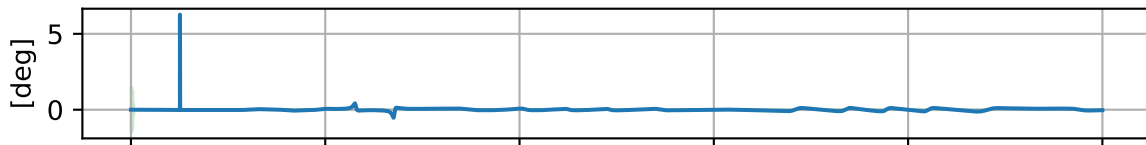
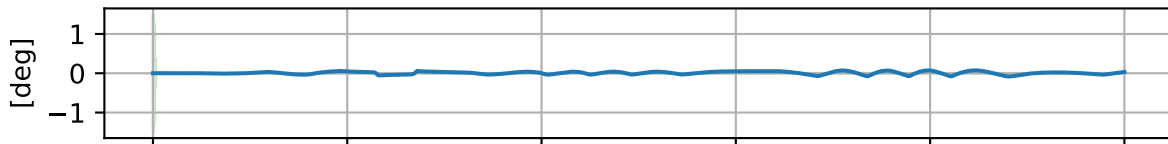


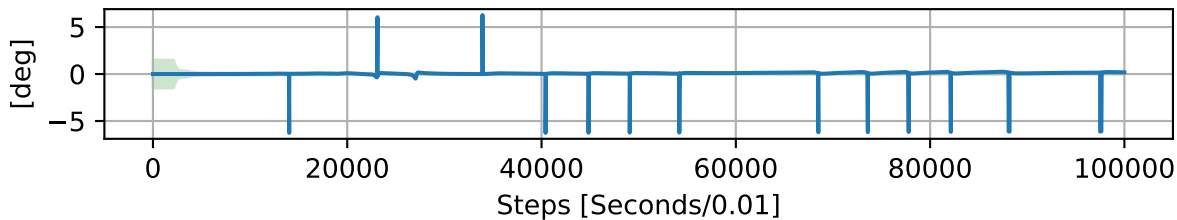
Pitch error (RMSE=0.111deg)



Roll error (RMSE=0.036deg)



Yaw error (RMSE=0.491deg)



— Attitude error



Estimated 3 times std