#### Introduction

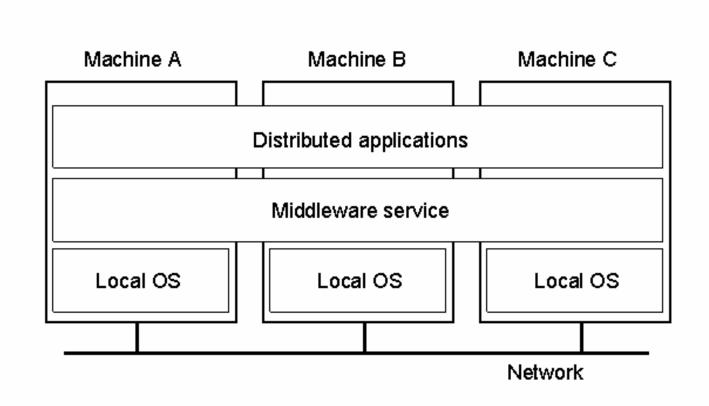
Chapter 1

#### Definition of a Distributed System (1)

A distributed system is:

A collection of independent computers that appears to its users as a single coherent system.

#### Definition of a Distributed System (2)



A distributed system organized as middleware. Note that the middleware layer extends over multiple machines.

### Transparency in a Distributed System

Transparency	Description		
Access	Hide differences in data representation and how a resource is accessed		
Location	Hide where a resource is located		
Migration	Hide that a resource may move to another location		
Relocation	Hide that a resource may be moved to another location while in use		
Replication	Hide that a resource may be shared by several competitive users		
Concurrency	Hide that a resource may be shared by several competitive users		
Failure	Hide the failure and recovery of a resource		
Persistence	Hide whether a (software) resource is in memory or on disk		

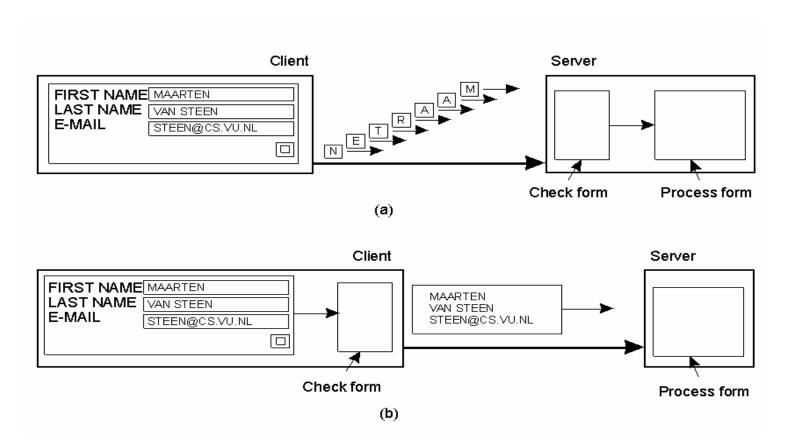
Different forms of transparency in a distributed system.

# Scalability Problems

Concept	Example		
Centralized services	A single server for all users		
Centralized data	A single on-line telephone book		
Centralized algorithms	Doing routing based on complete information		

Examples of scalability limitations.

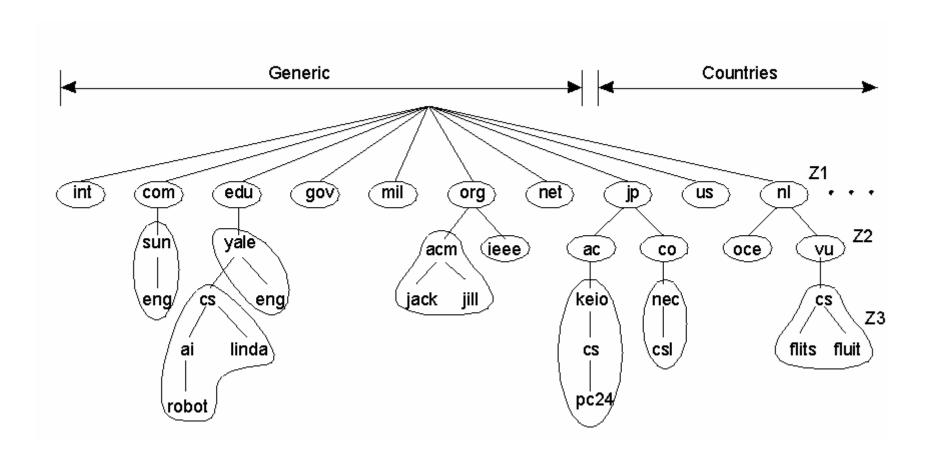
# Scaling Techniques (1)



