

# Supplemental Material for “A geometric defect marker predicts transport classes in directed photonic meshes”

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## S1. DIRECTED MESH ENSEMBLE AND INCOHERENT TRANSPORT MODEL

We study layered directed meshes with  $W$  parallel channels and  $L$  propagation stages. At each stage, candidate  $2 \times 2$  couplers between adjacent channels are present with bulk probability  $p_f$ ; a localized “knot” defect is embedded by raising the coupler probability to  $p_{\text{knot}}$  inside a compact layer–channel region. Transport is modeled in an incoherent intensity regime by nonnegative mixing,

$$x^{(\ell+1)} = T_\ell x^{(\ell)}, \quad y = x^{(L)}, \quad (\text{S1})$$

where  $T_\ell$  encodes the random coupler placement and splitting for stage  $\ell$ . The output is summarized by contrast  $C = y_{\text{max}}/\bar{y}$  and by an effective number of populated outputs  $n_{\text{eff}} = \exp(H)$ , where  $H$  is the Shannon entropy of the normalized output intensities.

*Ensembles used in the main text.*  $W=20$  selection (Fig. 1 left).  $W=20, L=50, p_f \in \{0.105, \dots, 0.135\}$ , 20 seeds per  $p_f$ . We compare a knot-off edge reference (inject=0) against a knot-on interior operating point (inject=9). The knot occupies channels 6–14 and layers 10–18.

*Fixed-injection size replicate* (Fig. 1 right).  $W=28, L=70, p_f \in \{0.11, 0.12, 0.13\}$ , 10 seeds per  $p_f$ . Injection is fixed to channel 14 for both knot-off and knot-on instances. The knot occupies channels 9–19 and layers 14–26.

## S2. CONDENSATION-DAG GEOMETRY DIAGNOSTIC (IMPLEMENTATION DETAILS)

Given the directed mesh graph, we compute strongly connected components and contract them to form the condensation DAG. On this DAG, for SCC nodes  $X$  define a one-step future-cone volume  $V(X) = 1 + |N^+(X)|$  and an edge-level cone-growth proxy  $\kappa(X \rightarrow Y) = V(Y) - V(X)$ . As a branching observable we define  $\rho(X) = \deg^+(X) - 1$ .

*Blocking and affine response.* At scale  $R$  we block the condensation DAG into many depth-local blocks of size  $\sim R$  (deterministic partitioning by depth slice and contiguous SCC ordering). For each block  $B$  we compute block averages  $(\kappa_R(B), \rho_R(B))$ . Across blocks we fit an affine response

$$\kappa_R \simeq a_R \rho_R + b_R, \quad (\text{S2})$$

estimating  $(a_R, b_R)$  by least squares and by the robust Theil–Sen method. We restrict to a healthy domain of blocks (minimum block count and positive branching) to avoid degenerate fits.

*Plateau selection and fixed points.* We evaluate scales  $R \in \{4, 5, 6, 7, 8, 9, 10\}$ . To identify a scaling window we scan contiguous windows of  $R$  values from large to small and select the first window in which the robust slope  $a_R$  has small relative variation (plateau window length  $k = 3$ , relative tolerance 0.15). Fixed points  $a_{\text{rob}}^*$  and  $a_{\text{LS}}^*$  are defined as the median slope over the selected window for robust and LS estimators, respectively. The defect marker is  $\Delta a^* = a_{\text{rob}}^* - a_{\text{LS}}^*$ .

## S3. BINNED DICTIONARY VISUALIZATION

Figure ?? shows a binned visualization of the geometry→transport dictionary, highlighting the transition band near  $\Delta a^* \approx -0.25$ .

## S4. CLASSIFIER-QUALITY AND THRESHOLD STABILITY

To quantify predictive performance, we treat  $\Delta a^*$  as a one-dimensional score for the defect-enabled class (knot on). Figure ?? reports ROC curves and AUC. Figure ?? shows the distribution of  $\Delta a^*$  under the fixed-injection control. Figure ?? reports AUC versus  $p_f$ . Figure ?? reports balanced accuracy versus the decision threshold on  $\Delta a^*$ .

