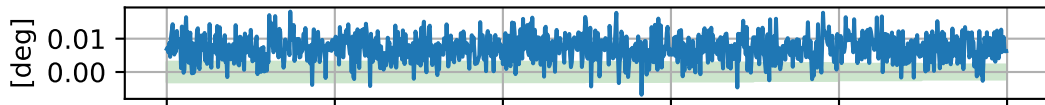


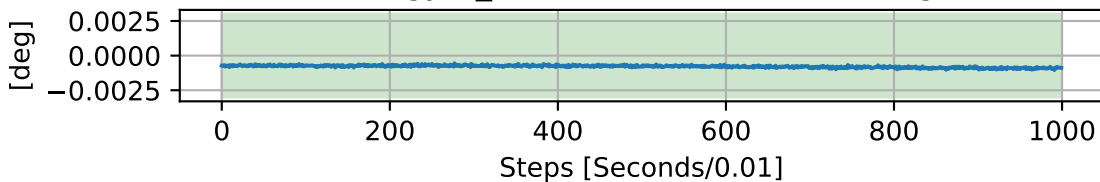
Pitch gyro_bias error (RMSE=0.008deg)



Roll gyro_bias error (RMSE=0.001deg)



Yaw gyro_bias error (RMSE=0.001deg)



Gyro bias error



Estimated 3 times std