# HARDWARE: LOCOMOTIONS & MECHANICAL DESIGN (2-ACTUATORS)

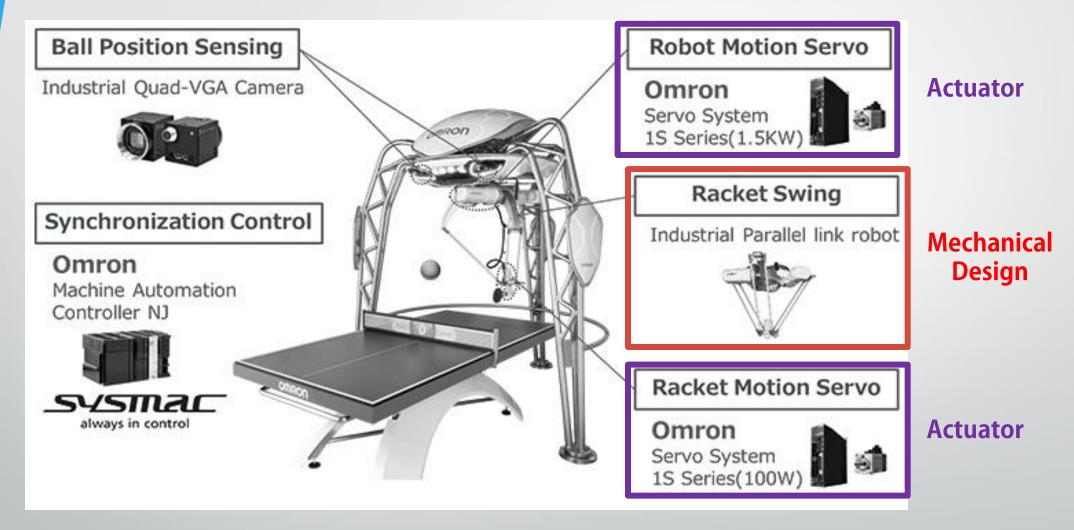
- Basic Motion Principle
- Hardware Components (Specifications, Brands and Price)

#### **Contents**

- 1. STATIONARY ROBOTS
  - a) Omron Forpheus Robot
- 2. WHEELED ROBOTS & TRACKED ROBOTS
  - a) Single Wheel BB-8
  - b) 4WD Omni-Directional Mobile Robot
  - c) Wall Climbing Robot (Metal vs Wall vs Glass)
- 3. LEGGED
  - a) Humanoid Robot (BIOLOID)
- 4. SWIMMING
  - a) Fish Robot
  - b) Underwater Glider Robot
- 5. OTHERS
  - a) Kilobot

#### 1. STATIONARY ROBOT

#### a) Omron Forpheus Robot



The **basic motion principle** of this robot uses the concept of **Parallel Link Robot**. A parallel link robot is composed of a mobile platform connected to a fixed base by a set of identical parallel kinematic chains, which are called legs. The end-effector is fixed to the mobile platform.

#### 1. STATIONARY ROBOT

- a) Omron Forpheus Robot
  - Actuators Hardware Components (Robot Motion Servo)

# Omron 230 V 1.5 kW Servo Motor, 3000 rpm, 14.3 Nm Max Output Torque

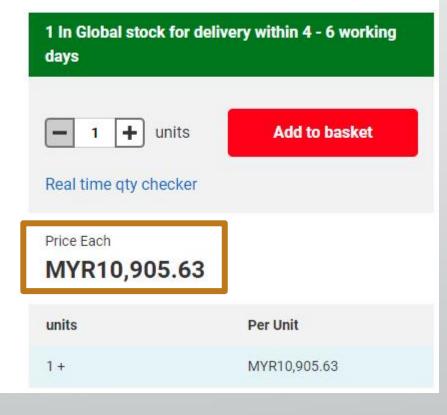
**OMRON** 

RS Stock No.: 215-3431 Mfr. Part No.: R88M-1L1K530H-S2 Manufacturer: Omron





Attribute	Value
Maximum Output Torque	14.3 Nm
Supply Voltage	230 V
Output Speed	3000 rpm
Power Rating	1.5 kW



#### 1. STATIONARY ROBOT

- a) Omron Forpheus Robot
  - **Actuators Hardware Components (Racket Motion Servo)**



Image shown is a representation only. Exact specifications should be obtained from the product data sheet.

