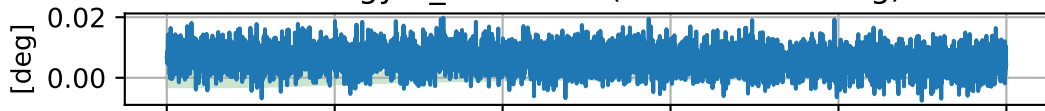
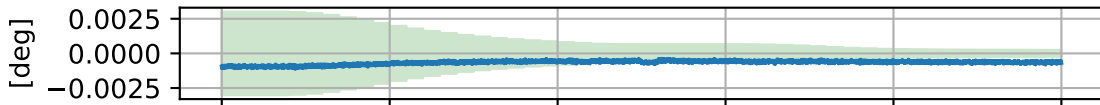


Pitch gyro_bias error (RMSE=0.007deg)



Roll gyro_bias error (RMSE=0.001deg)



Yaw gyro_bias error (RMSE=0.001deg)



— Gyro bias error

Estimated 3 times std