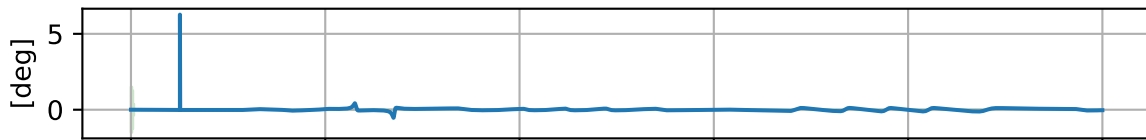
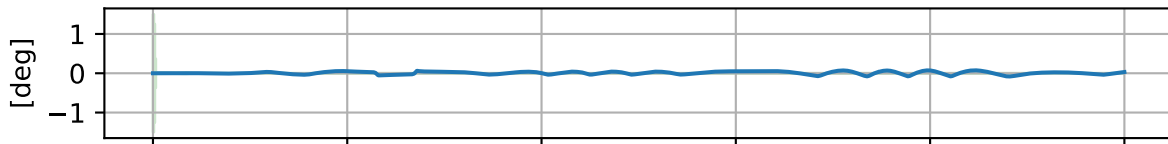


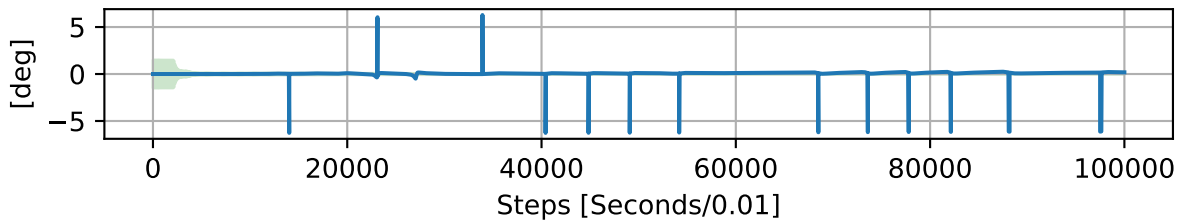
Pitch error (RMSE=0.111deg)



Roll error (RMSE=0.037deg)



Yaw error (RMSE=0.483deg)



— Attitude error



Estimated 3 times std