

# MTH499/599 Lecture Notes 04

Donghui Yan

Department of Math, Umass Dartmouth

December 23, 2015

# Outline

- Multivariate linear regression
- Properties of the OLS estimate

# Review on the simple linear model

- The simple linear model is specified as

$$Y = \beta_0 + \beta_1 X + \epsilon$$

where  $\epsilon$  is random error, and  $\beta_0, \beta_1$  are constants

- Model assumption
  - ▶  $\mathbb{E}(Y|X) = \beta_0 + \beta_1 X$  (linear model)
  - ▶  $\mathbb{E}\epsilon = 0, \text{Var}(\epsilon) = \sigma^2$  (Homoscedasticity)
  - ▶  $\epsilon \sim \mathcal{N}(0, \sigma^2)$  (normality)
- The least square formulation

$$\arg \min_{\{\beta_0, \beta_1\}} \sum_{i=1}^n (Y_i - \beta_0 - \beta_1 X_i)^2.$$

# Multivariate linear model

- Given a sample  $(\mathbf{X}_1, Y_1), (\mathbf{x}_2, Y_2), \dots, (\mathbf{X}_n, Y_n)$ , where  $\mathbf{X}_i = (X_{i1}, X_{i2}, \dots, X_{i(p-1)}) \in \mathbb{R}^{p-1}$  and  $Y_i \in \mathbb{R}$
- The multivariate linear model is specified as

$$Y_i = \beta_0 + \beta_1 X_{i1} + \beta_2 X_{i2} + \dots + \beta_{p-1} X_{i(p-1)} + \epsilon_i$$

where  $\epsilon$  is random error, and  $\beta_i$ 's are constants

- Model assumption
  - $\mathbb{E}(Y_i | \mathbf{X}_i) = \beta_0 + \beta_1 X_{i1} + \dots + \beta_{p-1} X_{i(p-1)}$  (linear model)
  - $\mathbb{E}\epsilon_i = 0, \text{Var}(\epsilon_i) = \sigma^2$  (Homoscedasticity)
  - $\epsilon \sim \mathcal{N}(0, \sigma^2)$  (normality)
- The least square formulation

$$\arg \min_{\{\beta_0, \dots, \beta_{p-1}\}} \sum_{i=1}^n (Y_i - \beta_0 - \beta_1 X_{i1} - \dots - \beta_{p-1} X_{i(p-1)})^2.$$

# The matrix version of OLS

- Given a sample  $(\mathbf{X}_1, Y_1), \dots, (\mathbf{X}_n, Y_n)$ , introduce notation

$$\mathbf{Y} = [Y_1, Y_2, \dots, Y_n]^T, \quad \boldsymbol{\beta} = [\beta_0, \beta_1, \dots, \beta_{p-1}]^T,$$

$$\mathbf{X} = \begin{bmatrix} 1 & X_{11} & X_{12} & \cdots & X_{1(p-1)} \\ 1 & X_{21} & X_{22} & \cdots & X_{2(p-1)} \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ 1 & X_{n1} & X_{n2} & \cdots & X_{n(p-1)} \end{bmatrix}$$

- The least square formulation becomes

$$\arg \min_{\boldsymbol{\beta}} (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}) \triangleq \arg \min_{\boldsymbol{\beta}} L(\boldsymbol{\beta}).$$

# The toy example in matrix notation

The data was given as the following sample

$$\cup_{i=1}^8 \{(X_i, Y_i)\} = \\ \{(6, 6), (5, 9), (4, 8), (3, 10), (2, 11), (2, 12), (1, 11), (1, 13)\}$$

$$\boldsymbol{\beta} = [\beta_0, \beta_1]^T,$$

$$\mathbf{Y} = [6, 9, 8, 10, 11, 12, 11, 13]^T,$$

$$\mathbf{X} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 6 & 5 & 4 & 3 & 2 & 2 & 1 & 1 \end{bmatrix}^T.$$

# A little matrix algebra

- Let  $\mathbf{X}$  be a vector. Then

$$\text{Cov}(\mathbf{X}) = \mathbb{E}[(\mathbf{X} - \mathbb{E}(\mathbf{X}))(\mathbf{X} - \mathbb{E}(\mathbf{X}))^T]$$

