

Short Term Power Burn Model

Gas Analytics

Rationale:

Python:

- Utilise more sophisticated time series forecasting techniques to try and improve forecast accuracy.
- Automate forecasts to allow for earlier model runs.

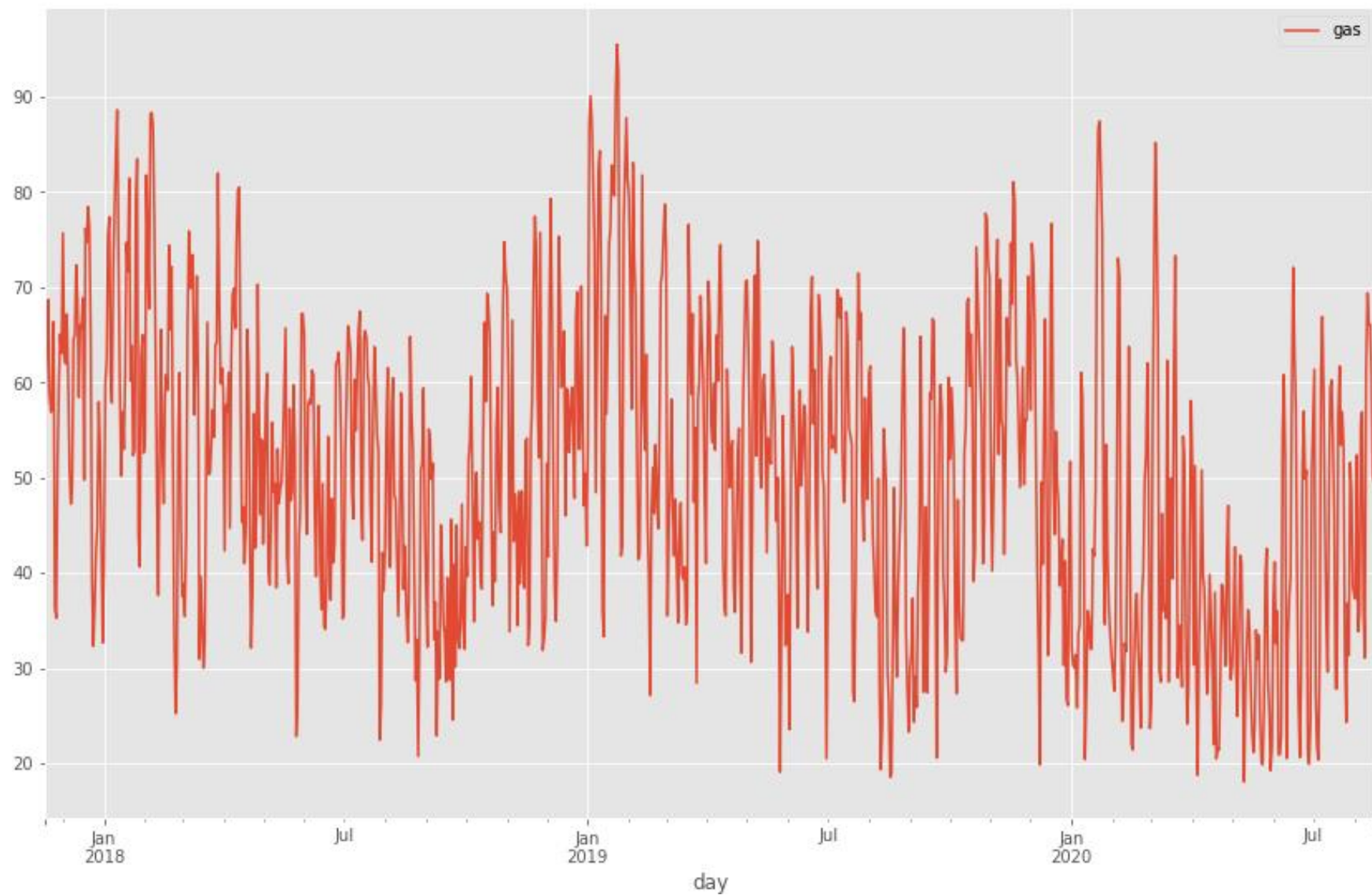
Creating Framework :

- How to approach forecasting within a framework
- Defining model accuracy

Short Term Power Burn:

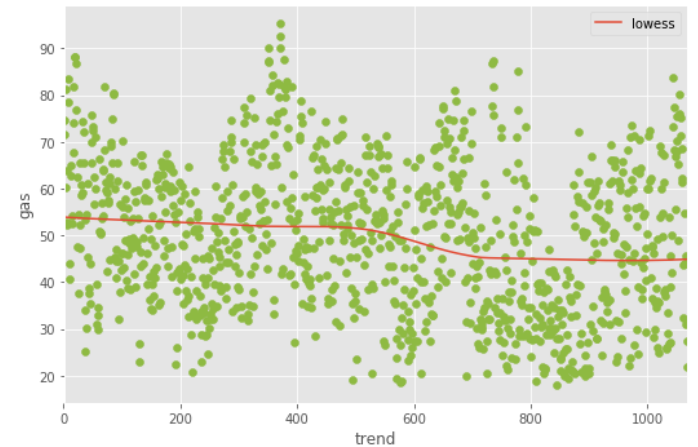
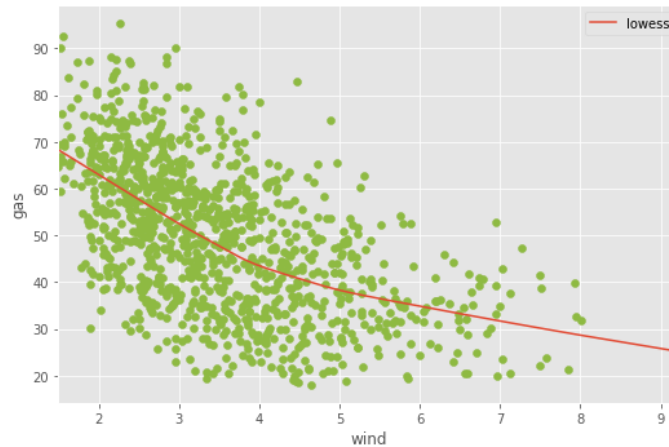
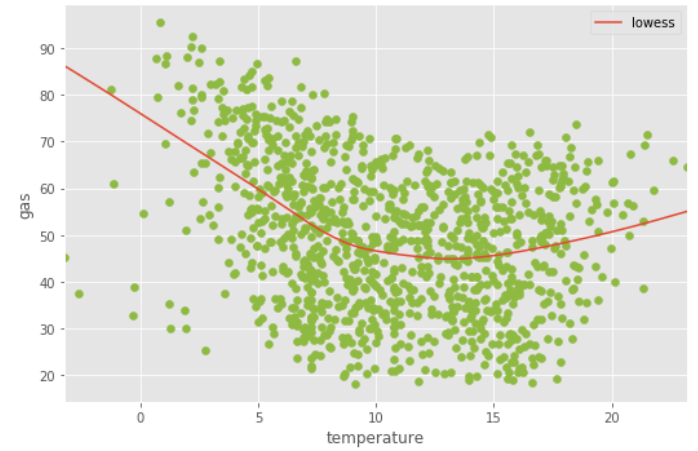
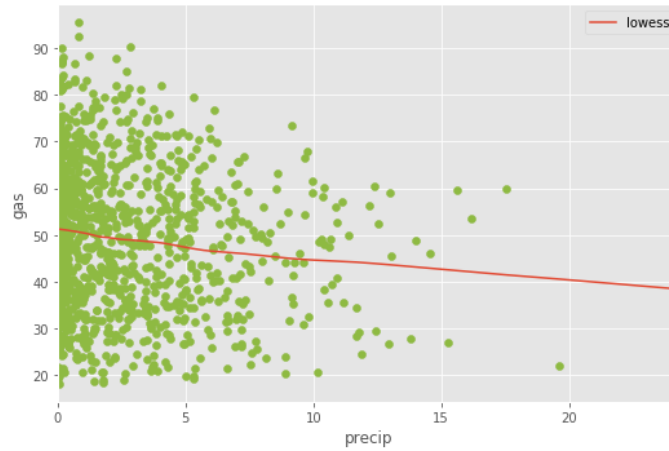
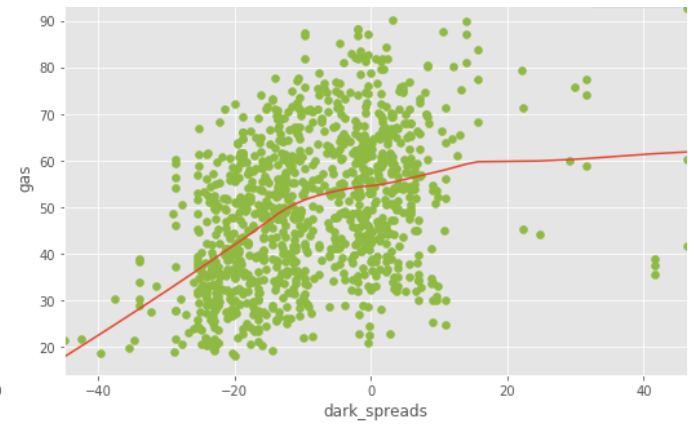
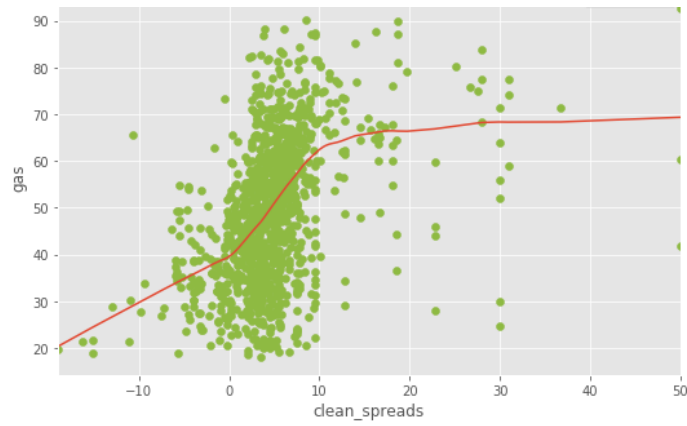
- Understand what drivers short-term gas burn.
- Provide the foundations for longer term (seasonal) forecasting.

