ALEXANDER ZENG

zeng.al@northeastern.edu | (978) 482-6082 | linkedin.com/in/a-zeng | a-zeng.github.io

EDUCATION

Northeastern University - Boston, MA

Expected May 2024

GPA: 3.95

Candidate for Bachelor of Science in Mechanical Engineering

Awards: Dean's Scholarship, Dean's List (Fall 2019 – Fall 2020)

Relevant Courses: System Analysis, Fluid Mechanics, Dynamics, Mechanics of Materials, Thermodynamics, Statics

Activities: SEDS Mars Rover Team (Mobility Co-Lead), ASME, Pep Band, Concert Band

WORK EXPERIENCE

Nextera Robotics - Boston, MA

Mechanical Engineering Intern (June 2021 – August 2021)

- Prototyped and constructed a cost-effective, vacuum suction end-of-arm tooling for a 6-axis industrial robotic arm in Fusion 360 capable of lifting 4'x8' drywall sheets according to FEA and material mechanics calculations
- Adapted geometry of a tablet interface to an infinite-Z 3D printer with DFM, reducing manufacturing time by two
- Consolidated a 360 degree and two USB cameras into a simple 4-part, 3D printed assembly
- Sourced mechanical and electrical components and compiled them into BoMs for purchase

MKS Instruments, Inc. - Andover, MA

Reliability Engineering Co-op (January 2021 – June 2021)

- Devised and designed heated, aluminum extrusion enclosures for life testing of gas analyzers, saving over \$2,000 and weeks of time compared to outsourcing
- Performed highly accelerated life testing on mass flow controllers in temperature and vibration chambers, verifying product performance specifications and writing a life testing report
- Streamlined arduous data entry by coding Python scripts to aggregate raw data into Excel spreadsheets, decreasing routine data entry time
- Improved future product reliability by keenly searching for abnormalities during testing by discovering a product series experienced memory corruption issues

PROJECTS

SEDS Mars Rover (NUROVER) – Northeastern University

Mobility Co-Lead (September 2019 – Present)

- Constructed a Mars rover with 33 Northeastern students for competition in the University Rover Challenge
- Designed numerous mobility system parts using SolidWorks with a safety factor between 3 and 10, then confirmed safety factors through iterative testing in competition-like environments under expected stresses
- Coordinated weekly team meetings to discuss design progress, ensuring Gantt chart deadlines are met
- Operated a plasma cutter, CNC mills, and power tools to manufacture parts in Northeastern's MIE machine shop

Marble Machine X CAD Team - Online

Subassembly Team Leader (June 2020 - Present)

- Collaborated weekly with 110 volunteers online to declutter and improve a machine with 6,000+ parts
- Modeled three "defeatured" parts according to QC standards, leading to an optimized, top-down master assembly controllable using one "skeleton" sketch
- Established a product breakdown structure (PBS) with an eight-digit number system to organize and group parts
- Scrutinized subassembly parts for interferences, fit, and balance of design intent with simplicity

TECHNICAL SKILLS

Applications: Fusion 360, SolidWorks, Excel, MATLAB, Maple, AutoCAD, PrusaSlicer, Cura

Other: FEA, Coding (Python, C, VBA), FDM and SLA 3D Printing, CNC Machining, Power & Hand Tools

BACKGROUND AND INTERESTS

- Enthusiastic about combining music and engineering; built a tuba using PVC pipes and 3D printing as a high school CAPStone project and saved thousands of dollars by building a practice marimba and refurbishing a broken tuba
- Enjoy tinkering with electronics and tools, building computers, discussing tech, and gaming