**Bayesian (Surrogate-Based) Optimization** 





# **Bayesian Optimization**

## We will use an approach known as Surrogate-Based Bayesian Optimization

- It is designed to optimize blackbox functions
- I.e. functions with an unknown structure, that can only be evaluated

## Formally, they address problems in the form:

$$\min_{x \in B} f(x)$$

- Where  $m{B}$  is a box, i.e. a specification of bounds for each component of  $m{x}$
- In our case, the decision variable x would be heta
- ...And the function to be optimized would be the cost

## The functions are typically assumed to be expensive to evaluate





# Why a Surrogate

# Since evaluating f is expensive, it should be done infrequently

The main trick to achieve this is using a surrogate model

- After each evaluation we train a Machine Learning model
- ...Then we perform optimization on the ML model
- ...Since it can be evaluate much more quickly

The process is usually start by sampling a few random points

#### This is where the name stems from

- Since we use the ML model instead of the function, we call it a surrogate
- Moreover, we optimize over prior information (i.e. the current model)
- ...And we refine the model based on the evaluation (posterior)
- Hence we call it Bayesian Optimization





## A Running Example

## Let's assume we want to minimize the following function over [0, 1]

```
In [2]: bbf = lambda x: (0.5 - x**2) * np.sin(2 * 4 * np.pi * x)
        xrange = np.linspace(0, 1, 1000)
        target = pd.Series(index=xrange, data=bbf(xrange))
        util.plot_series(target, figsize=figsize)
          0.2
          0.0
         -0.2
         -0.4
```

lacktriangle There multiple local minima, and the global minimum is at  $\simeq 0.19$ 





## A Running Example

## Let's start by sampling a few points at random

```
In [3]: np.random.seed(42)
        xtr = np.sort(np.random.random(4))
        ytr = bbf(xtr)
        util.plot_series(target, figsize=figsize)
        plt.scatter(xtr, ytr, color='tab:orange');
          0.2
          0.0
          -0.2
          -0.4
```

Using only the orange points we need to train a model ...That gives us a good idea for a new point to evaluate

Which properties should our surrogate model have?





# **Properties of a Good Surrogate**

Our surrogate model should





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## Our surrogate model should

Approximate very accurately all evaluted points

- Assuming the function is deterministic
- ...The available evaluations are exact values





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Approximate very accurately all evaluted points

- Assuming the function is deterministic
- ...The available evaluations are exact values.

Reflect our confidence level on unexplored regions

- If we have few samples in a certain region
- ...We might want to search there just to see what the function looks like

Can you think of a ML model with these properties?





# **Gaussian Process Surrogates**

#### Gaussian Processes check all the boxes!

- They can interpolate very well known measurements
- They provide a confidence level that decays with distance from observations

