Trajectory (first 50) — record27_1Hz_duplo_no_finetuning trajectory start (0.497, -0.138, 0.201) m end (0.152, -0.818, 0.521) m floor proj (z=-0.044 m) 0.7 0.6 0.5 0.4 0.3 0.2 0.1 0.0 -0.1-0.2-0.3 0.0

