E R	R O R	RIGHT LO	ADER C	ASSET	TE(R	L)		R L	- 1
		INPUT SI	ENSORS ( REQUI	REMENTS)		OUTPL	JT ACTUATORS		
ERROR	ERROR NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE				No.				No.	
1 0 0	RIGHT CASSE. TABLE.	Right cassette	L 00533	5 3 3	ON	Right cassette	S V 00733	7 3 3	
	FAILURE IN REVOLVING.	turning limit				turning	S V 00731	7 3 1	
		Right cassette	L 00534	5 3 4	ON	Right cassette	S V 00733	7 3 3	
		returning limit				turning	S V 00731	7 3 1	
1 0 9	RIGHT CASSE. TABLE.	4" Cassette	L S 00535	5 3 5	ON				
	CASSETTE DISLOCATED.	detected on							
		right loader							
		5" Cassette	L S 00536	5 3 6	ON				
		detected on							
		right loader							
		6" Cassette	L S 00537	5 3 7	ON				
		detected on							
		right loader							
		8" Cassette	L S 00538	5 3 8	ON				
		detected on							
		right loader							

E R	R O	R	LEFT LOA	DER CA	SSETT	E(LL	)		L L	- 1
			INPUT S	ENSORS ( REQUI	REMENTS)		OUTPL	JT ACTUATORS		
ERROR	ERROR	NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE					No.				No.	
1 3 0	LEFT CASSE.	TABLE.	Left cassette	L 00539	5 3 9	ON	Left cassette	S V 00732	7 3 2	
	FAILURE IN	REVOLVING.	turning limit				turning	S V 00734	7 3 4	
			Left cassette	L 00540	5 4 0	ON	Left cassette	S V 00732	7 3 2	
			Returning limit				turning	S V 00734	7 3 4	
1 3 9	LEFT CASSE.	TABLE.	4" Cassette	L S 00541	5 4 1	ON				
	CASSETTE DI	SLOCATED.	detected on							
			left loader							
			5" Cassette	L S 00542	5 4 2	ON				
			detected on							
			left loader							
			6" Cassette	L S 00543	5 4 3	ON				
			detected on							
			left loader							
			8" Cassette	L S 00544	5 4 4	ON				
			detected on							
			left loader							

## (OPTION)

E R	R O R	(ROBOT ARM)WAFER TRANSF	ER(RA) RA	- 1
ERROR CODE	ERROR NAME	CAUSES	COUNTERMEASURES	REMARKS
		When machine inquires robot state, Robot does not become stand-by state within the specified time.	Restart the machine according to error recovery procedure.	
	SCANNER CROSS WAFER DETECTED.	There is a cross slotted wafer.	Check cassette, if you find cross Slotted wafer, re-enter it into cassette correctly. Check a warp of a wafer. Make sure the black plate is attached on the side.	
156	SCANNER REMAINING WAFER DETECTED.	A wafer is left in the cassette.	Take out the wafer.  Make sure the black plate is attached on the side.	