Dependent Variable

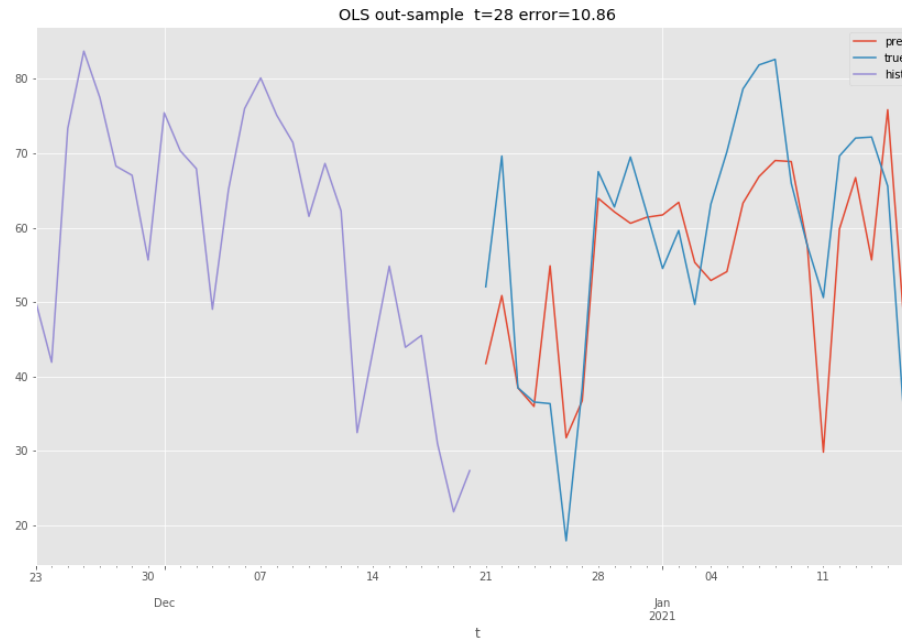
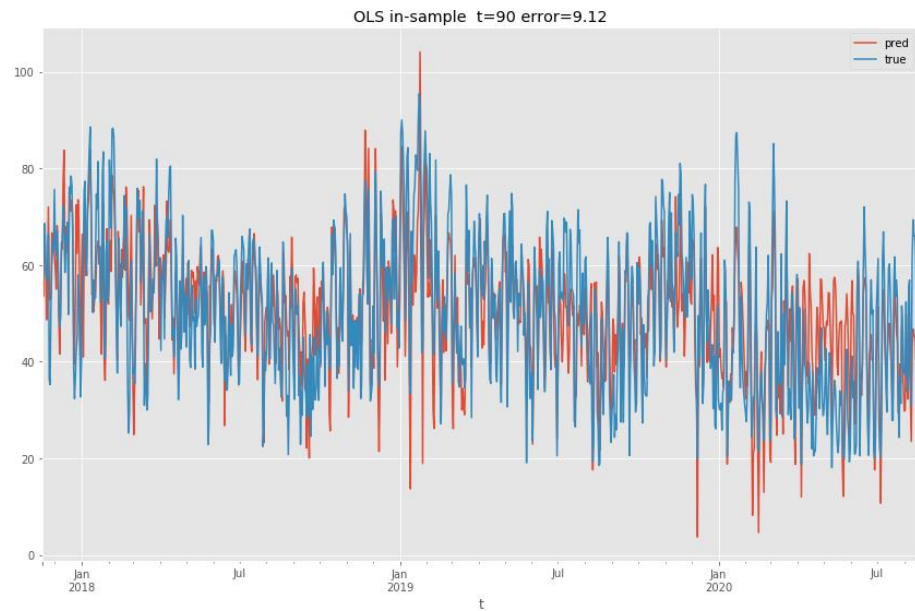
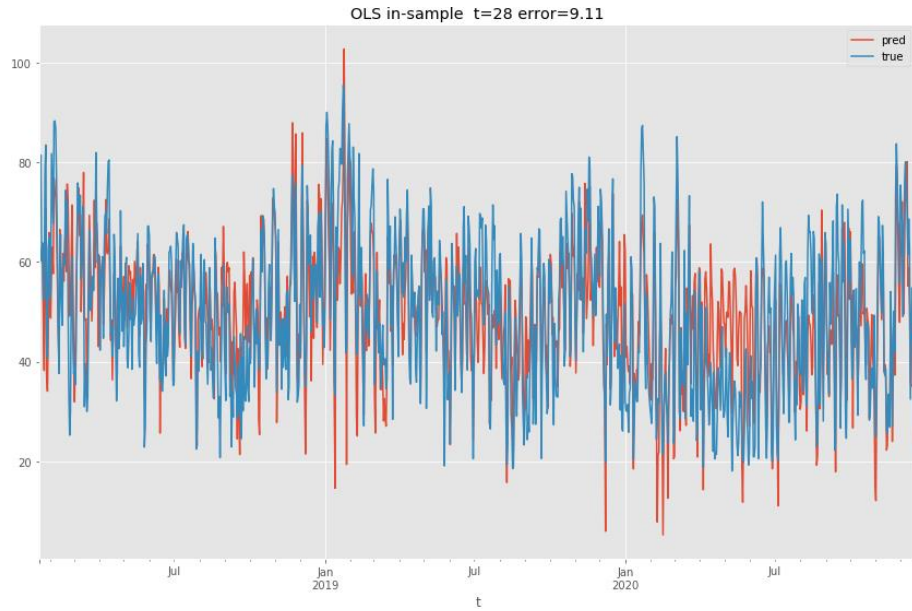


Covariates:

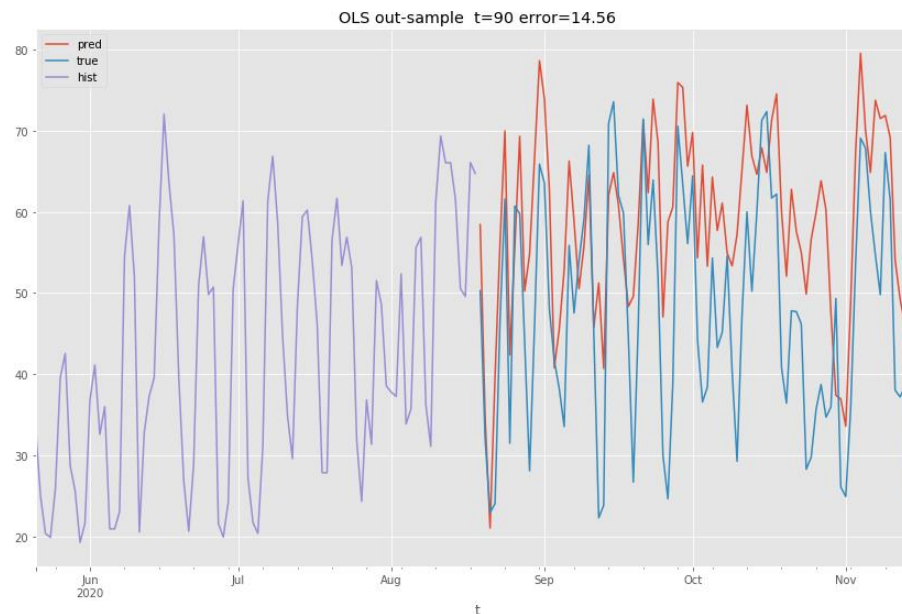
- clean spreads
- dark spreads
- temperature
- wind
- precipitation
- monday_thursday flag
- Fourier series