The difference between letting:

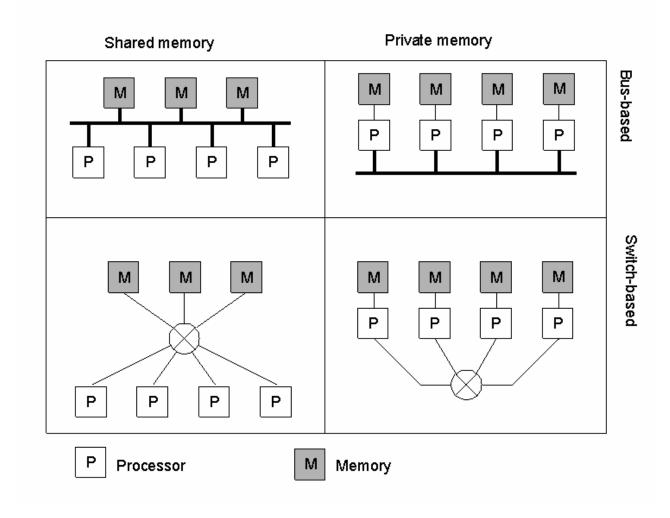
- a) a server or
- b) a client check forms as they are being filled

### Scaling Techniques (2)



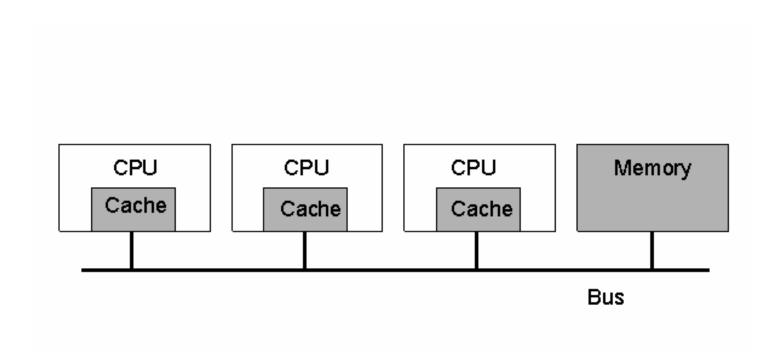
An example of dividing the DNS name space into zones.

### Hardware Concepts



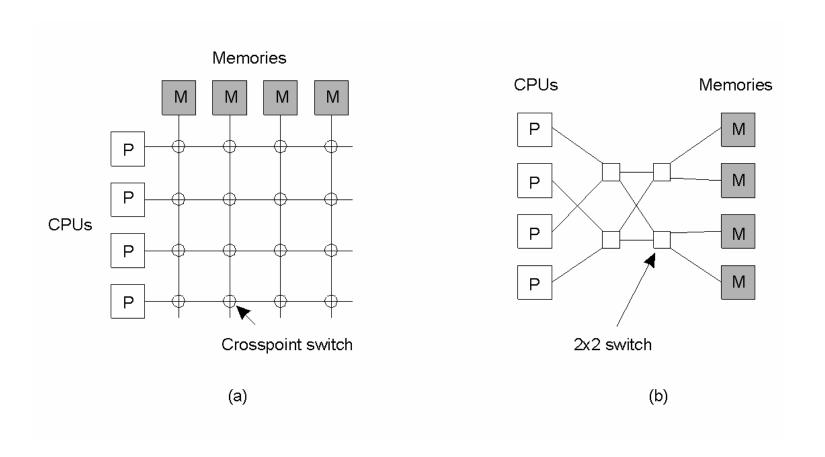
Different basic organizations and memories in distributed computer systems