E R	R O R	(ROBOT ARM)\	WAFER TRANSF	ER(RA)	R A	- 2		
ERROR	ERROR NAME	CAL	JSES	COUNTERMEASURE	ES	REMARKS		
CODE								
1 6 3	MEMORY FAULT.	Robot teaching data is	incorrect.	Refer to Robot troublesho		Perform initial resetting.		
1 6 4	WAFER CARRY UNIT R1 MOTOR FAULT.	R1-axis stepping motor	lost synchronism.	Refer to Robot troubleshood	oting manual.			
1 6 6	WAFER CARRY UNIT AXIS MOTOR FAULT.	Theta-axis stepping mot	or lost synchronism.	Refer to Robot troubleshoo	oting manual.			
1 6 7		Z-axis stepping motor I	ost synchronism.	Refer to Robot troubleshoo	oting manual.			
168	WAFER CARRY UNIT COMMAND ERROR.	Teaching data is incorr This data leads Robot t		Check MAX POSITION, PITCH SLOT of teaching data. Make equal Theta-axis data 2,6,7 and 8.				
169	NOT RESPONSE FROM ROBOT TIME OUT.	When the machine send of Robot doesn't reply wit	thin the specified time.		_			
170		·		Restart the machine accorderror recovery procedure.	ding to			
183	WAFER CARRY UNIT VACUUM FAILURE. WAFER STILL VACUUMED THOUGH CARRIED TO EACH POSITION.		fer chucking sensor doesn't become OFF.  Adjust the sensitivity of the vacuum sensor.  Make sure teaching data is correct.					
1 8 8	ROBOT SPEED DOWN READ WAIT TIME OVER.	•	eiving error. It does no vithin the specified tim	Press [RESET] [START]. Press [INITIAL].				
189	WAIT TIME OVER.	I -	eiving error. It does no within the specified tim	Press [RESET] [START]. Press [INITIAL].				
195	WAFER CARRY UNIT VACUUM FAILURE DURING WAFER PICK UP FROM CASSETTE.	Wafer chucking sensor d	doesn't become ON.	Adjust the sensitivity of sensor.	the vacuum			
199	WAFER PRESS DOWN PLAT E RETRACT ERROR.	late origin point.	611 ON	Press down pl SV 00762 ate forward	762			
		Press down p PH 00612 late end poi nt.	6 1 2 OFF	Press down pl SV 00763 ate backword	7 6 3			
2 1 0	WAFER CARRY UNIT VACUUM CHECK ERROR. WAFER STILL VACUUMED BEFORE TOUCHED WAFER.	Wafer chucking sensor d	doesn't become OFF.	Adjust the sensitivity of sensor.	the vacuum			
2 1 3	WAFER VACUUM ERROR BE FORE PRESS DOWN.	ROBOT vacuum PSW 00607 check	6 0 7 O N	Vacuum chuck SV 00746 ROBOT	7 4 6			
2 1 4		Receiving command error e operation.	due to press down plat	Press [RESET] [START]. Press [INITIAL].Refer to shooting manual.	Robot trouble			
2 1 5	WAFER CARRY UNIT VACUUM FAILURE BEFORE CARRYING WAFER TO EACH POSITION.	Wafer chucking sensor d	doesn't become ON.	Refer to Robot troubleshood Adjust the sensitivity of sensor.	-			
2 4 0	ROBOT PRESS UNIT RETU RN TO ERROR.	late origin point.	611 ON	Press down pl SV 00762 ate forward	7 6 2			
		Press down p PH 00612 late end point.	612 OFF	Press down pl SV 00763 ate backword	7 6 3			

E R	R O R	TABLE UN	IT(TA)					T A	- 1
		INPUT S	ENSORS ( REQUI	REMENTS)		OUTPL	JT ACTUATORS		
ERROR	ERROR NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE				No.				No.	
2 2 0	TABLE PAD GOING UP	Vacuum pad	L 00513	5 1 3	ON	Chuck table	S V 00741	7 4 1	
	AND DOWN FAILURE.	upper limit				unit pad up			
		Vacuum pad	L 00514	5 1 4	ON				
		lower limit							
2 2 3	CHUCKING WAFER TABLE	Wafer vacuum	PSW 00527	5 2 7	ON	Chuck table	S V 00742	7 4 2	
	VACUUM FAILURE.	check 4"				unit vacuum 4"			
		Wafer vacuum	PSW 00528	5 2 8	ON	Chuck table	S V 00743	7 4 3	
		check 5"				unit vacuum 5"			
		Wafer vacuum	PSW 00529	5 2 9	ON	Chuck table	S V 00744	7 4 4	
		check 6"				unit vacuum 6"			
		Wafer vacuum	PSW 00530	5 3 0	ON	Chuck table	S V 00745	7 4 5	
		check 8"				unit vacuum 8"			
2 2 4	CHUCKING WAFER TABLE	Wafer vacuum	PSW 00527	5 2 7	OFF	Chuck table	S V 00742	7 4 2	
	VACUUM FAILURE.	check 4"				unit vacuum 4"			
		Wafer vacuum	PSW 00528	5 2 8	OFF	Chuck table	S V 00743	7 4 3	
		check 5"				unit vacuum 5"			
		Wafer vacuum	PSW 00529	5 2 9	OFF	Chuck table	S V 00744	7 4 4	
		check 6"				unit vacuum 6"			
		Wafer vacuum	PSW 00530	5 3 0	OFF	Chuck table	S V 00745	7 4 5	
		check 8"				unit vacuum 8"			
2 2 5	TABLE WAFER VACUUM DE		PSW 00527	5 2 7	OFF	Chuck table	S V 00742	7 4 2	
	TECT MISSING.	check 4"				unit vacuum 4"			
		Wafer vacuum	PSW 00528	5 2 8	OFF	Chuck table	S V 00743	7 4 3	
		check 5"				unit vacuum 5"			
		Wafer vacuum	PSW 00529	5 2 9	OFF	Chuck table	S V 00744	7 4 4	
		check 6"				unit vacuum 6"			
		Wafer vacuum	PSW 00530	5 3 0	OFF	Chuck table	S V 00745	7 4 5	
		check 8"				unit vacuum 8"			
2 2 9	TABLE PAD	Pad vacuum	PSW 00526	5 2 6	ON	Table pad	S V 00741	7 4 1	
	VACUUM FAILURE.	check				chucking wafer			

