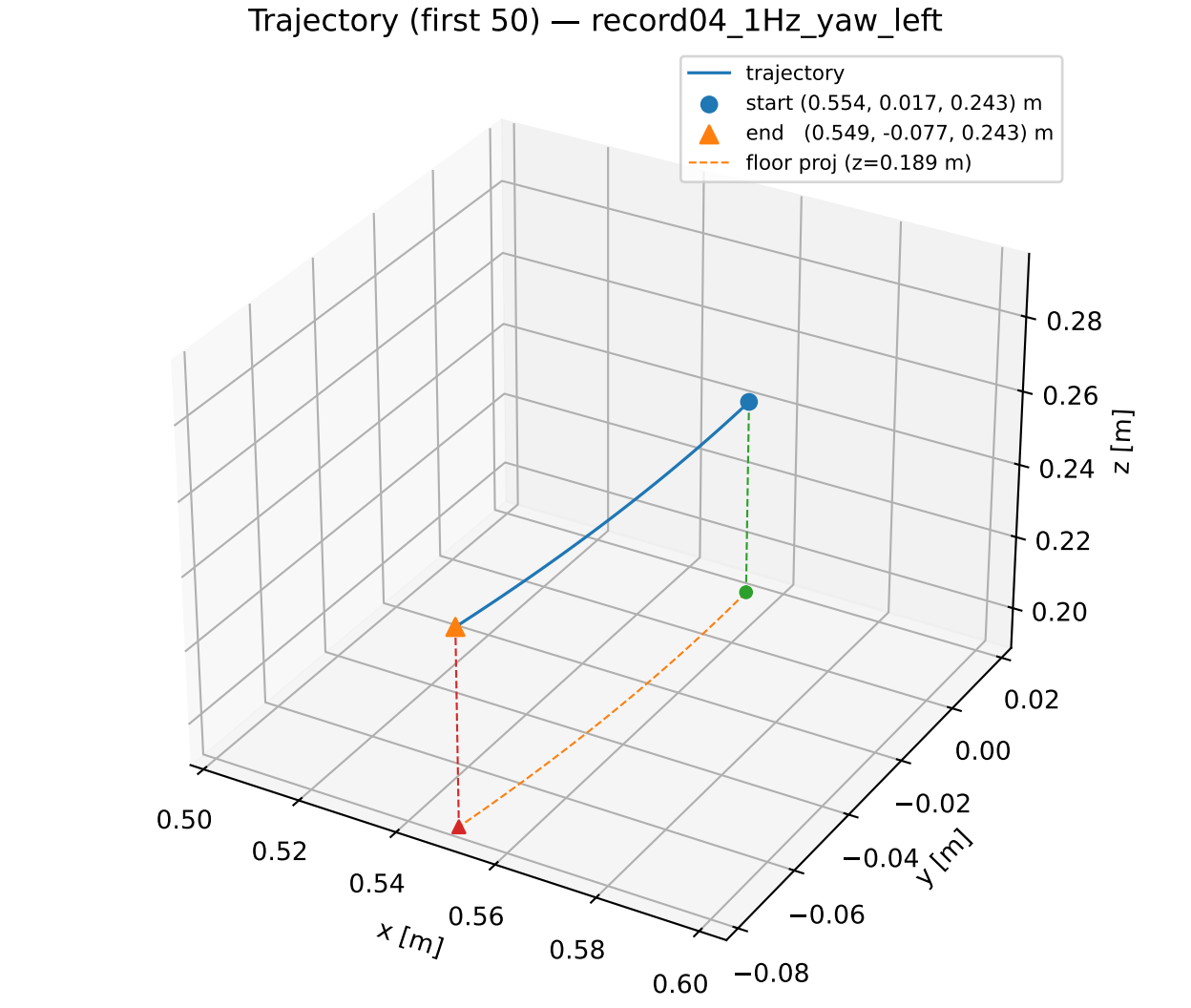
Trajectory (first 50) — record04_1Hz_yaw_left
trajectory
start (0.554, 0.017, 0.243) m
end (0.549, -0.077, 0.243) m
floor proj (z=0.189 m)
x [m]
y [m]
z [m]
0.50
0.52
0.54
0.56
0.58
0.60
0.02
0.00
−0.02
−0.04
−0.06
−0.08
0.28
0.26
0.24
0.22
0.20