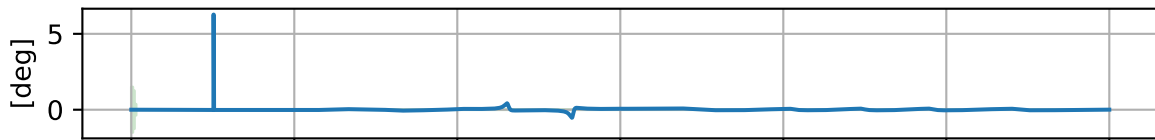
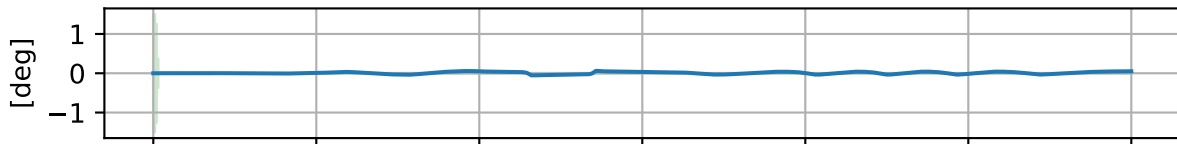


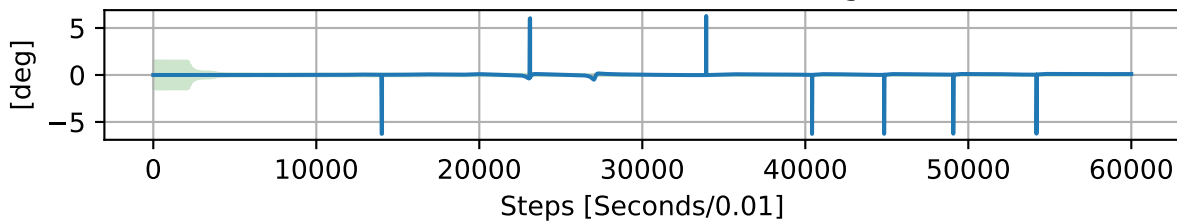
Pitch error (RMSE=0.131deg)



Roll error (RMSE=0.030deg)



Yaw error (RMSE=0.310deg)



— Attitude error      Estimated 3 times std