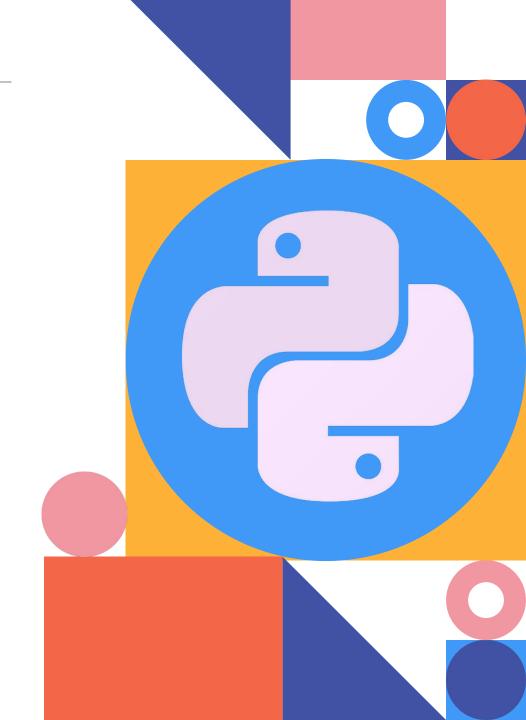
Image Processing I

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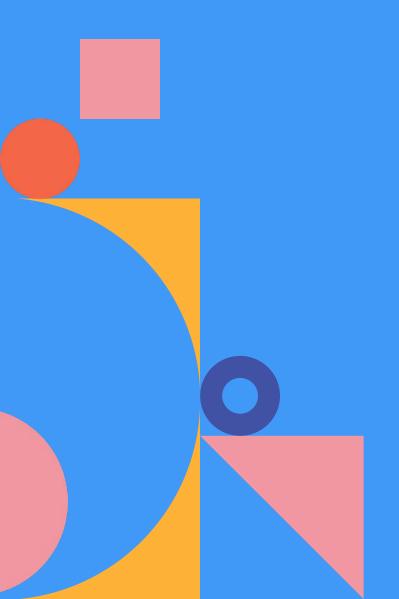
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01 Digital Image

Introduction to *scikit-image*What is Digital Image?

02 Mathematical Tools Used in DIP

Arithmetic Operations Image Transformation



01 Digital Image

Image Processing in Python



Scikit-image

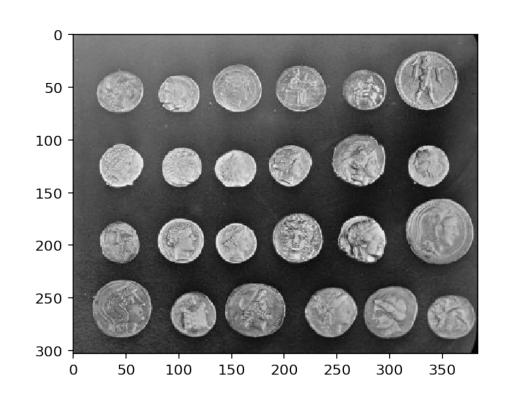
- Simple and efficient tools for image processing and computer vision techniques.
- Built on the top of NumPy, SciPy, and matplotlib.
- Open source, commercially usable BSD license.

\$ pip install scikit-image

Digital Image in skimage

How are images stored in Python with the skimage library?

```
from skimage import data
import matplotlib.pyplot as plt
coins = data.coins()
print('Type: ', type(coins))
print('dtype: ', coins.dtype)
print('shape: ', coins.shape)
plt.imshow(coins, cmap='gray')
plt.show()
```

