

Supervision work

Supervision 18 – Numerical Methods

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1 Exercise 2

(a) Let f be a function, r such as $f(r) = 0$ and x_0 a good estimate of r . $h = x_0 + r$. Thus, we can say that h is "small" and we can use the linear approximation to conclude that :

$$0 = f(r) = f(x_0 + h) \approx f(x_0) + h \times f'(x_0)$$

So, unless $f'(x_0)$ is close to 0,

$$h \approx -\frac{f(x_0)}{f'(x_0)}$$

We know that $r = x_0 + h$. Thus,

$$r \approx x_0 - \frac{f(x_0)}{f'(x_0)}$$

Let x_n a series of approximations of r . Therefore, the x_1 (the next approximation of r) has the value :

$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

The next estimate x_2 is obtained from x_1 the same way x_1 was obtained from x_0 :

$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)}$$

By mathematical induction, if x_n is our current estimate, the next one, x_{n+1} is given by :

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

(b) In numerical methods, the order of an algorithm represents the way in which the truncation error is affected by reducing h . For a second-order method, the truncation error is divided by 4.

An iteration that has order of convergence 2 is also called a quadratic convergence.

$$\lim \frac{|x_{n+1}-r|}{|x_n-r|^2} = \alpha,$$

where $\alpha > 0$.

(c) For Newton Raphson, the order of convergence is $q = 2$.

2 Exercise 3

(a) The Taylor series expansion for cosine, ignoring cubic and higher powers is :

$$\cos x = 1 - \frac{x^2}{2}$$

(b) $[-\frac{\pi}{2}, \frac{\pi}{2}]$ (just a guess...)

(c) If we divide the domain in 2 sub-domains, $[-\frac{\pi}{2}, 0]$ and $[0, \frac{\pi}{2}]$, we can study the monotony of the function :

For $[-\frac{\pi}{2}, 0]$, x^2 is monotonically decreasing. Thus, $\cos(x)$ is increasing. Similarly, on $[0, \frac{\pi}{2}]$ $\cos(x)$ is monotonically decreasing, as x^2 is increasing.

(d) In my opinion, the best range reduction of cosine would be $[0, 2\pi]$, as its period is 2π .

3 Exercise 4

(a) I wrote the following code in Java :

```
float n = (float) 3223.231;
float d = (float) 0.342;
for (int i = 1; i <= 30; i++) {
    System.out.println(Float.toString(n) + "␣" + |
        Float.toString(d) + "␣" + Float.toString((float)(n/d)));
    float f = (float) (2.0 - d);
    n *= f;
    d *= f;
}
```

The first 7 lines of the output are :

```
3223.231 0.342 9424.651
5344.1167 0.56703603 9424.651
7657.927 0.8125422 9424.651
9093.465 0.96485955 9424.651
9413.014 0.99876523 9424.651
9424.637 0.99999845 9424.651
9424.651 1.0 9424.651
```

and the following 23 lines coincide with the last one.

(b) The absolute error is 0 at every iteration, so not sure how to find the order of convergence ...

$$9424.651 = \frac{3223.231}{0.342}$$

Thus, the given iteration computes $\frac{n}{d}$.

4 Exercise 5

$$\begin{aligned}x^2 + 5x + 2 &= 0 \\x(x + 5) + 2 &= 0 \\x(x + 5) &= -2\end{aligned}$$

Thus, we can deduce the following two expressions:

$$\begin{aligned}(1) \quad x &= -\frac{2}{x+5} \\(2) \quad x &= -\frac{2}{x} - 5\end{aligned}$$

So, the two iterations in order to find the roots are :

$$\boxed{x_{n+1} = -\frac{2}{x_n+5} \text{ and } x_{n+1} = -\frac{2}{x_n} - 5}$$

5 Exercise 8

(b)

$$\arctan(x) \approx x - \frac{x^3}{3}$$

Thus, in base 10 there is one more significant figure added at every iteration. So in total we need 10 iteration for every significant figure in base 10. => a value in the [30,40] interval of iterations in binary.

(c) The CORDIC algorithm works as it relies on the fact that the following series can take any value within $[-2,2]$:

$$\pm 1 \pm \frac{1}{2} \pm \frac{1}{4} \pm \frac{1}{8} \pm \dots \quad (1)$$

If instead I choose the series :

$$\pm 1 \pm \frac{1}{3} \pm \frac{1}{9} \pm \frac{1}{27} \pm \dots$$

I can observe that it can no longer take any value within $[-2,2]$. So, if we multiply the series by 45° we get that :

$$\pm 45^\circ \pm \frac{45^\circ}{3} \pm \frac{45^\circ}{9} \pm \frac{45^\circ}{27} \pm \dots$$

does not represent any angle in $[-90^\circ, 90^\circ]$, so can't be used for CORDIC algorithm.

In conclusion, if $\arctan(0.5) < \frac{90^\circ}{4}$ CORDIC does not work.

(d) By multiplying the series (1) by 45° , we get the a new series, that can get any value within $[-90^\circ, 90^\circ]$ (i.e. in the first quadrant). We know that, when calculating the cosine, any angle can be reduced to an angle in the first quadrant. So, any angle $\alpha > 90^\circ$ can be brought to the first quadrant and just make the calculations with our new value.

In the same time, if $45^\circ < \alpha < 90^\circ$ the algorithm works without any issue.

In conclusion, the algorithm also works for an angle greater than 45° .

6 Exercise 10

The partial derivatives for F1 are :

$$\begin{aligned}\frac{\partial f_1}{\partial x} &= 1000 - 500y \\ &\text{and} \\ \frac{\partial f_1}{\partial y} &= 1000x - 500\end{aligned}$$

The partial derivatives for F2 are :

$$\begin{aligned}\frac{\partial f_2}{\partial x} &= \frac{2y(x-1)}{(x-y)^2} \\ &\text{and} \\ \frac{\partial f_2}{\partial y} &= \frac{2x(1-y)}{(x-y)^2}\end{aligned}$$