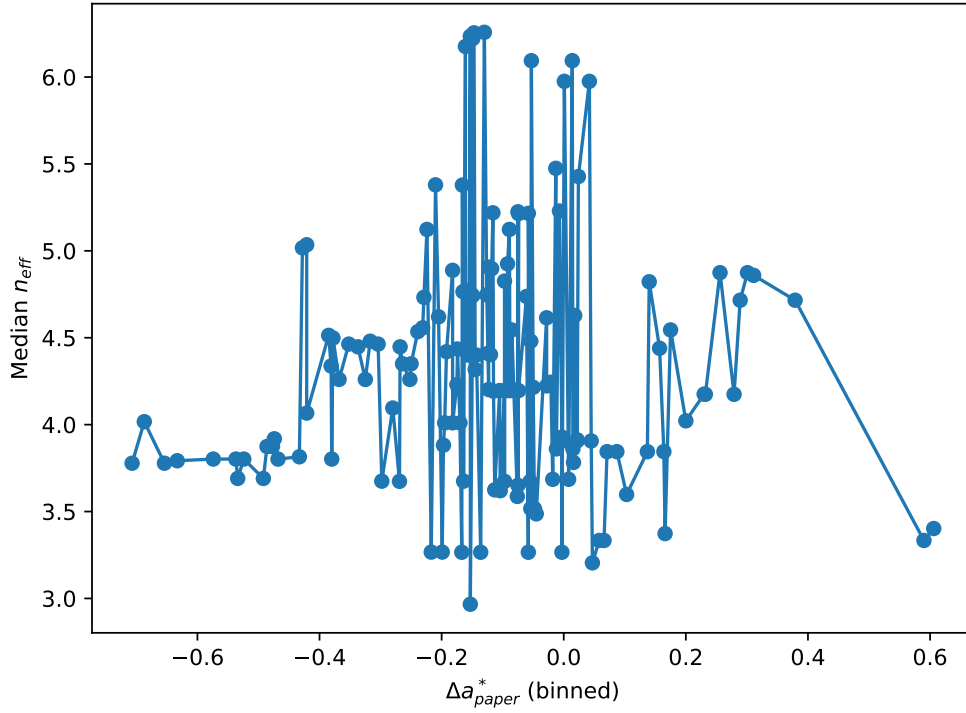


FIG. S1. **Binned geometry→transport dictionary.** Median  $n_{\text{eff}}$  within bins of  $\Delta a^*$  (paper convention) for the aggregated sweep.

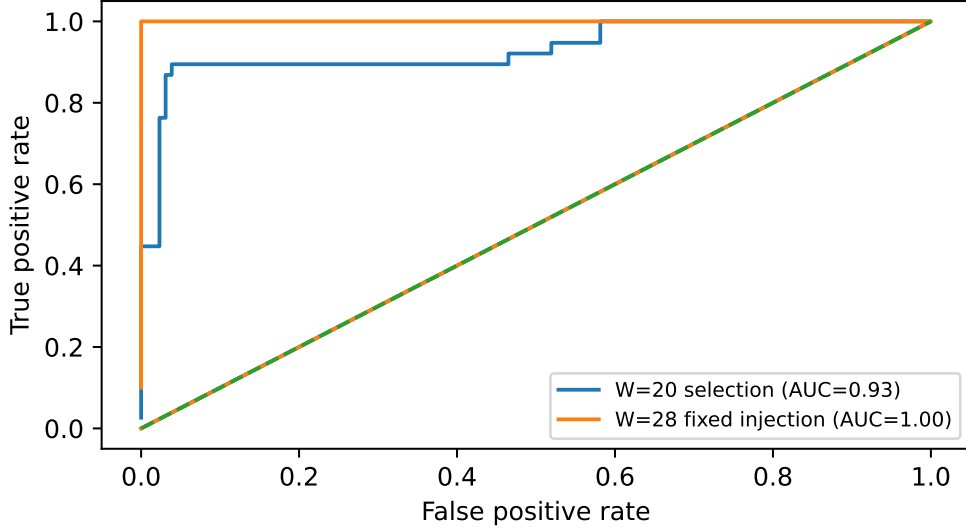


FIG. S2. **ROC curves for  $\Delta a^*$  as a scalar classifier.** AUC values are reported in the legend for the  $W=20$  selection and the fixed-injection size replicate (plateau-valid subset).

