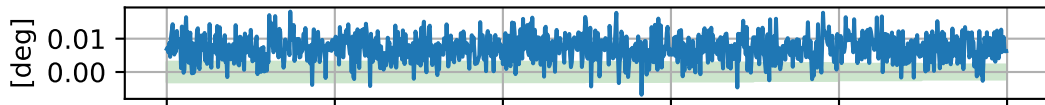


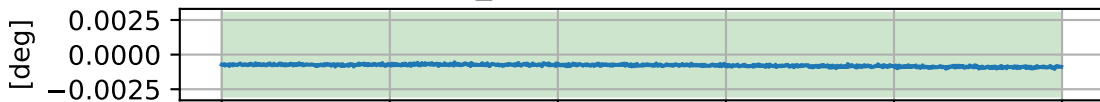
Pitch gyro_bias error (RMSE=0.008deg)



Roll gyro_bias error (RMSE=0.001deg)



Yaw gyro_bias error (RMSE=0.001deg)



0 200 400 600 800 1000

Steps [Seconds/0.01]

— Gyro bias error Estimated 3 times std