## (OPTION)

E R	R O R	(ROBOT ARI	M)WAF	ER TR	ANSF	ER(RA)		R A	- 3
		INPUT SENS	ORS ( REQUI	REMENTS)		OUTPL	JT ACTUATORS		
ERROR	ERROR NAME	NAME	NAME	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE			PLATE	No.				No.	
2 3 8	SCANNER RESPONSE TIME	The communication b	The communication between Sequencer(KZ-10T)				ction of conn	ectors	
	OVER.	and communication u	ın i t (RZ82-	0F, 2) is	impossib	between Sequence	er and commun	ication	
		le.				board.			
2 3 9	SCANNER DATA ERROR.	The communication b	etween Se	quencer(KZ	-10T)	Check the connection of connectors			
		and communication u	ın i t (RZ82-	OF, 2) is	impossib	between Sequence	er and commun	ication	
		le.				board.			
						Check LED for Se	equencer fail	ure.	
2 4 3	SCANNER HEAD GET	Scanner head right			OFF				
	ERROR.	Scanner head left			OFF				
2 4 7	SCANNER HEAD PUT	Scanner head right			ON				
	ERROR.(WAITING POINT)	Scanner head left			ON				

E R	R O R	TAPE SET	(TS)					T S	- 1
		INPUT SI	ENSORS ( REQUI	REMENTS)		OUTPL	JT ACTUATORS		
ERROR CODE	ERROR NAME	NAME	NAME PLATE	SELECT No.	ON/OFF	NAME	NAME PLATE	SELECT No.	REMARKS
2 5 0	PEELING ROLLER MOVING FAILURE.	Pinch roller pressing end	L 00512	5 1 2		Peeling roller pressing	S V 00736	7 3 6	
2 5 1	IS NOT IN PREPARATOR'		P H 00502	5 0 2	ON	Applying unit right moving	M 00701	7 0 1	
	POSITION.	Applying stand-by position 5"	P H 00503	5 0 3	ON				
		Applying stand-by position 6"	P H 00504	5 0 4	ON				
		Applying stand-by position 8 "	P H 00505	5 0 5	ON				
2 5 2	APPLYING ROLLER GOING UP AND DOWN FAILURE.	Apply roller lower end	L 00511	5 1 1		Apply roller lower end	S V 0 4 2	0 4 2	
2 5 3	APPLYING ROLLER PRESS ING FAILURE.	Tape pressing Point	P H 00501	5 0 1	OFF	Applying unit right moving	M 00701	7 0 1	
		Peeling unit check by approaching	P H 00508	5 0 8	ON	Applying unit left moving	M 00702	702	
2 5 9	APPLYING ROLLER UNIT. FAILED TO MOVE RIGHT SIDE DIRECTION.	Applying stop position	P H 00507	5 0 7	ON	Applying unit right moving	M 00701	7 0 1	
261	PEELING ROLLER UNIT FAILED TO MOVE RIGHT SIDE DIRECTION.	Peeling unit check by approaching	P H 00508	5 0 8	ON	Peeling unit right moving	M 00704	7 0 4	
2 6 3	PEELING UNIT VACUUM FAILURE.	Wafer vacuum check 4"	PSW 00527	5 2 7	ON	Chuck table vacuum 4"	S V 00742	7 4 2	
		Wafer vacuum check 5"	PSW 00528	5 2 8	ON	Chuck table vacuum 5"	S V 00743	7 4 3	
		Wafer vacuum check 6"	PSW 00529	5 2 9	ON	Chuck table vacuum 6"	S V 00744	7 4 4	
		Wafer vacuum check 8"	PSW 00530	5 3 0	ON	Chuck table vacuum 8"	S V 00745	7 4 5	

