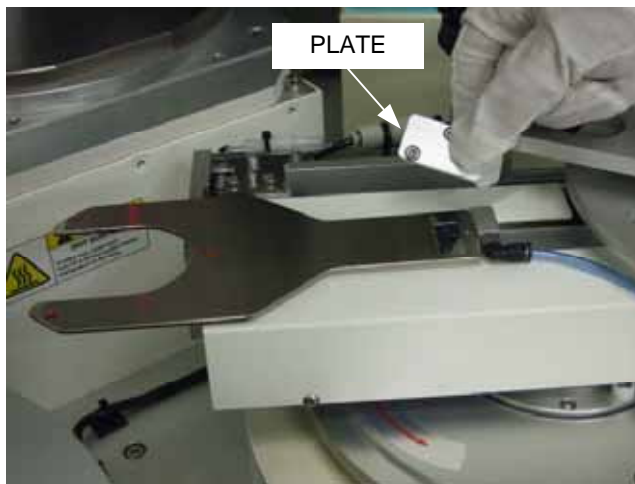


2.4 Attachment of robot arm



- (1) Attach the robot arm, and tighten the plate with two screws.

