

Branch-and-Bound Algorithm

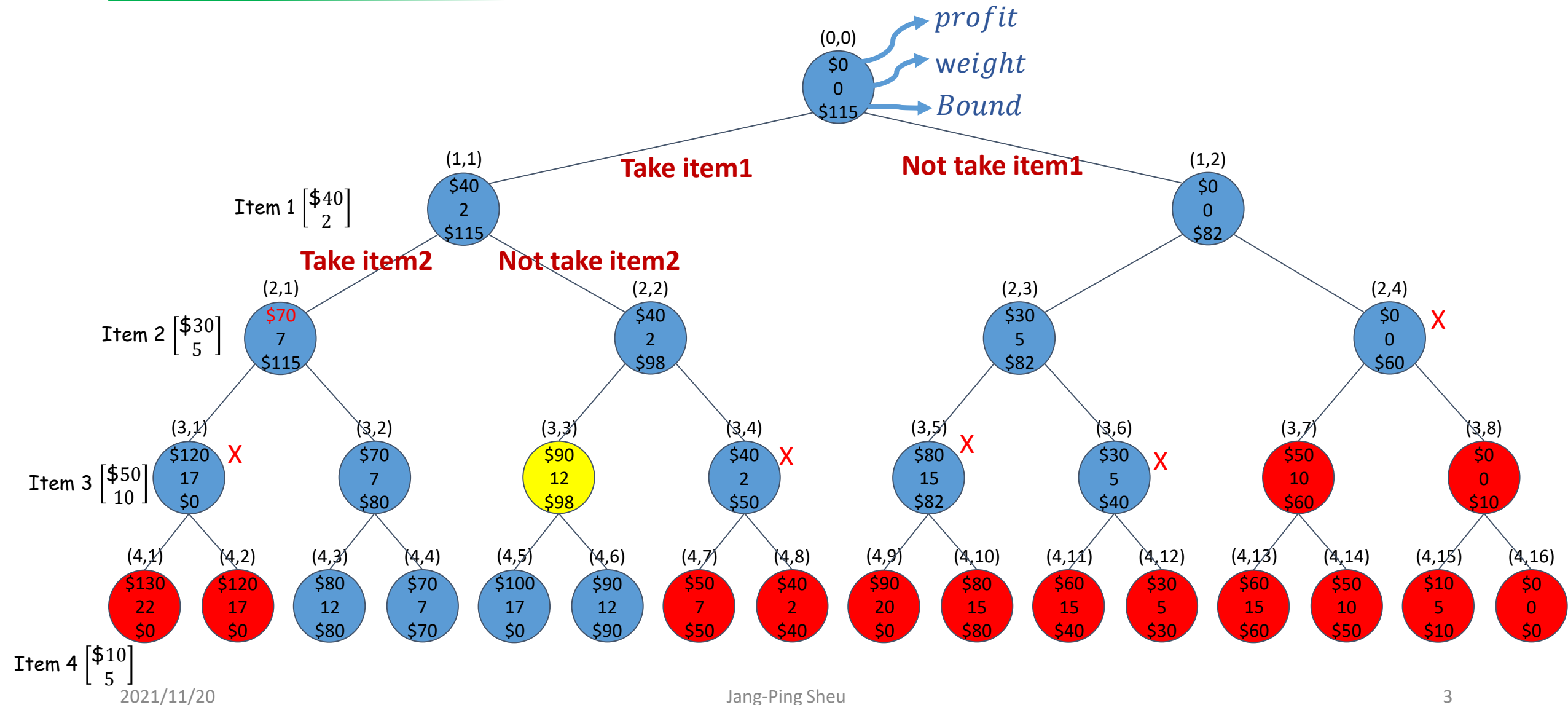
0-1 knapsack problem

- Given a set of items, each with a **weight** and a **value**, determine the number of each item to include in a collection so that the **total weight is less than or equal to a given limit** and the **total value is as large as possible**.
- Example : $n=4$, $W=16$

i : item
 p_i : profit
 w_i : weight

i	p_i	w_i	$\frac{p_i}{w_i}$
1	\$40	2	\$20
2	\$30	5	\$6
3	\$50	10	\$5
4	\$10	5	\$2

Breadth-First Search (take or not take)



Calculation of Bound

If the node is at level i , and the node at level k is the one whose weight would bring the weight above W , then

- $totweight = weight + \sum_{j=i+1}^{k-1} w_j$
- $Bound = (profit + \sum_{j=i+1}^{k-1} p_j) + (W - totweight) * \frac{p_k}{w_k}$

Breadth-First Search with Branch-and-Bound Pruning

Calculate the upperbound

- (0, 0)