## R88M-G10030L

Digi-Key Part Number Z10012-ND

Omron Automation and Safety Manufacturer

Manufacturer Product Number R88M-G10030L

Description SERVOMOTOR 3000 RPM 100V

Manufacturer Standard Lead Time 4 Weeks

- AC Motor Servomotor 3000 RPM 100W Incremental **Detailed Description** 

100VAC

Customer Reference

Customer Reference

Datasheet



Datasheet

#### Voltage - Rated

100VAC

#### RPM

3000 RPM

Torque - Rated (oz-in / mNm)

45.32 / 320

Power - Rated

100W

#### 1 In Stock

Can ship immediately Factory Stock: 2 ②

#### QUANTITY

Quantity

#### Add to Cart

Add to List

All prices are in MYR

#### Bulk

QTY	UNIT PRICE	EXT PRICE
1	RM3,912.02000	RM3,912.02

# a. Single Wheel BB-8

#### **How it Works**

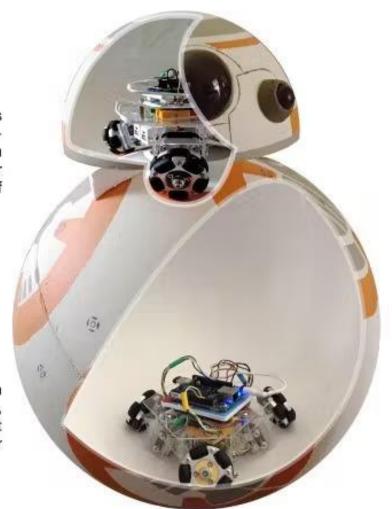
My BB-8 uses two robots that work independently. One to drive the body motion and the other to balance the head.

#### Balance

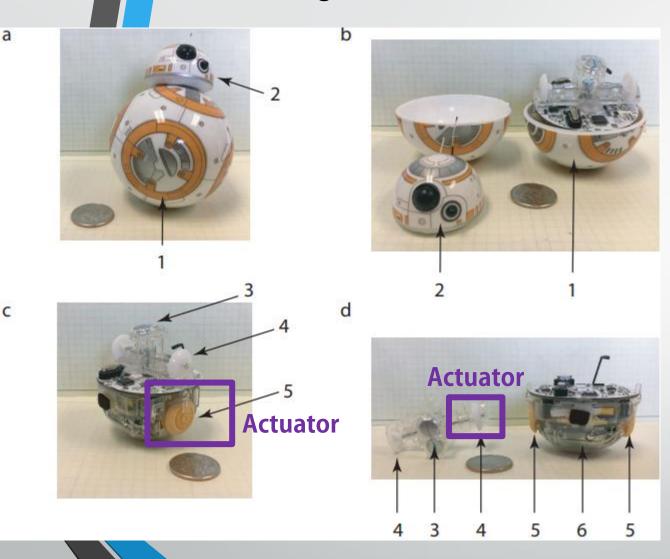
BB-8's head is kept on top of its body by a robot who has one job balance. It uses information from its gyroscope and accelerometer to magically counter the motion of the body.

#### Drive

BB-8 can roll in any direction thanks to a robot housed inside, running like a hamster in its ball. It can take direction via WiFi or follow a pre-programmed path.



a. Single Wheel BB-8



- a. The robot in motion showing the spherical shell
- b. Deconstructed robot following cutting the spherical shell into hemispheres and removal of cap
- c. The inner mechanism of the robot showing one of the two wheels
- d. Image of the inner mechanism showing the pair of wheels used to locomote the spherical shell and the pendular mechanism.
- 1. The spherical cap
- 2. The Cap
- 3. The Pendular Mechanism
- 4. The Pair of Wheels to help maintain contact
- 5. The Two Wheels to locomote the spherical shell
- 6. The Induction coil

