

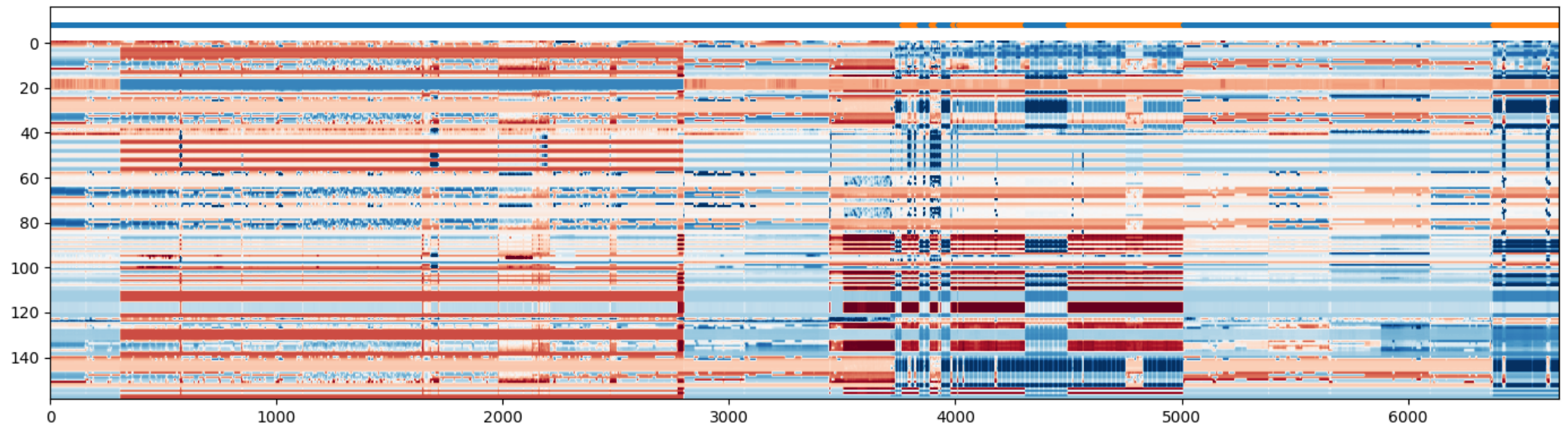
# GMMs for Anomaly Detection

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# Back to our HPC Problem

Let's go back to our anomaly detection problem

```
In [2]: hpcsv = hpc.copy()  
hpcsv[inputs] = (hpcsv[inputs] - hpcsv[inputs].mean()) / hpcsv[inputs].std()  
labels = pd.Series(index=hpcsv.index, data=(hpcsv['anomaly'] != 0), dtype=int)  
util.plot_dataframe(hpcsv[inputs], labels, figsize=figsize)
```



The colored line on the top identifies anomalies (in orange)

# Preprocessing

## We proceed to standardize the data again

- This is not strictly needed for GMMs
- ...but many optimization algorithms are designed for standardized data

```
In [3]: tr_end, val_end = 3000, 4500

hpcs = hpc.copy()
tmp = hpcs.iloc[:tr_end]
hpcs[inputs] = (hpcs[inputs] - tmp[inputs].mean()) / tmp[inputs].std()
```

## We separate the training, validation, and test set

```
In [79]: trdata = hpcs.iloc[:tr_end]
valdata = hpcs.iloc[tr_end:val_end]
tsdata = hpcs.iloc[val_end:]
```

- This time, we keep the validation set distinct from the training set

# Training and Number of Components

## We now need to pick a number of components

We'll do this by using grid search and cross validation

- We would have used other method (e.g. elbow method or BIC)
- There are also variants of GMMs that can infer the number of components

```
In [88]: %%time
opt = GridSearchCV(GaussianMixture(), {'n_components': [2, 4, 8]}, cv=5)
opt.fit(trdata[inputs])
print(f'Best parameters: {opt.best_params_}')
```

```
Best parameters: {'n_components': 2}
CPU times: user 1min 13s, sys: 2min 56s, total: 4min 9s
Wall time: 23 s
```

