Trajectory (first 50) — record26_5Hz_duplo_camera_left trajectory start (0.525, -0.098, 0.201) m end (0.522, -0.112, 0.201) m floor proj (z=0.192 m) 0.208 **∤**0.206 **∤**0.204 10.202 E ├0.200 [№] 0.198 0.196 0.194 -0.098 -0.100-0.1020.516 0.520 0.522 0.524 2 / 0.526 0.530 0.532 -0.104≠ -0.106 (n) -0.108 → -0.110-0.112