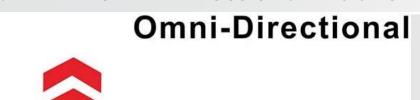
a. Single Wheel BB-8

35 ohms per winding

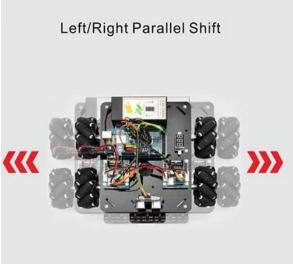
Actuators Hardware Components (Stepper Motors)

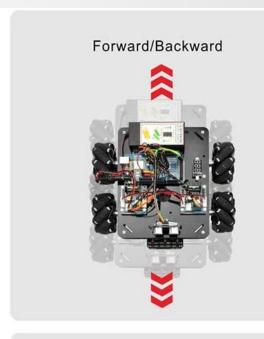


## 2. WHEELED ROBOTS & TRACKED ROBOTS b. 4WD Omni-Directional Mobile Robot





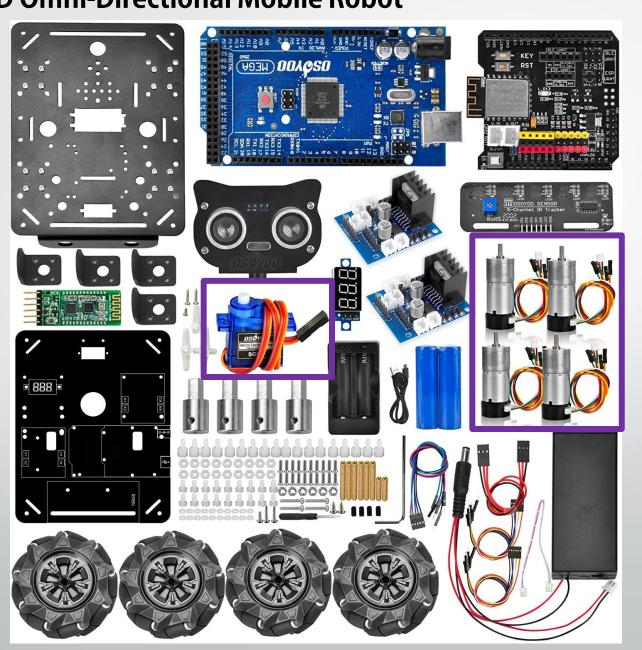








# 2. WHEELED ROBOTS & TRACKED ROBOTS b. 4WD Omni-Directional Mobile Robot



**Actuator** 

- b. 4WD Omni-Directional Mobile Robot
  - Actuators Hardware Components (DC Gear Motor)

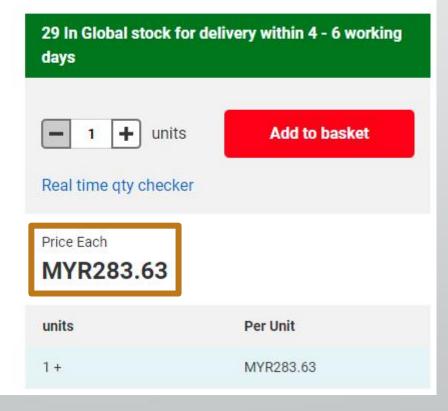
# Philips Brushed Geared DC Geared Motor, 2.2 W, 12 V, 25 mNm, 330 rpm, 4mm