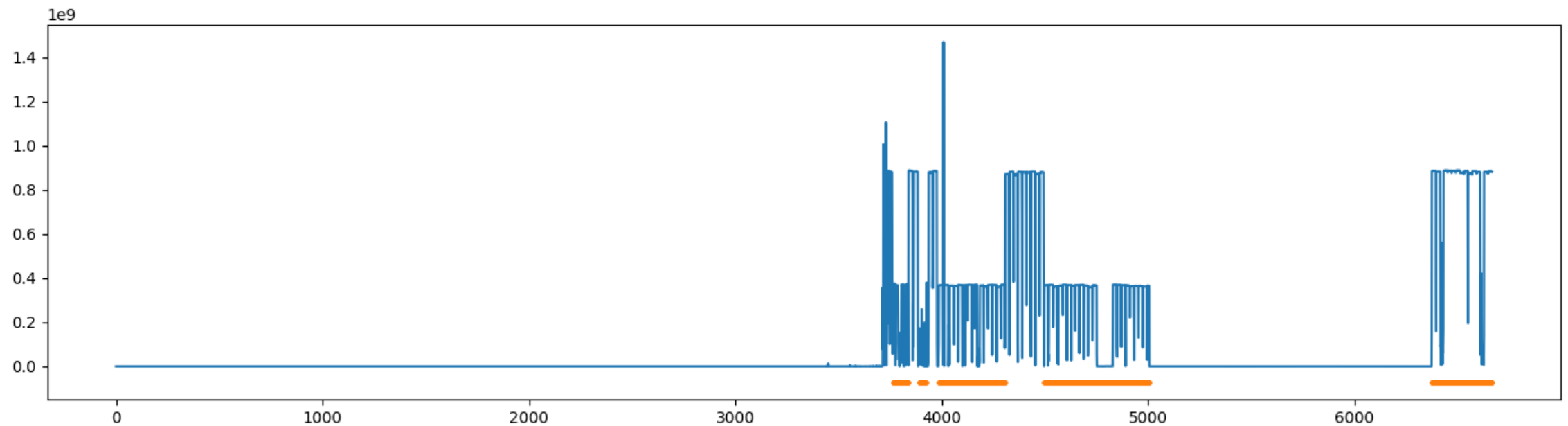
- While training is slow
- ...Generating the alarm signal is now much faster

```
In [89]: ldens = opt.score_samples(hpcs[inputs])
signal = pd.Series(index=hpcs.index, data=ldens)
```

# Inspecting the Alarm Signal

Let's have a look at the alarm signal

```
In [90]: util.plot_signal(signal, labels, figsize=figsize)
```



It's very similar to the one provided by KDE

# Threshold Optimization

**We can optimize the threshold in the usual fashion**

The cost model is the same as before

```
In [91]: c_alarm, c_missed, tolerance = 1, 5, 12
         cmodel = util.HPCMetrics(c_alarm, c_missed, tolerance)

         th_range = np.linspace(1e4, 1e9, 1000)
         th, val_cost = util.opt_threshold(signal[tr_end:val_end],
                                         valdata['anomaly'],
                                         th_range, cmodel)

         print(f'Best threshold: {th:.3f}')
         tr_cost = cmodel.cost(signal[:tr_end], hpcs['anomaly'][:tr_end], th)
         print(f'Cost on the training set: {tr_cost}')
         print(f'Cost on the validation set: {val_cost}')
         ts_cost = cmodel.cost(signal[val_end:], hpcs['anomaly'][val_end:], th)
         print(f'Cost on the test set: {ts_cost}')
```

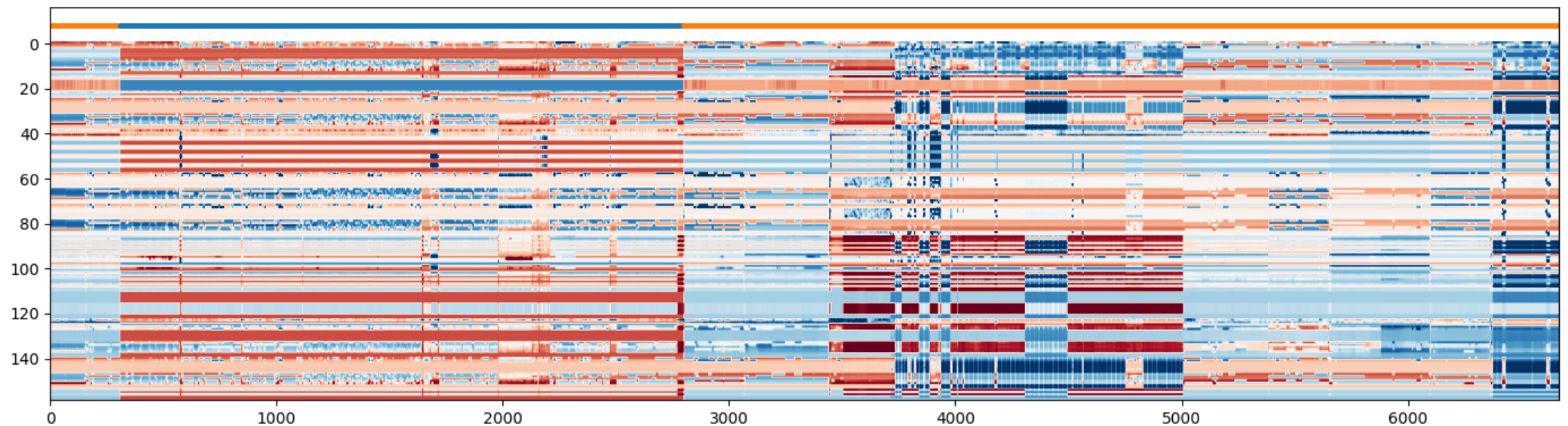
```
Best threshold: 244251801.802
Cost on the training set: 0
Cost on the validation set: 239
Cost on the test set: 275
```

The results are also similar to those from KDE

# Behavior Clusters

Finally, we can have a look at how the model is using its components

```
In [94]: zvals = opt.predict(hpcs[inputs])  
zsignal = pd.Series(index=hpcs.index, data=zvals)  
util.plot_dataframe(hpcsv[inputs], zsignal, figsize=figsize)
```



- The results may vary, since some steps of the process are stochastic
- ...But typically one or more component will be use for a single, long job