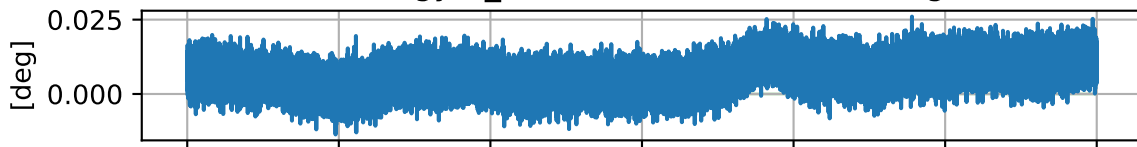
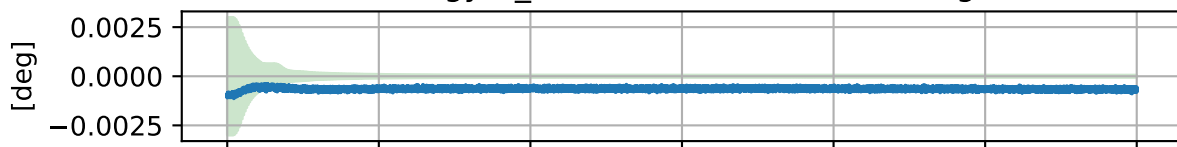


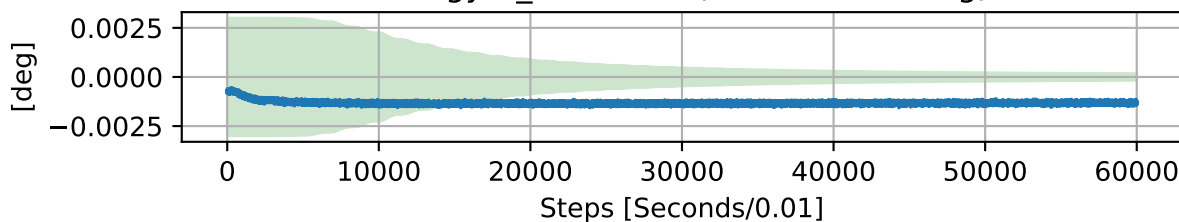
Pitch gyro\_bias error (RMSE=0.008deg)



Roll gyro\_bias error (RMSE=0.001deg)



Yaw gyro\_bias error (RMSE=0.001deg)



— Gyro bias error

Estimated 3 times std