## S5. PLATEAU VALIDITY AND SELECTION BIAS CHECK

Because  $\Delta a^*$  is defined from a detected plateau window, it is undefined for “plateau-fail” instances. Figure ?? reports plateau-valid fractions for each condition. In both ensembles, excluded knot-on instances exhibit similarly high participation, indicating that plateau filtering does not artificially create the high-participation defect cluster.

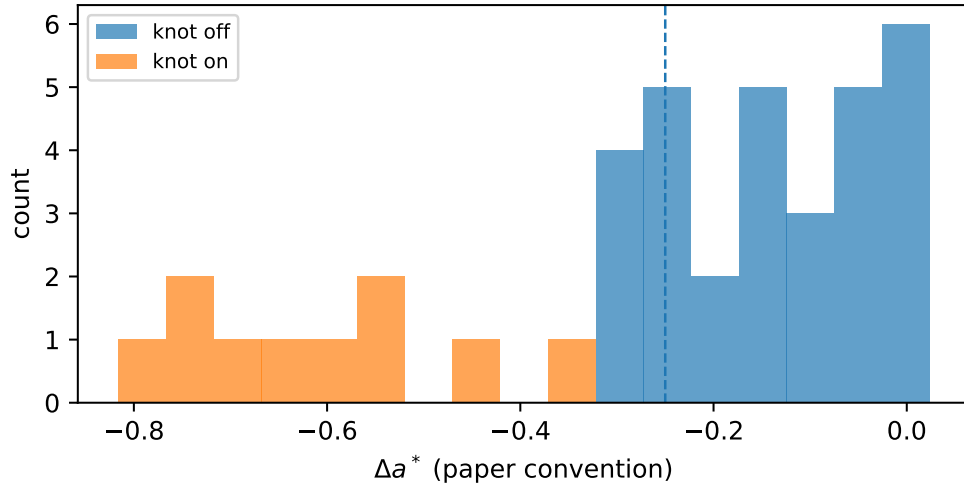


FIG. S3.  $\Delta a^*$  distributions under fixed interior injection. Overlapping histograms for knot-off and knot-on instances in the W=28 fixed-injection control.

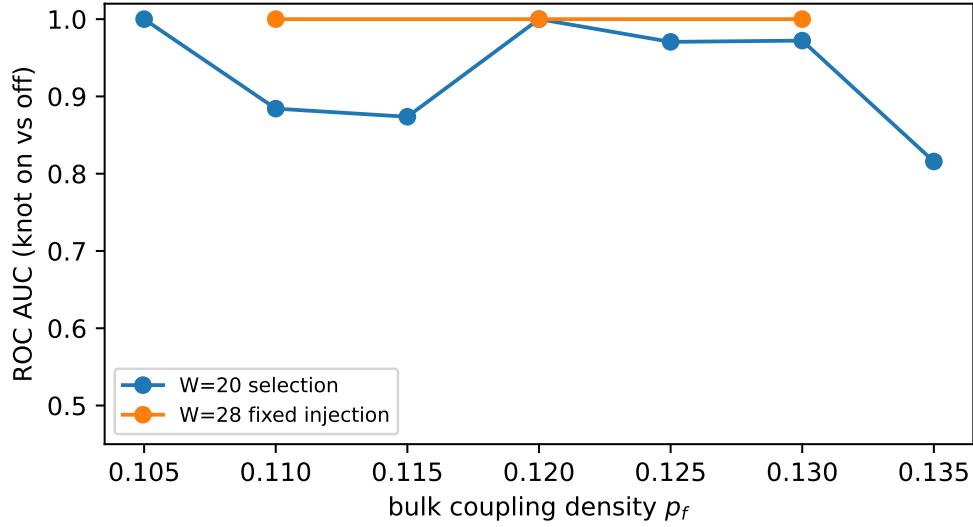


FIG. S4. AUC versus bulk coupling density  $p_f$ . Predictive performance remains high across the scanned  $p_f$  values.