PHILIPS

RS Stock No.: 336-321 Mfr. Part No.: 9904 120 52602 Manufacturer: Philips

**Shaft Diameter** 

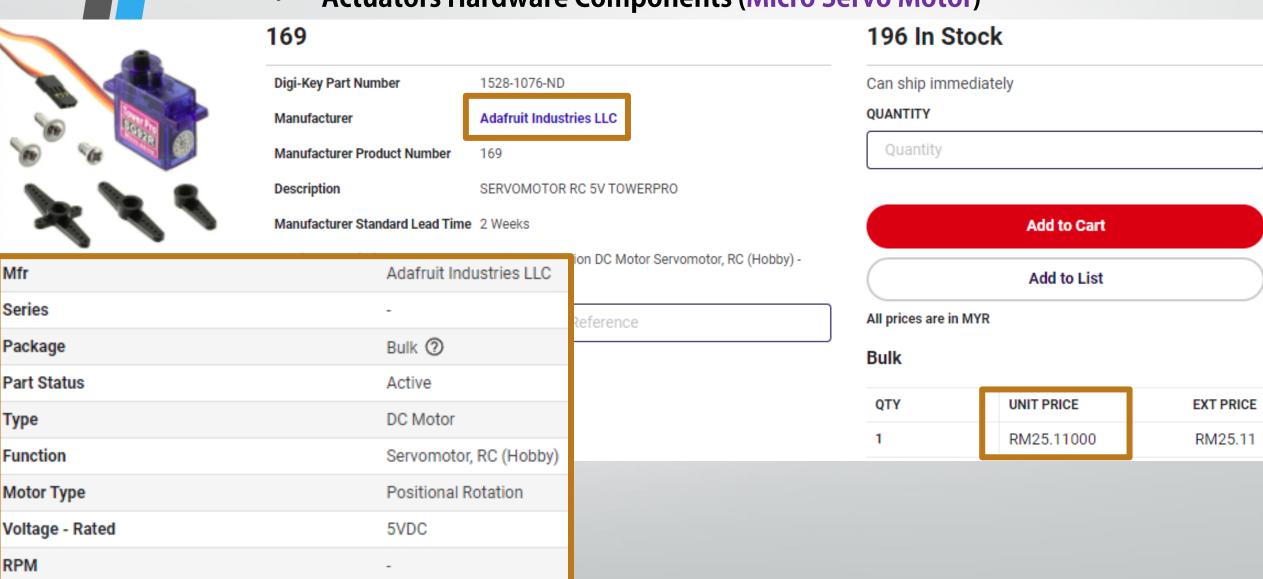




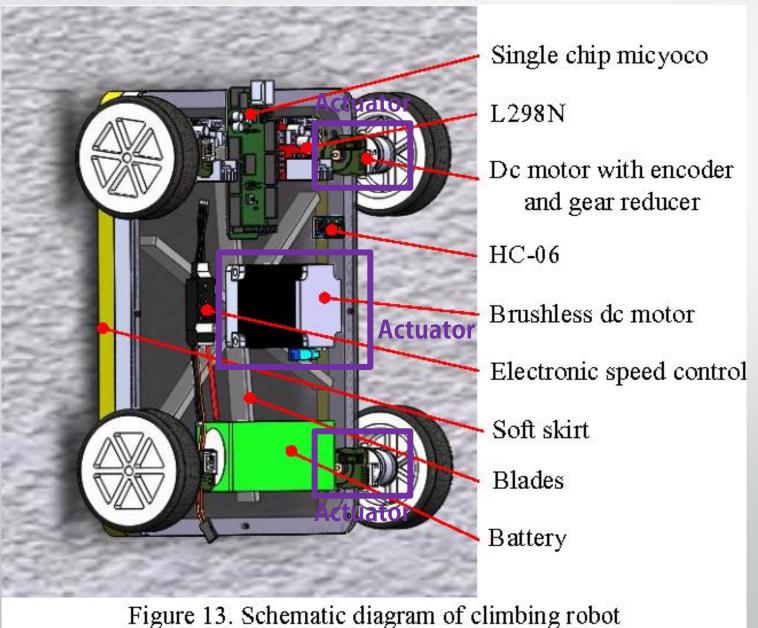
22.22 / 156.9

Torque - Rated (oz-in / mNm)

- b. 4WD Omni-Directional Mobile Robot
  - Actuators Hardware Components (Micro Servo Motor)



c. Wall Climbing Robot (Metal vs Wall vs Glass)



- c. Wall Climbing Robot (Metal vs Wall vs Glass)
  - Actuators Hardware Components (Gear Reducer DC Motor)