- $\mathbf{A}$  and  $\mathbf{B}$  constant matrices,  $\mathbf{c}$  and  $\mathbf{d}$  constant vectors. Then

$$\begin{aligned} \text{Cov}(\mathbf{A}\mathbf{x}_1 + \mathbf{c}, \mathbf{B}\mathbf{x}_2 + \mathbf{d}) &= \mathbf{A}\text{Cov}(\mathbf{x}_1, \mathbf{x}_2)\mathbf{B}^T \\ &\triangleq \mathbf{A} < \mathbf{x}_1, \mathbf{x}_2 > \mathbf{B}^T \end{aligned}$$

- Let matrix  $\mathbf{W}$  be symmetric. Then

$$\frac{\partial}{\partial \mathbf{s}} (\mathbf{Y} - \mathbf{A}\mathbf{s})^T \mathbf{W} (\mathbf{Y} - \mathbf{A}\mathbf{s}) = -2\mathbf{A}^T \mathbf{W} (\mathbf{Y} - \mathbf{A}\mathbf{s}).$$

# The matrix version of OLS

- Taking partial derivative of  $\mathcal{L}(\hat{\beta})$  and setting to 0 yields

$$\begin{aligned}0 &= \partial \mathcal{L}(\hat{\beta}) / \partial \hat{\beta} = -\mathbf{X}^T (\mathbf{y} - \mathbf{X} \hat{\beta}), \\ \mathbf{X}^T \mathbf{y} &= \mathbf{X}^T \mathbf{X} \hat{\beta},\end{aligned}$$

Thus

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

- The fitted value  $\hat{\mathbf{y}}$  can be expressed as

$$\hat{\mathbf{y}} = \mathbf{X} \hat{\beta} = \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

- ▶  $\mathbf{H} \triangleq \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T$  is called a hat matrix.



# The toy example in matrix notation (R code)

```
> x<-matrix(0,8,2);
> x[,1]<-1; x[,2]<-c(6,5,4,3,2,2,1,1);
> x
      [,1] [,2]
[1,]     1     6
[2,]     1     5
[3,]     1     4
[4,]     1     3
[5,]     1     2
[6,]     1     2
[7,]     1     1
[8,]     1     1
> y<-matrix(c(6,9,8,10,11,12,11,13),8,1);
> y
      [,1]
[1,]     6
[2,]     9
[3,]     8
[4,]    10
[5,]    11
[6,]    12
[7,]    11
[8,]    13
> solve(t(x) %*% x) %*% t(x) %*% y;
      [,1]
[1,] 13.375
[2,] -1.125
```

## Example (auto MPG in city)

- Data taken from UC Irvine machine learning repository
- # observations: 392
- Nine variables
  - ▶ Response variable: mpg
  - ▶ Predictor variables
    - # cylinders
    - Displacement
    - Horsepower
    - Weight
    - Acceleration
    - Model year
    - Origin
    - Car name.

# Example (auto MPG in city)

- The first few lines of the data look like

mpg	cylinders	displacement	horsepower	weight	acceleration	modelyear	origin	carname
18.0	8	307.0	130.0	3504.	12.0	70	1	"chevrolet chevelle malibu"
15.0	8	350.0	165.0	3693.	11.5	70	1	"buick skylark 320"
18.0	8	318.0	150.0	3436.	11.0	70	1	"plymouth satellite"
16.0	8	304.0	150.0	3433.	12.0	70	1	"amc rebel sst"
17.0	8	302.0	140.0	3449.	10.5	70	1	"ford torino"
15.0	8	429.0	198.0	4341.	10.0	70	1	"ford galaxie 500"
14.0	8	454.0	220.0	4354.	9.0	70	1	"chevrolet impala"
14.0	8	440.0	215.0	4312.	8.5	70	1	"plymouth fury iii"
14.0	8	455.0	225.0	4425.	10.0	70	1	"pontiac catalina"
15.0	8	390.0	190.0	3850.	8.5	70	1	"amc ambassador dpl"
15.0	8	383.0	170.0	3563.	10.0	70	1	"dodge challenger se"
14.0	8	340.0	160.0	3609.	8.0	70	1	"plymouth 'cuda 340"
15.0	8	400.0	150.0	3761.	9.5	70	1	"chevrolet monte carlo"
14.0	8	455.0	225.0	3086.	10.0	70	1	"buick estate wagon (sw)"
24.0	4	113.0	95.00	2372.	15.0	70	3	"toyota corona mark ii"
22.0	6	198.0	95.00	2833.	15.5	70	1	"plymouth duster"
18.0	6	199.0	97.00	2774.	15.5	70	1	"amc hornet"
21.0	6	200.0	85.00	2587.	16.0	70	1	"ford maverick"
27.0	4	97.00	88.00	2130.	14.5	70	3	"datsun pl510"

