# Poster Preparation

#### 1 Problem Statement

#### 1.1 Goal

Our project was to develop a code base for future Arduino-based prototyping for an existing transmission control system. CAN compatibility is required for integration with the existing testbed and other development tools.

#### 1.2 Requirements

The delivered code base should consist of independent modules that have no external dependencies. The operations accomplished by the modules should be complete and require minimal customization.

### 1.3 Objectives

- Implement sensor reading for Arduino
- Transmit useful readings by CAN protocol
- Implement data logging on a receiving CAN node
- Integrate project-specific sensor into existing network

## 1.4 Applications

- Integration of digital and analog sensors with existing testbed
- Rapid prototyping with modules from code base

# 2 Work accomplished

- Integration of digital sensor with Arudino-based controller
- CAN network integration of Arduino
  - Standard CAN integration

- Implementation of J1939 variant
- Integration of sensor into CAN network
  - Digital sensor
  - Analog sensor with external circuitry
- Real time data logging of transmitted network information
- System validation using industry tools and typical application parameters
- Out-of-the-box readiness of modules

## 3 Conclusions

- Agile concepts from software development useful for various environments
- Important part of project was selecting tools and systems, not developing from scratch
- Team work not comparable to previous experience and required adaptive approach