Calibrator (exog): Linear Regression

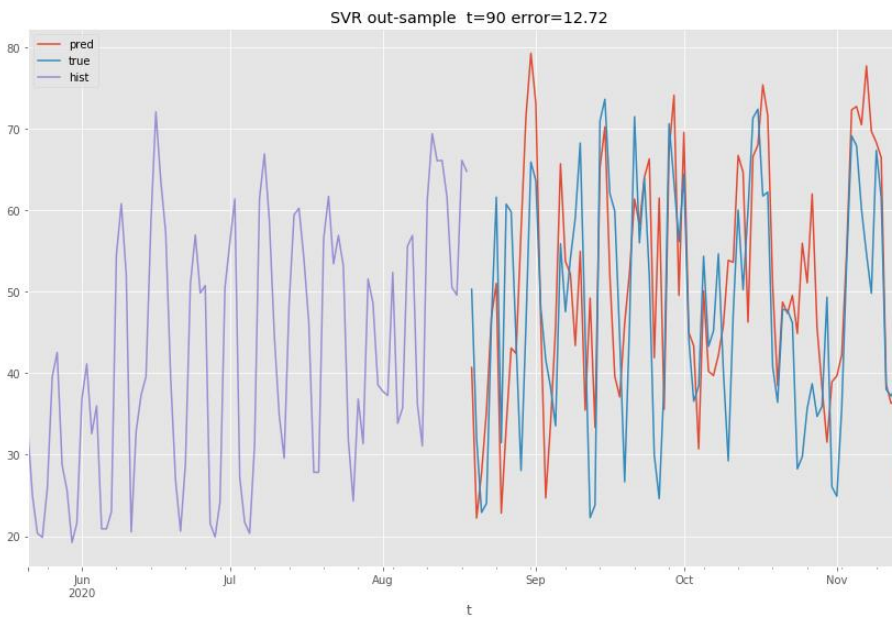
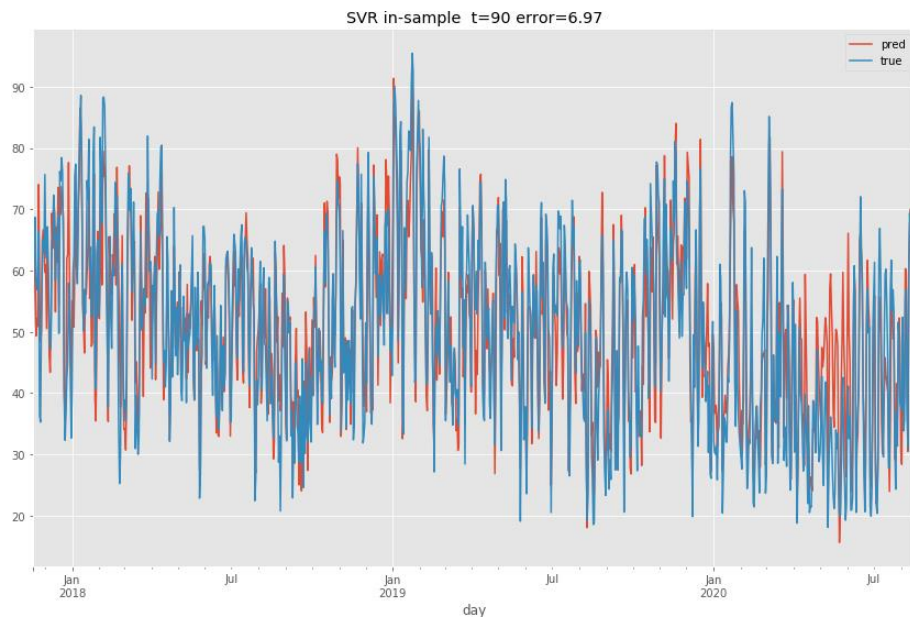
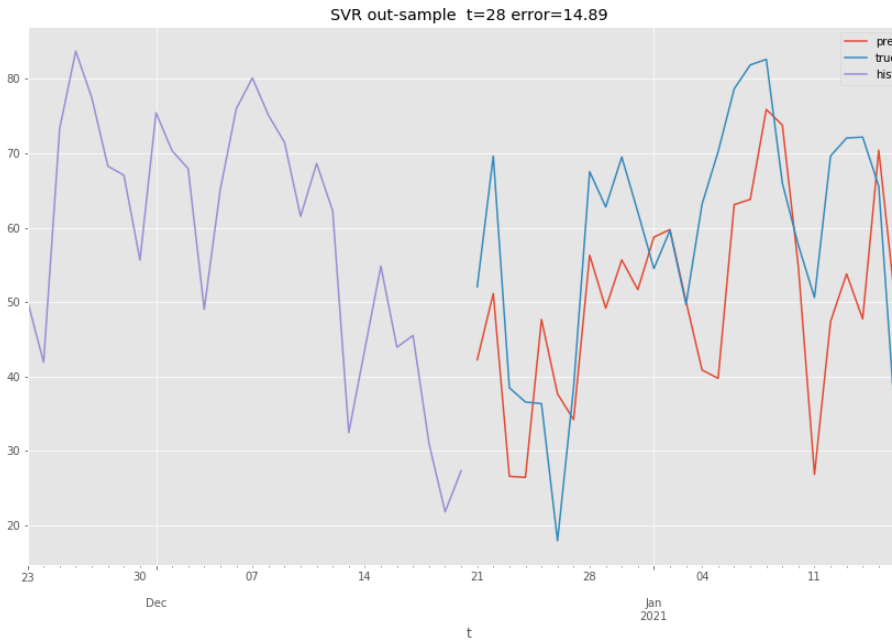
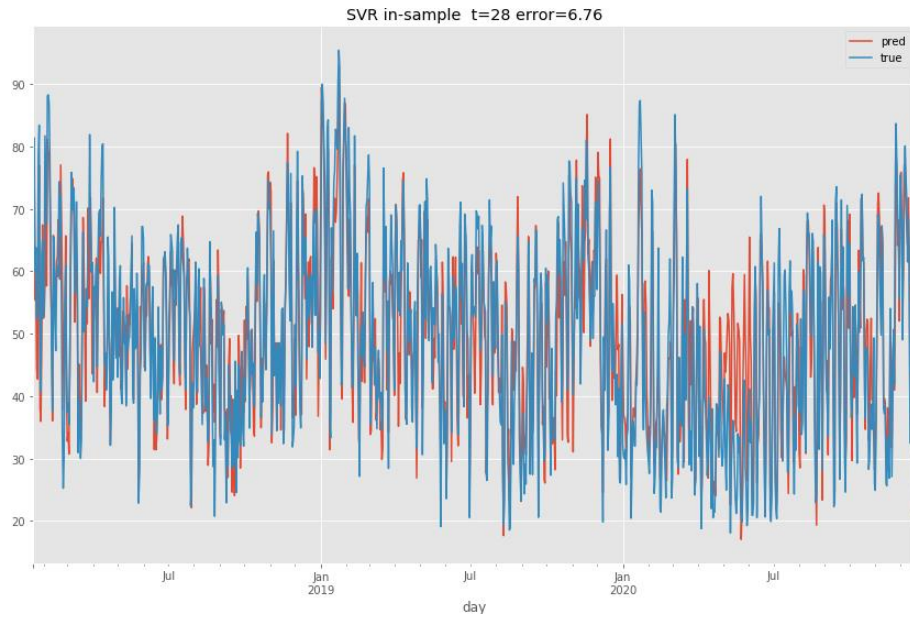