### Multiprocessors (1)



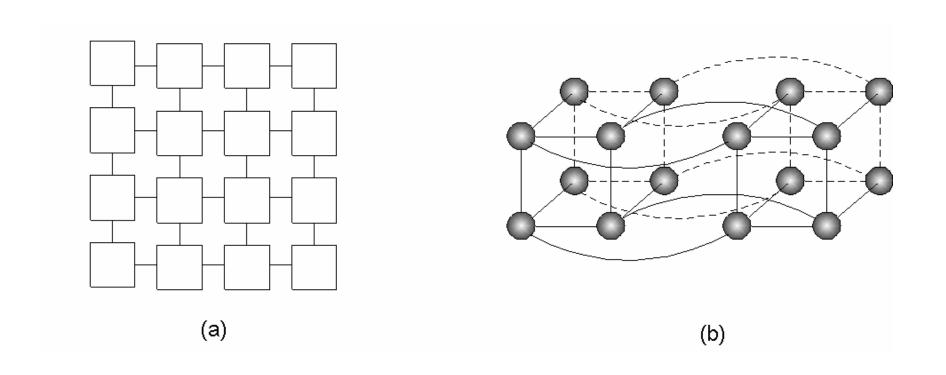
A bus-based multiprocessor.

### Multiprocessors (2)



- a) A crossbar switch
- b) An omega switching network

# Homogeneous Multicomputer Systems



- a) Grid
- b) Hypercube

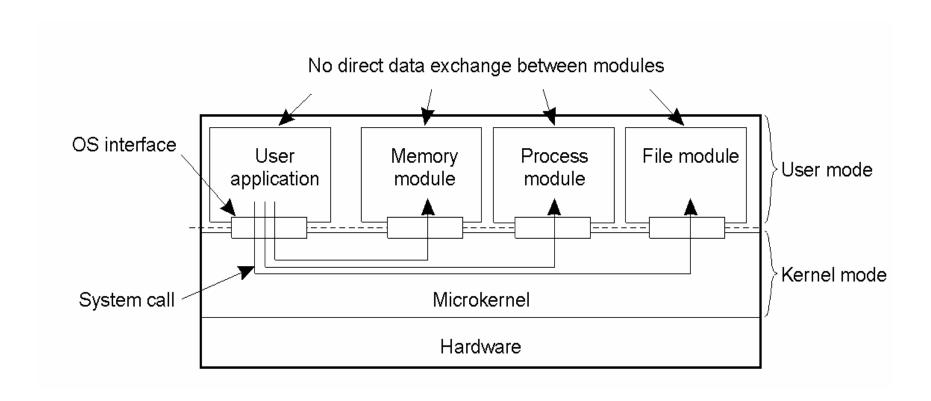
### Software Concepts

System	Description	Main Goal	
DOS	Tightly-coupled operating system for multi- processors and homogeneous multicomputers	Hide and manage hardware resources	
NOS	Loosely-coupled operating system for heterogeneous multicomputers (LAN and WAN)	Offer local services to remote clients	
Middleware	Additional layer atop of NOS implementing general-purpose services	Provide distribution transparency	

#### An overview of

- DOS (Distributed Operating Systems)
- NOS (Network Operating Systems)
- Middleware

### Uniprocessor Operating Systems



Separating applications from operating system code through a microkernel.

### Multiprocessor Operating Systems (1)

```
monitor Counter {
private:
  int count = 0;
public:
  int value() { return count;}
  void incr () { count = count + 1;}
  void decr() { count = count - 1;}
}
```

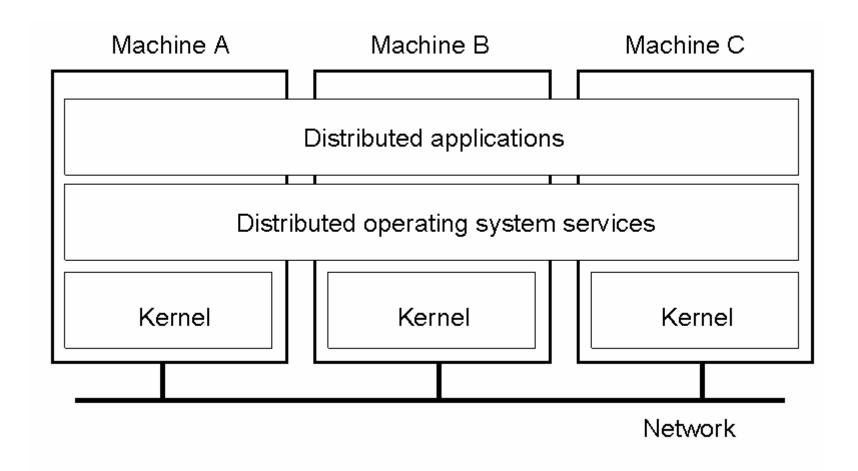
A monitor to protect an integer against concurrent access.