$$\text{totweight} = 2 + 5 = 7$$

$$\text{bound} = (40 + 30) + (16 - 7) * (50/5) :$$

- (1, 1) ---take item 1

$$\text{totweight} = 2 + 5 = 7$$

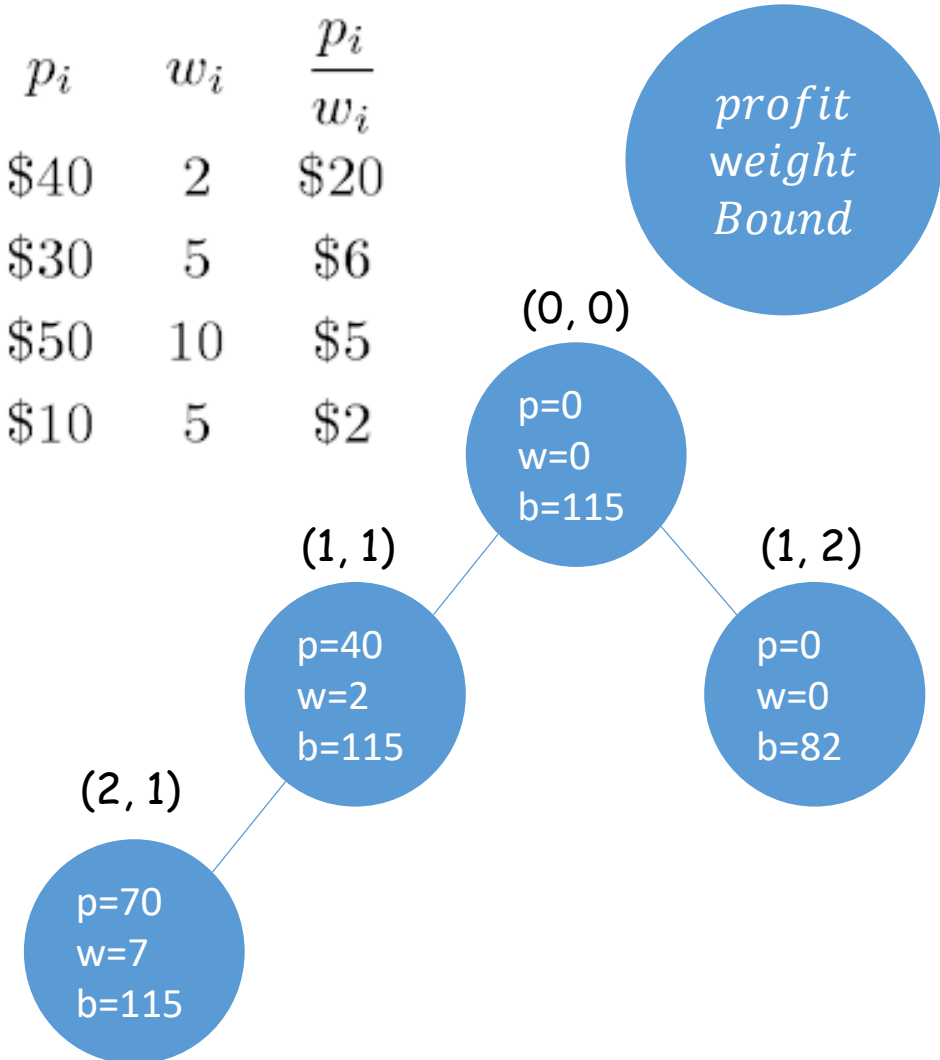
$$\text{bound} = (40 + 30) + (16 - 7) * (50/5) = 115$$

- (1, 2) ---don't take item 1

$$\text{totweight} = 5 + 10 = 15$$

$$\text{bound} = (30 + 50) + (16 - 15) * (10/5) = 82$$

i	p_i	w_i	$\frac{p_i}{w_i}$
1	\$40	2	\$20
2	\$30	5	\$6
3	\$50	10	\$5
4	\$10	5	\$2