E R	R O R	TAPE SET	(TS)					T S	- 2
		INPUT S	ENSORS ( REQU	REMENTS)		OUTP	UT ACTUATORS		
ERROR CODE	ERROR NAME	NAME	NAME PLATE	SELECT No.	ON/OFF	NAME	NAME PLATE	SELECT No.	REMARKS
264	PEELING UNIT MIS-PEELING AGAINST THREE TIME TRIAL.	Ack. of peeling	P H 00510	5 1 0	ON				Press "START" and the applying/peel-ing unit moves
265	PEELING UNIT MIS-PEELING AGAINST ONE TIME TRIAL.	Ack. of peeling	P H 00510	5 1 0	ON				left, and the peeling retry.
2 6 8	APPLYING ROLLER FAILED TO MOVE LEFT	Applying stand- by position 4"	P H00502	5 0 2	ON	Peeling unit left movement	M00705	7 0 5	
	SIDE DIRECTION.	Applying stand- by position 5"	P H 00503	5 0 3	ON	Applying unit left movement	M00702	7 0 2	
		Applying stand- by position 6"	P H 00504	5 0 4	ON				
		Applying stand- by position 8"	P H 00505	5 0 5	ON				
269	APPLYING/PEELING ROLLER FAILED TO	Applying stand- by position 4"	P H 00502	5 0 2	ON	Peeling unit left movement	M00705	7 0 5	
	MOVE LEFT SIDE DIRECTION.	Applying stand- by position 5"	P H 00503	5 0 3	ON	Applying unit left movement	M00702	7 0 2	
		Applying stand- by position 6"	P H 00504	5 0 4	ON				
		Applying stand- by position 8"	P H 00505	5 0 5	ON				
271	PEELING ROLLER NOT ROTATING PROPERLY.	Set the rewind t More than 6sec.							
273	PEELING BAR UPPER END DETECT ERROR.	Peeling baru L p limit	00609 6	0 9	ON	Peeling bar dow	SV 00764	764	
274	PEELING BAR LOWER END DETECT ERROR.	Peeling bar L down limit	00610 6	1 0	ON	Peeling bar dow	SV 00764	7 6 4	

E F	₹	R	0	R	TAPE REE	LREWI	NDER (	TRR)		Т	R R	- 1
					INPUT S	ENSORS ( REQUI	REMENTS)		OUTPL	JT ACTUATORS		
ERROR			ERROR	NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE							No.				No.	
3 5 0		SENS0	R FAILU	JRE AT	Tape take-up	P H 00518	5 1 8	ON	Tape take-up	B 00713	7 1 3	
		TAPE	TAKE-UF	)	Dancer				Brake			
		OVERT	IME WIN	NDING.	Lower limit				Cancellation			
									Tape take-up	M 00712	7 1 2	
									Section			
									Winding			

E R	R O R	WAFER ALIGNMENT UNIT(WA	) W A -	1
ERROR CODE	ERROR NAME	CAUSES	COUNTERMEASURES	REMARKS
	ALIGNER COMMAND UNCONFIRMED.	As Machine sends wrong command to Aligner, Aligner cannot recognize it. The software may have some bug.	The software has some bug.	
	ALIGNER NO RESPONSE FROM ALIGNER TIME OUT.	Though machine sends command to Aligner, Aligner does not reply to machine within the specified time.	Refer to Aligner troubleshooting Manual.	
	ALIGNER RESPONSE INDICATE BUSY ALL THE TIME. IT'S NOT REALLY STICK.	When machine inquires the state to Aligner, Aligner does not become Stand-by state within the specified time.	Restart the machine according to Error recovery procedure.	
4 4 1	ALIGNER VACUUM SENSOR OFF.	Aligner wafer chucking sensor does not become ON.	Adjust the sensitivity of wafer Chucking sensor.	
_	ALIGNER MIS-ALIGNMENT.	Aligner cannot detect O.F. and V-notch.	Check that the size and 0.F strength of the wafer is equal to other wafers	
4 5 4	ALIGNER VACUUM SENSOR ON.	Aligner wafer chucking sensor does not become OFF.	Adjust the sensitivity of wafer chucking sensor.	
	ALIGNER MOTOR BOARD ERROR.	Machine cannot communicate with Aligner DSP board.	Refer to Aligner trouble shooting manual.	
-	ALIGNER MIS-SETTING MODE.	The present wafer setting differs from the wafer setting when initial resetting.	Perform initial resetting.	
	ALIGNER CCD MIS-SETTING.	The center of wafer does not correspond with it of Aligner PAD.	Put the wafer on Aligner PAD so that The center may correspond.	
	ALIGNER CCD MEASUREMENT ERROR.	Periphery of the wafer is rugged. No response from DSP board.	Refer to Aligner trouble shooting manual.	