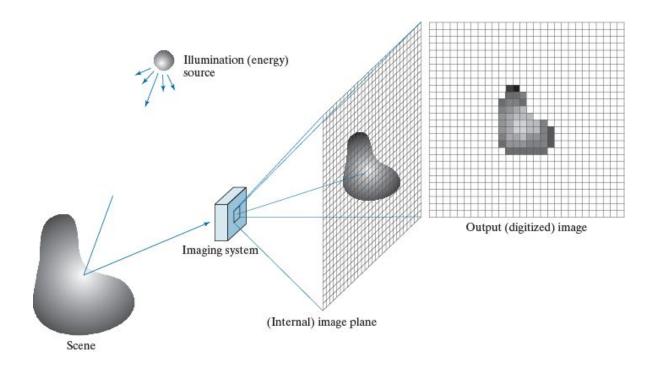


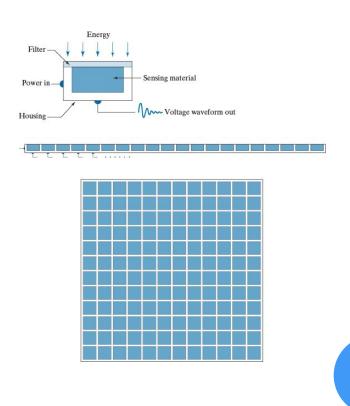
Digital Image



14	15	14	13	14	15	14	12	13	15	15	15	13	11	13	14	14
6	5	4	0	5	1	3	7	1	0	8	0	1	9	3	5	8
14	15	15	12	13	15	16	14	12	13	15	15	13	13	13	12	12
2	3	0	8	1	1	1	6	6	6	5	1	2	2	4	9	1
13 1	14 1	14 2	13 0	12 8	14 8	16 7	15 7	13 4	14 3	16 4	16 3	15 0	13 9	12 6		96
12 2	12 3	12 5	12 7	13 0	13 5	15 2	15 0	14 3	16 5	18 4	17 3	15 6	12 8			82
13 0	12 3		11 8	15 0	15 4	14 5	15 1	17 3	19 1	19 6	17 9	14 5	11 8			78
12 7	12 0	12 5	14 3	15 3	16 1	16 5	17 4	20 3	21 6	21 1	19 2	14 5				10 0
12	12	15	17	16	17	20	21	22	21	20	19	14		12	12	12
1	3	2	8	9	8	1	4	5	2	0	2	6		1	7	0
13	15	18	21	20	20	23	24	22	18	16	17	14	13	14	13	13
2	3	8	4	3	4	7	9	4	1	8	2	0	3	4	9	3
17 5	20 0	22 3	24 2	24 2	23	24	24 3	20 6	16 3	15 4	14 8	12 6	15 3	16 5	15 6	14 8
22	22	23	25	25	24	21	19	17	15	15	13	11	15	16	16	15
	9	8	5	5	6	3	2	3	8	1	2	6	2	6	5	7

Digital Image Acquisition





Types of Digital Image



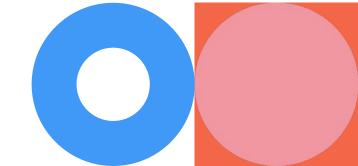
Binary



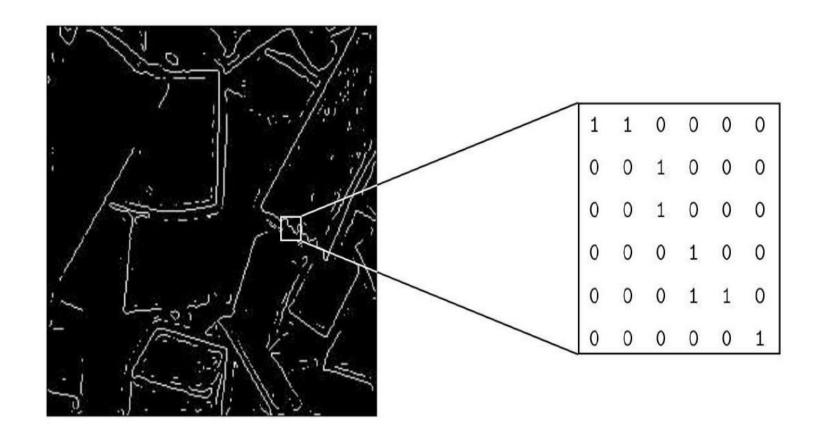
Grayscale



RGB



Binary Image



Grayscale Image



230	229	232	234	235	232	148
237	236	236	234	233	234	152
255	255	255	251	230	236	161
99	90	67	37	94	247	130
222	152	255	129	129	246	132
154	199	255	150	189	241	147
216	132	162	163	170	239	122