0.34

0.5

48

60

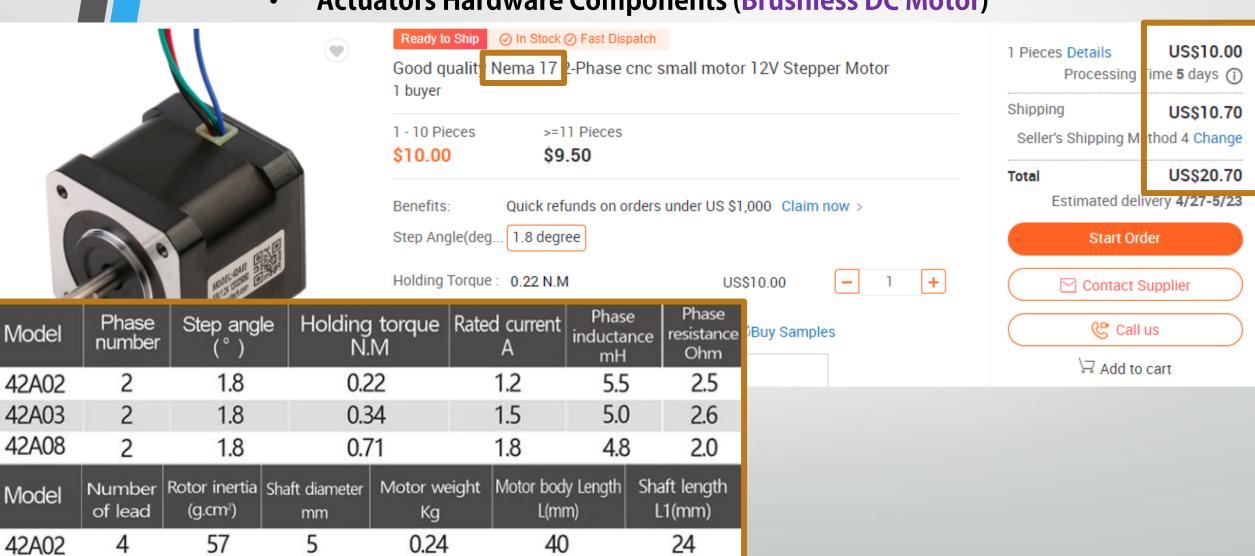
82

114

42A03

42A08

- **Wall Climbing Robot (Metal vs Wall vs Glass)** 
  - **Actuators Hardware Components (Brushless DC Motor)**

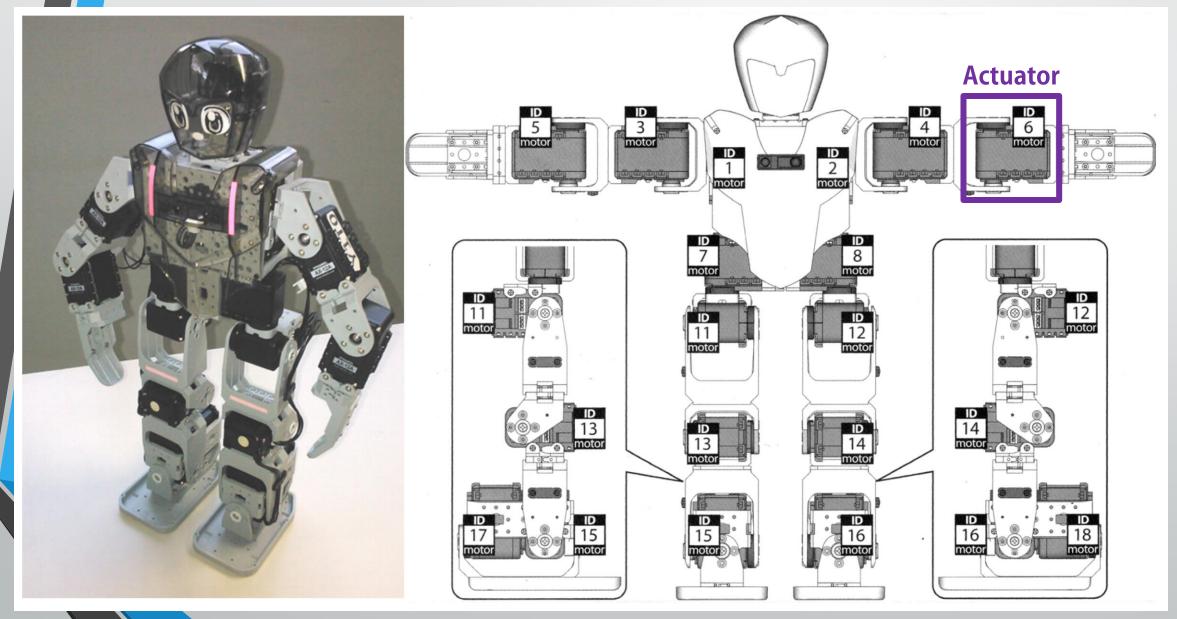


24

24

## 3. LEGGED

a. Humanoid Robot (BIOLOID)