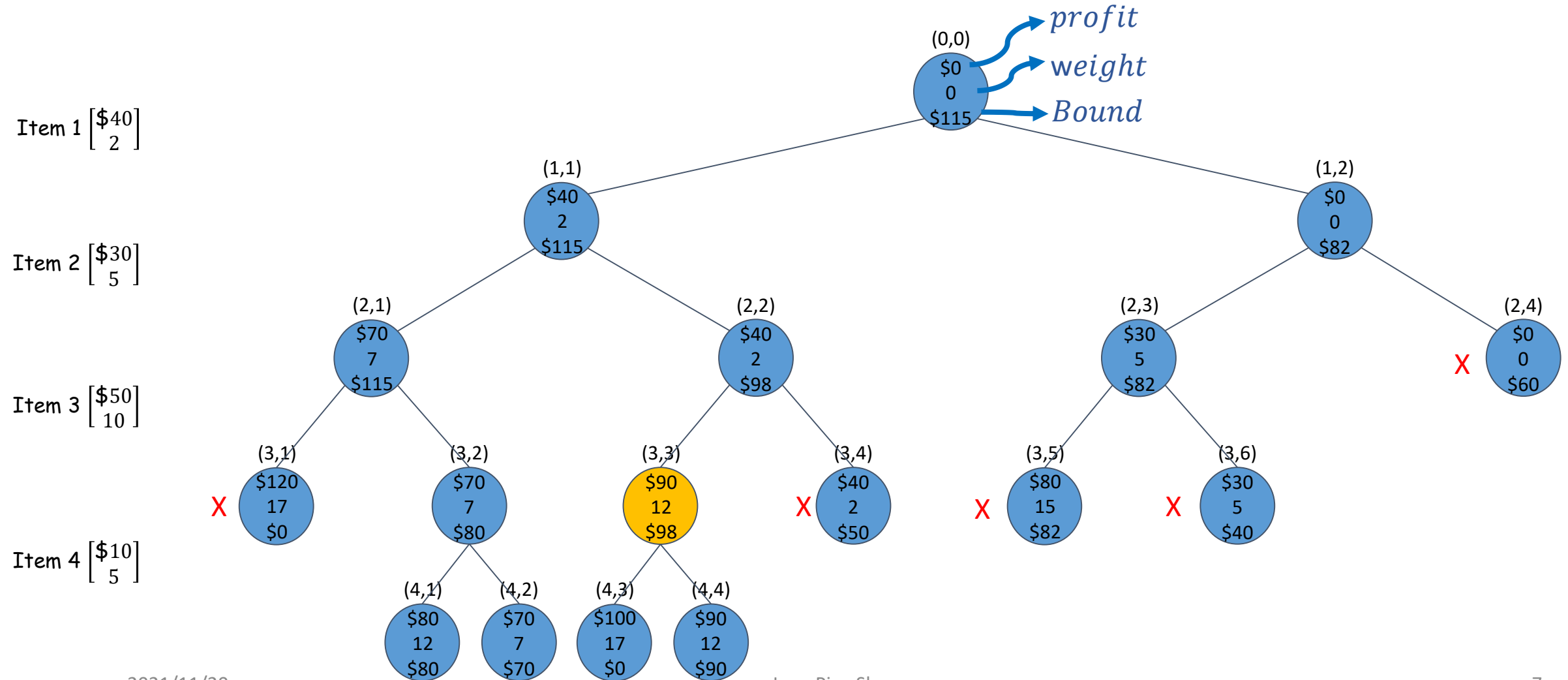


Non-promising

- A node is non-promising if this bound is **less than or equal to** *maxprofit*, which is the value of the best solution found up to that point.
- Recall that a node is also non-promising if

$$weight \geq W$$

Breadth-First Search with Branch-and-Bound



General algorithm

```
void breadth_first_branch_and_bound (state_space_tree T,
                                     number& best)
{
    queue_of_node Q;
    node u, v;

    initialize(Q);                                // Initialize Q to be empty.
    v = root of T;                                // Visit root.
    enqueue(Q, v);
    best = value(v);
    while (! empty(Q)){
        dequeue(Q, v);
        for (each child u of v){                  // Visit each child.
            if (value(u) is better than best)
                best = value(u);
            if (bound(u) is better than best)
                enqueue(Q, u);
        }
    }
}
```


The **Breadth-First Search** with Branch-and-Bound Pruning Algorithm for the 0-1 Knapsack problem

Problem: Let n items be given, where each item has a weight and a profit. The weights and profits are positive integers. Furthermore, let a positive integer W be given. Determine a set of items with maximum total profits, under the constraint that the sum of their weights cannot exceed W .

Inputs: positive integers n and W , arrays of positive integers w and p , each indexed from 1 to n , and each of which is sorted in nonincreasing order according to the values of $p[i]/w[i]$

Outputs: an integer *maxprofit* that is the sum of the profits in an optimal set

```
struct node
{
    int level;           // the node's level in the tree
    int profit;
    int weight;
};
```

A specific algorithm for the 0-1 knapsack problem(1/2)

```
void knapsack2 (int n,
               const int p[], const int w[],
               int W,
               int& maxprofit)
{
    queue_of_node Q;
    node u, v;

    initialize(Q); // Initialize Q to be empty.
    v.level = 0; v.profit = 0; v.weight = 0; // Initialize v to be the root.

    maxprofit = 0;
    enqueue(Q, v);
    while (! empty(Q)){
        dequeue(Q, v);
        u.level = v.level + 1; // Set u to a child of v.
        u.weight = v.weight + w[u.level]; // Set u to the child
        u.profit = v.profit + p[u.level]; // that includes the
        // next item.

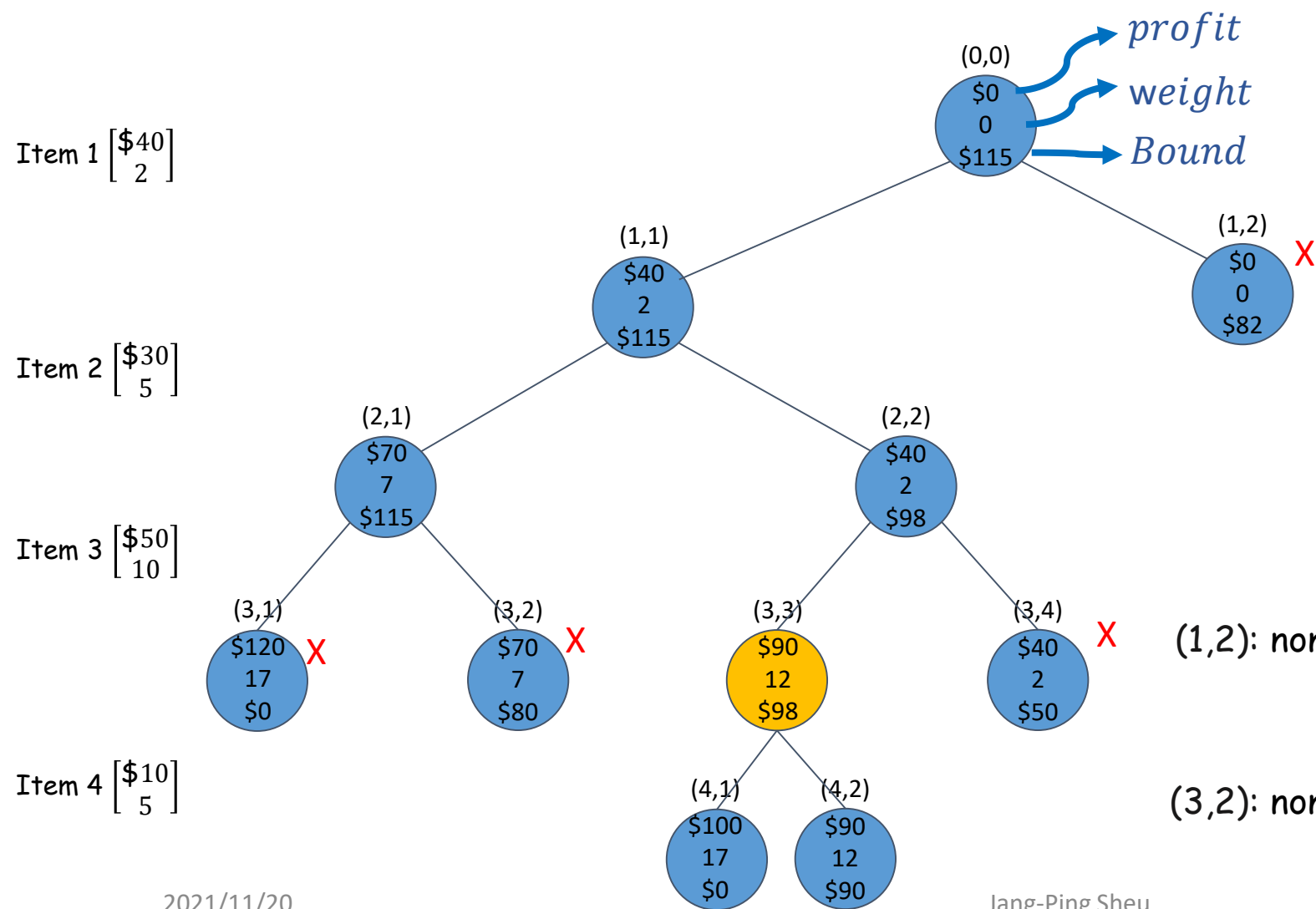
        if (u.weight <= W && u.profit > maxprofit)
            maxprofit = u.profit;
        if (bound(u) > maxprofit)
            enqueue(Q, u);

        u.weight = v.weight; // Set u to the child that
        u.profit = v.profit; // does not include the
        if (bound(u) > maxprofit) // next item.
            enqueue(Q, u);
    }
}
```