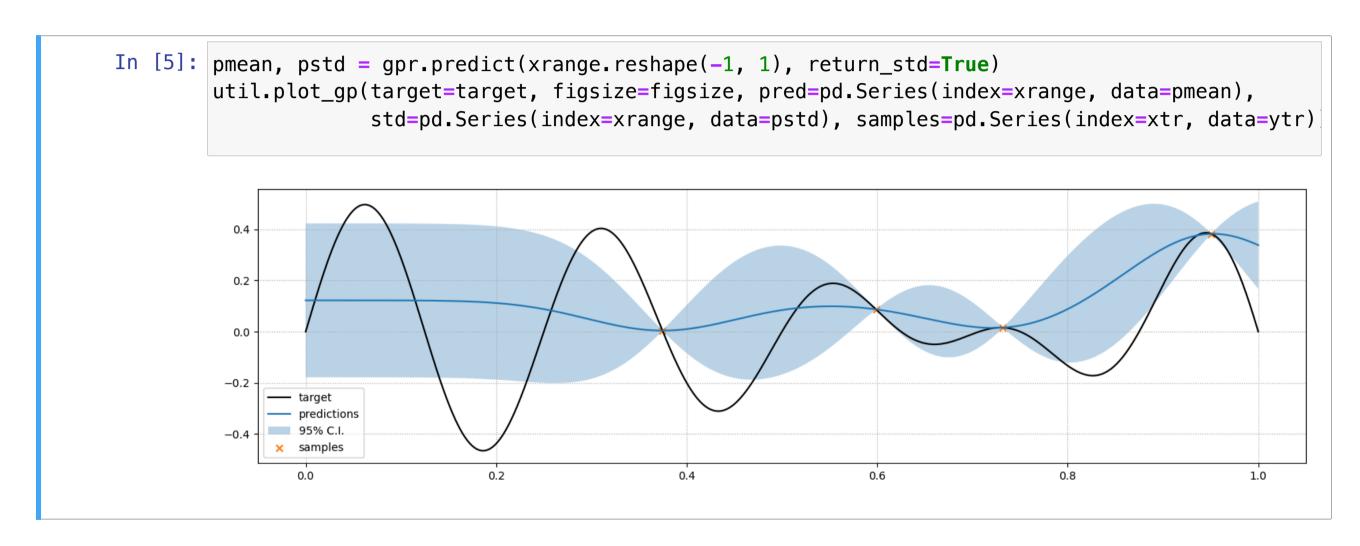
## Let's try to train a simple GP for our example

```
In [4]: kernel = RBF(0.01, (1e-3, 1e3)) + WhiteKernel(1e-3, (1e-6, 1e-2))
    gpr = GaussianProcessRegressor(kernel=kernel, n_restarts_optimizer=9, normalize_y=True)
    gpr.fit(xtr.reshape(-1, 1), ytr);
    gpr.kernel_
Out[4]: RBF(length_scale=0.0792) + WhiteKernel(noise_level=0.000126)
```

- We use an RBF kernel to capture the distance-based correlation
- We also use a white noise kernel to avoid numerical instability
- ...But we keep it at a low value since the target function is deterministic

# **Gaussian Process Surrogate**

## Let's inspect our Gaussian Process Surrogate



- All known points are interpolated (almost) exactly
- ...And the confidence intervals behave in an intuitive fashion

# What to Optimize?

## Now we need to search over the surrogate model

This is the same as choosing which function to optimize

In [6]: pmean, pstd = gpr.predict(xrange.reshape(-1, 1), return\_std=True) util.plot\_gp(target=target, figsize=figsize, pred=pd.Series(index=xrange, data=pmean), std=pd.Series(index=xrange, data=pstd), samples=pd.Series(index=xtr, data=ytr) 0.2 0.0 -0.2target predictions 0.2 0.4 0.6 0.8 1.0 0.0





# **Acquisition Function**

## We need to account for both the predictions and their confidence

- Area with low predictions are promising
- ...But so are also areas with high confidence

## This issue is solved in SBO by optimizing an acquisition function

...Which should balance exploration and exploitation.

- <u>Examples</u> include the Probability of improvement, the Expected Improvement
- ...And the Lower/Upper confidence bound