CV= 9.43 (2.08)

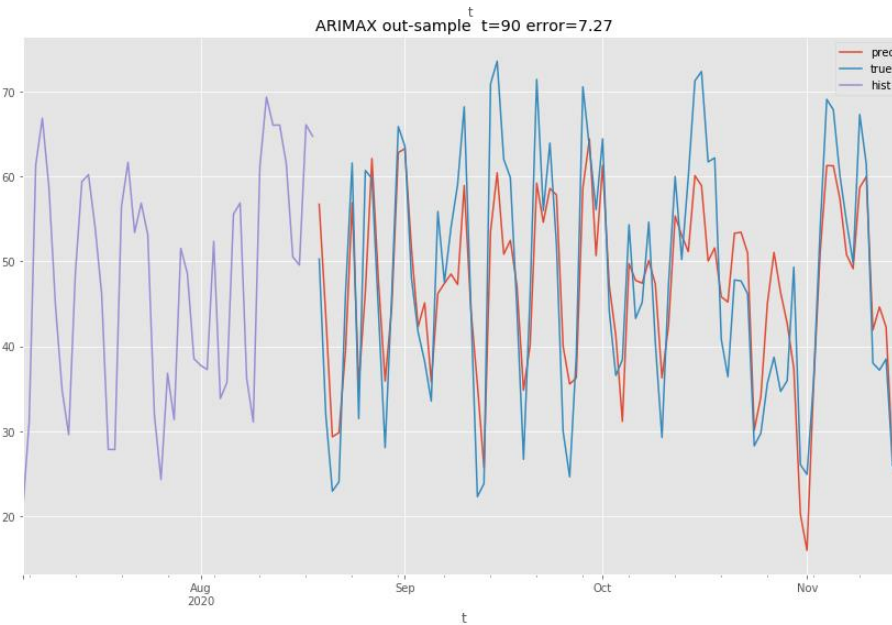
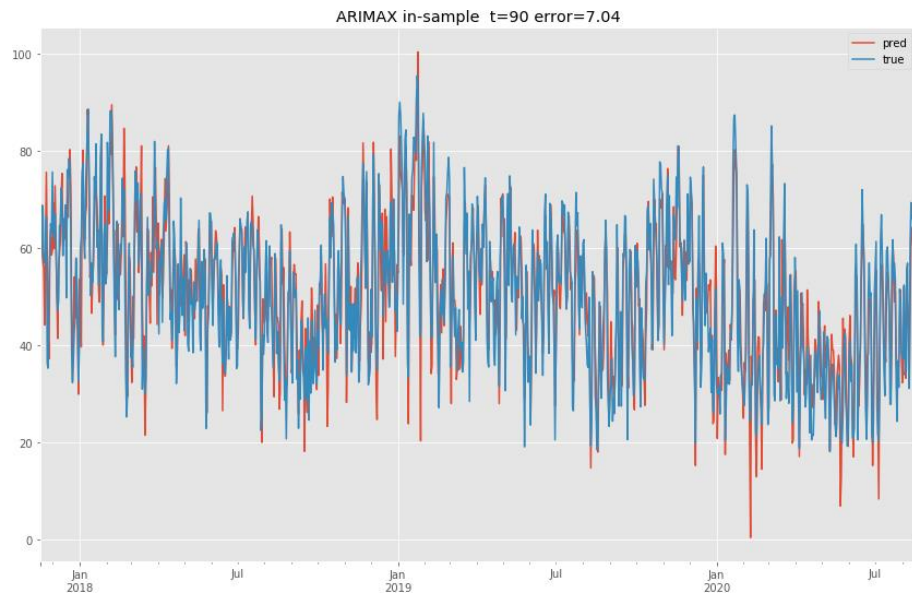
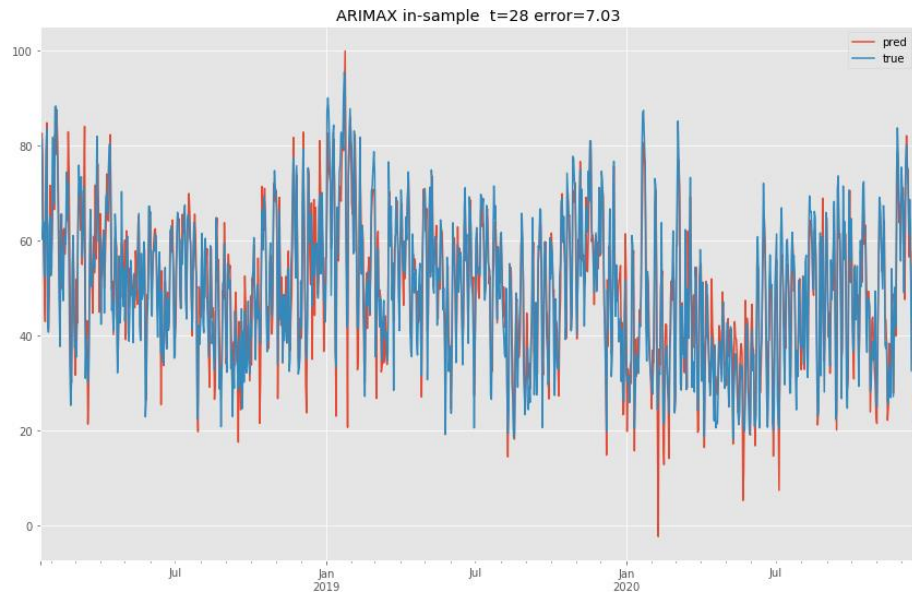


CV= 10.57 (1.79)