### Multiprocessor Operating Systems (2)

```
monitor Counter {
private:
                                                  void decr() {
 int count = 0;
                                                  if (count ==0) {
 int blocked_procs = 0;
                                                    blocked_procs = blocked_procs + 1;
 condition unblocked:
                                                   wait (unblocked);
public:
                                                    blocked_procs = blocked_procs - 1;
 int value () { return count;}
 void incr () {
                                                    else
    if (blocked_procs == 0)
                                                    count = count - 1:
      count = count + 1;
    else
      signal (unblocked);
```

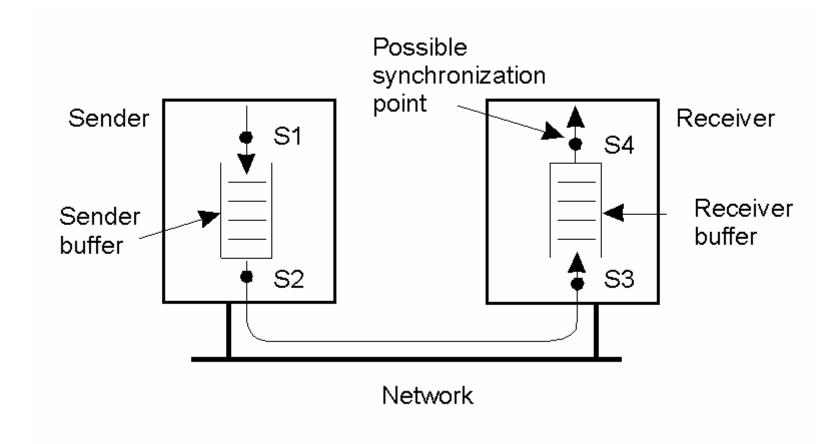
A monitor to protect an integer against concurrent access, but blocking a process.

# Multicomputer Operating Systems (1)



General structure of a multicomputer operating system

### Multicomputer Operating Systems (2)



Alternatives for blocking and buffering in message passing.

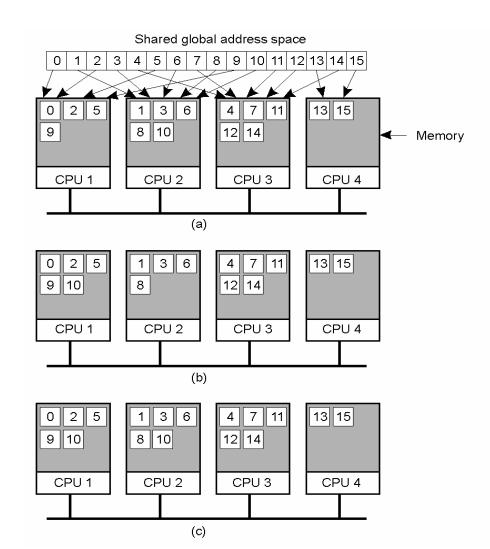
# Multicomputer Operating Systems (3)

Synchronization point	Send buffer	Reliable comm. guaranteed?	
Block sender until buffer not full	Yes	Not necessary	
Block sender until message sent	No	Not necessary	
Block sender until message received	No	Necessary	
Block sender until message delivered	No	Necessary	

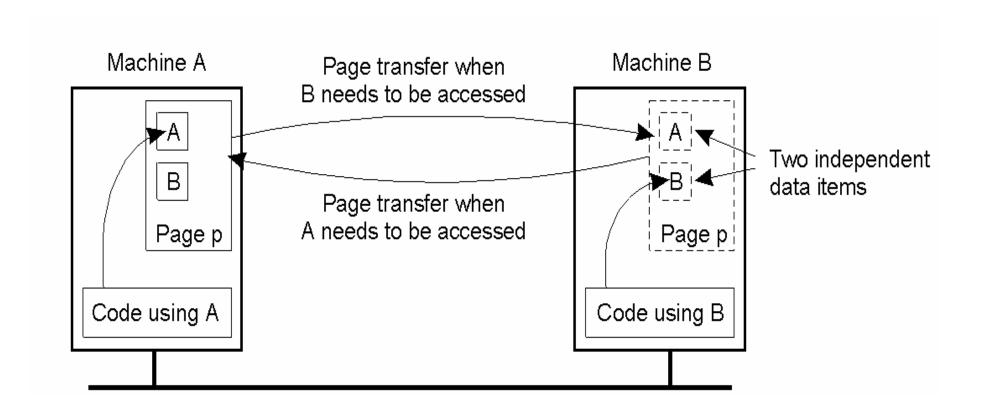
Relation between blocking, buffering, and reliable communications.

