Abhishek Raghuwanshi

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EDUCATION

University of British Columbia

Vancouver, BC

Bachelor of Applied Science in Electrical Engineering (3rd Year)

Sep. 2022 - May 2027

Awards: Martin Sikes Memorial Award in ECE UBC 2024, OIS Award 2022 Activities: VP Student Life @ <u>UBC ECESS</u>, Facilities director+Company relations manager @ <u>UBC EUS</u>

• Wrote a project paper on Atomic Layer Deposition (ALD) for Semiconductor device optimization.

SKILLS

Hardware: System Verilog, RTL, Testbench+simulation, Quartus + Modelsim, PCB design(Altium, KiCAD), SPICE, Serial protocols (UART, I2C, SPI), microcontroller systems(STM32, ESP32, Nrf5280, Nuvoton, EFM8, ATMEGA) Languages: C, C++, Python, HTML+CSS, JavaScript, Assembly(ARM and 8051), SQL, Pascal, LaTeX, makefiles Tools: Matlab, Simulink, Git, VS Code, Visual Studio, PyCharm, IntelliJ, STMCube IDE, Solidworks, Onshape, Microsoft Office, Google Workspaces, Oscilloscopes, Arduino, Raspberry Pi, 3D printing

TECHNICAL EXPERIENCE

Electronics Team Lead

Sep. 2023 - Present

@ UBC Subbots

Vancouver, BC

- Led a team of 18 students in designing electronics for an Autonomous Underwater Vehicle (AUV) competing in the International RoboSub Competition.
- Developed a custom ESC PCB, converting PWM signals to 3-phase motor outputs with closed-loop IMU feedback using C++ and Simulink.
- Designed power distribution PCB in Altium, improving efficiency by 25% while also integrating BMS and an emergency safety kill switch.
- Delivered a modular and debug-friendly electronics system using I2C communication, helping the team reach RoboSub semifinals for the first time.
- Currently developing a PoE-based Ethernet interface PCB to communicate and power an Nvidia Jetson TX2 over tether without needing battery for testing.

Projects

Webserver controlled BLE robot | ESP32, Nrf52840, C++, HTML+CSS, Py(Flask+BLEak), Node.js Jan 2025

- Designed a custom motor driver PCB, improving motor control efficiency and reducing power consumption by 20%, and developed **BLE** controlled robot with <100ms latency and stable 10-meter connection.
- Built a local web server (with both Js and Python) and responsive website for real-time robot control, supporting up to 5 users simultaneously with a joystick web-interface for intuitive movement.
- Implemented PID control on an Nrf52840 based BLE microcontroller for a self-balancing robot, enhancing stability and movement accuracy for smooth operation.

Metal detecting RC robot | PIC32, ATmega, STM32, C, Python, Putty, makefiles

Mar 2024

- Developed two-way UART communication via JDY40 Bluetooth (100m range) with <5% data loss and programmed PIC32 microcontroller for magnetic flux detection (1.40mH) with 98% accuracy.
- Built a software control interface using Python for UI and STM32(in C), enabling robot control via keyboard (WASD), and feedback including position tracking + data plot for verifying accuracy.
- Created analog display for inductance controlled by timer interrupts on PIC32 to show metal presence in specified

Reflow Oven Controller | Nuvoton microcontroller system, 8051 assembly, Python

Feb 2024

- Designed hardware controls for selecting reflow profile parameters (soak temperature/time, reflow temperature/time) and oven settings using N76E003 microcontroller in pure 8051 assembly.
- Developed Python script for logging temperature data and displaying animations to improve user awareness.
- Implemented dual timers in assembly to track state durations, display time information, and generate PWM for controlling oven power via SSR box.

RISC Machine | System Verilog (RTL+Testbench), ARM assembly, Altera FPGA

Nov 2023

- Made a fully-functioning 32 bit CPU and Datapath using System Verilog that decodes ARM instructions and executes them completely on a **DE1-SOC FPGA**.
- Executed extensive coding in System Verilog synthesized in Quartus and created extensive test benches to verify the functioning of every feature using RTL simulation waveforms using Modelsim.

Extracurricular Activities and Interests

- Organized NASA International Space Apps hackathon successfully in Vancouver, with 132 participants.
- Sports: Triathlete Ultra-Iron Person, Intramural Tier-1 Basketball Champion, ECE and EUS sports team captain.
- Recreational electric guitar player, made a project to use an FPGA board as a digital FX pedal.