Calibrator (exog): Support Vector (kernel) Regression



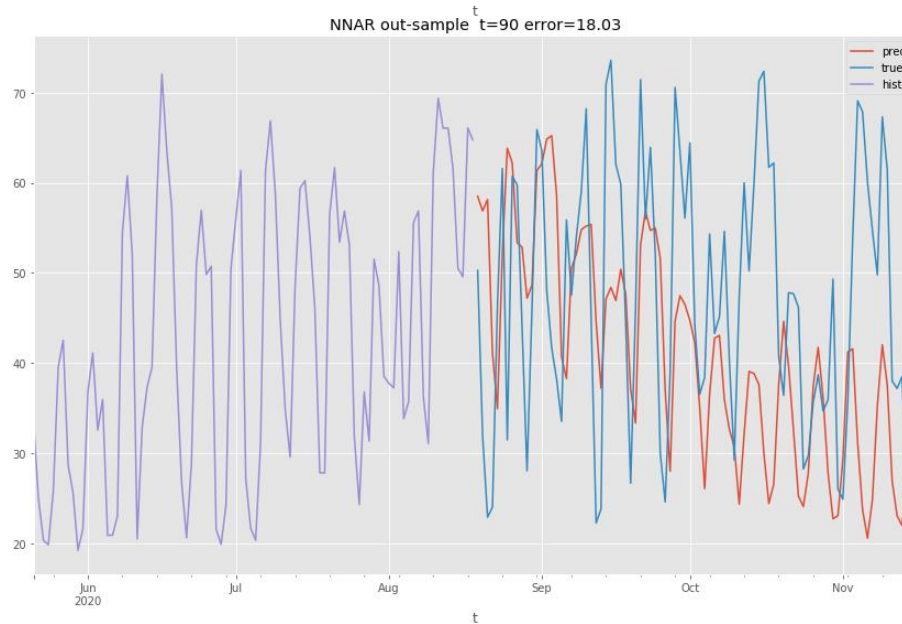
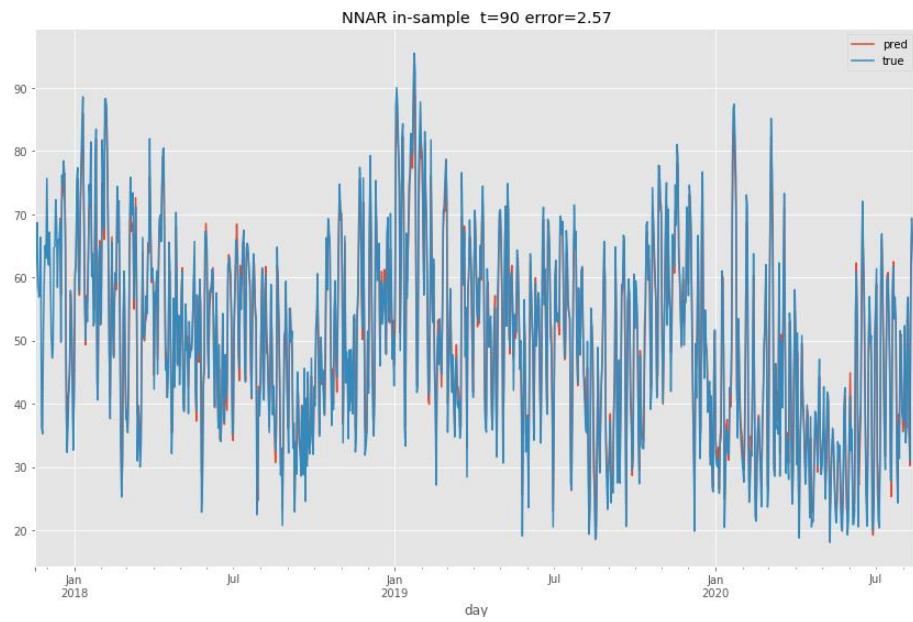
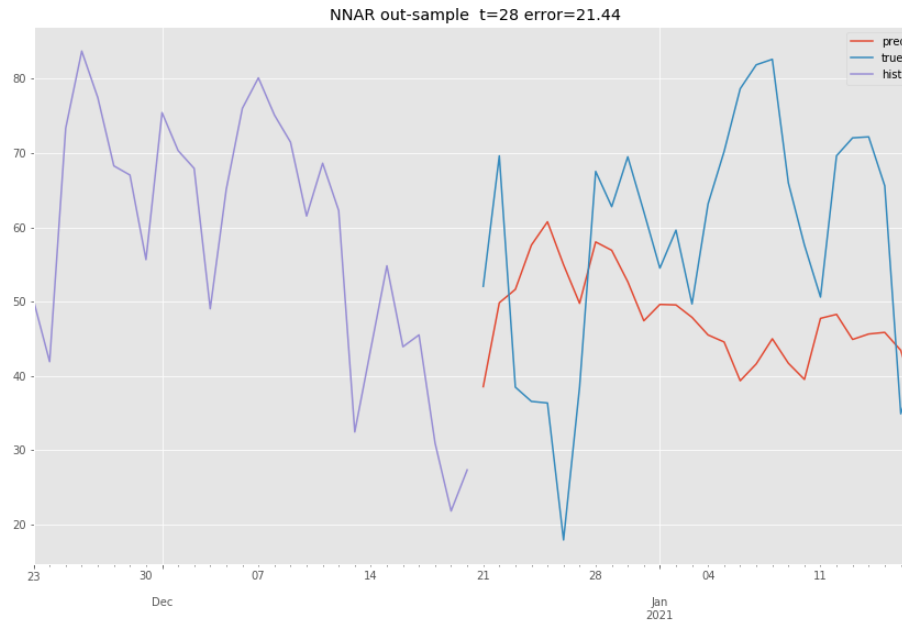
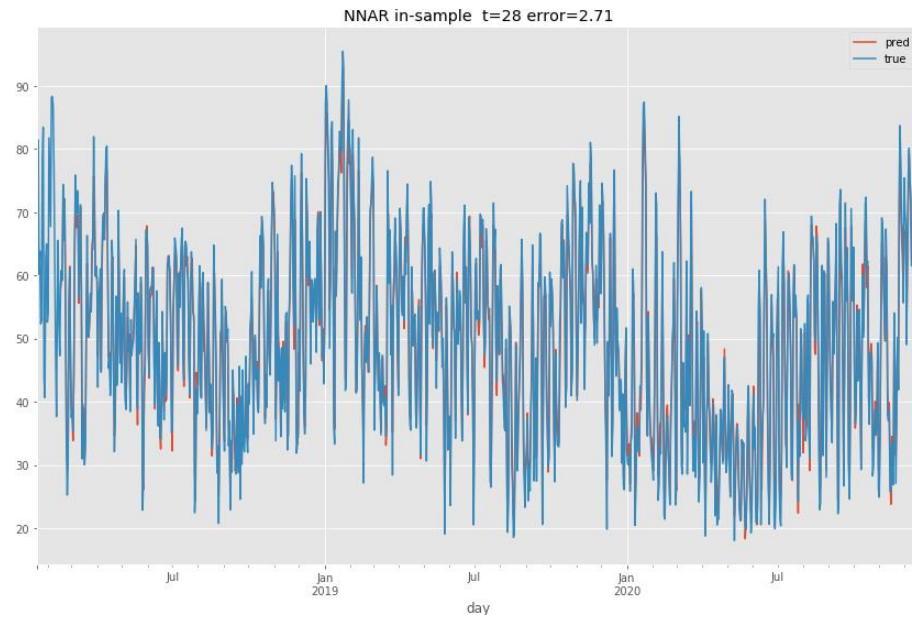
Calibrator (exog): SARIMAX