E R	R O R	UV UNIT(	UV)			U V - 1			
		INPUT SE	ENSORS ( REQUI				JT ACTUATORS		
ERROR CODE	ERROR NAME	NAME	NAME PLATE	SELECT No.	ON/OFF	NAME	NAME PLATE	SELECT No.	REMARKS
5 0 0	UV UNIT CHAMBER MOVING FAILURE.	Chamber shutter open	L 00546	5 4 6		UV chamber open	S V 00758	7 5 8	
		Chamber shutter close	L 00547	5 4 7					
5 0 4	UV UNIT UV SHUTTER MOVE FAILURE.	UV shutter open	L 00556	5 5 6	ON	UV shutter open	S V 00757	7 5 7	
5 0 5	UV UNIT UV SHUTTER MOVE FAILURE.	UV shutter close	L 00557	5 5 7	ON	UV shutter open	S V 00757	7 5 7	
5 0 6	N2 TIMER BEYOND SETTING RANGE.	Set the N2 purge More than 30sec.			•				
5 0 7	UV UNIT PAD VACUUM FAILURE.	UV pad vacuum check	PSW00531	5 3 1	ON	UV pad chucking wafer	S V 00760	760	
5 1 0	UV UNIT NO RESPONSE FROM UV PAD TIME OUT.	No response from	Link master			Check that conne			
5 1 1	UV UNIT PULSE MOTOR AT UV UNIT FAILED SERIAL COMMUNICATION.	Response from Li	nk master is	not corre	ect.	Link master. Test for continu	uity between	them.	
5 1 2	UV UNIT NOT INITIAL POSITION.	UV pad is not in Check the home p	•			Check that the Uturns. Test for continu	iity between		
5 1 3	UV UNIT UV PAD VACUUM FAILURE.	UV pad vacuum Check	PSW00531	5 3 1	OFF	master, Driver, UV pad chucking wafer		760	
5 1 4	UV UNIT RS COMMAND ERROR.	Command from the communication Unit (RZ82-OF) to Link master is not correct.				Check that connection between the Communication Unit (RZ82-OF,2) and Link master. Test for continuity between them.			
5 1 5	UV UNIT RS SYSTEM ERROR.	the communication Unit (RZ82-0F) broken.				Check that conne Communication Un Link master. Test for continu	nit (RZ82-OF,	2) and	
5 1 6	UV UNIT RS COMMAND TIME OUT.	Sending / receiving command error between the communication unit(RZ82-OF) and link master.				Check that conne Communication Un Link master. Test for continu	nit (RZ82-OF,	2) and	[RESET] [START]を して下さい。
5 1 7	UV UNIT RS RESPONSE TIME OUT.	Command receiving the communicat	•		master t				
5 1 8	UV UNIT RS ACCESS ERROR.	Command sending nit(RZ82-0F) to			cation u				
5 1 9	UV UNIT RS UNIT BREAK RECIVE ERROR.	Command receivin unit(RZ82-0F) t	_		ınication	Check that conne Communication Un Link master. Test for continu	nit (RZ82-OF,	2) and	
	UV UNIT RS UNIT CHARACTER TIME OVER.	Z82-0F) - link m	aster are no	t proper.		Replace the comm			
	UV UNIT RS RECIVE BUFA OVER FLOW ERROR.	o the communicat	ion unit(RZ8	2-0F).		Replace the comm			
5 2 2	UV UNIT RS PARITY ERROR.	The parity setti (RZ82-OF) — link				Replace the comm	nunication un	it.	
	UV UNIT RS FRAME ERROR.	, ,				th Remove the communication unit(RZ82-OF, 2), and attach it again. Replace the communication unit.			
	UV UNIT RS OVER RUN ERROR.	Command receiving error from link master to the communication unit (RZ82-OF).			th Remove the communication unit(RZ82-OF, 2), and attach it again.  Replace the communication unit.				
	UV UNIT RS DEFAULT ERROR.	The communication unit (RZ82-OF) default has not completed.							
5 2 6	UV UNIT RS PARAMETER SETTING ERROR.	The setting of t F) has not compl		ation unit	(RZ82-0	Remove the commu 2), and attach i Replace the comm	t again.	•	