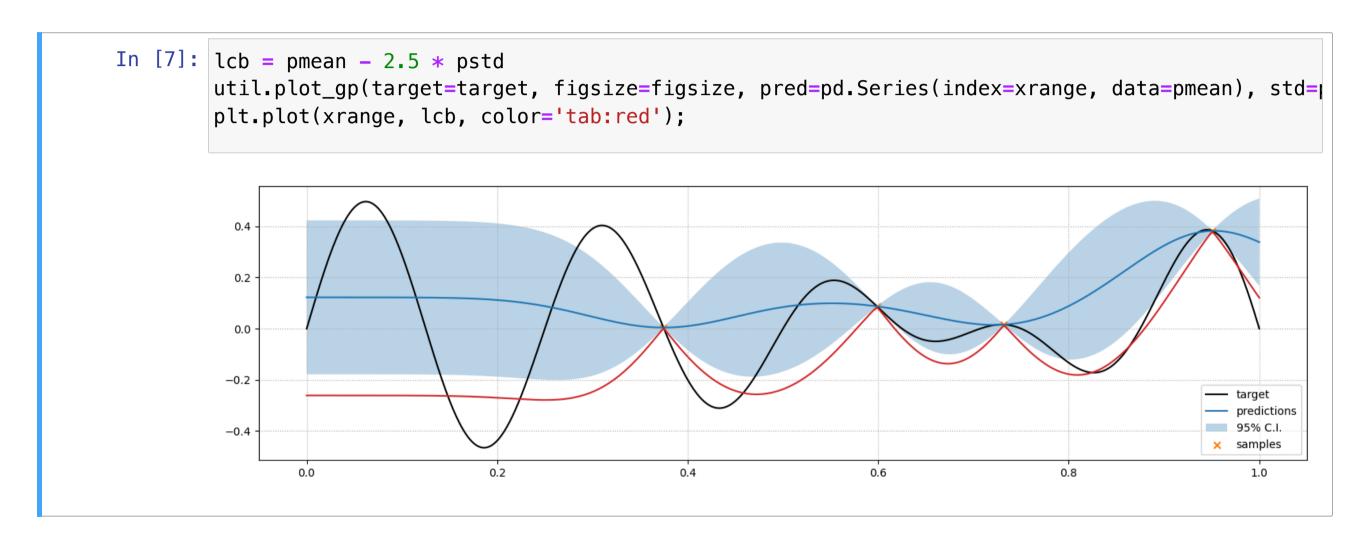
## We will use the Lower Confidence Bound, which is given by:

$$LCB(x) = \mu(x) - Z_{\alpha}\sigma(x)$$

- Where  $\mu(x)$  is the predicted mean,  $\sigma(x)$  is the predicted standard deviation
- $\blacksquare$  ...And  $Z_lpha$  is multiplier for a lpha% Normal confidence inteval

## **Lower Confidence Bound**

# Let's see an examle in our case with $Z_{\alpha}=2.5$



- We can then optimize via any method applicable to our surrogate
- E.g. <u>Nelder-Mead</u>, Mathmatical Programming, or even simple grid search

## **Lower Confidence Bound**

## Let's see which point we would choose in our case

```
In [8]: best_idx = np.argmin(lcb)
         util.plot_gp(target=target, figsize=figsize, pred=pd.Series(index=xrange, data=pmean), std=
         plt.plot(xrange, lcb, color='tab:red');
         plt.scatter(xrange[best_idx], lcb[best_idx], marker='x', color='tab:red');
           0.2
           0.0
          -0.2
          -0.4
                                                                                                    x samples
                                                                    0.6
                0.0
                                  0.2
                                                   0.4
                                                                                      0.8
                                                                                                       1.0
```

lacktriangle The  $oldsymbol{x}$  value with the best acquisition function is highlighted with a red "x"





# **Updating the Surrogate**

## Now wen update our surrogate model

First, we evaluate f for the new point and grow our training set:

```
In [9]: xtr2 = np.hstack((xtr, [xrange[best_idx]]))
ytr2 = np.hstack((ytr, [bbf(xrange[best_idx])]))
```

Then we can retrain our Gaussian Process:

```
In [10]: gpr2 = GaussianProcessRegressor(kernel=kernel, n_restarts_optimizer=9, normalize_y=True)
    gpr2.fit(xtr2.reshape(-1, 1), ytr2);
    gpr2.kernel_
Out[10]: RBF(length_scale=0.0999) + WhiteKernel(noise_level=2.46e-06)
```

- Then we should optimize the acquisition function again
- ...But we will limit ourselves to showing the updated predictions

