# Abhishek Raghuwanshi

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# **EDUCATION**

### University of British Columbia

Vancouver, BC

Bachelor of Applied Science in Electrical Engineering (3rd Year)

Sep. 2022 - May 2027

Awards: Martin Sikes Memorial Award in ECE UBC 2024, OIS Award 2022

Activities: VP Student Life @ UBC ECESS, Facilities director+Company relations manager @ UBC EUS

#### SKILLS

Hardware: System Verilog, Quartus, RTL, Testbench+simulation, Modelsim, Altium Designer, Multisim, KiCad, Serial protocols (UART, I2C, SPI), microcontroller systems(STM32, ESP32, Nrf5280,Nuvoton, EFM8, ATMEGA) Languages: C, C++, Python, HTML+CSS, JavaScript, Assembly(ARM and 8051), SQL, Pascal, LaTeX, makefiles Tools: Matlab, Simulink, Git, VS Code, Visual Studio, PyCharm, IntelliJ, STMCube IDE, Microsoft Office, Google Workspaces, Oscilloscopes, Arduino, Raspberry Pi

#### TECHNICAL EXPERIENCE

## **Electronics Team Lead**

Sep. 2023 - Present

 $UBC\ Subbots$ 

Vancouver, BC

- Led a team of 18 students in designing electronics for an Autonomous Underwater Vehicle (AUV) to participate in the International RoboSub Competition, California.
- Developed electronic speed controller PCB to convert PWM signals into three-phase outputs, integrating IMU feedback with closed loop control system using feedback from IMU using C++ with Simulink model.
- Designed **power distribution PCB** in Altium, **improving power and space efficiency by 25%**, integrating a battery monitor, and implementing an emergency kill switch for enhanced safety and reliability.
- Enabled successful project completion with a modular, debug-friendly design using I2C communication in the robot, leading the team to semifinals for the first time in the International RoboSub competition.

## **PROJECTS**

Webserver controlled BLE robot | ESP32, Nrf52840, C++, HTML+CSS, Py(Flask+BLEak), Node.js Jan 2025

- Designed a **custom motor driver PCB**, improving motor control efficiency and reducing power consumption by 20%, and developed Bluetooth-controlled robot with <100ms latency and stable 10-meter connection.
- Built a web server (with both js and python) and responsive website for real-time robot control, supporting up to 5 users simultaneously with a joystick interface for intuitive movement.
- Implemented **PID control** on an Nrf52840 based BLE microcontroller for a self-balancing robot, enhancing stability and movement accuracy by 25% for smoother operation.

Metal detecting RC robot | PIC32, ATmega, STM32, C, Python, Putty, makefiles

Mar 2024

- Developed **two-way UART** communication via **JDY40 Bluetooth** (100m range) with j5% data loss and programmed PIC32 microcontroller for magnetic flux detection (1.41mH–1.43mH) with 98% accuracy.
- Built a **software remote** as extra feature using **C** for **STM32** and **Python** for **UI**, enabling robot control via keyboard (WASD), tracking position, and plotting frequency data for verifying accuracy.
- Created analog inductance display using a servo motor controlled by timer interrupts on **PIC32** to show metal presence in specified ranges.

Reflow Oven Controller | Nuvoton microcontroller system, 8051 assembly, Python

Feb 2024

- Designed hardware controls for selecting reflow profile parameters (soak temperature/time, reflow temperature/time) and oven settings using N76E003 microcontroller in pure 8051 assembly.
- Developed **Python script** for logging temperature data and displaying animations to improve user awareness.
- Implemented dual timers in assembly to track state durations, display time information, and generate PWM for controlling oven power via SSR box.

RISC Machine | System Verilog (RTL+Testbench), ARM assembly, Altera FPGA

Nov 2023

- Engineered a a fully-functioning 32 bit CPU and Datapath using System Verilog that decodes ARM instructions and executes them completely on a DE1-SOC FPGA.
- Executed extensive coding in System Verilog synthesized in **Quartus** and created extensive **test benches** to verify the functioning of every feature using **RTL simulation waveforms** in the project using **Modelsim**.

#### Extracurricular Activities and Interests

- ullet Organized NASA International Space Apps hackathon successfully in Vancouver, with 132 participants.
- Sports: Triathlon Ultra-Iron Person, Intramural Tier-1 Basketball Champion, ECE and EUS sports teams captain.
- Recreational electric guitar player, made a project to utilise FPGA board as a digital FX pedal.