LaTeX (Matematik)

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1 Getting Started

LaTeX (Matematik) Today I am learning LATEX. LATEX is a great program for writing math. I can write in line math such as $a^2 + b^2 = c^2$. I can also give equations their own space:

$$\gamma^2 + \theta^2 = \omega^2 \tag{1}$$

"Maxwell's equations" are named for James Clark Maxwell and are as follow:

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\varepsilon_0}$$
 Gauss's Law (2)

$$\vec{\nabla} \cdot \vec{B} = 0$$
 Gauss's Law for Magnetism (3)

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$
 Faraday's Law of Induction (4)

$$\vec{\nabla} \times \vec{B} = \mu_0 \left(\varepsilon_0 \frac{\partial \vec{E}}{\partial t} + \vec{J} \right)$$
 Ampere's Circuital Law (5)

Denklem 2, 3, 4 and 5 are some of the most important in Physics.

2 What about Matrix Equations?

$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix}$$

$$\iiint_{V} f(x, y, z) \, dV = F$$

$$\frac{dx}{dy} = x' = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h} = 0$$

$$|x| = \begin{cases} -x & \text{if } x < 0 \text{ ise} \\ x & \text{if } x \ge 0 \text{ ise} \end{cases}$$

$$F(x) = A_0 + \sum_{n=1}^{N} \left[A_n \cos\left(\frac{2\pi n}{P}\right) + B_n \sin\left(\frac{2\pi n}{P}\right) \right]$$

$$\sum_{n=1}^{\infty} \frac{1}{n^s} = \prod_{P} \frac{1}{1 - \frac{1}{P^n}}$$

$$m\ddot{x} + c\dot{x} + kx = F_0 \sin(2\pi f t)$$

$$f(x) = x^2 + 3x + 5x^2 + 8 + 6x$$

$$= 6x^2 + 9x + 8$$

$$= x(6x+9) + 8$$

$$X = \frac{F_0}{k} \frac{1}{\sqrt{(1 - r^2)^2 + (2\zeta r^2)}}$$

$$G_{\mu\nu} \equiv R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = \frac{8\pi G}{c^4} T_{\mu\nu}$$

$$6CO_2 + 6H_2O \to C_6H_12O_6 + 6O_2$$

$$SO_4^{2-} + Ba^{2+} \to BaSO_4$$

$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} \quad \begin{array}{c} w_1 \\ w_2 \\ \vdots \\ v_n \end{bmatrix}$$

$$\frac{\partial_u}{\partial_t} + (u.\nabla)u - v\nabla^2(u) = -\nabla h$$

 $\alpha A\beta B\gamma \Gamma\delta\Delta\pi\Pi\omega\Omega$