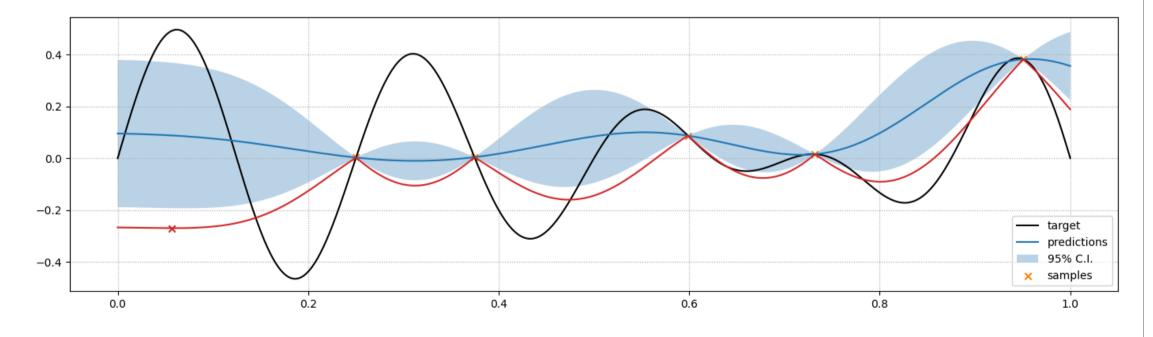




# **Updating the Surrogate**

## Here are the estimates for the udpate surrorate

...Together with the acquisition function and the next iterate







# **Surrogate-Based Bayesian Optimization**

## Let's review the general method

- Given a collection  $\{x_i, y_i\}_i$  of evaluated points
- ...We train a surrogate-model  $\hat{f}$  for f

## Then we proceed as follows:

- lacktriangle We optimize an acquisition function  $a_{\hat{f}}(x)$  to find a value x'
- We evaluate y' = f(x')
- If y' is better than the current optimum  $f(x^*)$ :
  - lacksquare Then we replace  $x^*$  with x'
- We expand our collection of measurements to include (x', y')
- We retrain  $\hat{f}$
- We repeat until a termination condition is reached

## **A Few Considerations**

## Different Bayesian optimization algorithms:

- Make use of different surrogate models
- Rely on different criteria for choosing x'
- ullet Strike different trade-offs in terms of number of (expensive) evaluations of f
- ...And the quality of the obtained solutions

## For more information, see (e.g.) this tutorial

## In practice, you don't have to code from scratch

...Since multiple libraries are available, like:

- The <u>scikit-optimize package</u> (crude, reasonably fast, unfortunately unmaintained)
- The <u>bayesian-optimization python module</u> (more stable, but also slower)
  - The <u>RBFOpt solver</u> (stable, fast, more complex in terms of requirements)

# SBO for Threshold Calibration





# **Back to Our Motivating Problem**

## We will use SBO to tackle our policy definition problem

$$\underset{\varepsilon}{\operatorname{argmin}} \sum_{k \in K} cost(f(x_k \, \theta^*), 1/2)$$

$$\text{s.t.: } \theta^* = \underset{\theta}{\operatorname{argmin}} L(f(x_k, \lambda), 1_{y_k \ge \varepsilon})$$

## Here's our plan:

- lacksquare We need to optimize over  $oldsymbol{arepsilon}$
- Our goal is minimizing the cost
- Computing the cost requires to re-define the classes
- ...And therefore to repeat training

## Our implementation will be based on bayesian-optimization





## As a first step, we need to define our black box function

We will use a function class (in the util module) with this structure:

```
class ClassifierCost:
    def __init__(self, machines, X, y, cost_model, init_epochs=20, inc_epochs=3):
        ...

    def __call__(self, params):
        ...
```

- In the constructor, we provide parameters that are fixed during optimization
- In the \_\_call\_\_ method, we retrain the model and evaluate the cost
- The \_\_call\_\_ method is executed when we try to invoke an object of this class
- ...Meaning that we can treat an object of this class as a normal function





## It is worth having a deeper look at the \_\_call\_ method

- At each execution we redefine the classes
- We use warm starting to make the process faster
- Each training attempt after the first uses only a few epochs





