

Prac 1

```
import queue as q

from RMP import dict_gn

def bfs(current_city, goal_city, explored_list, exploration_queue):

    explored_list.append(current_city)

    goal_reached = False

    if current_city == goal_city:

        return explored_list, True

    for each_city in dict_gn[current_city].keys():

        if each_city not in explored_list and each_city not in
exploration_queue.queue:

            exploration_queue.put(each_city)

    try:

        explored_list, goal_reached = bfs(exploration_queue.get(False), goal_city,
explored_list, exploration_queue)

    except q.Empty:

        return explored_list, False

    if goal_reached:

        return explored_list, True

    return explored_list, False


def main():

    start_city = 'Arad'

    goal_city = 'Bucharest'
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explored_list = []
exploration_queue = q.Queue()
exploration_queue.put(start_city)
goal_reached = False

explored_list, goal_reached = bfs(exploration_queue.get(False), goal_city,
explored_list, exploration_queue)

if not goal_reached:
    print('Could not find', goal_city)

print(explored_list)

main()

```

Prac 2

```

import queue as Q
from RMP import dict_gn
start='Arad'
goal='Bucharest'
result=""

def DLS(city, visitedstack, startlimit, endlimit):
    global result
    found=0
    result=result+city+' '
    visitedstack.append(city)
    if city==goal:
        return 1

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if startlimit==endlimit:

    return 0

for eachcity in dict_gn[city].keys():

    if eachcity not in visitedstack:

        found=DLS(eachcity, visitedstack, startlimit+1, endlimit)

        if found:

            return found

def IDDFS(city, visitedstack, endlimit):

    global result

    for i in range(0, endlimit):

        print("Searching at Limit: ",i)

        found=DLS(city, visitedstack, 0, i)

        if found:

            print("Found")

            break

        else:

            print("Not Found! ")

            print(result)

            print("-----")

            result=' '

            visitedstack=[]

def main():

    visitedstack=[]

    IDDFS(start, visitedstack, 9)

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print("IDDFS Traversal from ",start," to ", goal," is: ")
print(result)
main()
```

Prac 3

```
from RMP import dict_hn
from RMP import dict_gn
import queue as Q
start = 'Arad'
goal = 'Bucharest'
result = ""
def get_fn(citystr):
    cities = citystr.split(" , ")
    hn = gn = 0
    for ctr in range(0, len(cities)-1):
        gn = gn + dict_gn[cities[ctr]][cities[ctr+1]]
    hn = dict_hn[cities[len(cities)-1]]
    return(hn + gn)
def expand(cityq):
    global result
    tot, citystr, thiscity = cityq.get()
    if thiscity == goal:
        result = citystr + " : : " + str(tot)
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        return

    for cty in dict_gn[thiscity]:

        cityq.put((get_fn(citystr + " , " + cty), citystr + " , " + cty, cty))

    expand(cityq)

def main():

    cityq = Q.PriorityQueue()

    thiscity = start

    cityq.put((get_fn(start), start, thiscity))

    expand(cityq)

    print("The A* path with the total is: ")

    print(result)

main()

```

Prac 4

```

import queue as Q

from RMP import dict_gn

from RMP import dict_hn

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```

start='Arad'

```

```

goal='Bucharest'

```

```

result=""

```

```

def get_fn(citystr):

    cities=citystr.split(',')

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hn=gn=0
for ctr in range(0,len(cities)-1):
    gn=gn+dict_gn[cities[ctr]][cities[ctr+1]]
    #01print("gn",gn)
hn=dict_hn[cities[len(cities)-1]]
return(hn+gn)

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def printout(cityq):
    for i in range(0,cityq.qsize()):
        print(cityq.queue[i])

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def expand(cityq):
    global result
    tot,citystr,thiscity=cityq.get()
    nexttot=999
    if not cityq.empty():
        nexttot,nextcitystr,nextthiscity=cityq.queue[0]
    if thiscity==goal and tot<nexttot:
        result=citystr+'::'+str(tot)
        return
    print("Expanded city-----",thiscity)
    print("Second best f(n)-----",nexttot)
    tempq=Q.PriorityQueue()
    for cty in dict_gn[thiscity]:

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        tempq.put((get_fn(citystr+', '+cty),citystr+', '+cty,cty))
for ctr in range(1,3):
    ctrtot,ctrcitystr,ctrthiscity=tempq.get()
    if ctrtot<nexttot:
        cityq.put((ctrtot,ctrcitystr,ctrthiscity))
    else:
        cityq.put((ctrtot,citystr,thiscity))
        break
printout(cityq)
expand(cityq)
def main():
    cityq=Q.PriorityQueue()
    thiscity=start
    cityq.put((999,"NA","NA"))
    cityq.put((get_fn(start),start,thiscity))
    expand(cityq)
    print(result)
main()

