

## Alexander James Wallar

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### SUMMARY

I am a student contractor at the Naval Center for Applied Research in Artificial Intelligence at the Naval Research Laboratory. I received a First Class Honours degree in computer science from the University of St Andrews in Scotland. Starting September 2015, I will be a Ph.D. candidate in the Distributed Robotics Laboratory at MIT.

### EDUCATION

Ph.D. Electrical Engineering and Computer Science      Starting September 2015  
Massachusetts Institute of Technology      Cambridge, Massachusetts

Will be working under the supervision of Dr. Daniela Rus as part of the Distributed Robotics Laboratory working on algorithms for multi-agent surveillance and persistent monitoring. Receiving the School of Engineering Lemelson Presidential Fellowship and the Office of the Dean of Graduate Education Diversity Fellowship.

B.Sc. (Honours) Computer Science      September 2012 – June 2015  
University of St Andrews      St Andrews, Scotland

First class honours degree. Direct entry into second year.

Dissertation Title: Generating Safe Trajectories in Stochastic Dynamic Environments by Leveraging Information About Obstacle Motion.

International Baccalaureate Diploma      September 2011 – June 2012  
George Mason High School      Falls Church, Virginia

Extended Essay Title: To What Extent Can Numbers of Different Bases be Used to Hide Information Effectively?

### EXPERIENCE

Student Contractor      January 2015 – Present  
Naval Research Laboratory      Washington DC, USA

Working as part of the Distributed Autonomous Systems Group at the Naval Center for Applied Research in Artificial Intelligence developing algorithms for multi-agent surveillance and persistent monitoring. Also developing middlewares that provide abstractions for controlling multi-agent systems

Undergraduate Research Assistant      August 2013 – Present  
The Catholic University of America      Various Locations

Working as part of the Computational Robotics Laboratory developing algorithms for swarm manipulation that seek to enable a group of unmanned aerial vehicles to provide surveillance over a given region. Also creating path planning algorithms for swarms that generate paths through cluttered dynamic environments.

Research Intern      May 2014 – August 2014  
Naval Research Laboratory      Washington DC, USA

Was selected as part of the Naval Research Enterprise Internship Program. Worked as part of the Distributed Autonomous Systems Group at the Naval Center for Applied Research in Artificial Intelligence and developed algorithms for surveillance of risk sensitive areas by a team of UAVs.

Research Assistant February 2014 – October 2015  
School of Computer Science, University of St Andrews St Andrews, Scotland  
Worked with Dr. Juan Ye to develop computer vision techniques to produce haptic feedback from two dimensional images.

Research Assistant September 2013 – June 2014  
School of Psychology, University of St Andrews St Andrews, Scotland  
Configured a novel experimental setup that involves three active-shutter 3D displays of different sizes that can be viewed simultaneously through beam splitters.

Research Intern May 2013 – August 2013  
University of Notre Dame Notre Dame, USA  
Was selected as part of the National Science Foundation Research Experience for Undergraduates program. Developed web applications for concussion detection. Also developed a framework for in browser eye tracking and gaze prediction.

High School Research Intern July 2012 – August 2012  
The Catholic University of America Washington DC, USA  
Created an interface for controlling an iRobot Create using voice commands spoken to an Android enabled device. Also developed algorithms for swarm path planning that enabled a group of robots to move from an initial configuration to a goal configuration.

## AWARDS

### Fellowships & Grants

- School of Engineering Lemelson Presidential Fellowship, MIT
- Office of the Dean of Graduate Education Diversity Fellowship, MIT
- Symposium Series on Computational Intelligence Travel Grant, IEEE

### Academic Prizes & Recognition

- Best Paper Award Nominee, Symposium Series for Computational Intelligence, IEEE
- Dean's List, University of St Andrews
- Best Poster Prize, University of Notre Dame

### Hackathons

- Second place, KCL Tech Society HackKing's Hackathon
- Finalist, Barclays Openminds Hackathon
- First place, J.P. Morgan Code for Good Hackathon
- Second place, University of Edinburgh Security Appathon
- Third place, University College London Hackin' the City

<b>Professional Affiliations</b>	• Student Member, IEEE	Nov '14 – Present
	• Student Member, IEEE Computational Intelligence Society	Nov '14 – Present
	• Student Member, IEEE Robotics and Automation Society	Mar '15 – Present
<b>Positions of Responsibility</b>	• Class Representative, University of St Andrews	September 2014 – Present
	• President, St Andrews Computing Society	May 2013 – June 2014
<b>Technical Interests</b>	Swarm Robotics, Emergent Behaviour, Complex Systems, Autonomous Systems, Path Planning, Aerial Robotics, Artificial Intelligence, Computational Intelligence, Evolutionary Algorithms, Robotic Middleware, Stochastic Planning, Sampling Based Motion Planning, Evolutionary Robotics, Swarm Intelligence, Consensus Filtering, Mapping, Surveillance, Search & Rescue, Game Theory	
<b>Programming Languages</b>	Python, C, C++, Java, JavaScript, Matlab, Go, C#, Maple, Mathematica, Haskell	
<b>Programming Libraries</b>	ROS, OpenCV, ZeroMQ, Flask, NumPy, Matplotlib, OpenKinect, SciPy	
<b>Publications</b>		

#### Peer-reviewed

1. **Wallar A**, Plaku E, and Sofge D (2014): “**Reactive Motion Planning for Unmanned Aerial Surveillance of Risk-Sensitive Areas.**”, IEEE Transactions on Automation Science and Engineering, in press
2. Sofge D, Sydney N, **Wallar A**, and Sullivan K (2015): “**Mobile Autonomous Navy Teams for Information Surveillance and Search (MANTISS).**”, Naval Research Laboratory Review, in press
3. **Wallar A** and Plaku E (2014): “**Path Planning for Swarms in Dynamic Environments by Combining Probabilistic Roadmaps and Potential Fields.**”, IEEE Symposium on Swarm Intelligence
4. **Wallar A**, Plaku E, and Sofge D (2014): “**A Planner for Autonomous Risk-Sensitive Coverage (PARCov) by a Team of Unmanned Aerial Vehicles.**”, IEEE Symposium on Swarm Intelligence
5. **Wallar A** and Plaku E (2014): “**Path Planning for Swarms by Combining Probabilistic Roadmaps and Potential Fields.**”, Springer LNAI Towards Autonomous Robotic Systems, vol. 8069, pp. 417 – 428

#### Theses

1. **Wallar A** (2015): “**Generating Safe Trajectories in Stochastic Dynamic Environments by Leveraging Information About Obstacle Motion**”, Undergraduate Thesis, University of St Andrews

## Posters & Presentations

1. **Wallar A**, Plaku E, and Sofge D (2014): **Risk Sensitive Surveillance with Optimal Sensor Quality for Distributed Robotic Systems**, Entrepreneur First UnHacked, London, UK
2. **Wallar A**, Poellabauer C, Sazonovs A, and Flynn P (2014): **Camgaze.js: A JavaScript Library for Eye Tracking and Gaze Prediction**, Edinburgh University Young Scientific Researchers Association (EUYSRA) Conference, Edinburgh, UK
3. **Wallar A**, Choi C, and Sazonovs A (2013): **Bowtie: In-browser Mobile Aided Sensor Acquisition using HTML5**, Scottish Informatics and Computer Science Alliance (SICSA) DemoFest, Glasgow, UK
4. **Wallar A**, Poellabauer C, Sazonovs A, and Flynn P (2013): **Camgaze.js: A JavaScript Library for Eye Tracking**, Scottish Informatics and Computer Science Alliance (SICSA) DemoFest, Glasgow, UK