A specific algorithm for the 0-1 knapsack problem(2/2)

```
float bound (node u)
{
    index j, k;
    int totweight;
    float result;
    if (u.weight >= W)
        return 0;
    else{
        result = u.profit;
        j = u.level + 1;
        totweight = u.weight;
        while (j <= n && totweight + w[j] <= W){
            totweight = totweight + w[j];           // Grab as many items
            result = result + p[j];                 // as possible.
            j++;
        }
        k = j;                                       // Use k for consistency
        if (k <= n)                                  // with formula in text.
            result = result + (W - totweight) * p[k]/w[k];
                                                    // Grab fraction of kth
                                                    // item.
    }
    return result;
}
```

Best-First Search with Branch-and-Bound



(0,0)

(0,0)		
115		

(1,1)

(1,1)	(1,2)	
115	82	

(2,1)

(2,1)	(2,2)	(1,2)
115	98	82

(2,2)

(2,2)	(1,2)	(3,2)
98	82	80

(3,1):non

(3,3)

(3,3)	(1,2)	(3,2)
98	82	80

(3,4):non

(1,2): non-promising

(1,2)	(3,2)	
82	80	

(4,1):non
(4,2):non

(3,2): non-promising

(3,2)		
80		

12

General algorithm

```
void best_first_branch_and_bound (state_space_tree T,
                                  number& best)
{
    priority_queue_of_node PQ;
    node u, v;

    initialize(PQ);                // Initialize PQ to be empty.
    v = root of T;
    best = value(v);
    insert(PQ, v);
    while (!empty(PQ)){            // Remove node with best
        remove(PQ, v);             // bound.
        if (bound(v) is better than best) // Check if node is still
            for (each child u of v){ // promising.
                if (value(u) is better than best)
                    (best = value(u);
                if (bound(u) is better than best)
                    insert(PQ, u);
            }
    }
```

The **Best-First Search** with Branch-and-Bound Pruning Algorithm for the 0-1 Knapsack problem

```
--  
struct node  
{  
    int level;           // the node's level in the tree  
    int profit;  
    int weight;  
    float bound;  
};  
  
void knapsack3 (int n,  
               const int p[], const int w[],  
               int W,  
               int& maxprofit)  
{  
    priority_queue_of_node PQ;  
    node u, v;  
  
    initialize(PQ);                               // Initialize PQ to be  
    v.level = 0; v.profit = 0; v.weight = 0;       // empty.  
    maxprofit = 0;                                // Initialize v to be the  
    v.bound = bound(v);                            // root.  
    insert(PQ, v);  
}
```

```

while (!empty(PQ)){                                // Remove node with
    remove(PQ, v);                                // best bound.
    if (v.bound > maxprofit){                      // Check if node is still
        u.level = v.level + 1;                   // promising.
        u.weight = v.weight + w[u.level];        // Set u to the child
        u.profit = v.profit + p[u.level];        // that includes the
                                                    // next item.
        if (u.weight <= W && u.profit > maxprofit)
            maxprofit = u.profit;
        u.bound = bound(u);
        if (u.bound > maxprofit)
            insert(PQ, u);
        u.weight = v.weight;                      // Set u to the child
        u.profit = v.profit;                      // that does not include
        u.bound = bound(u);                      // the next item.
        if (u.bound > maxprofit)
            insert(PQ, u);
    }
}