#### Distributed Shared Memory Systems (1)

- a) Pages of address space distributed among four machines
- b) Situation after CPU 1 references page 10
- c) Situation if page 10 is read only and replication is used

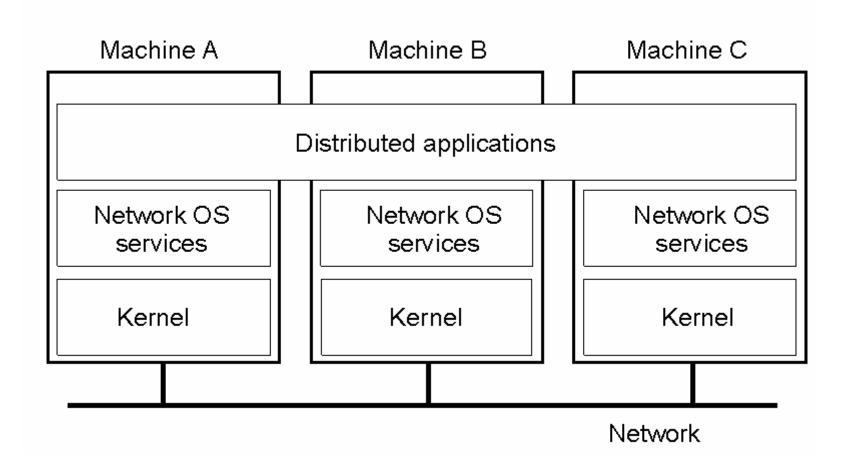


#### Distributed Shared Memory Systems (2)



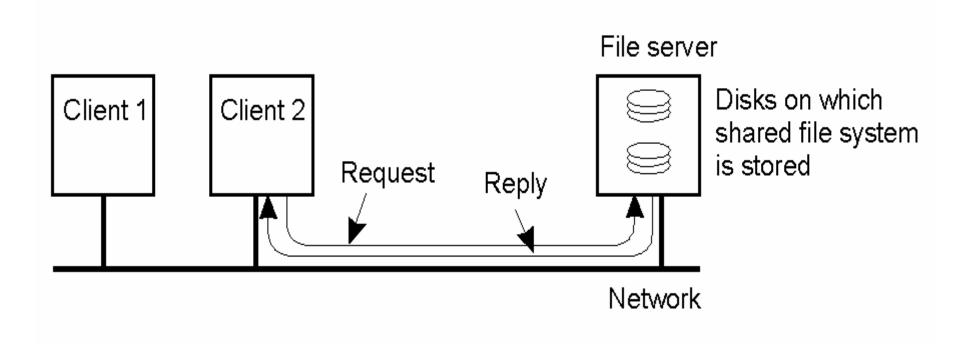
False sharing of a page between two independent processes.

### Network Operating System (1)



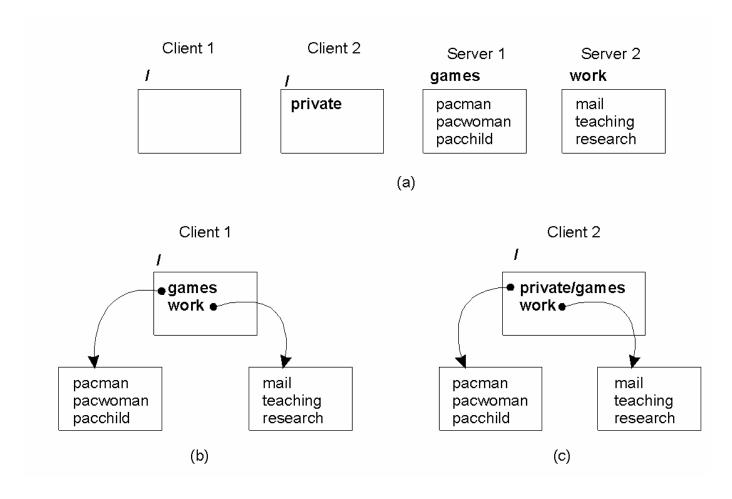
General structure of a network operating system.

