + O(\Delta t^2) \right) \\
&= (u^n - u^n) + \Delta t \left(F^n - \frac{1}{4} 4F^n \right) + \Delta t^2 \left(\frac{1}{2} \frac{d^2u}{dt^2} + \frac{3}{4} \frac{d^2u}{dt^2} \right) \\
&= O(\Delta t^2)
\end{aligned}$$

$$e = O(\Delta t^{p+1}) = O(\Delta t^2) \Rightarrow p = 1 \quad (2)$$

The local truncation error is $O(\Delta t^2)$ and the local order of accuracy is $p = 1$

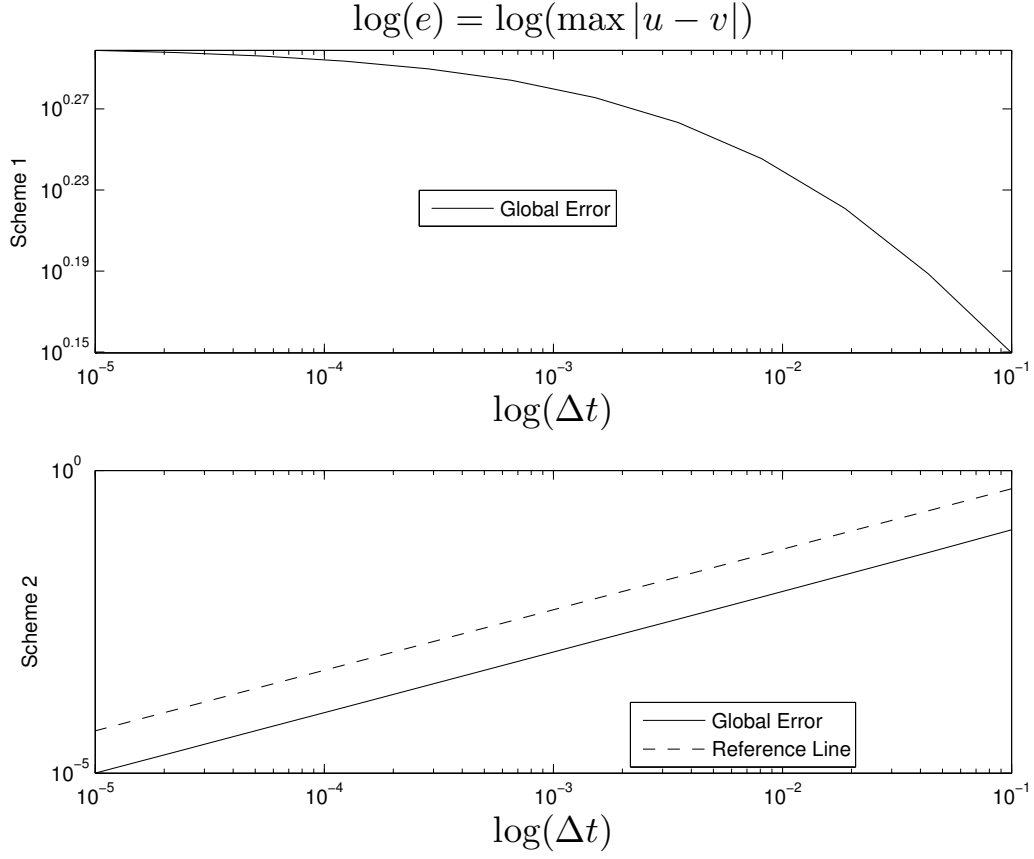


Figure 1: Log-Log Plots of Global Error with Δt

2.3 Numerical Experiments

Figure 1 shows the maximum absolute global error as a function of the time step Δt for schemes 1 and 2. Scheme 2 has an order of accuracy of 1, as you'd expect, the global error is proportional to Δt . Scheme 1 has rather large errors and the error is basically constant for small Δt (i.e. $p = 0$).

3 Code Example

```

1 clear all; close all; clc;
2
3
4 T = 1.0;
5 u0 = 0;
6 c = 1;
7
8 %Define ODE
9 F = @(u) c - u;
10
11 %True ODE solution
12 u = @(t) 1 - exp(-t);
13
14 dt_s = logspace(-1, -5, 12);
15
16 e1 = zeros( size(dt_s) );
17 e2 = zeros( size(dt_s) );
18
19 for i = 1:length(dt_s);
20     dt = dt_s(i);
21
22     t = -dt:dt:1;
23     N = length(t);
24
25     v1 = zeros(1,N); v2 = zeros(1,N);
26     F1 = zeros(1,N); F2 = zeros(1,N);
27
28     v1(1) = u0; v2(1) = u0; % j=1 is at  $t = -\Delta t$ , before ode starts
29     v1(2) = u0; v2(2) = u0; % b/c scheme 1 needs a previous step
30     F1(1) = 0 - u0; F2(1) = 0 - u0; % Remember c = 0 for  $t < 0$ 
31     F1(2) = F(u0); F2(2) = F(u0);
32
33     for j = 2:N-1;
34         v1(j+1) = 2*v1(j) - v1(j-1) + dt*F1(j) ;
35         v2(j+1) = v2(j) + .25*dt*( F2(j) + 3*F2(j-1) );
36
37         F1(j+1) = F( v1(j+1) );
38         F2(j+1) = F( v2(j+1) );
39     end;
40
41     % Use max absolute error as measure of global error
42     % Other measures are possible
43     e1(i) = max(abs( u(t) - v1)); e2(i) = max(abs( u(t) - v2));
44
45 end;

```