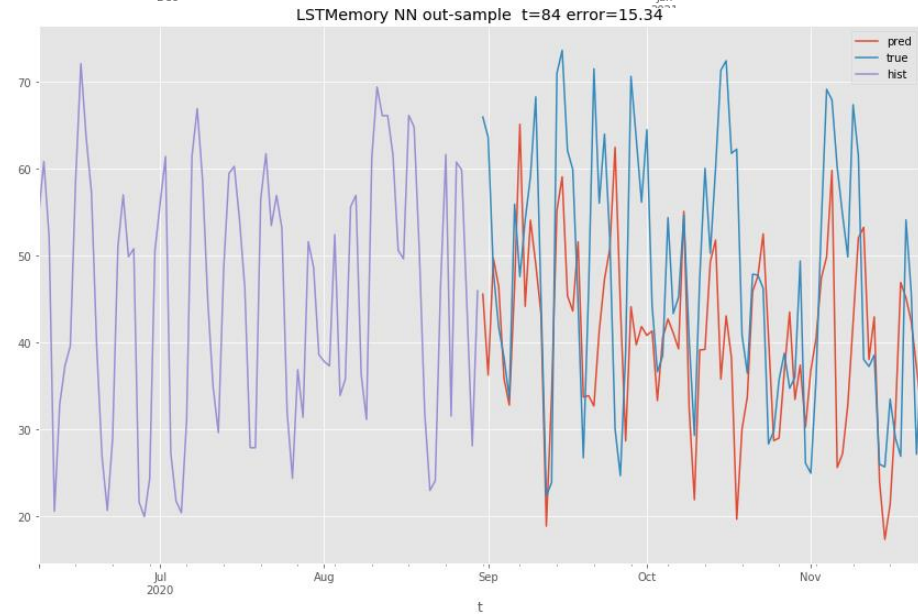
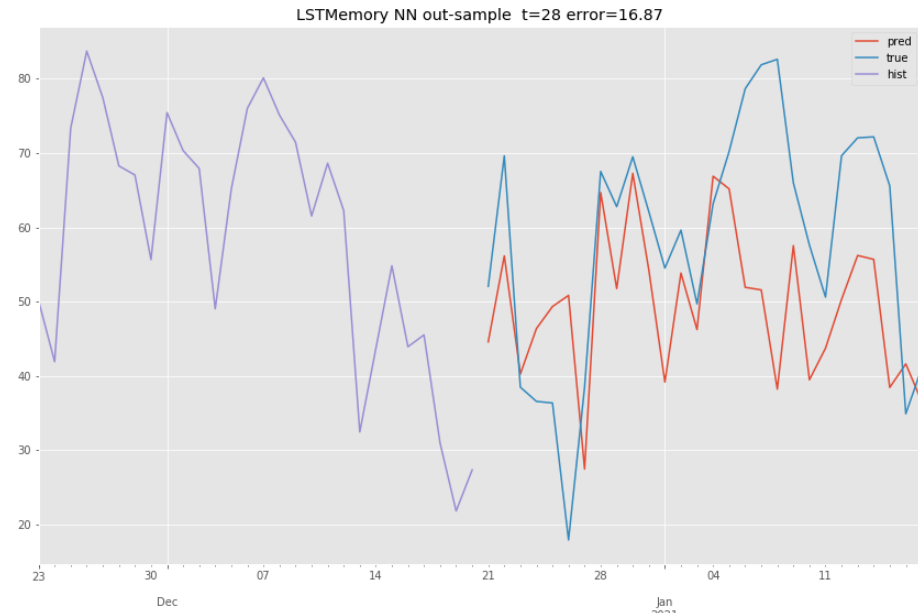
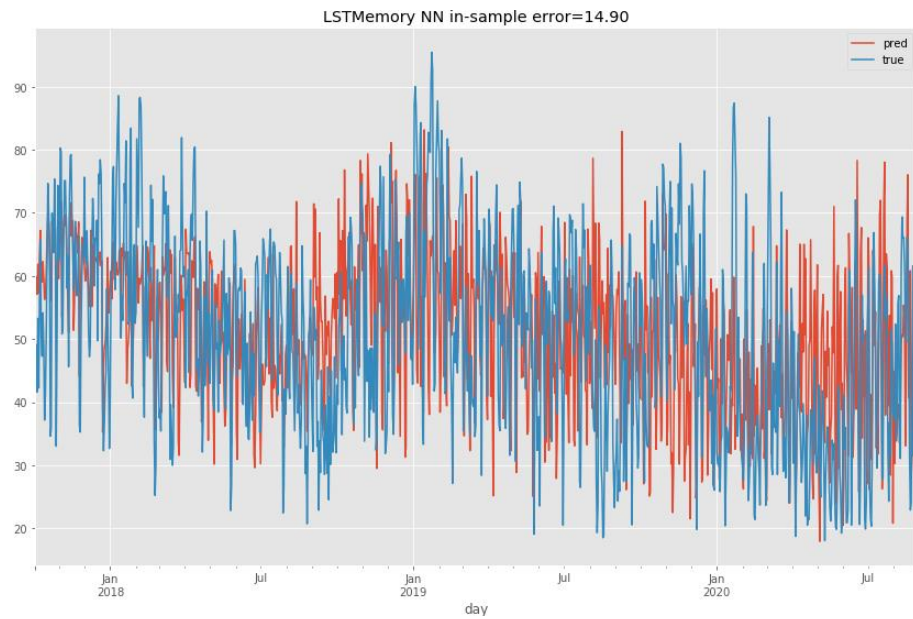
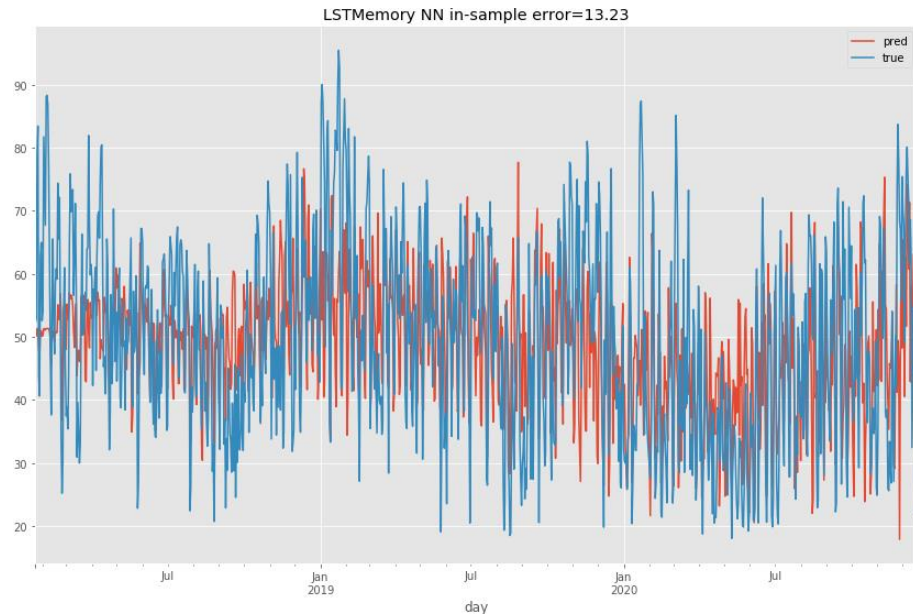
CV= 8.44 (1.71)