#### 3. LEGGED

- a. Humanoid Robot (BIOLOID)
  - Actuators Hardware Components (Servo Motor)



Specification:

Model: XL-320 Weight: 16.7g

Size: 24mm\*36mm\*27mm

Gear ratio: 238:1

Operating voltage: 6~8.4V (recommended voltage 7.4V)

Static torque: 0.39Nm No-load speed: 114RPM Motor: core motor

Minimum control angle: about 0.29°\*1024

Operating range: steering gear mode: 300°, wheel mode: unlimited rotation

Operating temperature: -5°C~70°C Command signal: data packet

Communication protocol: half-duplex asynchronous serial communication (8bit, 1 stop, no parity)

Physical connection: TTL multipoint bus (daisy chain connection)

ID: 253ID (0~252) Baud rate: 7843~1Mbps

Feedback function: position, temperature, load, input voltage, etc.

Material: engineering Plastic

XL-320 Servo Dynamixel X Servo Core Motor 114RPM 0.39Nm Torque for Darwin Robot

Condition: New

Quantity:

More than 10 available

Price: US \$47.76

**Buy It Now** 

Add to cart

Add to Watchlist

30-day returns

Shipping: FREE SpeedPAK Economy | See details

International shipment of items may be subject to customs processing and additional charges.

Located in: 深圳, China

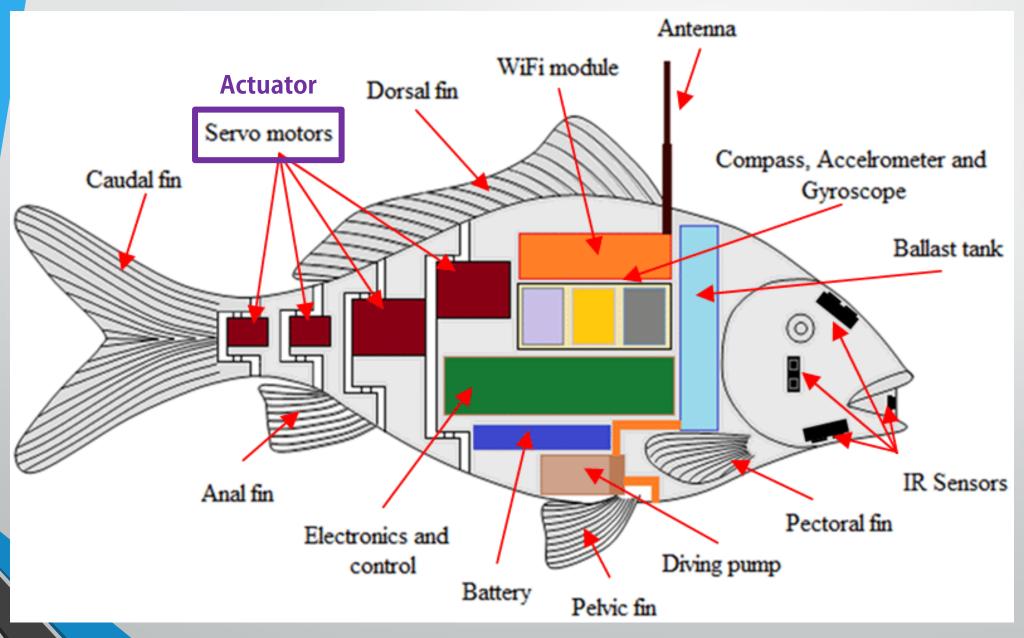
Delivery: Estimated between Thu, Jun 9 and Thu, Jul 28 (i)

