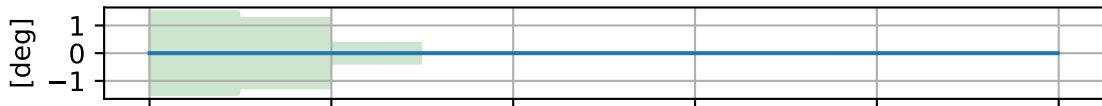
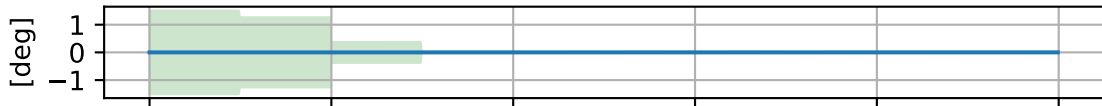


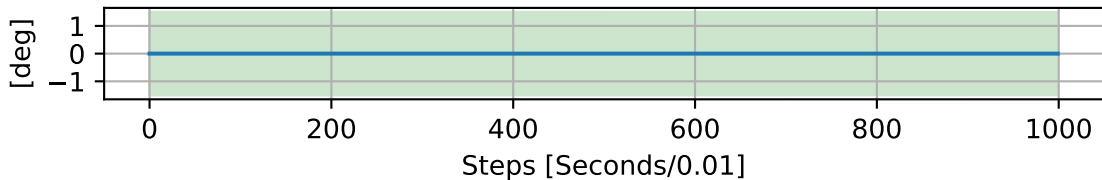
Pitch error (RMSE=0.000deg)



Roll error (RMSE=0.000deg)



Yaw error (RMSE=0.000deg)



— Attitude error      Estimated 3 times std