```

```

float bound (node u)
{
    index j, k;
    int totweight;
    float result;
    if (u.weight >= W)
        return 0;
    else{
        result = u.profit;
        j = u.level + 1;
        totweight = u.weight;
        while (j <= n && totweight + w[j] <= W){
            totweight = totweight + w[j];           // Grab as many items
            result = result + p[j];                 // as possible.
            j++;
        }
        k = j;                                       // Use k for consistency
        if (k <= n)                                  // with formula in text.
            result = result + (W - totweight) * p[k]/w[k];
                                                    // Grab fraction of kth
                                                    // item.
        return result;
    }
}

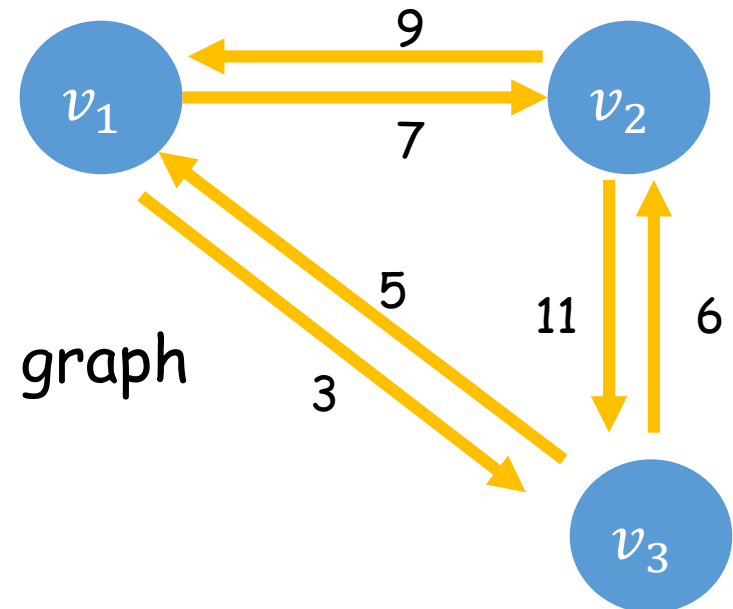
```


The Travelling Salesman Problem (TSP)

- The **TSP** asks the following question: "Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city and returns to the origin city?"
- An adjacency matrix representation of a graph

	v1	v2	v3
v1	0	7	3
v2	9	0	11
v3	5	6	0

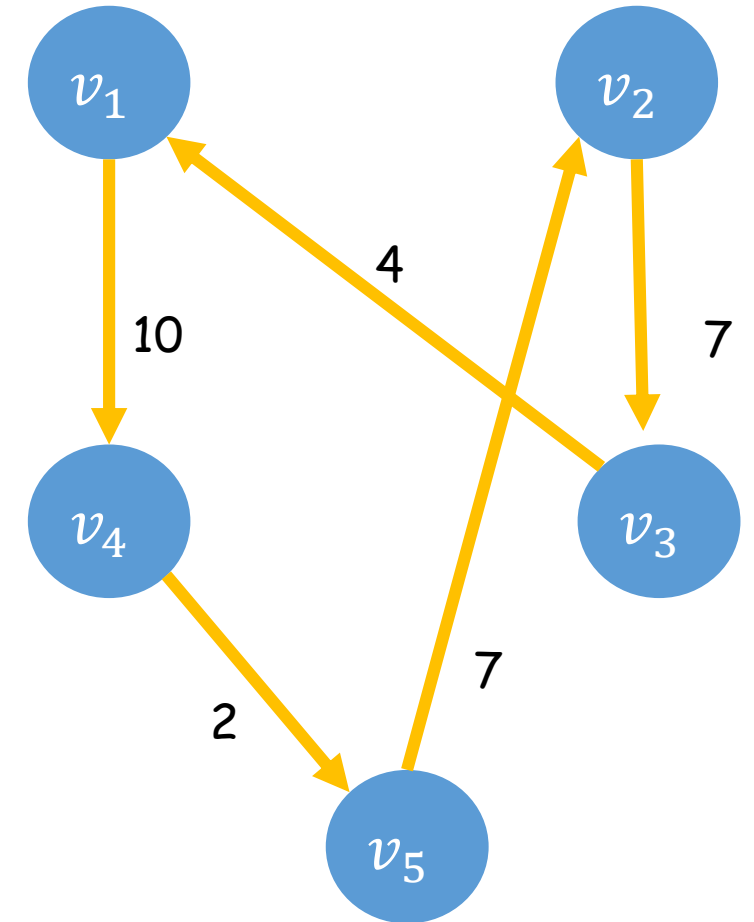
- A weighted directed graph



Example:

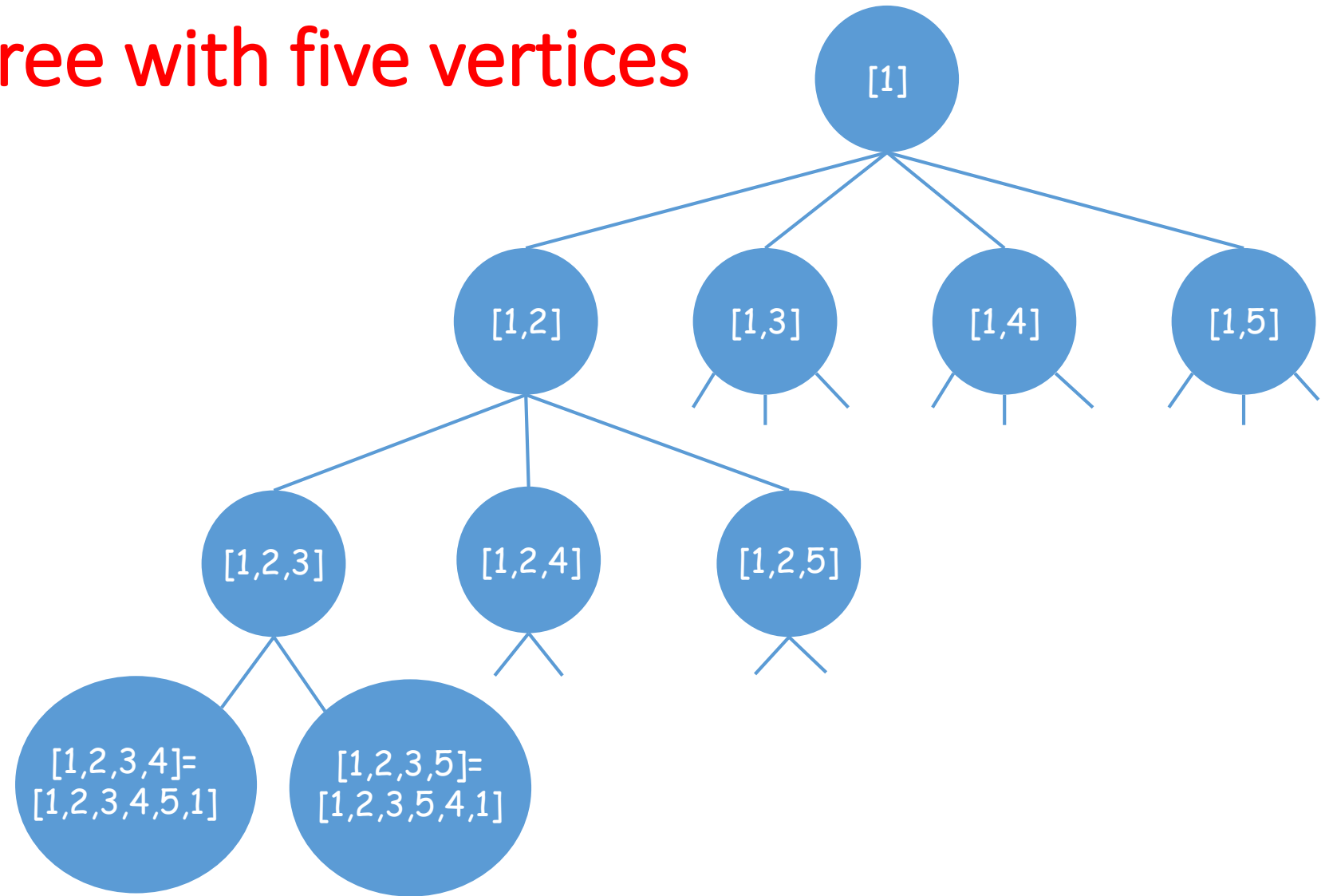
$$\begin{bmatrix} 0 & 14 & 4 & 10 & 20 \\ 14 & 0 & 7 & 8 & 7 \\ 4 & 5 & 0 & 7 & 16 \\ 11 & 7 & 9 & 0 & 2 \\ 18 & 7 & 17 & 4 & 0 \end{bmatrix}$$

- An adjacency matrix representation of a graph



- An optimal tour:
[1, 4, 5, 2, 3, 1]

A state space tree with five vertices



Computed the lower bound [1]:

$$v_1 \quad \text{minimum}(14, 4, 10, 20) = 4$$

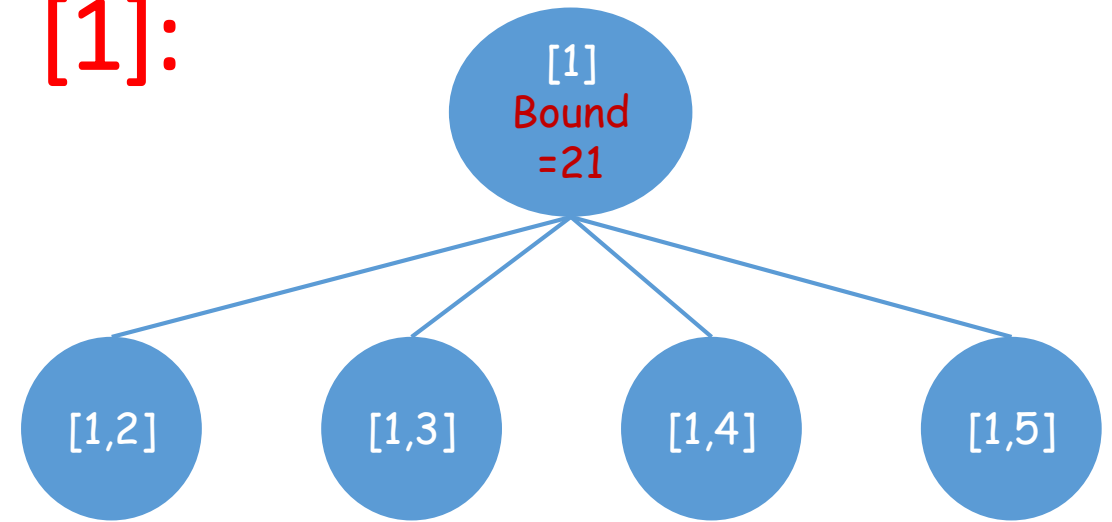
$$v_2 \quad \text{minimum}(14, 7, 8, 7) = 7$$

$$v_3 \quad \text{minimum}(4, 5, 7, 16) = 4$$

$$v_4 \quad \text{minimum}(11, 7, 9, 2) = 2$$

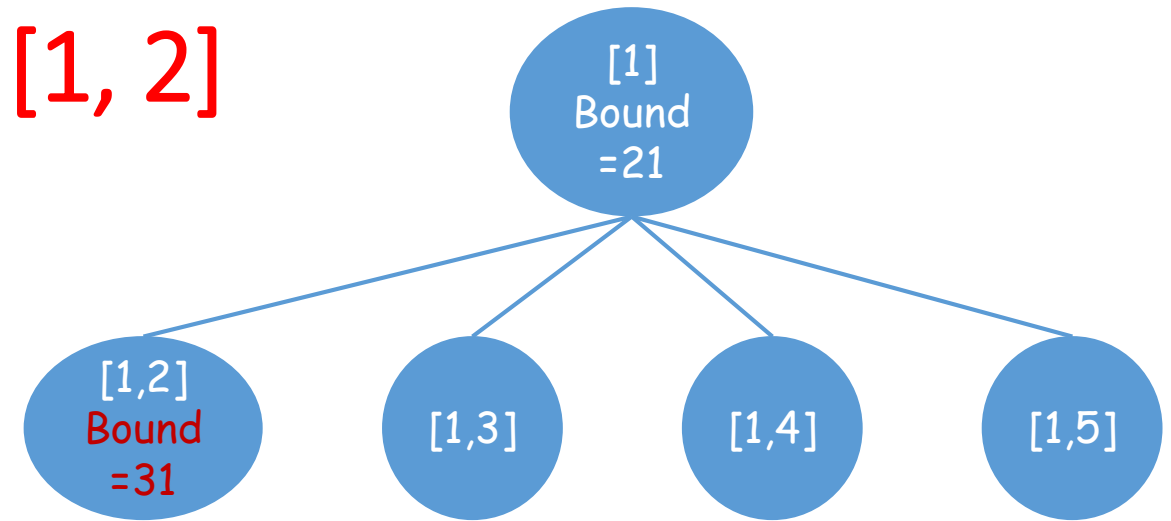
$$v_5 \quad \text{minimum}(18, 7, 17, 4) = 4$$