This item has an extended handling time and a delivery estimate greater than 25

hucinace dave

#### 4. SWIMMING

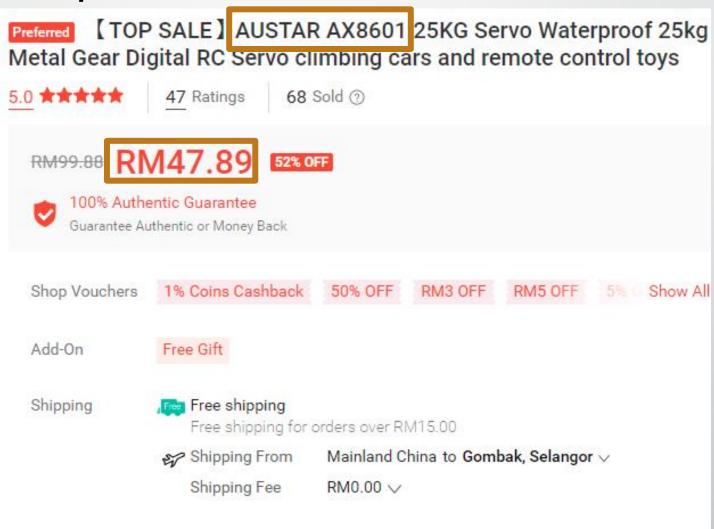
#### a. Fish Robot



#### 4. SWIMMING

- a. Fish Robot
  - Actuators Hardware Components (Servo Motor)





Weight: 60g

Angle: 130-160°

Size: 40 \* 40 \* 20mm

#### 4. SWIMMING b. Underwater Glider Robot **Actuators** O-ring Rear Tank Front O-ring Wing Groove Plate Piston Inside) Plate Linear Rotary Groove Rotary Pressure Servo Servo Battery Mass Sensor Control Mass Back Cap (flooded) Electronics Ballast Front Cap Assembly (Pump Inside)

#### 4. SWIMMING

- b. Underwater Glider Robot
  - Actuators Hardware Components (Linear Actuator)



Material: Aluminum, Stainless Steel

- Voltage: 12V

Outer tube Diameter: 35mm

Inner tube Diameter: 20mm

- Stroke: 150mm

- Speed: 7mm/s

- Thrust: 2000N

- Hole diameter: 6mm

Installment pitch of holes: 353mm/ 13.9inch

kokiya 35mm 12V 150mm Stroke 7mm/s 2000N Electric Linear Actuator IP65 Waterproof

ជាជាជាជាជា No Ratings

Brand: No Brand | More Power Tools from No Brand

Free Shipping



#### 4. SWIMMING

- b. Underwater Glider Robot
  - Actuators Hardware Components (Rotary Servo Motor)



