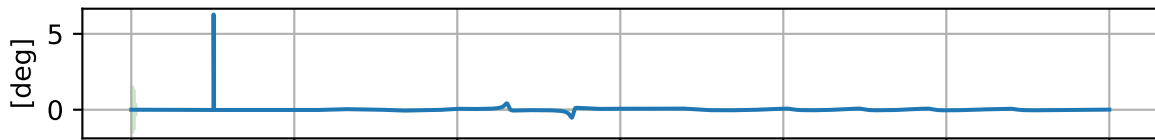
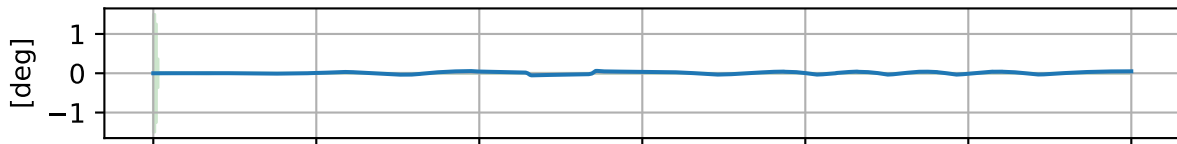


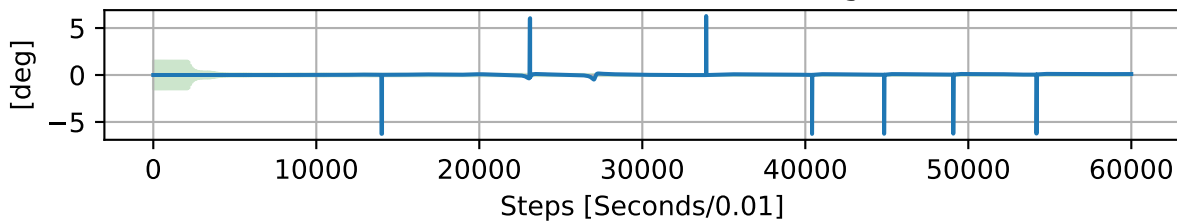
Pitch error (RMSE=0.128deg)



Roll error (RMSE=0.029deg)



Yaw error (RMSE=0.313deg)



— Attitude error    Estimated 3 times std