### Network Operating System (2)



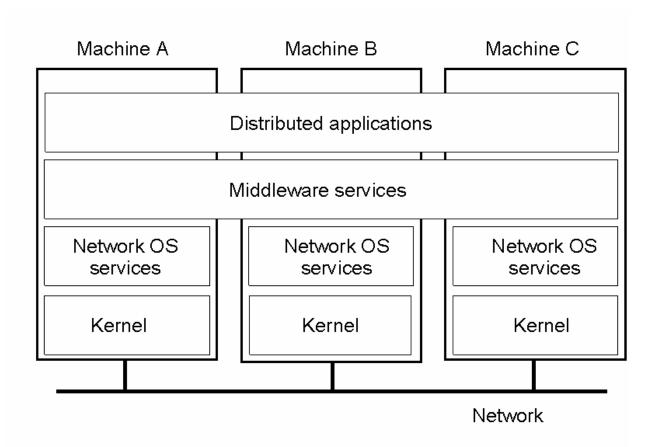
Two clients and a server in a network operating system.

### Network Operating System (3)



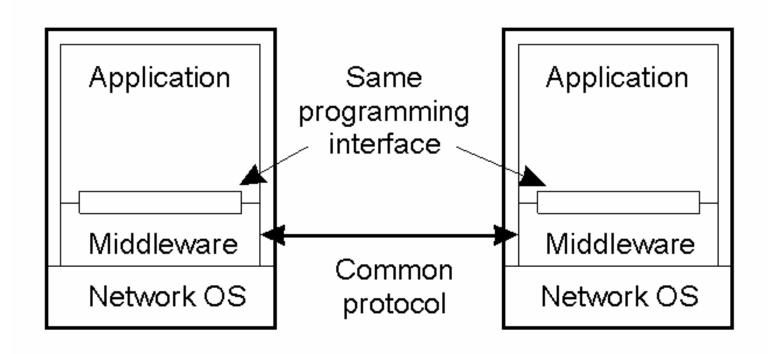
Different clients may mount the servers in different places.

### Positioning Middleware



General structure of a distributed system as middleware.

### Middleware and Openness



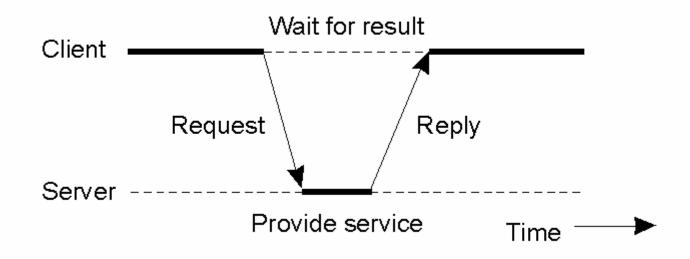
In an open middleware-based distributed system, the protocols used by each middleware layer should be the same, as well as the interfaces they offer to applications.

# Comparison between Systems

	Distributed OS		Network	Middleware-
Item	Multiproc.	Multicomp.	os	based OS
Degree of transparency	Very High	High	Low	High
Same OS on all nodes	Yes	Yes	No	No
Number of copies of OS	1	N	N	N
Basis for communication	Shared memory	Messages	Files	Model specific
Resource management	Global, central	Global, distributed	Per node	Per node
Scalability	No	Moderately	Yes	Varies
Openness	Closed	Closed	Open	Open

A comparison between multiprocessor operating systems, multicomputer operating systems, network operating systems, and middleware based distributed systems.

#### Clients and Servers



General interaction between a client and a server.

### An Example Client and Server (1)

```
/* Definitions needed by clients and servers.
#define TRUE
                          255 /* maximum length of file name
#define MAX_PATH
                          1024 /* how much data to transfer at once
#define BUF_SIZE
                          243 /* file server's network address
#define FILE_SERVER
/* Definitions of the allowed operations */

    1 /* create a new file

#define CREATE
                          2 /* read data from a file and return it
#define READ
                          3 /* write data to a file
#define WRITE
                          4 /* delete an existing file
#define DELETE
/* Error codes. */
                             /* operation performed correctly
#define OK
#define E_BAD_OPCODE -1 /* unknown operation requested
#define E_BAD_PARAM -2 /* error in a parameter
                                 /* disk error or other I/O error
#define E_IO
/* Definition of the message format. */
struct message {
                                 /* sender's identity
    long source;
                                 /* receiver's identity
    long dest;
                                 /* requested operation
    long opcode;
                                 /* number of bytes to transfer
    long count;
                                 /* position in file to start I/O
    long offset;
                                 /* result of the operation
    long result;
                                 /* name of file being operated on
    char name[MAX_PATH];
                                 /* data to be read_or written
    char data[BUF_SIZE];
```

The *header.h* file used by the client and server.