RGB (Color) Image



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66 80 77 80 87 77 81 93 96 99 86 85 83 83 91 94 92 88 135 128 126 112 107 106 141 129 129 117 115 101 95 99 109 108 112 109 84 93 107 101 105 102



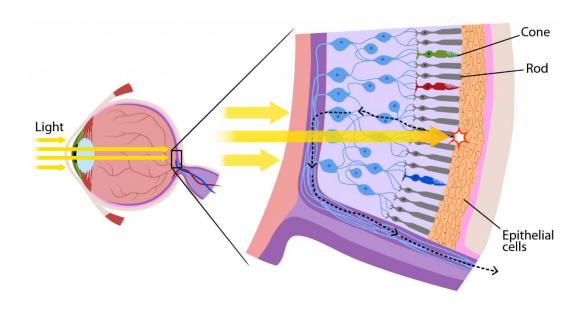
Quiz

Which one is G, which one is B, and which one is R?



Quiz

RGB is an acronym for "Red Green Blue," and it refers how colors are composed. But why red, green, and blue?



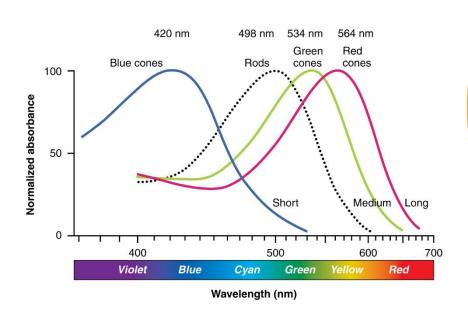
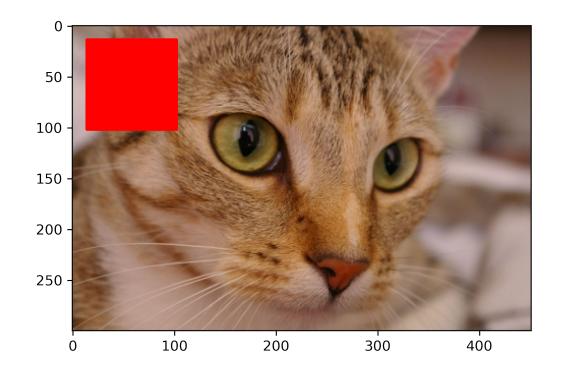


Image Processing

```
cat[10:110, 10:110, :] = [255, 0, 0]
```



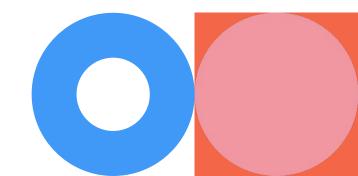


Image I/O

Reading an image

```
from skimage import io

deer = io.imread('deer.jpg')
gray_deer = io.imread('deer.jpg', as_gray=True)
```

Writing an image

```
io.imsave('deer1.jpg', deer)
io.imsave('deer2.png', gray_deer)
```

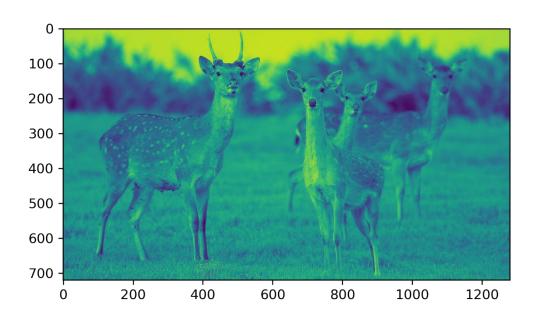
imsave() function automatically determines the type of the file, based on the file extension we provide.