# Regression output of the auto MPG example

```
> tmp<-read.table("autompg.Data", header=TRUE);
> y<-tmp[,1];
> n<-nrow(tmp); p<-8;
> x<-matrix(0,nrow(tmp),(p-1));
> for(i in 1:(p-1)) { x[,i]<-tmp[,i+1]};
> mylm<-lm(y ~ x);
> summary(mylm);
```

```
Call:
lm(formula = y ~ x)
```

```
Residuals:|
      Min       1Q   Median       3Q      Max
-9.5903 -2.1565 -0.1169  1.8690 13.0604
```

```
Coefficients:
              Estimate Std. Error t value Pr(>|t|)
(Intercept) -17.218435   4.644294  -3.707  0.00024 ***
x1            -0.493376   0.323282  -1.526  0.12780
x2             0.019896   0.007515   2.647  0.00844 **
x3            -0.016951   0.013787  -1.230  0.21963
x4            -0.006474   0.000652  -9.929 < 2e-16 ***
x5             0.080576   0.098845   0.815  0.41548
x6             0.750773   0.050973  14.729 < 2e-16 ***
x7             1.426141   0.278136   5.127  4.67e-07 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 3.328 on 384 degrees of freedom
Multiple R-squared:  0.8215, Adjusted R-squared:  0.8182
F-statistic: 252.4 on 7 and 384 DF, p-value: < 2.2e-16
```

```
> tmp<-read.table("autompg.Data", header=TRUE);
> Y<-tmp[,1];
> X<-matrix(0,nrow(tmp),p);
> X[,1]<-1;
> for(i in 2:p) { X[,i]<-tmp[,i]};
> ##Regression estimates by matrix
> solve(t(X) %*% X) %*% t(X) %*% Y
```

```
              [,1]
[1,] -17.218434622
[2,]  -0.493376319
[3,]   0.019895644
[4,]  -0.016951144
[5,]  -0.006474043
[6,]   0.080575838
[7,]   0.750772678
[8,]   1.426140495
```

```
>
> ##The first few lines of X looks like
> X
```

	[,1]	[,2]	[,3]	[,4]	[,5]	[,6]	[,7]	[,8]
[1,]	1	8	307.0	130	3504	12.0	70	1
[2,]	1	8	350.0	165	3693	11.5	70	1
[3,]	1	8	318.0	150	3436	11.0	70	1
[4,]	1	8	304.0	150	3433	12.0	70	1
[5,]	1	8	302.0	140	3449	10.5	70	1
[6,]	1	8	429.0	198	4341	10.0	70	1
[7,]	1	8	454.0	220	4354	9.0	70	1
[8,]	1	8	440.0	215	4312	8.5	70	1
[9,]	1	8	455.0	225	4425	10.0	70	1
[10,]	1	8	390.0	190	3850	8.5	70	1

# Properties of the hat matrix

- The hat matrix is symmetric and idempotent, i.e.,  $H^2 = H$

$$\begin{aligned}H^2 &= \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \cdot \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \\&= \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T = H\end{aligned}$$

- For matrices  $A$  and  $B$ ,  $\text{trace}(AB) = \text{trace}(BA)$
- $\text{trace}(H) = p$

$$\begin{aligned}\text{trace}(H) &= \text{trace}(\mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T) \\&= \text{trace}((\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X}) \\&= \text{trace}(\mathbf{I}_p) \\&= p.\end{aligned}$$

# Properties of the hat matrix

- The diagonals of hat matrix,  $0 \leq h_{ii} \leq 1$

Proof.

Consider the  $i$  -  $th$  element along the diagonal of  $H$ . Since  $H^2 = H$ , we have

$$h_{ii} = \sum_{j=1}^n h_{ij}^2 = h_{ii}^2 + \sum_{j \neq i} h_{ij}^2,$$

implying that

$$h_{ii}^2 \leq h_{ii}.$$

Thus the result follows. □

# Properties of OLS estimate

- The least square estimate is unbiased.

