Homework 2 Graded Student Kevin Vuong View or edit group **Total Points** 24 / 25 pts Question 1 Question #1 6 / 6 pts ✓ - 0 pts Correct - 1 pt #1b incorrect - 0.5 pts #1c partially incorrect **- 6 pts** Click here to replace this description. Question 2 Question #2 4 / 4 pts ✓ - 0 pts Correct - 1 pt #2b incorrect - 1 pt No python code Question 3 Question #3 3.5 / 4 pts - 0 pts Correct ✓ - 0.5 pts #3a incorrect - 1 pt #3d missing **- 4 pts** Click here to replace this description. Question 4 Question #4 1.5 / 2 pts - 0 pts Correct ✓ - 0.5 pts #4b incorrect

- 1 pt No link to python code

## Question 5

Question #5 3 / 3 pts

- ✓ 0 pts Correct
  - 1 pt #5 incorrect
  - **3 pts** Click here to replace this description.

## Question 6

Question #6 6 / 6 pts

- ✓ 0 pts Correct
  - 2 pts #6b incomplete
  - **1 pt** No code for part c
  - 1 pt #6c incorrect
  - **2 pts** #6c incomplete

Questions assigned to the following page: 1, 2, 3, and 4

## Homework 2

Instructions: Solutions must be typed using LATEX. All work and any accompanying Python code should be uploaded to Gradescope by 11:59PM on Friday, February 2, 2024.

1. (6 pts) Consider the system

$$\begin{cases} x - y + 2z &= a \\ 2x + 4y - 3z &= b \\ 4x + 2y + z &= a \end{cases}$$

Find the values of a, b, and c for which the system will have

- (a) no solution
- (b) exactly one solution
- (c) infinitely many solutions

$$\operatorname{let}\,A = \left[\begin{array}{cc|c} x & -y & 2z & a \\ 2x & 4y & -3z & b \\ 4x & 2y & z & c \end{array}\right]$$

if we perform rref(A) (Subtract  $2 \times Row1$  from Row 2,  $4 \times Row1$  from Row 3, and then subtract  $1 \times (\text{New})$  Row 2

from Row 3), we get. 
$$A = \begin{bmatrix} x & -y & 2z & a \\ 0 & 6y & -7z & b-2a \\ 0 & 0 & 0 & c-2a-b \end{bmatrix}$$

- (a) A will have no solution when the bottom row is not all 0's, i.e.  $c \neq 2a + b$
- (b) A cannot have exactly one solution. rank(A) = 2 < 3 = n = m. This implies A must have either no solutions or infinite solutions.
- (c) A will have infinitely many solutions when the bottom row is all 0's i.e. c = 2a + b

2. (4 pts) Let 
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 3 & 6 \\ 2 & 6 & 13 \end{bmatrix}$$
.

- (a) Use Python to find  $A^{-1}$ . Please check this Colab for answers to part a and b
- (b) Use  $A^{-1}$  to solve the linear system  $A\mathbf{x} = \mathbf{b}$  where  $\mathbf{b} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$ .
- 3. (4 pts) Let  $A, B \in \mathbb{R}^{3\times 3}$  with det (A) = 2 and det (B) = 3. Evaluate each of the following:
  - (a)  $\det(-2A^{-1})$
- (b)  $\det(AB^T)$
- (c)  $\det(A^{-1}B^T)$
- (d)  $\det((AB)^{-1})$
- (a). By the rules of Determinant linearity (i.e. multiplying a row/column by a scalar n multiplies the determinant by n) and the fact that the dimension of our matrices is 3x3, we have

$$\det(-2A^{-1}) = (-2)^3 * \frac{1}{\det(A)} = \frac{-8}{6} = -\frac{4}{3}$$

(b).

$$\det(AB^T) = \det(A) * \det(B^T) = \det(A) * \det(B) = 6$$

(c).

$$\det(A^{-1}B^T) = \det(A^{-1}) * \det(B^T) = \frac{1}{\det(A)} * \det(B) = \frac{3}{2}$$

(d).

$$\det((AB)^{-1}) = \det(B^{-1}A^{-1}) = \det(B^{-1}) * \det(A^{-1}) = \frac{1}{\det(B)} * \frac{1}{\det(A)} = \frac{1}{6}$$

4. (2 pts) Use Python to find the determinant of each of the following:

Questions assigned to the following page:  $\underline{4}$ ,  $\underline{5}$ , and  $\underline{6}$ 

(a) 
$$\begin{bmatrix} 6 & 9 \\ 1 & 3 \end{bmatrix}$$
 (b)  $\begin{bmatrix} 2 & 7 & 11 \\ 3 & 4 & 10 \\ 5 & 6 & 16 \end{bmatrix}$ 

Please follow this Here

5. (3 pts) Find all vectors in  $\mathbb{R}^2$  that are orthogonal to  $\mathbf{v} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  with respect to the dot product.