Displaying Images

```
import matplotlib.pyplot as plt
plt.imshow(deer)
plt.show()
plt.imshow(gray_deer)
plt.show()
```

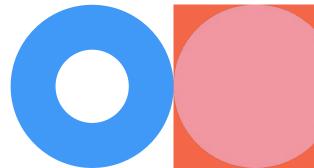
```
plt.imshow(gray_deer, cmap='gray')
plt.show()
```



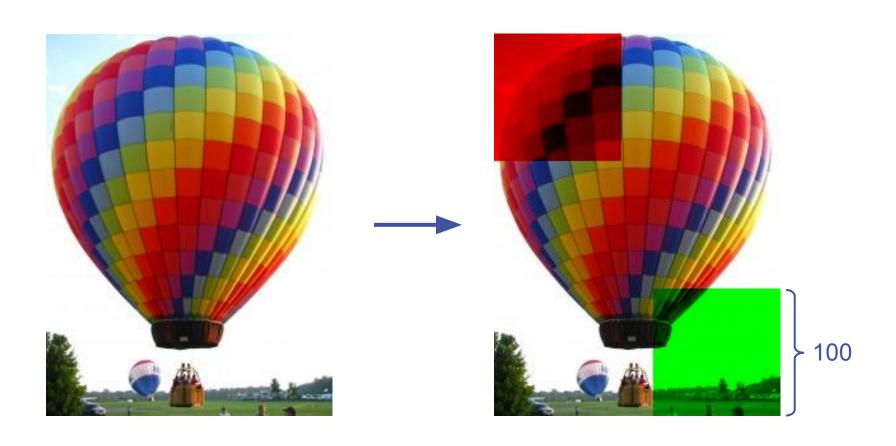
Exercise 1 (5 mins)







Exercise 2 (5 mins)





Exercise – 3 GRB to Grayscale (5 mins)

The relative luminance of an image is the intensity of light coming from each point. Different colors contribute differently to the luminance: it's very hard to have a bright, pure blue, for example. So, starting from an RGB image, the luminance is given by:

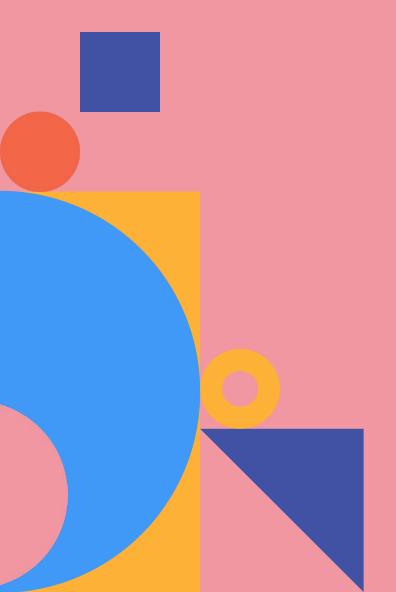
$$Y = 0.2126R + 0.7152G + 0.0722B$$

$$2 Y = \frac{1}{3}R + \frac{1}{3}G + \frac{1}{3}B$$

Compare your results to that obtained with skimage.color.rgb2gray. 3

Change the coefficients to 1/3 (i.e., take the mean of the red, green, and blue channels, to see how that approach compares with rgb2gray).





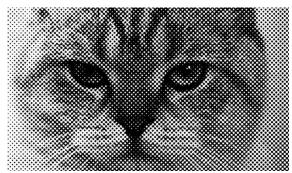
02 Mathematical Tools

Image Processing

Any form of signal processing for which the input is an image

Halftone





Deblur







Image Arithmetic

Name	Operator	Equivalent func.		
Addition	+	np.add		
Subtraction	-	np.subtrat		
Multiplication	*	np.multiply		
Division	/	np.divide		
Modulus	%	np.mod		
Exponentiation	**	np.power		
Floor Division	//	np.floor_divide		



Image Addition

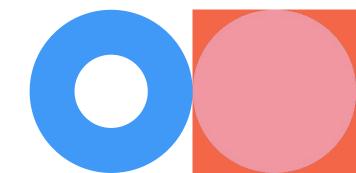
```
camera = data.camera()
cmaera50 = camera + 10
```





Changing the pixels values adjust the brightness of the image.

Any problem with "image+10"? Try "image+50".



Integers can overflow

Integer data types are 8-, 16- or 32-bytes, signed or unsigned.

The value of an integer overflow if it is added or multiplied with a large number.