CV= 10.37 (2.41)

Calibrator (endog): Neural Network Autoregression



Calibrator (endog): Neural Network Long Short Term Memory



Appendix A:

Model	Parameters	Description
EXOGENEOUS RELATIONSHIP:		
Linear Regression	const, trend, clean_spreads, precipitation, temperature, wind, S1-7, C1-7, S2-7, C2-7, S3-7, C3-7, mo_th_yes	Modelling in levels Exog variables: grid search with BIC criterion 3 terms of Fourier series at weekly frequency
SARIMAX	SARIMAX(1, 0, 1)x(1, 0, 1, 7) const, dark_spreads, precipitation, temperature, wind,	Modelling in levels Specification: grid search with BIC criterion Exog variables: grid search with BIC criterion
Support Vector Regression	type="eps-regression" kernel='radial' <ul style="list-style-type: none"> cost= 8 gamma= 0.0625 epsilon= 0.3 	Dependent variable and features scaling: standardization Specification: grid search with 10-fold CV
ENDOGENEOUS RELATIONSHIP:		
Neural Network Autoregression	<ul style="list-style-type: none"> Model: NNAR(29,1,15)[7] Average of 20 networks, each of which is a 29-15-1 network with 466 weights options were - linear output units 	Dependent variable scaling: standardization
Long Short Term Memory Neural Network		

Appendix B:

ALL DATA: IN TIME : ACTUALS 4y								OUT OF TIME: FUTURE	
IN SAMPLE 3y						OUT SAMPLE 28days			
CROSS VALIDATION 3y:									
FOLD1 1y		FOLD2 1.5y		FOLD3 2.5y		FOLD4 3y			
train sample 0.8y	test sample 28days	train sample 1.3y	test sample 28days	train sample 2.3y	test sample 28days	train sample 2.8y	test sample28 days		
	error 1		error 2		error 3		error 4		
CV error = 1/4 * (error1 + error2 + error 3 + error4)									
CV std = Standard Deviation (error1, error2, error3, error4)									
IN SAMPLE ERROR						OUT SAMPLE ERROR		OUT OF TIME ERROR	

error = Root Mean Square Error

Appendix C:

Modelling Framework

Design Matrix:

- Imputations
- Design Matrix:

$$t \mid y_t \xrightarrow{f} v_t, \mid x_t^1, x_t^2, \dots, x_t^k \xrightarrow{g} g_1x_t^1, g_2x_t^2, \dots, g_kx_t^k$$

$$DM_t = DM_t(y_t, f, f^{-1}, \{x_t^j\}_{j=1,k}, \{g_t^j\}_{j=1,k})$$

Exploratory analysis

- Autocorrelation:
 - $ACF(x_t)$
 - $PACF(x_t)$
- Scatter Plots:
 - y_t next to v_t and x_t^k next to $g_kx_t^k$
 - y_t vs. x_t^j for $j = 1, k$ with LOWESS for dependency shape analysis
 - x_t vs. x_{t-h} with LOWESS for autocorrelation analysis
 - y_t vs. x_{t-h}^k for given k with LOWESS for lagged-leading relationship

Calibrator:

$$C(HyperParams) \rightarrow C$$

Model:

$$M = \mathbb{M}(C, DM) \rightarrow \{\hat{\theta}_t\}_{t=1,m}$$

Model Specification

$$\{\hat{\theta}_t\} \xrightarrow[\text{GridSearch}]{I(\theta): AIC, AICc, BIC} \{\hat{\theta}_t^*\}$$

Model Selection:

Cross Validation

$$CV = CV(M, Partitioning, Performance Metric)$$

$$C \xrightarrow{cv} C^*$$

Residuals Diagnostics:

$$\hat{\epsilon}_t = v_t - \hat{v}_t; \hat{\epsilon}_t^{std}; \hat{\epsilon}_t^{stu}$$

$$RD = RD(\hat{\epsilon}_t, \hat{\epsilon}_t^{std}, \hat{\epsilon}_t^{stu})$$

Forecast:

$$C^*(DM_{t+1} = g_t(x_{t+1}^i)_{i=1,k} \mid \{\hat{\theta}_t^*\}_{t=1,m}) = \hat{v}_{t+1} \xrightarrow{f^{-1}, y_t} \hat{y}_{t+1}$$