E R	R O R	(ROBOT ARM)WAFER TRANSF	ER(RA) RA	- 4
ERROR	NAME	CAUSES	COUNTERMEASURES	
CODE				
6 2 0	WAFER CARRY UNIT	Solenoid valve for wafer vacuum is not turned	Perform initial resetting.	
	COMMAND RECEPTION	on or off.		
	ERROR.	Robot cannot start.		
6 2 2	WAFER CARRY UNIT	Wafer chucking sensor is not turned off.	Adjust the sensitivity of wafer	
	WAFER SENSED.		vacuum switch.	
6 2 3	WAFER CARRY UNIT LINE	When machine inquires the state to Robot,	Perform initial resetting.	
	BUSY. NO LINE ACCESS	Robot does not become state within the		
	TO ROBOT TIMEOUT.	specified time.		
6 3 0	WAFER CARRY UNIT	Solenoid valve for wafer vacuum is not turned	Perform initial resetting.	
	COMMAND ERROR.	on or off.		
		Robot cannot do resetting.		
6 3 9	ROBOT PRESS UNIT RETU	Press down p PH 00611 6 1 1 O N	Press down pl SV 00762 7 6 2	
	RN TO ERROR.	late origin	ate forward	
		point.		
		Press down p PH 00612 6 1 2 O F F	Press down pl SV 00763 7 6 3	
		late end poi	ate backword	
		nt.		

E R	R	0	R	TABLE UN	IIT(TA)					T A	١ .	-	2
	INPUT S			SENSORS ( REQUIREMENTS ) OUTPUT ACTUATORS					_				
ERROR		ERROR	NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	Γ		REMARKS
CODE						No.				No.			
6 4 0	TABLE	UNIT	PAD NOT	Vacuum pad	L 00526	5 2 6	ON	Chuck table	S V 00737	7 3 7	,		
	INITI	AL POS	ITION.	lower limit				unit pad up					

E R	R O R	TAPE SET	(TS)					T S	- 3
		INPUT SI	SENSORS ( REQUIREMENTS )			OUTPU	T ACTUATORS		
ERROR	ERROR NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE				No.				No.	
6 5 0	APPLYING ROLLER GOING UP FAILURE.	Applying roller down end	L 00511	5 1 1	OFF	Applying roller down	S V 00735	7 3 5	
6 5 1	APPLY/PEEL UNIT FAILED TO MOVE LEFT	Applying stand- by position 4"	P H 00502	5 0 2	ON	Peeling unit left movement	M 00705	7 0 5	
	SIDE DIRECTION.	Applying stand- by position 5"	P H 00503	5 0 3	ON				
		Applying stand- by position 6"	P H 00504	5 0 4	ON				
		Applying stand- by position 8"	P H 00505	5 0 5	ON				
653	APPLYING UNIT FAILED TO MOVE LEFT SIDE DIRECTION.	Peeling unit check by approaching	P H 00508	5 0 8	ON	Applying unit	M 00702	702	
6 5 4	PEELING ROLLER NOT ROTATING PROPERLY.								
6 5 5	PEELING ROLLER MOVING FAILURE.	Pinching roller pressing end	L 00512	5 1 2		Peeling roller pressing	S V 00736	7 3 6	

E R	R	0	R	TAPE REE	L REWI	NDER (	TRR)		T	R R	- 2
				INPUT S	ENSORS ( REQUI	REMENTS)		OUTPUT ACTUATORS			
ERROR		ERROR	NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE						No.				No.	
7 0 0	TAPE	TAKE-UI	PUNIT	Tape take-up	P H 00518	5 1 8	ON	Tape take-up	M 00712	7 1 2	
	OVERT	IME WI	ND.	dancer				Section winding			
				lower limit							
								Tape take-up	B 00713	7 1 3	
								Brake			
								cancellation			