Strategy: convert integer to float.

```
from skimage import img_as_float
camera_float = img_as_float(camera)
print(camera.max(), camera_float.max())
```



Image Multiplication

```
camera_float_15 = camera_float*1.5
plt.imshow(camera)
plt.imshow(camera_float_15)
plt.imshow(camera_float_15, vmax=1)
```









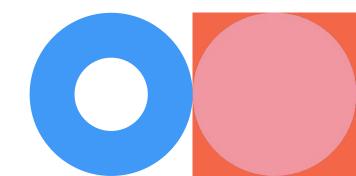


Image Addition





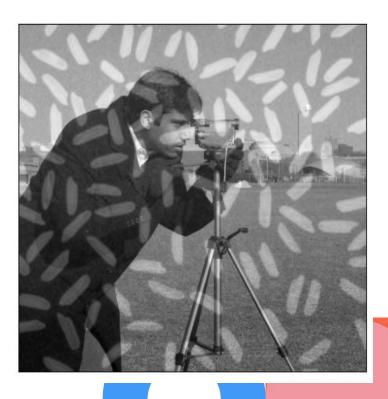


Image Subtraction

Detecting changes between two images, or levelling uneven sections of an image such as half an image having a shadow on it.







Geometric Transformation

Moving the coordinates (not the gray-levels) of the pixels in an image.







Image Rotation

```
from skimage import transform, data

camera = data.camera()

rotate_camera = transform.rotate(camera, 30, resize=False, order=1)

rotate_camera = transform.rotate(camera, 30, resize=False, order=1)

rotate_camera_resize = transform.rotate(camera, 30, resize=True, order=1)
```

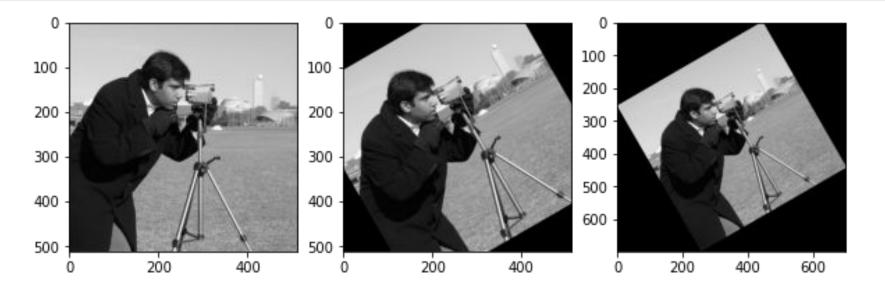
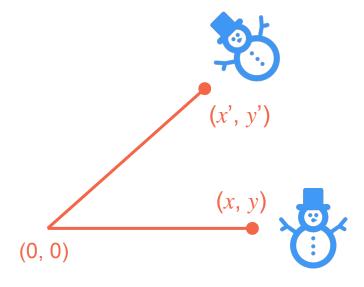




Image Rotation

In two dimensions, rotation of a point (x, y) for an angle θ "counter-clockwise" can be written as:

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$



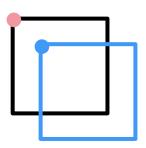


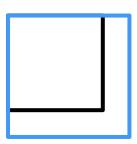
Affine Transformation Matrices

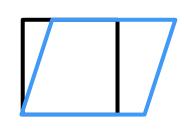
Translation

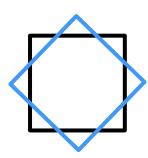












$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \begin{bmatrix} S_x & 0 & 0 \\ 0 & S_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & h_x & 0 \\ h_y & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} S_{x} & 0 & 0 \\ 0 & S_{y} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$egin{bmatrix} 1 & h_{\chi} & 0 \ h_{y} & 1 & 0 \ 0 & 0 & 1 \end{bmatrix}$$

$$egin{bmatrix} cos heta & sin heta & 0 \ -sin heta & cos heta & 0 \ 0 & 0 & 1 \end{bmatrix}$$