### An Example Client and Server (2)

```
#include <header.h>
void main(void) {
                                         /* incoming and outgoing messages
    struct message ml, m2;
                                         /* result code
    int r:
                                         /* server runs forever
    while(TRUE) {
                                       /* block waiting for a message
        receive(FILE_SERVER, &ml);
                                         /* dispatch on type of request
        switch(ml.opcode) {
            case CREATE: r = do_create(&ml, &m2); break;
                             r = do_read(&ml, &m2); break;
            case READ:
                             r = do_write(&ml, &m2); break;
            case WRITE:
            case DELETE: r = do_delete(&ml, &m2); break;
                            r = E_BAD_OPCODE:
            default:
        m2.result = r:
                                        /* return result to client
        send(ml.source, &m2);
                                         /* send reply
```

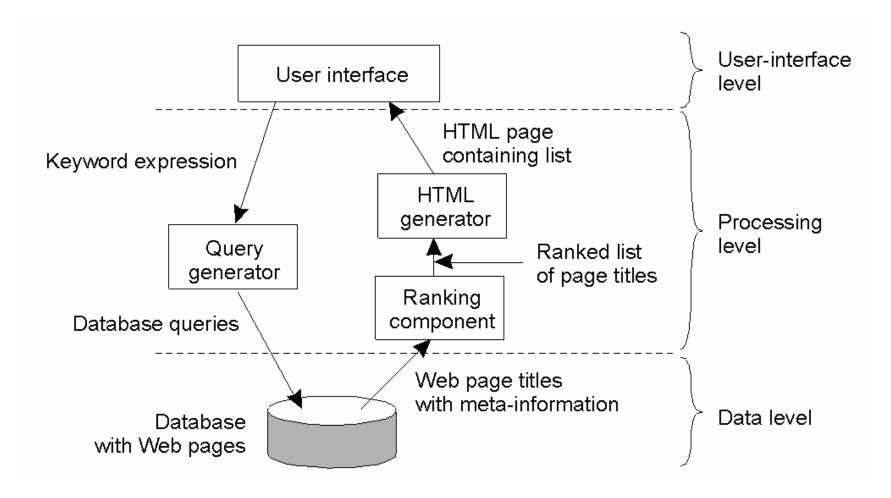
A sample server.

### An Example Client and Server (3)

```
#include <header.h>
                                             /* procedure to copy file using the server
int copy(char *src, char *dst){
                                             /* message buffer
    struct message ml;
                                             /* current file position
    long position;
                                             /* client's address
    long client = 110;
                                             /* prepare for execution
    initialize();
    position = 0;
    do {
                                             /* operation is a read
         ml.opcode = READ;
                                             /* current position in the file
         ml.offset = position;
                                                                                            /* how many bytes to read*/
         ml.count = BUF_SIZE;
         strcpy(&ml.name, src);
                                              /* copy name of file to be read to message
                                             /* send the message to the file server
         send(FILESERVER, &ml);
                                             /* block waiting for the reply
         receive(client, &ml);
         /* Write the data just received to the destination file.
         ml.opcode = WRITE;
                                             /* operation is a write
         ml.offset = position;
                                             /* current position in the file
                                             /* how many bytes to write
         ml.count = ml.result;
         strcpy(&ml.name, dst);
                                             /* copy name of file to be written to buf
                                             /* send the message to the file server
         send(FILE_SERVER, &ml);
                                             /* block waiting for the reply
         receive(client, &ml);
                                             /* ml.result is number of bytes written
         position += ml.result;
    } while( ml.result > 0 );
                                             /* iterate until done
    return(ml.result >= 0 ? OK : ml result); /* return OK or error code
```