E R	R O R	WAFER ALIGNMENT UNIT(WA	) W A	- 2
ERROR CODE	ERROR NAME	CAUSES	COUNTERMEASURES	REMARKS
	ALIGNER RESPONSE INDICATE BUSY ALL THE TIME. IT'S REALLY STICK.	When machine inquires the state to Aligner, Aligner does not become Stand-by state within the specified time.	Restart the machine according to Error recovery procedure.	
	ALIGNER COMMAND RECEPTION FAULT.	As Machine sends command to Aligner, Aligner cannot recognize it. The software may have some bug.	The software has some bug.	
7 3 4		Aligner wafer chucking sensor doesn't become OFF.	Adjust the sensitivity of the wafer chucking sensor.	
7 4 4	ALIGNER DATA FAILURE.	The data of DSP board is incorrect. The data for Aligner calibration is eliminated	Perform the calibration of Aligner. Refer to Aligner troubleshooting manual.	
	ALIGNER X AXIS RESET ERROR.	X-axis home sensor cannot be detected X-axis stepping motor doesn't run.	Check the status of X-axis home sensor. Refer to Aligner troubleshooting manual.	
7 4 6	ALIGNER Y AXIS RESET ERROR.	Y-axis home sensor cannot be detected Y-axis stepping motor doesn't run.	Check the status of Y-axis home sensor. Refer to Aligner troubleshooting manual.	
	ALIGNER LAMP AXIS RESET ERROR.	Lamp-axis home sensor cannot be detected Lamp-axis stepping motor doesn't run.	Check the status of Lamp-axis home sensor. Refer to Aligner troubleshooting manual.	

E R	R O R	UV UNIT(	UV)					U V		2
	INPUT SENSORS ( REQUIREMENTS )					OUTPUT ACTUATORS				
ERROR	ERROR NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT		REMARKS
CODE				No.				No.		
8 0 0	UV UNIT SHUTTER MOVE	UV shutter close	L 00557	5 5 7	ON	UV shutter open	S V 00757	7 5 7		
	FAILURE.									
8 0 6	UV UNIT NO RESPONSE	No response from	Link master		Check that connection between the					
	FROM UV PAD TIME OUT.					communication unit(RZ82-0F, 2) and				
8 0 7	UV UNIT PULSE MOTOR	Response from Li	nk master is	not corre	ct.	Link master.				
	AT UV UNIT FAILED					Test for continuity between them.				
	SERIAL COMMUNICATION.									
8 1 0	UV UNIT UV PAD FAILED	UV pad is not in	the home pos	sition.		Check that the U	JV pad turnin	ng motor		
	TO DETECT INITIAL	Check the home position sensor.				turns.				
	POSITION.						Test for continuity between Generate			
					master, Driver, and motor.					

E R	R O R	UV UNIT(	UV)					U V	- 3
		INPUT SI	ENSORS ( REQUI	REMENTS)		OUTP	PUT ACTUATORS		
ERROR CODE	ERROR NAME	NAME	NAME PLATE	SELECT No.	ON/OFF	NAME	NAME PLATE	SELECT No.	REMARKS
8 5 0	UV UNIT UNUSUAL EXHAUST TEMP.	UV exhaust temp. trouble	THA00559	5 5 9	OFF				
8 5 1	UV UNIT UNUSUAL UV BOX TEMP.	UV outside wall temp.trouble	THA00560	5 6 0	ON				
8 5 2	UV UNIT UV POWER SOURCE TROUBLE.	UV voltage check	U V 00563	5 6 3	OFF				
8 5 3	UV UNIT UV LAMP UNIT OPEN.	UV lamp house open	L S 00558	5 5 8	ON				
8 5 4	UV UNIT N2 PRESSURE INSUFFICIENT.	N2 vacuum check	PSW00532	5 3 2	ON	N2 purge	S V 00759	7 5 9	
8 5 5	UV UNIT UV LAMP TROUBLE.	UV power signal	U V 00561	5 6 1	ON				
8 5 6	UV UNIT IN OPERATION UV LAMP PRESSED OFF.								

E R	R O R							Е -	1
		INPUT SI	ENSORS ( REQUI		OUTPL				
ERROR	ERROR NAME	NAME	NAME PLATE	SELECT	ON/OFF	NAME	NAME PLATE	SELECT	REMARKS
CODE				No.				No.	
8 3 9	DOOR COVER OPENED.	Cover switch	CSW 00545	5 4 5	ON				
8 4 0	AIR PRESSURE NOT	Pressure	PSW 00525	5 2 5	ON				
	SUFFICIENT.	switch							
8 4 5	TABLE TEMP OUT OF SET	Table	THA 00549	5 4 9	OFF				The table temp.
	TING.	heater trouble							is out of setting
									range.
8 4 7	IONIZER TROUBLE.	lonizer trouble	I N 00548	5 4 8	OFF				Please check the
									ionizer.