$$\text{Lower bound} = 4 + 7 + 4 + 2 + 4 = 21$$



	v_1	v_2	v_3	v_4	v_5
v_1	0	14	4	10	20
v_2	14	0	7	8	7
v_3	4	5	0	7	16
v_4	11	7	9	0	2
v_5	18	7	17	4	0

Computed the lower bound [1, 2]



v_1		14
v_2	$\text{minimum}(7, 8, 7)$	$= 7$
v_3	$\text{minimum}(4, 7, 16)$	$= 4$
v_4	$\text{minimum}(11, 9, 2)$	$= 2$
v_5	$\text{minimum}(18, 17, 4)$	$= 4$

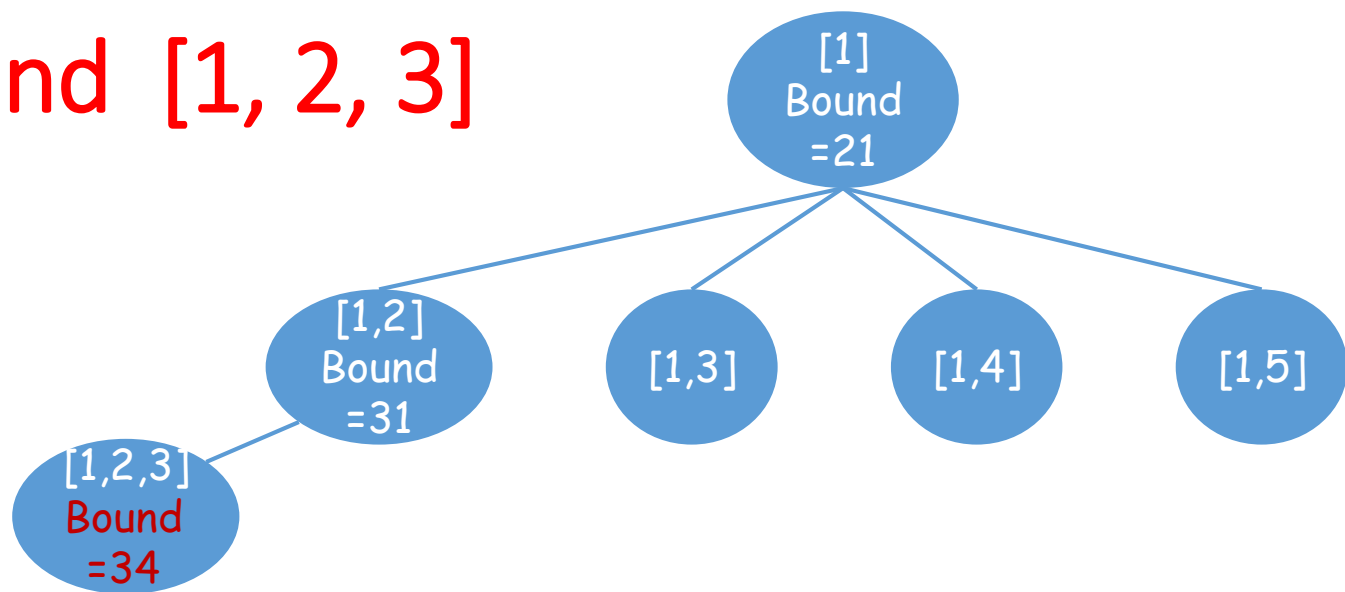
Lower bound = $14 + 7 + 4 + 2 + 4 = 31$

	v_1	v_2	v_3	v_4	v_5
v_1	0	14	4	10	20
v_2	×	0	7	8	7
v_3	4	5	0	7	16
v_4	11	7	9	0	2
v_5	18	7	17	4	0

Computed the lower bound [1, 2, 3]