## S6. JITTER INVARIANCE OF DISTRIBUTIONAL OBSERVABLES

Figure ?? shows that participation and contrast are invariant across 0–50 ps jitter in our pulsed implementation.

## REPRODUCIBILITY

All scripts, configurations, and processed datasets required to reproduce the figures are available at [github.com/a7midi/PTPP](https://github.com/a7midi/PTPP). The figure-generation script used for the referee-facing plots is provided in the repository as `scripts/make_referee_response_fig`.

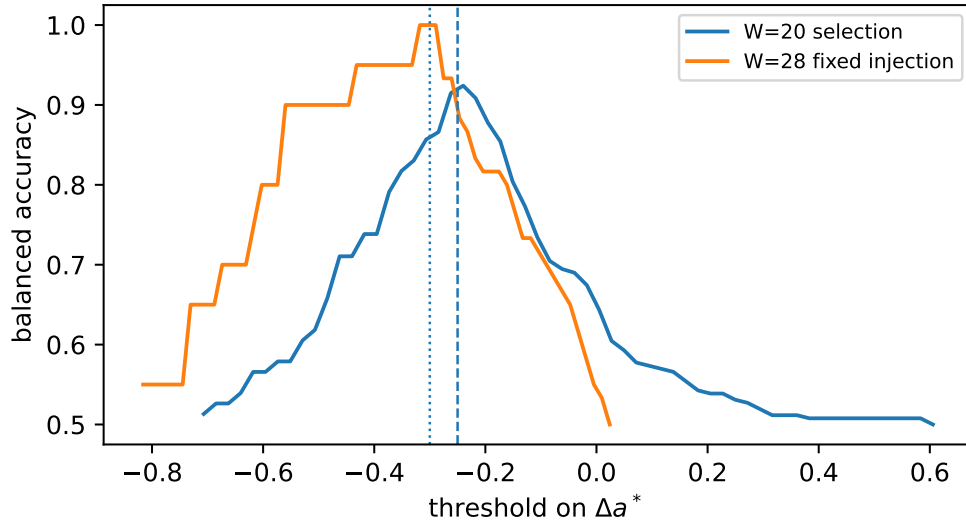


FIG. S5. **Threshold stability.** Balanced accuracy for knot-on classification as a function of a decision threshold on  $\Delta a^*$ . Vertical lines indicate representative operating thresholds discussed in the main text.

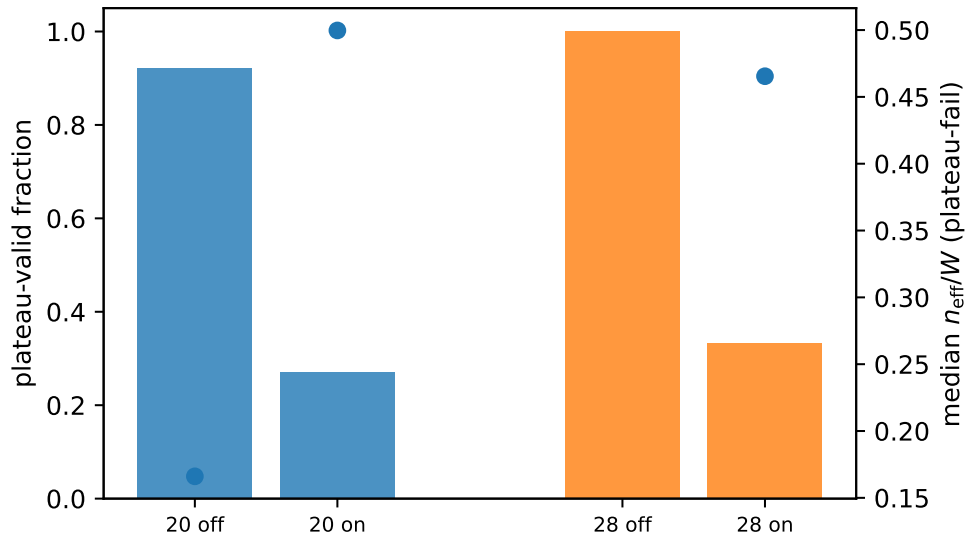


FIG. S6. **Plateau validity fractions.** Fraction of instances for which the algorithmic plateau criterion succeeds, shown for knot-off and knot-on conditions in each ensemble selection.