Proof.

$$\begin{aligned}\mathbb{E}(\hat{\beta}) &= \mathbb{E}((\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}) \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbb{E}(\mathbf{y}) \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} \beta \\ &= \beta.\end{aligned}$$



## Properties of OLS estimate (continued)

- The variance of  $\hat{\beta}$  is given by  $(\mathbf{X}^T \mathbf{X})^{-1} \sigma^2$ .

Proof.

$$\begin{aligned} \text{Var}(\hat{\beta}) &= \text{Var}((\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}) \\ &= \text{Cov}((\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}, (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}) \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T < \mathbf{y}, \mathbf{y} > [(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T]^T \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \sigma^2 \mathbf{I} \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \sigma^2. \end{aligned}$$





# Hypothesis testing on OLS estimate

- If  $\sigma^2$  is known, then  $\hat{\beta} \sim \mathcal{N}(0, (\mathbf{X}^T \mathbf{X})^{-1} \sigma^2)$  thus a normal test otherwise a  $t_{n-p-1}$ -test under  $H_0 : \beta = \mathbf{0}$ .
  - ▶  $\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$ , a linear combination of i.i.d. normal r.v.'s thus follows a normal distribution
  - ▶ If  $\sigma^2$  is known, the testing statistic  $T = \hat{\beta} / SD(\hat{\beta}) \sim \mathcal{N}(0, 1)$
  - ▶ Otherwise,  $\sigma^2$  is replaced by

$$\hat{\sigma}^2 = SSE / (n - p - 1) \sim \chi_{n-p-1}$$

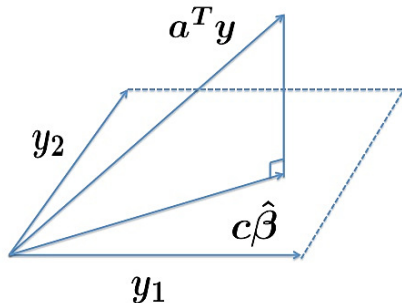
thus

$$T = \hat{\beta} / SD(\hat{\beta}) \sim t_{n-p-1}.$$

# The Gauss-Markov Theorem

## Theorem (Gauss-Markov)

Consider linear model  $\mathbf{y} = \mathbf{X}\beta + \epsilon$  with  $\mathbb{E}(\epsilon) = 0$  and  $\text{Var}(\epsilon) = \sigma^2 \mathbf{I}$ . Then the OLS estimate  $\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$  is the Best Linear Unbiased Estimate (BLUE) of  $\beta$ .



# The Gauss-Markov Theorem

*Proof.* Consider the linear parameter of interest  $\mathbf{c}\beta$ .

Let  $\mathbf{a}^T \mathbf{y} \triangleq \bar{\beta}$  be an unbiased estimate of  $\mathbf{c}\beta$  (since any estimate would be a linear combination of  $\mathbf{y}$ 's components. Unbiasedness of  $\mathbf{a}^T \mathbf{y}$  implies that

$$\mathbb{E}(\mathbf{a}^T \mathbf{y}) = \mathbf{a}^T X \beta = \mathbf{c}\beta$$

for all  $\beta$ . Thus  $\mathbf{a}^T X = \mathbf{c}^T$ .

## The Gauss-Markov Theorem (continued)

Write  $\bar{\beta}$  as  $\bar{\beta} = (\mathbf{a}^T \mathbf{y} - \mathbf{c}\hat{\beta}) + \mathbf{c}\hat{\beta}$ . Easily we can verify

$$\begin{aligned} & Cov(\mathbf{a}^T \mathbf{y} - \mathbf{c}\hat{\beta}, \mathbf{c}\hat{\beta}) \\ &= Cov(\mathbf{a}^T \mathbf{y}, \mathbf{c}\hat{\beta}) - Cov(\mathbf{c}\hat{\beta}, \mathbf{c}\hat{\beta}) \\ &= Cov(\mathbf{a}^T \mathbf{y}, \mathbf{a}^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}) - \mathbf{c} Var(\hat{\beta}) \mathbf{c}^T \\ &= \mathbf{a}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{a} \sigma^2 - \mathbf{a}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{a} \sigma^2 \\ &= 0. \end{aligned}$$

Thus variance decomposition

$$Var(\mathbf{a}^T \mathbf{y}) = Var(\mathbf{a}^T \mathbf{y} - \mathbf{c}\hat{\beta}) + Var(\mathbf{c}\hat{\beta})$$

and the result follows. □