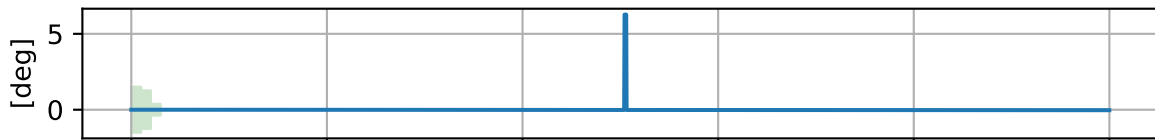
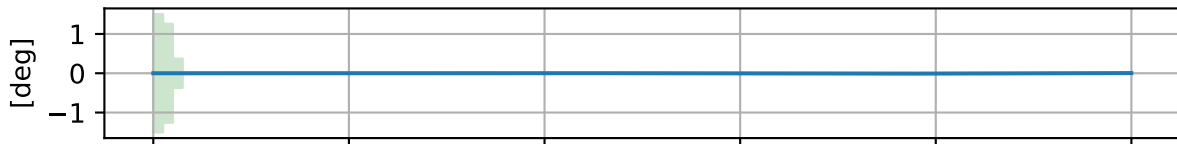


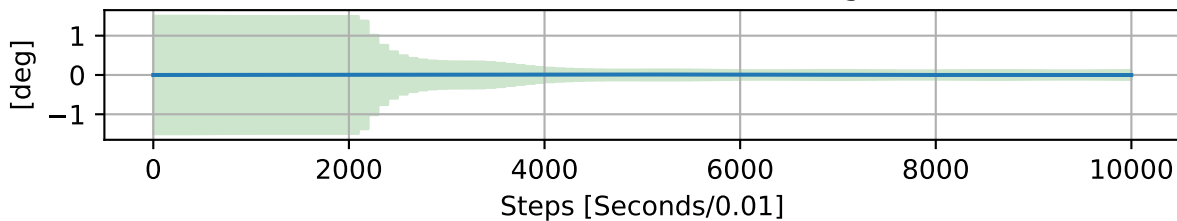
Pitch error (RMSE=0.288deg)



Roll error (RMSE=0.005deg)



Yaw error (RMSE=0.006deg)



— Attitude error    Estimated 3 times std