```

Prac 5

```
import numpy as np

import pandas as pd

import sklearn as sk

from sklearn.metrics import confusion_matrix

from sklearn.model_selection import train_test_split

from sklearn.tree import DecisionTreeClassifier

from sklearn.metrics import accuracy_score

from sklearn.metrics import classification_report

#func importing dataset

def importdata():

    balance_data=pd.read_csv("balance-scale.data")

    #print the dataset shape

    print("Dataset Length : ",len(balance_data))

    print("=====check1")

    #printing the dataset observations

    print("Dataset : ",balance_data.head())

    print("=====check2")

    return balance_data

#func to split the dataset

def splitdataset(balance_data):

    #seperating the target variable

    X=balance_data.values[:,1:5]

    Y=balance_data.values[:,0]
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#splitting the dataset into train and test

X_train,X_test,y_train,y_test=train_test_split(X,Y,test_size=0.3,random_state=
100)

    return X,Y,X_train,X_test,y_train,y_test

#function to perform training with entropy

def train_using_entropy(X_train,X_test,y_train,y_test):

    #decision tree with entropy

    clf_entropy=DecisionTreeClassifier(criterion="entropy",random_state=100,max
_depth=3,min_samples_leaf=5)

    #performing training

    clf_entropy.fit(X_train,y_train)

    return clf_entropy

def prediction(X_test,clf_object):

    y_pred=clf_object.predict(X_test)

    print("Predicted Values : ")

    print(y_pred)

    return y_pred

def cal_accuracy(y_test,y_pred):

    print("Accuracy : ",accuracy_score(y_test,y_pred)*100)

def main():

    data=importdata()

    X,Y,X_train,X_test,y_train,y_test=splitdataset(data)

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clf_entropy=train_using_entropy(X_train,X_test,y_train,y_test)
print("Results using entropy : ")
y_pred_entropy=prediction(X_test,clf_entropy)
cal_accuracy(y_test,y_pred_entropy)
main()

```

Prac 6

```

import numpy as np

class NeuralNetwork():

    def __init__(self):
        np.random.seed()
        self.synaptic_weights=2*np.random.random((3,1))-1

    def sigmoid(self, x):
        return 1/(1+np.exp(-x))

    def sigmoid_derivative(self,x):
        return x*(1-x)

    def train(self,training_inputs,training_outputs,training_iterations):
        for iteration in range(training_iterations):
            output=self.think(training_inputs)
            error=training_outputs-output

        adjustments=np.dot(training_inputs.T,error*self.sigmoid_derivative(output))
        self.synaptic_weights+=adjustments

    def think(self,inputs):
        inputs=inputs.astype(float)

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        output=self.sigmoid(np.dot(inputs,self.synaptic_weights))

    return output

if __name__=="__main__":

    neural_network=NeuralNetwork()

    print("Beginning randomly generated weights: ")

    print(neural_network.synaptic_weights)

    training_inputs=np.array([[0,0,1],[1,1,1],[1,0,1],[0,1,1]])

    training_outputs=np.array([[0,1,1,0]]).T

    neural_network.train(training_inputs,training_outputs,15000)

    print("Ending weights after training: ")

    print(neural_network.synaptic_weights)

    user_input_one=str(input("User Input One: "))

    user_input_two=str(input("User Input Two: "))

    user_input_three=str(input("User Input Three: "))

    print("Considering new situation:
",user_input_one,user_input_two,user_input_three)

    print("New output data: ")

    print(neural_network.think(np.array([user_input_one,user_input_two,user_input
_three])))

```

Prac 7

```
import pandas

from sklearn import model_selection

from sklearn.ensemble import AdaBoostClassifier

url = "https://raw.githubusercontent.com/jbrownlee/Datasets/master/pima-indians-diabetes.data.csv"

names = ['preg', 'plas', 'pres', 'skin', 'test', 'mass', 'pedi', 'age', 'class']

dataframe = pandas.read_csv(url, names=names)

array = dataframe.values

X = array[:,0:8]

Y = array[:,8]

seed = 7

num_trees = 30

#kfold makes trees with split number.

#kfold = model_selection.KFold(n_splits=10, random_state=seed)

#n_estimators : This is the number of trees you want to build before predictions.

#Higher number of trees give you better voting options and performance

model = AdaBoostClassifier(n_estimators=num_trees, random_state=seed)

#cross_val_score method is used to calculate the accuracy of model sliced into
x, y

#cross validator cv is optional cv=kfold

results = model_selection.cross_val_score(model, X, Y)

print(results.mean())
```