## It is worth having a deeper look at the \_\_call\_ method

```
def __call__(self, params):
    ...
    self.stored_weights[theta] = self.nn.get_weights() # Store weights
    # Evaluate cost
    pred = np.round(self.nn.predict(self.X, verbose=0).ravel())
    cost, fails, slack = self.cost_model.cost(self.machines, pred, 0.5, return_margin=Tr
    return cost
```

- We store the weights in a dictionary for later retrieval
- We need this to rebuild the optimal network once optimization is over
- Finally, we evaluate the cost
- The actual code in util also prints some information





## We can build an object in the usual way

```
In [13]: ccf = util.ClassifierCost(machines=tr['machine'], X=tr_s[dt_in], y=tr['rul'], cost_model=cmodel
```

...But since it is a function, we can invoke it:

- The function returns the negated cost
- ...Since bayesian-optimization is designed for maximization





# Running the Solver

## Now we can define our box constraints and run the optimization process

```
In [15]: pbounds = {'eps': (1, 20)} # Box constraints
         optimizer = BayesianOptimization(f=ccf, pbounds=pbounds, random state=42)
         optimizer.maximize(init points=3, n iter=10)
             iter
                        target
                                       eps
                       1.871e+04
                                    8.116
                       1.657e+04
                                   19.06
                       1.73e+04
                                   14.91
                                   1.192
                       -5.761e+0
                                   11.33
                       1.815e+04
                                   17.07
                       1.632e+04
                                    9.54
                       1.812e+04
                       1.764e+04
                                    13.09
                       1.641e+04
                                    20.0
                       1.827e+04
                                    7.082
           11
                                    7.599
                       1.814e+04
                                    5.732
                       1.909e+04
                       1.586e+04
```

The implementation is very close to what we have showed the results will be a bit noisy, since training is stochastic

### Retrieve the Results

#### We can access the best $\varepsilon$ value from a result data structure

```
In [16]: print(optimizer.max)
  best_eps = optimizer.max['params']['eps']

{'target': 19091.0, 'params': {'eps': 5.731594133424523}}
```

We will use it to retrive the weights of the best network:

```
In [17]: nn = keras.models.clone_model(ccf.nn)
    nn.set_weights(ccf.stored_weights[best_eps])
```

■ This is possible since we stored all the tested weights in our class





## **Evaluate the Classifier**

## Finally, we can evaluate our classifier

```
In [18]: tr_pred = np.round(nn.predict(tr_s[dt_in], verbose=0).ravel())
    ts_pred = np.round(nn.predict(ts_s[dt_in], verbose=0).ravel())

    tr_c, tr_f, tr_sl = cmodel.cost(tr['machine'].values, tr_pred, 0.5, return_margin=True)
    ts_c, ts_f, ts_sl = cmodel.cost(ts['machine'].values, ts_pred, 0.5, return_margin=True)
    print(f'Avg. cost: {tr_c/len(tr_mcn)} (training), {ts_c//len(ts_mcn)} (test)')
    print(f'Avg. fails: {tr_f/len(tr_mcn)} (training), {ts_f/len(ts_mcn)} (test)')

    Avg. cost: -102.63978494623656 (training), -113 (test)
    Avg. fails: 0.0 (training), 0.0 (test)
    Avg. slack: 13.42 (training), 11.06 (test)
```

The performance is now better than the regression approach!





## **AutoML**

## Many ML models have hyper parameters!

- ...And tuning them may sometimes improve the performance
- The problem is that tuning multiple parameters may be complicated
- ...And every training attempts is expensive

## This makes hyper-parameter tuning a perfect application for SBO

- ...And other similar approaches. A few libraries you might have heard of:
- Hyperopt
- Optuna

## In recent years the concept has been generalized to AutoML

- ...Where we can start chanking the architecture and model type, too!
- It's a big topic (and big techs have some available SW solutions)
- A good starting reference is <u>this web site</u>