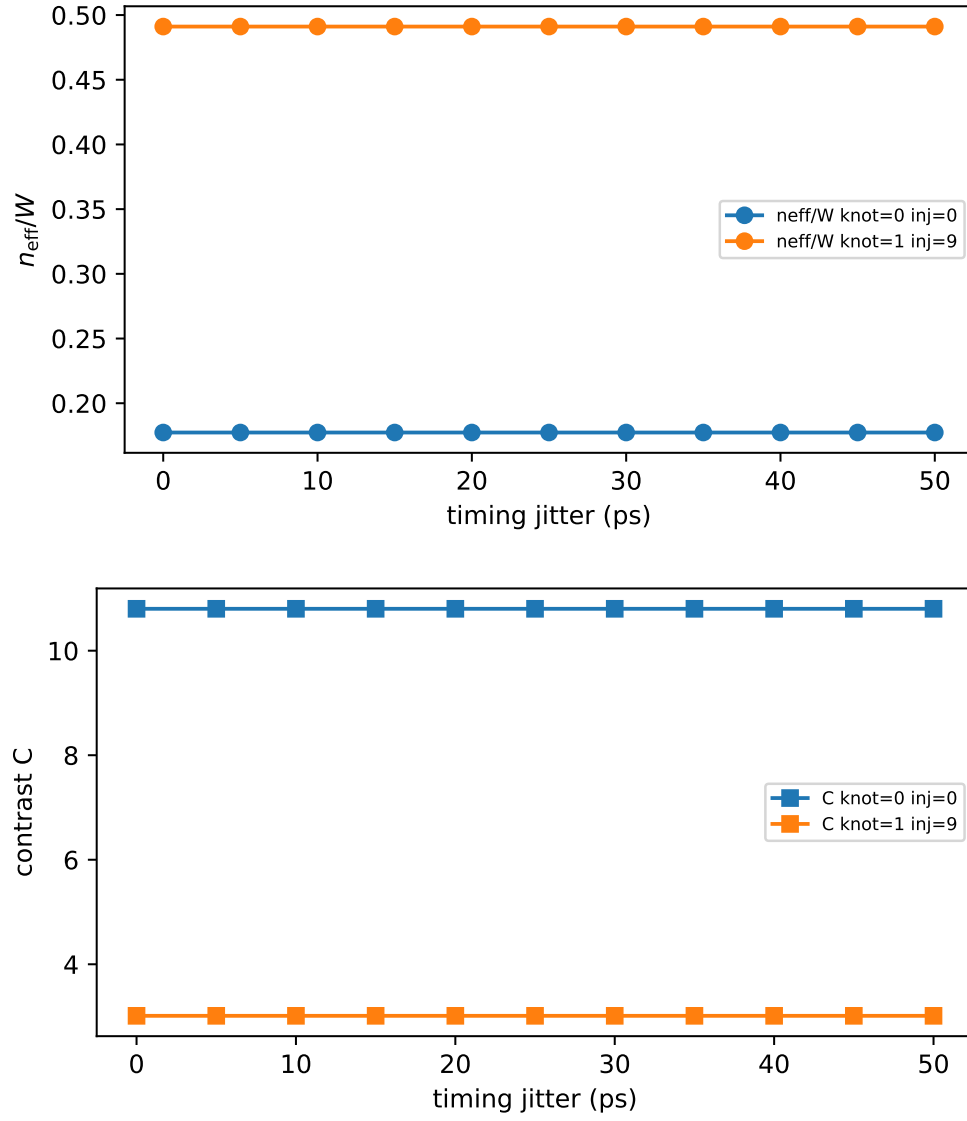


FIG. S7. **Distributional jitter invariance.** Top: mean  $n_{\text{eff}}/W$  versus jitter. Bottom: mean contrast versus jitter.