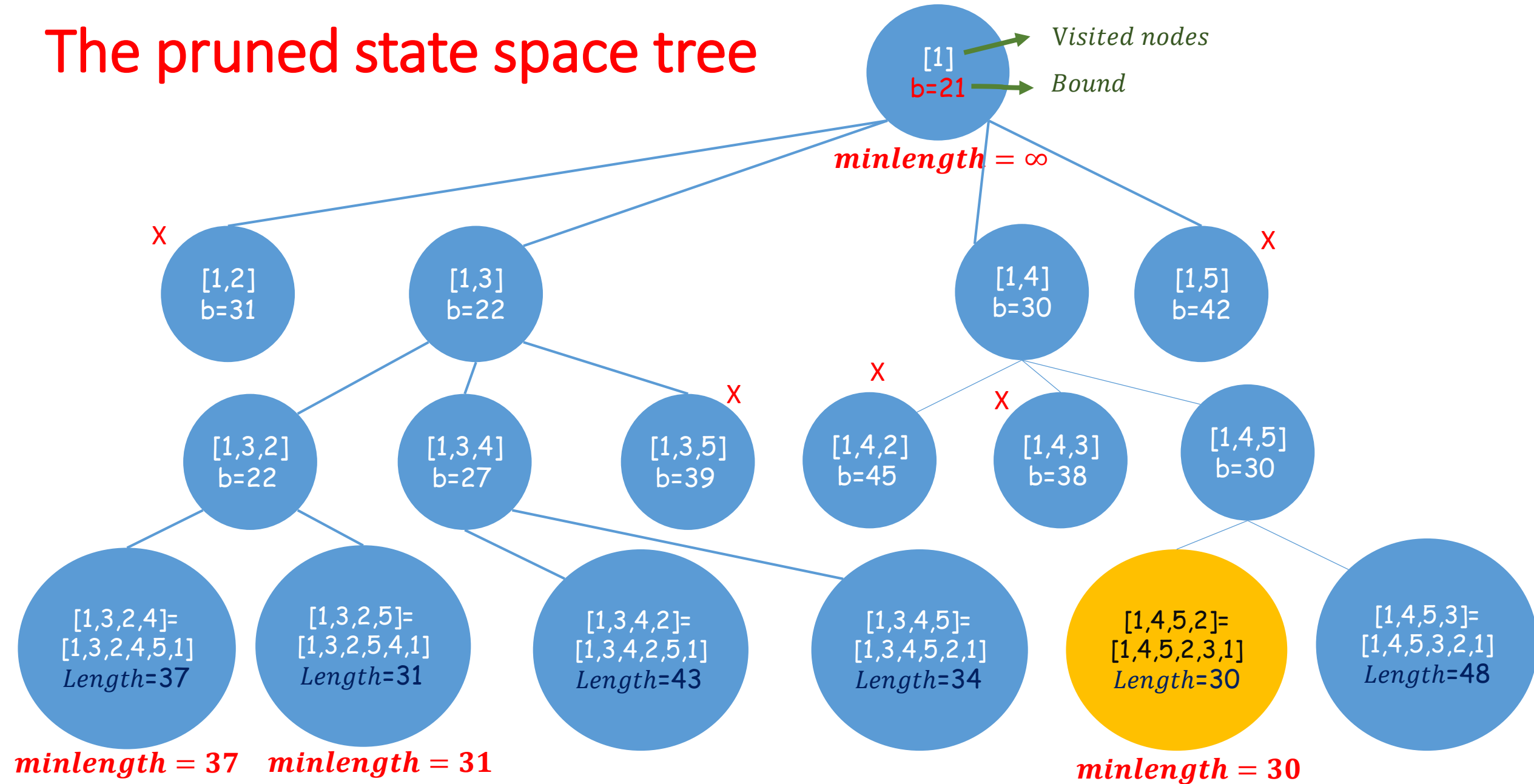
v_1 14
 v_2 7
 v_3 $\text{minimum}(7, 16) = 7$
 v_4 $\text{minimum}(11, 2) = 2$
 v_5 $\text{minimum}(18, 4) = 4$

Lower bound = $14 + 7 + 7 + 2 + 4 = 34$



	v_1	v_2	v_3	v_4	v_5
v_1	0	14	0	10	20
v_2	×	0	7	8	7
v_3	×	5	0	7	16
v_4	11	7	9	0	2
v_5	18	7	17	4	0

The pruned state space tree



- A node is nonpromising if this bound is greater than or equal to $minlength$

The **Best-First Search** with Branch-and-Bound Pruning Algorithm for the TSP

Problem: Determine an optimal tour in a weighted, directed graph. The weights are nonnegative numbers.

Inputs: a weighted, directed graph, and n , the number of vertices in the graph. The graph is represented by a two-dimensional array W , which has both its rows and columns indexed from 1 to n , where $W[i][j]$ is the weight on the edge from the i th vertex to the j th vertex.

Outputs: variable *minlength*, whose value is the length of an optimal tour, and variable *opttour*, whose value is an optimal tour.

The **Best-First Search** with Branch-and-Bound Pruning Algorithm for the the Traveling Salesman Problem

```
struct node
{
    int level;           // the node's level in the tree
    ordered_set path;
    number bound;
};

void travel2 (int n,
              const number W[] [],
              ordered-set& opttour,
              number& minlength)
{
    priority_queue_of_node PQ;
    node u, v;
```

```

    initialize(PQ);
    v.level = 0;
    v.path = [1];
    v.bound = bound(v);
    minlength =  $\infty$ ;
    insert(PQ, v);
    while (! empty(PQ)){
        remove(PQ, v);
        if (v.bound < minlength){
            u.level = v.level + 1;
            for (all i such that  $2 \leq i \leq n$  && i is not in v.path){
                u.path = v.path;
                put i at the end of u.path;
                if (u.level == n - 2){
                    put index of only vertex
                    not in u.path at the end of u.path;
                    put 1 at the end of u.path;
                    if (length(u) < minlength){
                        minlength = length(u);
                        opttour = u.path;
                    }
                }
            }
            else{
                u.bound = bound(u);
                if (u.bound < minlength)
                    insert(PQ, u);
            }
        }
    }
}

```

// Initialize PQ to be empty.

// Make first vertex the starting one.

// Remove node with best bound.

// Set u to a child of v.

// Check if next vertex completes a tour.

// Make first vertex last one.

// Function length computes the length of the tour.

Homework

- Write a program to solve the Travelling Salesman Problem (TSP) problem by using branch-and-bound strategy.
- Can the branch-and-bound design strategy be used to solve the matrix-chain multiplication problem? Please explain your answer.