We want to find all vectors in the left nullspace of A  $(N(A^T))$ , i.e. all w such that  $v^Tw = \begin{bmatrix} 1 & 3 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = 0$ Trivially, we see that  $v^Tw = 0$ ,  $\forall w$  such that  $-3w_1 = w_2$ .

$$\implies N(A^T) = \operatorname{span}\{w\} = c \begin{bmatrix} -3 \\ 1 \end{bmatrix}, c \in \mathbb{R}$$

- 6. (6 pts) Let  $\mathbf{v}_1 = \begin{bmatrix} 4 \\ 2 \\ -3 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$ , and  $\mathbf{v}_3 = \begin{bmatrix} 0 \\ -2 \\ 5 \end{bmatrix}$ .
  - (a) Verify that  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is a basis for  $\mathbb{R}^3$ .
  - (b) Use Gram-Schmidt to find an orthonormal basis for  $\mathbb{R}^3$ .
  - (c) Use Python to check that the basis you obtained is orthonormal.
  - (a) we check for linear independence by showing  $\det[\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] \neq 0$  through the big/permutation formula.

$$\det([\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3]) = \det\begin{pmatrix} 4 & 1 & 0 \\ 2 & 0 & -2 \\ -3 & 3 & 5 \end{pmatrix}) = a_{11}b_{22}c_{33} + a_{12}b_{23}c_{31} + a_{13}b_{21}c_{32} - a_{13}b_{22}c_{31} - a_{11}b_{23}c_{32} - a_{12}b_{21}c_{31}$$
$$= 0 + 6 + 0 - 0 - (-24) - 10 = 20$$

Thus,  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  forms a basis for  $\mathbb{R}^3$ 

(b). We will normalize at the end. We set our first orthogonal vector  $u_1 = v_1$ . We then set our next vector

$$u_2 = v_2 - \frac{u_1^T v_2}{||u_1||^2} u_1 = \begin{bmatrix} 1\\0\\3 \end{bmatrix} - \frac{-5}{29} \begin{bmatrix} 4\\2\\-3 \end{bmatrix} = \frac{1}{29} \begin{bmatrix} 49\\10\\72 \end{bmatrix}$$

Finally, we set our third vector

$$u_3 = v_3 - \frac{u_1^T v_3}{||u_1||^2} u_1 - -\frac{u_2^T v_3}{||u_2||^2} u_2 = \begin{bmatrix} 0 \\ -2 \\ 5 \end{bmatrix} - \frac{19}{29} \begin{bmatrix} 4 \\ 2 \\ -3 \end{bmatrix} - \frac{(340/29)}{(265/29)} (\frac{1}{29} \begin{bmatrix} 49 \\ 10 \\ 72 \end{bmatrix}) = \frac{1}{53} \begin{bmatrix} 24 \\ -60 \\ -8 \end{bmatrix}$$

Thus, our orthogonal basis is

$$\left\{ \begin{bmatrix} 4\\2\\-3 \end{bmatrix}, \frac{1}{29} \begin{bmatrix} 49\\10\\72 \end{bmatrix}, \frac{1}{53} \begin{bmatrix} 24\\-60\\-8 \end{bmatrix} \right\}$$

We now create an orthnormalized basis by dividing each vector by its length

$$\left\{ \begin{bmatrix} 4\\2\\-3 \end{bmatrix} / ||u_1||, \frac{1}{29} \begin{bmatrix} 49\\10\\72 \end{bmatrix} / ||u_2||, \frac{1}{53} \begin{bmatrix} 24\\-60\\-8 \end{bmatrix} / ||u_3|| \right\}$$



$$=\{\frac{1}{\sqrt{29}}\begin{bmatrix}4\\2\\-3\end{bmatrix},\frac{1}{\sqrt{265}}\begin{bmatrix}49\\2\\72\end{bmatrix},\frac{1}{53}\begin{bmatrix}24\\-60\\-8\end{bmatrix}/1.74\}$$

Please note that I rounded off the last norm to approximately 1.74, since I couldn't determine a rational-number divisor in NumPy. I display the full solution within the next solution's colab.

(c) Please check this Colab

1

 $<sup>{}^{1}(</sup>Raw\ Link\ in\ case\ links\ don't\ work):\ https://colab.research.google.com/drive/1XpQFOrN7kJzPh20q1wfvm8lsnf4vPWX8?usp=sharing$