Dead band: 1µs

Working frequence: 1520µs / 330hz

Motor: Coreless

Operating Speed 6.0v 0.11 sec/60°

Operating Speed 8.4v 0.09 sec/60°

Stall Torque 6.0v 24.7 kg.cm

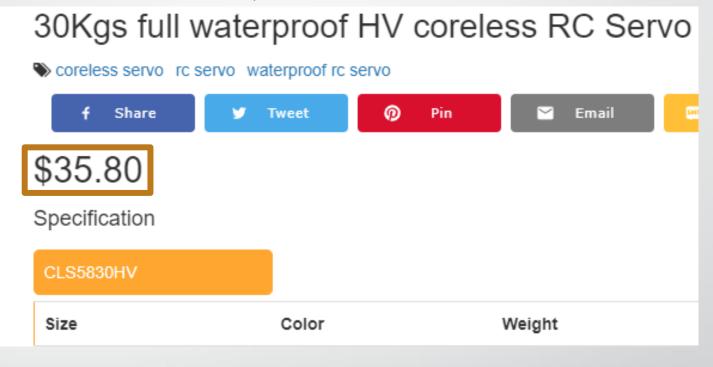
Stall Torque 8.4v 30.3 kg.cm

Dimensions: 40.5X20.2X38mm

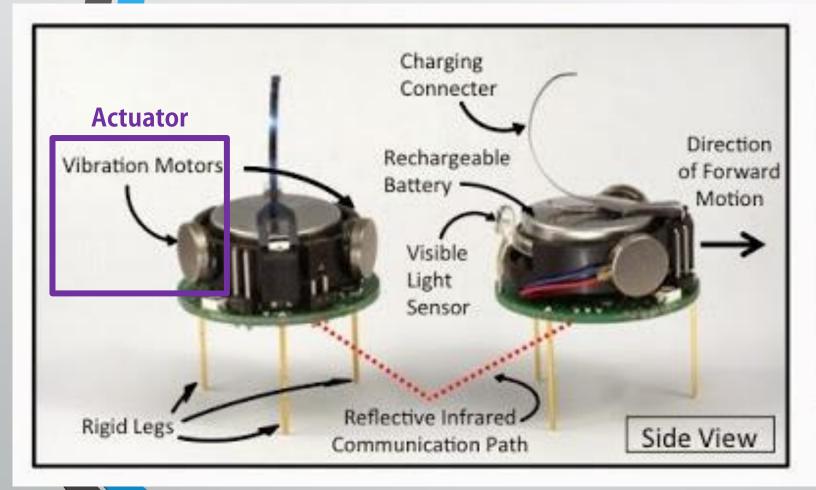
Weight: 58 g

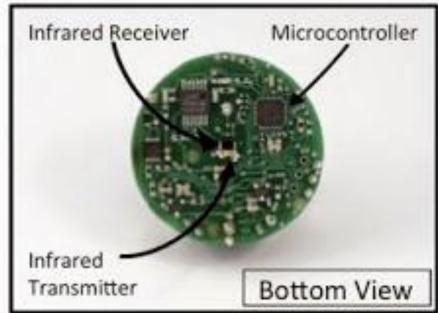
Wire/Color: JR 265 mm/ -Brown +Red S Orange

Bearing: 2 ball bearings



# 5. OTHERS a. Kilobot





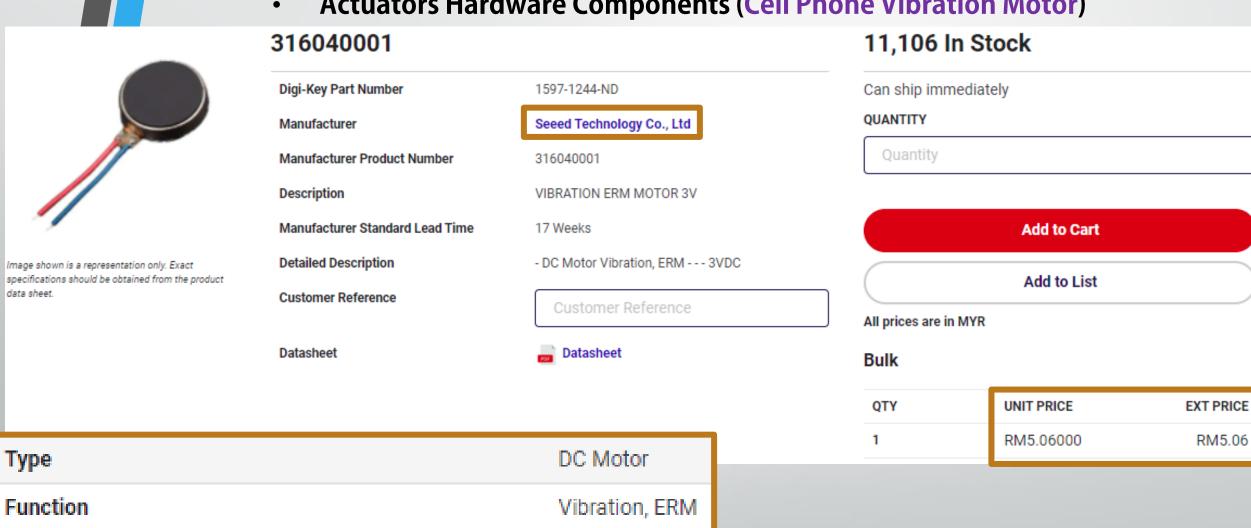
#### **OTHERS**

Motor Type

Voltage - Rated

#### a. Kilobot

**Actuators Hardware Components (Cell Phone Vibration Motor)** 



3VDC