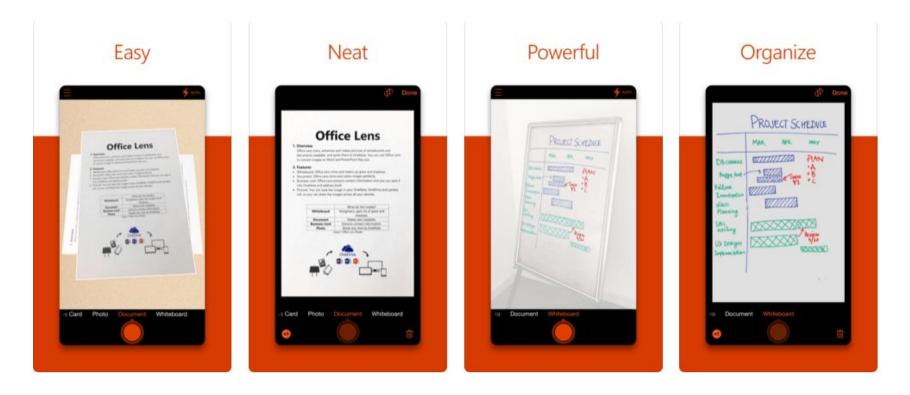
transform.AffineTransform()

$$\begin{bmatrix} 1 & 2 & -400 \\ -1.732 & 3.464 & 200 \\ 0 & 0 & 1 \end{bmatrix}$$

tf_camera = transform.warp(camera, tform)



Projective Transformation



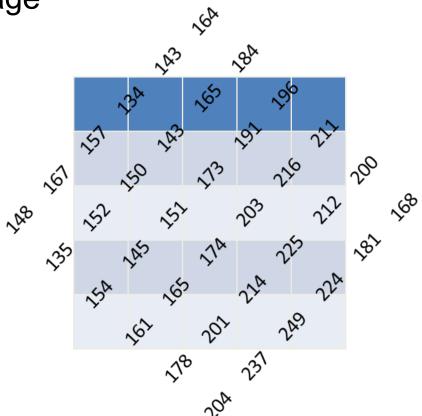
Try transform.ProjectiveTransform()



Exercise | Rotation

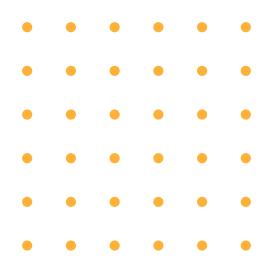
Implement a function to rotate an image

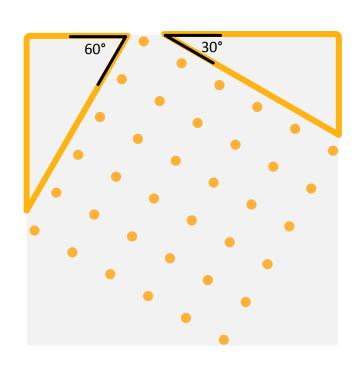
14	16	15	13	14	16
8	7	7	4	3	4
13	15	15	14	16	18
5	2	0	3	5	4
15	14	15	17	19	19
4	5	1	3	1	6
16	16	17	20	21	21
1	5	4	3	6	1
17	20	21	22	21	20
8	1	4	5	2	0
20	23	24	22	18	16
4	7	9	4	1	8





Solution | step1

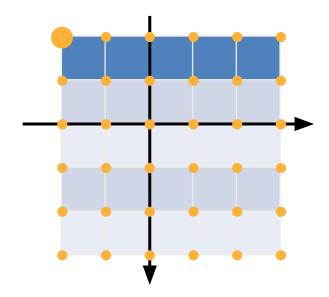


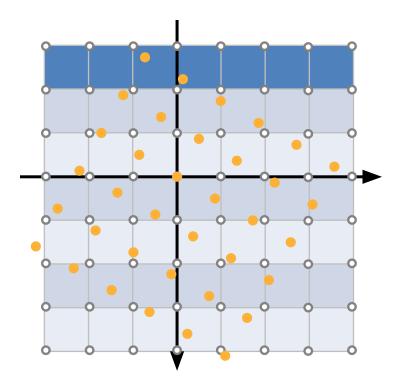


Solution | step2

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} -0.732 \\ -2.732 \end{bmatrix} = \begin{bmatrix} cos \frac{30}{sin \frac{30}{30}} & -sin \frac{30}{cos \frac{30}{30}} \end{bmatrix} \begin{bmatrix} -2 \\ -2 \end{bmatrix}$$





Solution | step2

$$\begin{bmatrix} cos\theta & -sin\theta \\ sin\theta & cos\theta \end{bmatrix}^{-1} \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

