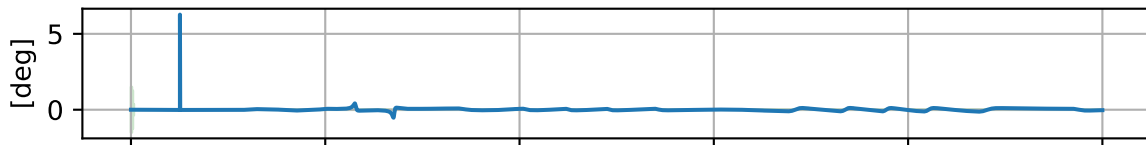
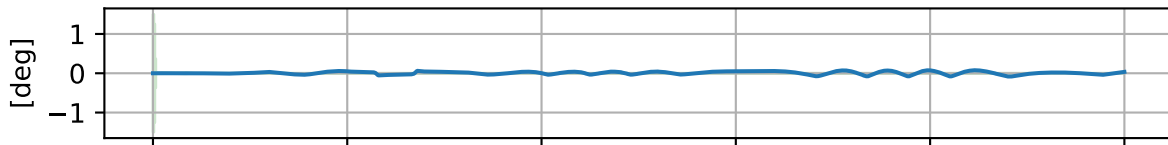


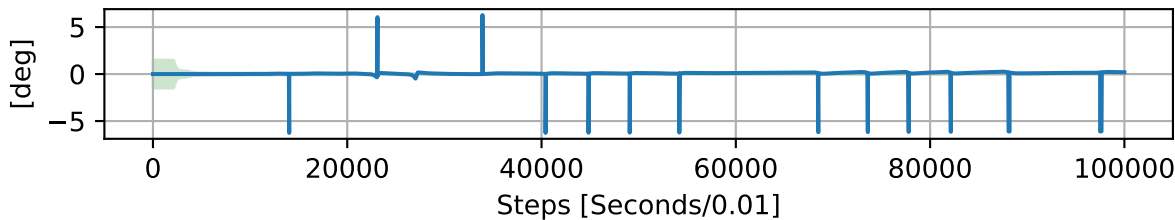
Pitch error (RMSE=0.110deg)



Roll error (RMSE=0.037deg)



Yaw error (RMSE=0.510deg)



— Attitude error      Estimated 3 times std