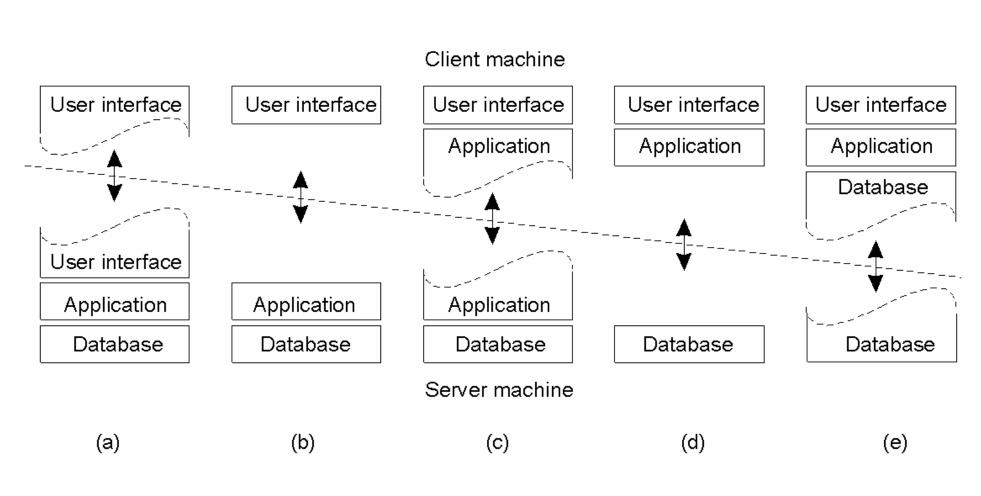
A client using the server to copy a file.

### Processing Level



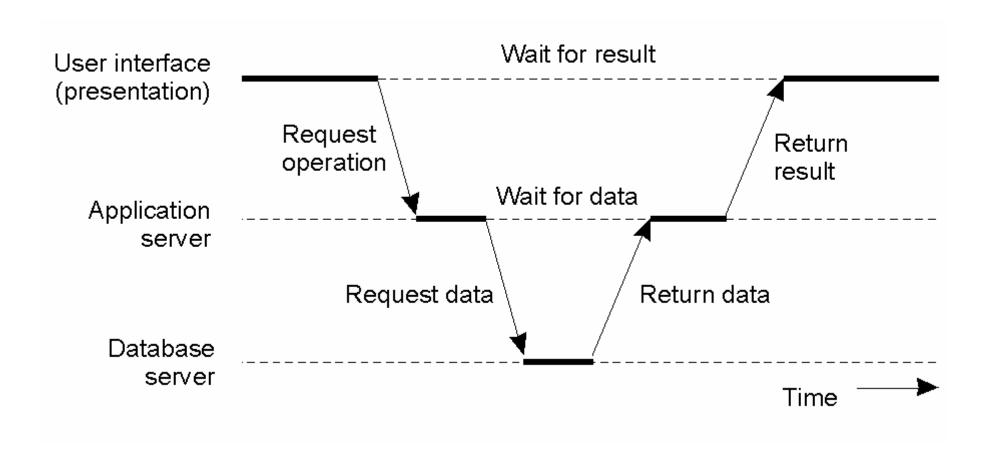
The general organization of an Internet search engine into three different layers

### Multitiered Architectures (1)



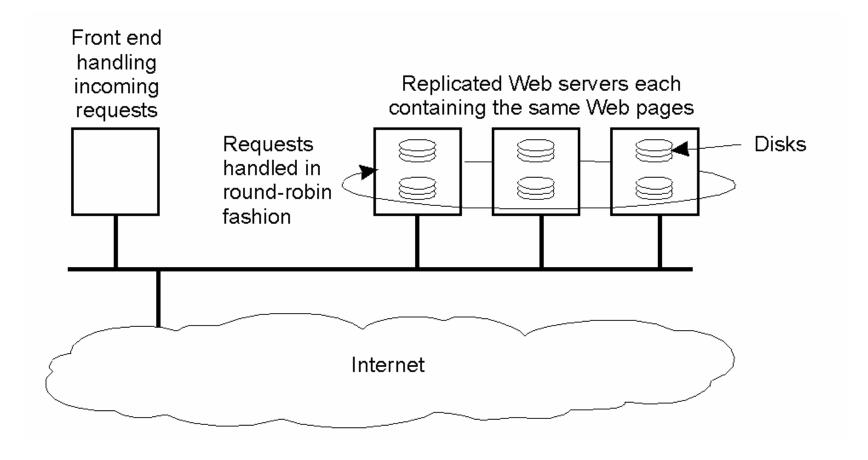
Alternative client-server organizations (a) - (e).

### Multitiered Architectures (2)



An example of a server acting as a client.

#### Modern Architectures



An example of horizontal distribution of a Web service.